PI74FCT16646T
PI74FCT162646T
PI74FCT162H646T

Fast CMOS 16-Bit Registered Transceivers

Product Features

Common Features:

• PI74FCT16646T, PI74FCT162646T, and PI74FCT162H646 are high-speed, low power devices with high current drive

• V_{CC} = 5V ± 10%

• Hysteresis on all inputs

• Packages available:
  – 56-pin 240 mil wide plastic TSSOP (A)
  – 56-pin 173 mil wide plastic TVSOP (JEDEC TSSOP K)
  – 56-pin 300 mil wide plastic SSOP (V)

PI74FCT16646T Features:

• High output drive: I_{OH} = –32mA; I_{OL} = 64mA

• Power off disable outputs permit "live insertion"

• Typical V_{OLP} (Output Ground Bounce)
  < 1.0V at V_{CC} = 5V, T_A = 25°C

PI74FCT162646T Features:

• Balanced output drivers: ±24mA

• Reduced system switching noise

• Typical V_{OLP} (Output Ground Bounce)
  < 0.6V at V_{CC} = 5V, T_A = 25°C

PI74FCT162H646T Features:

• Bus Hold retains last active bus state during Three-state

• Eliminates the need for external pull-up resistors

Product Description

Pericom Semiconductor's PI74FCT series of logic circuits are produced in the Company's advanced 0.6 micron CMOS technology, achieving industry leading speed grades.

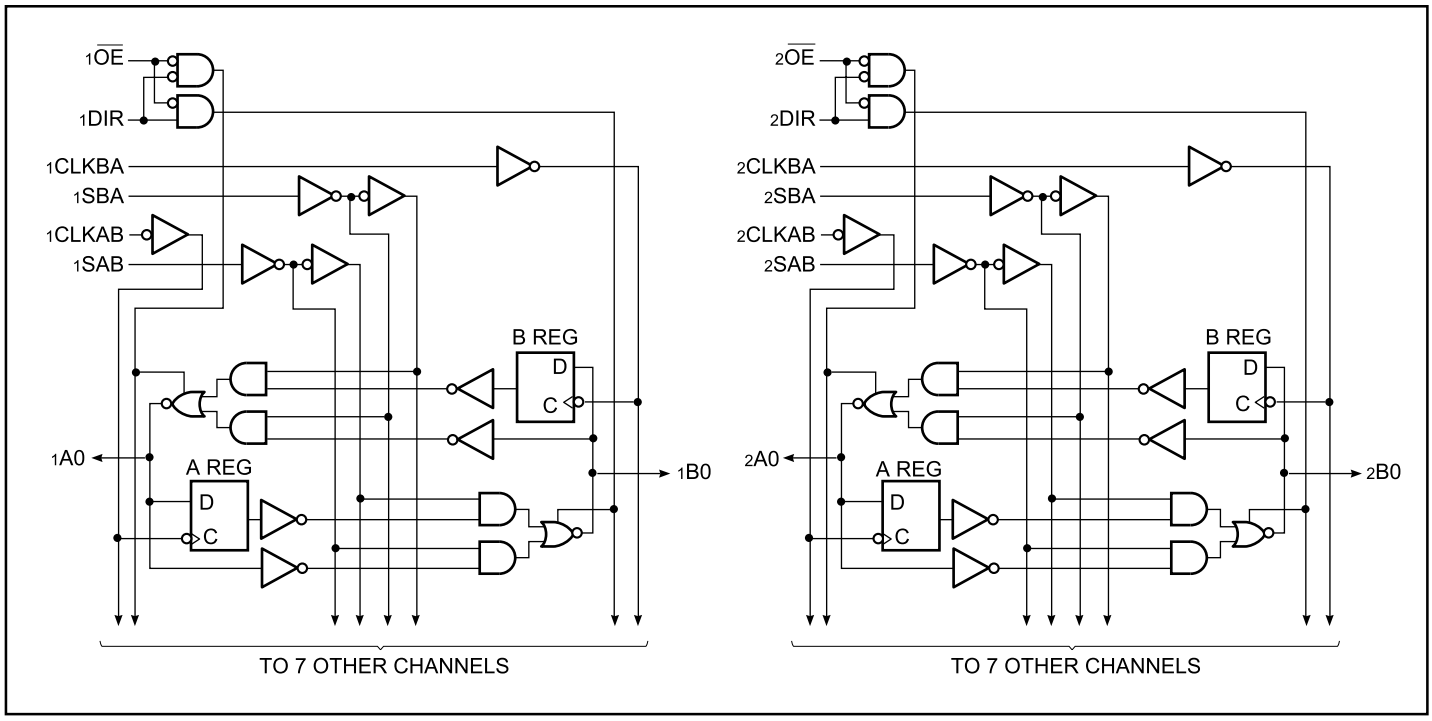
The PI74FCT16646T, PI74FCT162646T, and PI74FCT162H646 are 16-bit registered transceivers organized as two independent 8-bit bus transceivers designed with 3-state D-type flip-flops and control circuitry arranged for multiplexed transmission of data directly from the data bus or from the internal storage registers. Each 8-bit transceiver utilizes the enable control ($x\overline{OE}$) and direction pins (xDIR) to control the transceiver functions. The Select (xSAB and xSBA) control pins are used to select either real-time or stored data transfer. The circuitry used for select control will eliminate the typical decoding glitch that occurs in a multiplexer during the transition between real-time and stored data. A low input level selects real-time data and a high selects stored data.

The PI74FCT16646T output buffers are designed with a Power-Off disable allowing "live insertion" of boards when used as backplane drivers.

The PI74FCT162646T has ±24mA balanced output drivers. It is designed with current limiting resistors at its outputs to control the output edge rate resulting in lower ground bounce and undershoot. This eliminates the need for external terminating resistors for most interface applications.

The PI74FCT162H646T has "Bus Hold" which retains the input's last state whenever the input goes to high-impedance preventing "floating" inputs and eliminating the need for pull-up/down resistors.

Logic Block Diagram

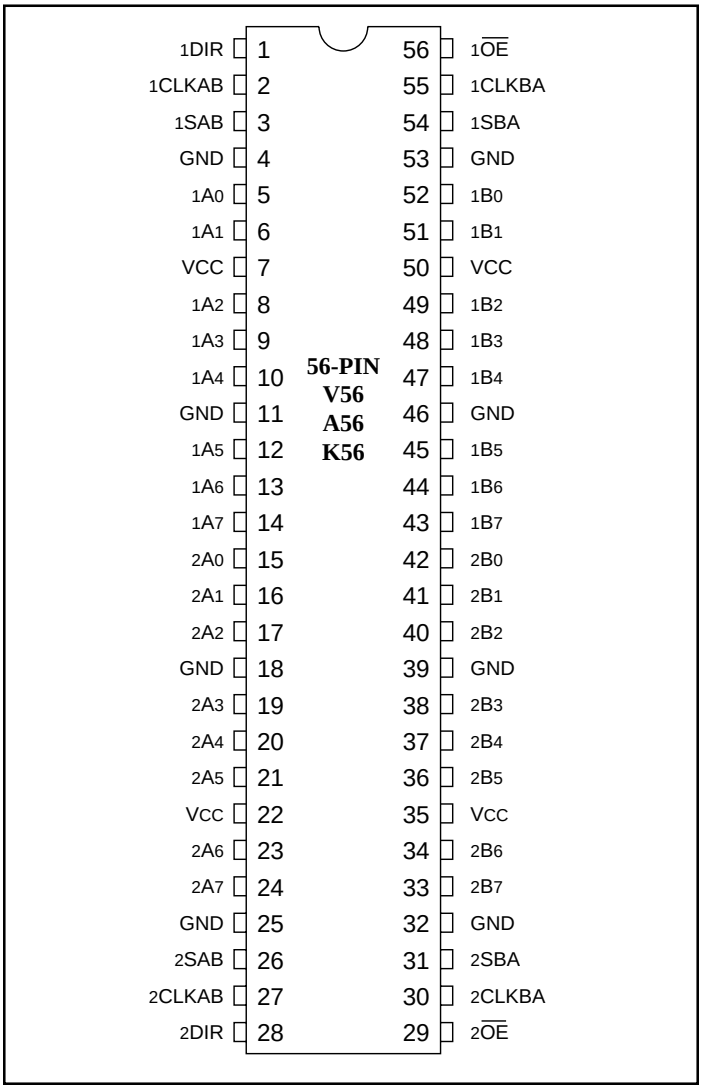


Truth Table

	Inputs						DATA I/O[2]	
Function/Operation	**x$\overline{OE}$**	**xDIR**	**xCLKAB**	**xCLKBA**	**xSAB**	**xSBA**	**xAx**	**xBx**
Isolation	H	X	H or L	H or L	X	X	Input	Input
Store A and B Data	H	X	↑	↑	X	X		
Real Time B Data to A Bus	L	L	X	X	X	L	Output	Input
Stored B Data to A Bus	L	L	X	H or L	X	H		
Real Time A Data to B Bus	L	H	X	X	L	X	Input	Output
Stored A Data to B Bus	L	H	H or L	X	H	X		

Notes:
1.The data output functions may be enabled or disabled by various signals at the x$\overline{OE}$ or xDIR inputs.
Data input functions are always enabled, i.e., data at the bus pins will be stored on every low-to-high transition on the clock inputs.
2. Select control = L: clocks can occur simultaneously.
Select control = H: clocks must be staggered to load both registers.
H = High Voltage Level; L = Low Voltage Level; X = Don't Care; ↑ = LOW-to-HIGH transition

Product Pin Configuration

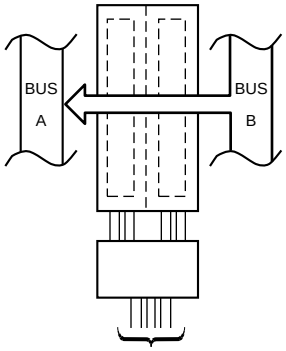


Product Pin Description

Pin Name	Description
xAx[1]	Data Register A Inputs Data Register B Outputs
xBx[1]	Data Register B Inputs Data Register A Outputs
xCLKAB, xCLKBA	Clock Pulse Inputs
SAB, SBA	Output Data Source Select Inputs
xDIR, x$\overline{OE}$	Output Enable Inputs
GND	Ground
V_{CC}	Power

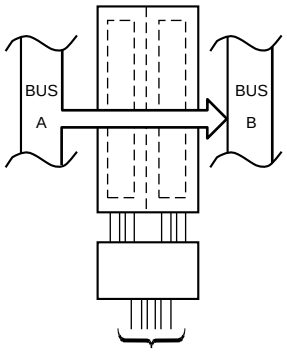
Note: 1.For the PI74FCT162H646T, these pins have "Bus Hold." All other pins are standard, outputs, or I/Os.

REAL-TIME TRANSFER
BUS B TO A



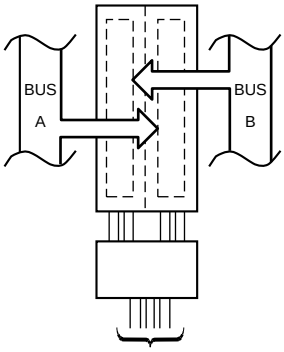
xDIR	$\overline{\text{xOE}}$	xCLKAB	xCLKBA	xSAB	xSBA
L	L	X	X	X	L

REAL-TIME TRANSFER
BUS A TO B



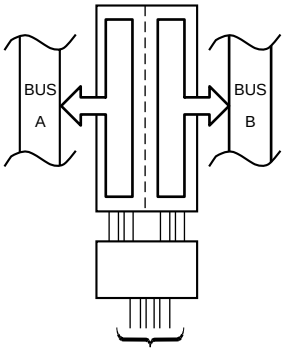
xDIR	$\overline{\text{xOE}}$	xCLKAB	xCLKBA	xSAB	xSBA
H	L	X	X	L	X

STORAGE FROM
A AND/OR B



xDIR	$\overline{\text{xOE}}$	xCLKAB	xCLKBA	xSAB	xSBA
H	L		X	X	X
L	L	X		X	X
X	H			X	X

TRANSFER STORES
DATA TO A AND/OR B



xDIR	$\overline{\text{xOE}}$	xCLKAB	xCLKBA	xSAB	xSBA
L	L	X	H or L	X	H
H	L	H or L	X	H	X

Maximum Ratings

(Above which the useful life may be impaired. For user guidelines, not tested.)

Storage Temperature	–65°C to +150°C
Ambient Temperature with Power Applied	–40°C to +85°C
Supply Voltage to Ground Potential (Inputs & Vcc Only)	–0.5V to +7.0V
Supply Voltage to Ground Potential (Outputs & D/O Only)	–0.5V to +7.0V
DC Input Voltage	–0.5V to +7.0V
DC Output Current	120mA
Power Dissipation	1.0W

Note:
Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

DC Electrical Characteristics (Over the Operating Range, T_A = –40°C to +85°C, V_{CC} = 5.0V ± 10%)

Parameters	Description	Test Conditions[1]		Min.	Typ.[2]	Max.	Units
V_{IH}	Input HIGH Voltage	Guaranteed Logic HIGH Level		2.0			V
V_{IL}	Input LOW Voltage	Guaranteed Logic LOW Level				0.8	V
I_{IH}	Input HIGH Current	Standard Input, V_{CC} = Max.	V_{IN} = V_{CC}			1	µA
I_{IH}	Input HIGH Current	Standard I/O, V_{CC} = Max.	V_{IN} = V_{CC}			1	µA
I_{IH}	Input HIGH Current	Bus Hold Input[4], V_{CC} = Max.	V_{IN} = V_{CC}			±100	µA
I_{IH}	Input HIGH Current	Bus Hold I/O[4], V_{CC} = Max.	V_{IN} = V_{CC}			±100	µA
I_{IL}	Input LOW Current	Standard Input, V_{CC} = Min.	V_{IN} = GND			–1	µA
I_{IL}	Input LOW Current	Standard I/O, V_{CC} = Min.	V_{IN} = GND			–1	µA
I_{IL}	Input LOW Current	Bus Hold Input[4], V_{CC} = Min.	V_{IN} = GND			±100	µA
I_{IL}	Input LOW Current	Bus Hold I/O[4], V_{CC} = Min.	V_{IN} = GND			±100	µA
I_{BHH}	Bus Hold	Bus Hold Input[4], V_{CC} = Min.	V_{IN} = 2.0V	–50			µA
I_{BHL}	Sustain Current		V_{IN} = 0.8V	+50			
I_{OZH}[5]	High-Impedance	V_{CC} = Max.	V_{OUT} = 2.7V			1	µA
I_{OZL}[5]	Output Current (3-State Outputs)	V_{CC} = Max.	V_{OUT} = 0.5V			–1	µA
V_{IK}	Clamp Diode Voltage	V_{CC} = Min., I_{IN} = –18mA			–0.7	–1.2	V
I_{OS}	Short Circuit Current	V_{CC} = Max.[3], V_{OUT} = GND		–80	–140	–200	mA
I_O	Output Drive Current	V_{CC} = Max.[3], V_{OUT} = 2.5V		–50		–180	mA
V_H	Input Hysteresis				100		mV

Notes:
1. For Max. or Min. conditions, use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at Vcc = 5.0V, +25°C ambient and maximum loading.
3. Not more than one output should be shorted at one time. Duration of the test should not exceed one second.
4. Pins with Bus Hold are identified in the pin description.
5. This specification does not apply to bi-directional functionalities with Bus Hold.

PI74FCT16646T Output Drive Characteristics (Over the Operating Range)

Parameters	Description	Test Conditions[1]		Min.	Typ.[2]	Max.	Units
V_{OH}	Output HIGH Voltage	V_{CC} = Min., V_{IN} = V_{IH} or V_{IL}	I_{OH} = –3.0mA	2.5	3.5		V
			I_{OH} = –15.0mA	2.4	3.5		
			I_{OH} = –32.0mA	2.0	3.0		
V_{OL}	Output LOW Voltage	V_{CC} = Min., V_{IN} = V_{IH} or V_{IL}	I_{OL} = 64mA		0.2	0.55	V
I_{OFF}	Power Down Disable	V_{CC} = 0V, V_{IN} or $V_{OUT} \leq$ 4.5V		—	—	±100	µA

PI74FCT162646T/162H646T Output Drive Characteristics (Over the Operating Range)

Parameters	Description	Test Conditions[1]		Min.	Typ.[2]	Max.	Units
V_{OH}	Output HIGH Voltage	V_{CC} = Min., V_{IN} = V_{IH} or V_{IL}	I_{OH} = –24.0mA	2.4	3.3		V
V_{OL}	Output LOW Voltage	V_{CC} = Min., V_{IN} = V_{IH} or V_{IL}	I_{OL} = 24mA		0.3	0.55	V
I_{ODL}	Output LOW Current	V_{CC} = 5V, V_{IN} = V_{IH} OR V_{IL}, V_{OUT} = 1.5V[3]		60	115	150	mA
I_{ODH}	Output HIGH Current	V_{CC} = 5V, V_{IN} = V_{IH} OR V_{IL}, V_{OUT} = 1.5V[3]		–60	–115	–150	mA

Capacitance (T_A = 25°C, f = 1 MHz)

Parameters[4]	Description	Test Conditions	Typ.	Max.	Units
C_{IN}	Input Capacitance	V_{IN} = 0V	4.5	6	pF
C_{OUT}	Output Capacitance	V_{OUT} = 0V	5.5	8	pF

Notes:
1. For Max. or Min. conditions, use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at Vcc = 5.0V, +25°C ambient and maximum loading.
3. Not more than one output should be shorted at one time. Duration of the test should not exceed one second.
4. This parameter is determined by device characterization but is not production tested.

Power Supply Characteristics

Parameters	Description	Test Conditions[1]		Min.	Typ.[2]	Max.	Units
I_{CC}	Quiescent Power Supply Current	V_{CC} = Max.	V_{IN} = GND or V_{CC}		0.12	500	µA
ΔI_{CC}	Supply Current per Input @ TTL HIGH	V_{CC} = Max.	V_{IN} = 3.4V[3]		0.5	1.5	mA
I_{CCD}	Supply Current per Input per MHz[4]	V_{CC} = Max., Outputs Open xDIR = x$\overline{OE}$ = GND One Bit Toggling 50% Duty Cycle	V_{IN} = V_{CC} V_{IN} = GND		75	120	µA/ MHz
I_C	Total Power Supply Current[6]	V_{CC} = Max., Outputs Open f_{CP} = 10 MHz (xCLKBA) 50% Duty Cycle xDIR = x$\overline{OE}$ = GND One Bit Toggling f_I = 5 MHz 50% Duty Cycle	V_{IN} = V_{CC} V_{IN} = GND		0.8	1.7[5]	mA
			V_{IN} = 3.4V V_{IN} = GND		1.3	3.2[5]	
		V_{CC} = Max., Outputs Open f_{CP} = 10 MHz (xCLKBA) 50% Duty Cycle xDIR = x$\overline{OE}$ = GND 16 Bits Toggling f_I = 2.5 MHz 50% Duty Cycle	V_{IN} = V_{CC} V_{IN} = GND		3.8	6.5[5]	
			V_{IN} = 3.4 V_{IN} = GND		8.3	20.0[5]	

Notes:

1. For Max. or Min. conditions use appropriate value specified under Electrical Characteristics for the applicable device.
2. Typical values are at Vcc = 5.0V, +25°C ambient.
3. Per TTL driven input (V_{IN} = 3.4V); all other inputs at Vcc or GND.
4. This parameter is not directly testable, but is derived for use in Total Power Supply Calculations.
5. Values for these conditions are examples of the Icc formula. These limits are guaranteed but not tested.
6. $I_C = I_{QUIESCENT} + I_{INPUTS} + I_{DYNAMIC}$
   $I_C = I_{CC} + \Delta I_{CC} D_H N_T + I_{CCD} (f_{CP}/2 + f_I N_I)$
   I_{CC} = Quiescent Current
   ΔI_{CC} = Power Supply Current for a TTL High Input (V_{IN} = 3.4V)
   D_H = Duty Cycle for TTL Inputs High
   N_T = Number of TTL Inputs at D_H
   I_{CCD} = Dynamic Current Caused by an Input Transition Pair (HLH or LHL)
   f_{CP} = Clock Frequency for Register Devices (Zero for Non-Register Devices)
   f_I = Input Frequency
   N_I = Number of Inputs at f_I
   All currents are in milliamps and all frequencies are in megahertz.

PI74FCT16646T Switching Characteristics over Operating Range

Parameters	Description	Conditions[1]	16646T Com. Min.	16646T Com. Max.	16646AT Com. Min.	16646AT Com. Max.	16646CT Com. Min.	16646CT Com. Max.	16646DT Com. Min.	16646DT Com. Max.	16646ET Com. Min.	16646ET Com. Max.	Units
t_{PLH} t_{PHL}	Propagation Delay Bus to Bus	C_L = 50 pF R_L = 500Ω	2.0	9.0	2.0	6.3	1.5	5.4	1.5	4.4	1.5	3.8	ns
t_{PZH} t_{PZL}	Output Enable Time xDIR or x$\overline{OE}$ to Bus		2.0	14.0	2.0	9.8	1.5	7.8	1.5	5.0	1.5	4.8	ns
t_{PHZ} t_{PLZ}	Output Disable Time[3] xDIR or x$\overline{OE}$ to Bus		2.0	9.0	2.0	6.3	1.5	6.3	1.5	4.3	1.5	4.0	ns
t_{PLH} t_{PHL}	Propagation Delay Clock to Bus		2.0	9.0	2.0	6.3	1.5	5.7	1.5	4.4	1.5	3.8	ns
t_{PLH} t_{PHL}	Propagation Delay xSBA or xSAB to Bus		2.0	11.0	2.0	7.7	1.5	6.2	1.5	5.0	1.5	4.2	ns
t_{SU}	Setup Time HIGH or LOW, Bus to Clock		4.0	—	2.0	—	2.0	—	2.0	—	2.0	—	ns
t_H	Hold Time HIGH or LOW, Bus to Clock		2.0	—	1.5	—	1.5	—	1.0	—	0.0	—	ns
t_W	Clock Pulse Width HIGH or LOW[3]		6.0	—	5.0	—	5.0	—	3.0	—	3.0	—	ns
$t_{SK}(o)$	Output Skew[4]		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns

PI74FCT162646T Switching Characteristics over Operating Range

Parameters	Description	Conditions[1]	162646T Com. Min.	162646T Com. Max.	162646AT Com. Min.	162646AT Com. Max.	162646CT Com. Min.	162646CT Com. Max.	162646DT Com. Min.	162646DT Com. Max.	162646ET Com. Min.	162646ET Com. Max.	Units
t_{PLH} t_{PHL}	Propagation Delay Bus to Bus	C_L = 50 pF R_L = 500Ω	2.0	9.0	2.0	6.3	1.5	5.4	1.5	4.4	1.5	3.8	ns
t_{PZH} t_{PZL}	Output Enable Time xDIR or x$\overline{OE}$ to Bus		2.0	14.0	2.0	9.8	1.5	7.8	1.5	5.0	1.5	4.8	ns
t_{PHZ} t_{PLZ}	Output Disable Time[3] xDIR or x$\overline{OE}$ to Bus		2.0	9.0	2.0	6.3	1.5	6.3	1.5	4.3	1.5	4.0	ns
t_{PLH} t_{PHL}	Propagation Delay Clock to Bus		2.0	9.0	2.0	6.3	1.5	5.7	1.5	4.4	1.5	3.8	ns
t_{PLH} t_{PHL}	Propagation Delay xSBA or xSAB to Bus		2.0	11.0	2.0	7.7	1.5	6.2	1.5	5.0	1.5	4.2	ns
t_{SU}	Setup Time HIGH or LOW, Bus to Clock		4.0	—	2.0	—	2.0	—	2.0	—	2.0	—	ns
t_H	Hold Time HIGH or LOW, Bus to Clock		2.0	—	1.5	—	1.5	—	1.0	—	0.0	—	ns
t_W	Clock Pulse Width HIGH or LOW[3]		6.0	—	5.0	—	5.0	—	3.0	—	3.0	—	ns
$t_{SK}(o)$	Output Skew[4]		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns

Notes:
1. See test circuit and wave forms.
2. Minimum limits are guaranteed but not tested on Propagation Delays.
3. This parameter is guaranteed but not production tested.
4. Skew between any two outputs, of the same package, switching in the same direction. This parameter is guaranteed by design.

PI74FCT162H646T Switching Characteristics over Operating Range

Parameters	Description	Conditions[1]	162H646T Com.		162H646AT Com.		162H646CT Com.		162H646DT Com.		162H646ET Com.		Units
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
t_{PLH} t_{PHL}	Propagation Delay Bus to Bus	C_L = 50 pF R_L = 500Ω	2.0	9.0	2.0	6.3	1.5	5.4	1.5	4.4	1.5	3.8	ns
t_{PZH} t_{PZL}	Output Enable Time xDIR or x$\overline{OE}$ to Bus		2.0	14.0	2.0	9.8	1.5	7.8	1.5	5.0	1.5	4.8	ns
t_{PHZ} t_{PLZ}	Output Disable Time[3] xDIR or x$\overline{OE}$ to Bus		2.0	9.0	2.0	6.3	1.5	6.3	1.5	4.3	1.5	4.0	ns
t_{PLH} t_{PHL}	Propagation Delay Clock to Bus		2.0	9.0	2.0	6.3	1.5	5.7	1.5	4.4	1.5	3.8	ns
t_{PLH} t_{PHL}	Propagation Delay xSBA or xSAB to Bus		2.0	11.0	2.0	7.7	1.5	6.2	1.5	5.0	1.5	4.2	ns
t_{SU}	Setup Time HIGH or LOW, Bus to Clock		4.0	—	2.0	—	2.0	—	2.0	—	2.0	—	ns
t_H	Hold Time HIGH or LOW, Bus to Clock		2.0	—	1.5	—	1.5	—	1.0	—	0.0	—	ns
t_W	Clock Pulse Width HIGH or LOW[3]		6.0	—	5.0	—	5.0	—	3.0	—	3.0	—	ns
$t_{SK}(o)$	Output Skew[4]		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns

Notes:
1. See test circuit and wave forms.
2. Minimum limits are guaranteed but not tested on Propagation Delays.
3. This parameter is guaranteed but not production tested.
4. Skew between any two outputs, of the same package, switching in the same direction. This parameter is guaranteed by design.