

RC2211

FSK Demodulator/Tone Decoder

Features

- Wide frequency range – 0.01 Hz to 300 kHz
- Wide supply voltage range – 4.5V to 20V
- DTL/TTL/ECL logic compatibility
- FSK demodulation with carrier-detector
- Wide dynamic range – 2 mV to 3 VRMS
- Adjustable tracking range – $\pm 1\%$ to $\pm 80\%$
- Excellent temperature stability – 20 ppm/ $^{\circ}\text{C}$ typical

Applications

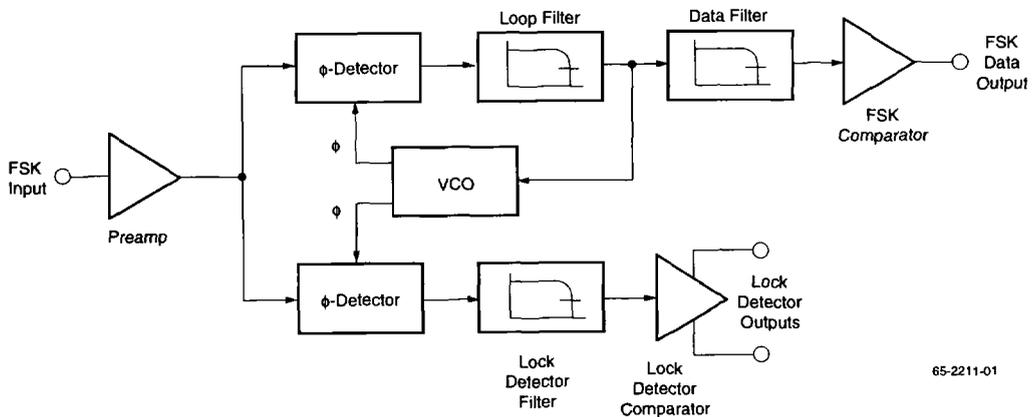
- FSK demodulation
- Data synchronization
- Tone decoding
- FM detection
- Carrier detection

Description

The RC2211 is a monolithic phase-locked loop (PLL) system especially designed for data communications. It is particularly well-suited for FSK modem applications, and operates over a wide frequency range of 0.01 Hz to 300 kHz. It can accommodate analog signals between 2 mV and 3V, and can interface with conventional DTL, TTL and ECL logic families. The circuit consists of a basic PLL for

tracking an input signal frequency within the passband, a quadrature phase detector which provides carrier detection, and an FSK voltage comparator which provides FSK demodulation. External components are used to independently set carrier frequency, bandwidth and output delay.

Block Diagram



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Description of Circuit Controls

Signal Input (Pin 2)

The input signal is AC coupled to this terminal. The internal impedance at pin 2 is 20 kΩ. Recommended input signal level is in the range of 10 mVRMS to 3 VRMS.

Quadrature Phase Detector Output, Q (Pin 3)

This is the high impedance output of the quadrature phase detector, and is internally connected to the input of lock detector voltage comparator. In tone detection applications, pin 3 is connected to ground through a parallel combination of R_D and C_D (see Figure 1) to eliminate chatter at the lock detector outputs. If this tone detector section is not used, pin 3 can be left open circuited.

Lock Detector Output, Q (Pin 5)

The output at pin 5 is at a "high" state when the PLL is out of lock and goes to a "low" or conducting state when the PLL is locked. It is an open collector output and requires a pull-up resistor, R_L , to $+V_S$ for proper operation. In the "low" state it can sink up to 5 mA of load current.

Lock Detector Complement, \bar{Q} (Pin 6)

The output at pin 6 is the logic complement of the lock detector output at pin 5. This output is also an open collector type stage which can sink 5 mA of load current in the low or "on" state.

FSK Data Output (Pin 7)

This output is an open collector stage which requires a pull-up resistor, R_L , to $+V_S$ for proper operation. It can sink 5 mA of load current. When decoding FSK signals the FSK data output will switch to a "high" or off state for low input frequency, and will switch to a "low" or on state for high input frequency. If no input signal is present, the logic state at pin 7 is indeterminate.

FSK Comparator Input (Pin 8)

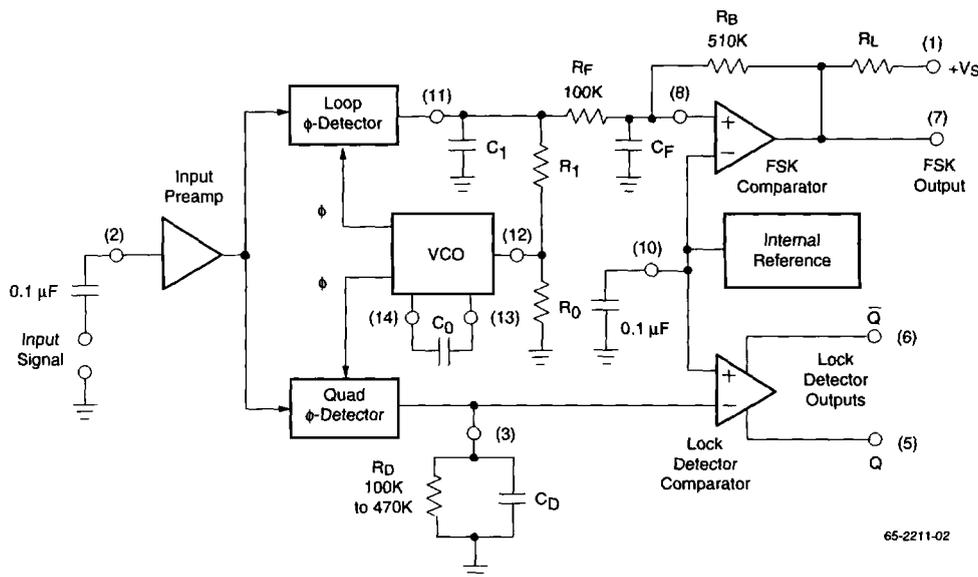
This is the high impedance input to the FSK voltage comparator. Normally, an FSK post detection or data filter is connected between this terminal and the PLL phase detector output (pin 11). This data filter is formed by R_F and C_F of Figure 1. The threshold voltage of the comparator is set by the internal reference voltage, V_R , available at pin 10.

Reference Bypass (Pin 9)

This pin can have an optional 0.1 μ F capacitor connected to the ground.

Reference Voltage, V_R (Pin 10)

This pin is internally biased at the reference voltage level, V_R ; $V_R = +V_S/2 - 650$ mV. The DC voltage level at this pin forms an internal reference for the voltage levels at pin 3, 8, 11 and 12. Pin 10 must be bypassed to ground with a 0.1 μ F capacitor.



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Figure 1. Generalized Circuit Connection for FSK and Tone Detection

Loop Phase Detector Output (Pin 11)

This terminal provides a high impedance output for the loop phase detector. The PLL loop filter is formed by R1 and C1 connected to pin 11 (see Figure 1). With no input signal, or with no phase error within the PLL, the DC level at pin 11 is very nearly equal to VR. The peak voltage swing available at the phase detector output is equal to ±VR.

VCO Control Input (Pin 12)

VCO free running frequency is determined by external timing resistor, R0, connected from this terminal to ground. The VCO free running frequency, F0 is given by:

$$F_0 \text{ (Hz)} = \frac{1}{R_0 C_0}$$

where C0 is the timing capacitor across pins 13 and 14. For optimum temperature stability R0 must be in the range of 10 kΩ to 100 kΩ (see Typical Performance Characteristics).

This terminal is a low impedance point, and is internally biased at a DC level equal to VR. The maximum timing current drawn from pin 12 must be limited to ≤3 mA for proper operation of the circuit.

VCO Timing Capacitor (Pins 13 and 14)

VCO frequency is inversely proportional to the external timing capacitor, C0, connected across these terminals. C0 must be non-polarized, and in the range of 200 pF to 10 μF.

VCO Frequency Adjustment

VCO can be fine tuned by connecting a potentiometer, Rx, in series with R0 at pin 12 (see Figure 2).

VCO Free-Running Frequency, F0

The RC2211 does not have a separate VCO output terminal. Instead, the VCO outputs are internally connected to the phase detector sections of the circuit. However, for set-up or adjustment purposes, the VCO freerunning frequency can be measured at pin 3 (with CD disconnected) with no input and with pin 2 shorted to pin 10.

Design Equations

See Figure 1 for Definitions of Components.

1. VCO Center Frequency, F0:

$$F_0 \text{ (Hz)} = \frac{1}{R_0 C_0}$$

2. Internal Reference Voltage, VR (measured at pin 10)

$$V_R = \left(\frac{+V_S}{2} \right) - 650 \text{ mV}$$

3. Loop Lowpass Filter Time Constant, τ

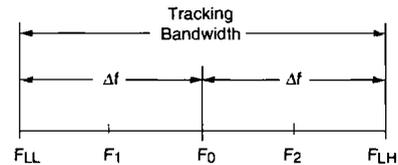
$$\tau = R_1 C_1$$

4. Loop Dampening, ζ:

$$\zeta = \left(\sqrt{\frac{C_0}{C_1}} \right) \left(\frac{1}{4} \right)$$

5. Loop Tracking Bandwidth, ±ΔF/F0:

$$\Delta F/F_0 = R_0/R_1$$



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6. FSK Data Filter Time Constant, τF:

$$\tau_F = R_F C_F$$

7. Loop Phase Detector Conversion Gain, Kφ (Kφ is the differential DC voltage across pins 10 and 11, per unit of phase error at phase-detector input):

$$k_\phi \text{ (in volts per radian)} = \frac{(-2)(V_R)}{\pi}$$

8. VCO Conversion Gain, K0 is the amount of change in VCO frequency per unit of DC voltage change at pin 11:

$$K_0 \text{ (in Hertz per volt)} = \frac{-1}{C_0 R_1 V_R}$$

9. Total Loop Gain, KT:

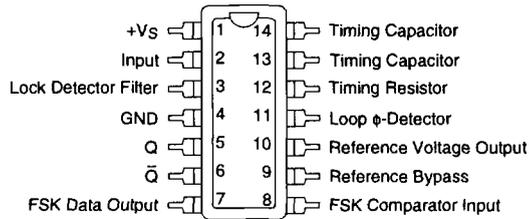
$$K_T \text{ (in radians per second per volt)} = 2 \pi K_\phi K_0$$

$$= \frac{4}{C_0 R_1}$$

10. Peak Phase Detector Current, IA:

$$I_A \text{ (mA)} = \frac{V_R}{25}$$

Pin Assignments



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Absolute Maximum Ratings

Parameter		Min	Max	Unit
Supply Voltage		-20	+20	V
Input Signal Level			3	VRMS
Storage Temperature Range		-65	+150	°C
Operating Temperature Range	RM2211D	-55	+125	°C
	RV2211N	-25	+85	°C
	RC2211N	-0	+70	°C
Junction Temperature	PDIP		+125	°C
	CerDIP		+175	°C
Lead Soldering Temperature (60 sec.)			+300	°C
Max. Pd TA<50°C	PDIP		468	mW
	CerDIP		1042	mW

Thermal Characteristics

Parameter	14 Lead Plastic DIP	14 Lead Ceramic DIP
Therm. Res. θ_{JC}	—	60°C/W
Therm. Res. θ_{JA}	160°C/W	120°C/W
For TA > 50°C Derate at	6.5 mW/°C	8.33 mW/°C

Electrical Characteristics

(Test Conditions $+V_S = +12V$, $T_A = +25^\circ C$, $R_0 = 30\text{ k}\Omega$, $C_0 = 0.033\text{ }\mu F$. See Figure 1 for component designations.)

Parameters	Test Conditions	RV/RM2211			RC2211			Units
		Min	Typ	Max	Min	Typ	Max	
General								
Supply Voltage ²		4.5		20	4.5		20	V
Supply Current	$R_0 \geq 10\text{ k}\Omega$		4.0	9.0		5.0	11	mA
Oscillator								
Frequency Accuracy	Deviation from $f_0 = 1/R_0C_0$		± 1.0	± 3.0		± 1.0		%
Frequency Stability ¹								
Temperature Coefficient	$R_1 = \infty$		± 20	± 50		± 20		ppm/ $^\circ C$
Power Supply Rejection	$+V_S = 12 \pm 1V$ $+V_S = 5 \pm 0.5V$		0.05 0.2	0.5	0.2	0.05		%/V %/V
Upper Frequency Limit	$R_0 = 8.2\text{ k}\Omega$, $C_0 = 400\text{ pF}$	100	300			300		kHz
Lowest Practical Operating Frequency ¹	$R_0 = 2\text{ M}\Omega$, $C_0 = 50\text{ }\mu F$			0.01		0.01		Hz
Timing Resistor, R_0								
Operating Range		5.0		2000	5.0		2000	k Ω
Recommended Range		15		100	15		100	k Ω
Loop Phase Detector								
Peak Output Current	Measured at pin 11	± 150	± 200	± 300	± 100	± 200	± 300	μA
Output Offset Current			± 1.0			± 2.0		μA
Output Impedance			1.0			1.0		M Ω
Maximum Swing	Ref. to pin 10	± 4.0	± 5.0		± 4.0	± 5.0		V
Quadrature Phase Detector								
Peak Output Current ³	Measured at pin 3	100	150			150		μA
Output Impedance			1.0			1.0		M Ω
Maximum Swing			11			11		VP-P
Input Preamp								
Input Impedance	Measured at pin 2		20			20		k Ω
Input Signal Voltage Required to Cause Limiting ³			2.0	10		2.0		mVRMS
Voltage Comparator								
Input Impedance	Measured at pins 3 & 8		2.0			2.0		M Ω
Input Bias Current			100			100		nA
Voltage Gain ¹	$R_L = 5.1\text{ k}\Omega$	55	70		55	70		dB
Output Voltage Low	$I_C = 3\text{ mA}$		300			300		mV
Output Leakage Current	$V_0 = 12V$		0.01			0.01		μA
Internal Reference								
Voltage Level	Measured at pin 10	4.9	5.3	5.7	4.75	5.3	5.85	V
Output Impedance			100			100		Ω

Notes:

- Guaranteed by design.
- Individual applications may need special circuitry to function at $<12V$.
- Sample tested.

Applications

FSK Decoding

Figure 2 shows the basic circuit connection for FSK decoding. With reference to Figures 1 and 2, the functions of external components are defined as follows: R₀ and C₀ set the PLL center frequency, R₁ sets the system bandwidth, and C₁ sets the loop filter time constant and the loop damping factor. C_F and R_F form a one pole post-detection filter for the FSK data output. The resistor R_B (510 kΩ) from pin 7 to pin 8 introduces positive feedback across FSK comparator to facilitate rapid transition between output logic states.

Recommended component values for some of the most commonly used FSK bauds are given in Table 1.

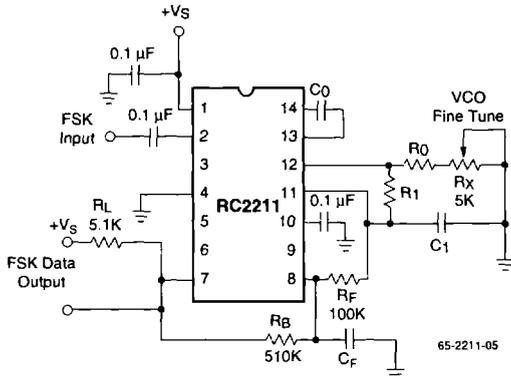


Figure 2. Circuit Connectbn for FSK Decoding

Table 1. Recommended Component Values for Commonly Used FSK Bands (see Circuit of Figure 2)

FSK Band	Component Values
300 Baud F ₁ = 1070 Hz F ₂ = 1270 Hz	C ₀ = 0.039 μF, C _F = 0.005 μF C ₁ = 0.01 μF, R ₀ = 18 kΩ R ₁ = 100 kΩ
300 Baud F ₁ = 2025 Hz F ₂ = 2225 Hz	C ₀ = 0.022 μF, C _F = 0.005 μF C ₁ = 0.0047 μF, R ₀ = 18 kΩ R ₁ = 200 kΩ
1200 Baud F ₁ = 1200 Hz F ₂ = 2200 Hz	C ₀ = 0.027 μF, C _F = 0.0022 μF C ₁ = 0.01 μF, R ₀ = 18 kΩ R ₁ = 30 kΩ

Design Instructions

The circuit of Figure 2 can be tailored for any FSK decoding application by the choice of five key circuit components: R₀, R₁, C₀, C₁ and C_F. For a given set of FSK mark and space frequencies, F₁ and F₂, these parameters can be calculated as follows:

1. Calculate PLL center frequency, F₀

$$F_0 = \frac{F_1 + F_2}{2}$$

2. Choose a value of timing resistor R₀ to be in the range of 10 kΩ to 100 kΩ. This choice is arbitrary. The recommended value is R₀ = 20 kΩ. The final value of R₀ is normally finetuned with the series potentiometer, R_X.
3. Calculate value of C₀ from Design Equation No. 1 or from Typical Performance Characteristics:

$$C_0 = 1/R_0 F_0$$

4. Calculate R₁ to give a Δf equal to the markspace deviation:

$$R_1 = R_0 [F_0 / (F_1 - F_2)]$$

5. Calculate C₁ to set loop damping. (See Design Equation No. 4)

Normally, ζ ≈ 1/2 is recommended
Then: C₁ = C₀/4 for ζ = 1/2

6. Calculate Data Filter Capacitance, C_F:
For R_F = 100 kΩ, R_B = 510 kΩ, the recommended value of C_F is:

$$C_F \text{ (in } \mu\text{F)} = \frac{3}{\text{Baud Rate}}$$

Note: All calculated component values except R₀ can be rounded off to the nearest standard value, and R₀ can be varied to fine-tune center frequency through a series potentiometer, R_X (see Figure 2).

Design Example

75 Baud FSK demodulator with mark space frequencies of 1110/1170 Hz:

- Step 1: Calculate F₀:

$$F_0 = (1110 + 1170) / 2 = 1140 \text{ Hz}$$

- Step 2: Choose R₀ = 20 kΩ (18 kΩ fixed resistor in series with 5 kΩ potentiometer)

- Step 3: Calculate C₀ from VCO Frequency vs. Timing Capacitor: C₀ = 0.044 μF

- Step 4: Calculate R₁: R₁ = R₀ (1140/60) = 380 kΩ

- Step 5: Calculate C₁: C₁ = C₀/4 = 0.011 μF

Note: All values except R₀ can be rounded off to nearest standard value.

Design Examples

Tone detector with a detection band of 1 kHz \pm 20 Hz:

- Step 1: Choose $R_0 = 20\text{ k}\Omega$ (18 k Ω in series with 5 k Ω potentiometer).
- Step 2: Choose C_0 for $F_0 = 1\text{ kHz}$: $C_0 = 0.05\text{ }\mu\text{F}$.
- Step 3: Calculate R_1 : $R_1 = (R_0) (1000/20) = 1\text{ M}\Omega$.
- Step 4: Calculate C_1 : for $\zeta = 1/2$, $C_1 = 0.25\text{ }\mu\text{F}$, $C_0 = 0.013\text{ }\mu\text{F}$.
- Step 5: Calculate C_D : $C_D = 16/38 = 0.42\text{ }\mu\text{F}$.
- Step 6: Fine tune the center frequency with the 5 k Ω potentiometer. R_X .

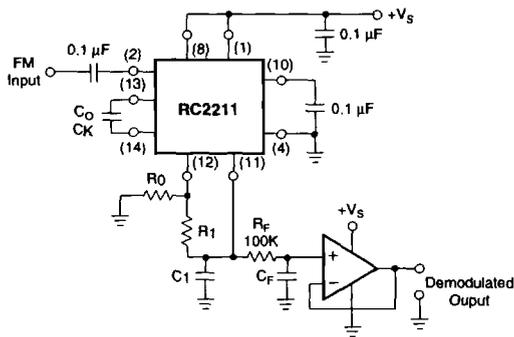
Linear FM Detection

The RC2211 can be used as a linear FM detector for a wide range of analog communications and telemetry applications. The recommended circuit connection for the application is shown in Figure 5. The demodulated output is taken from the loop phase detector output (pin 11), through a post detection filter made up of R_F and C_F , and an external buffer amplifier. This buffer amplifier is necessary because of the high impedance output at pin 11. Normally, a non-inverting unity gain op amp can be used as a buffer amplifier, as shown in Figure 5.

The FM detector gain, i.e., the output voltage change per unit of FM deviation, can be given as:

$$V_{OUT} = R_1 V_R / 100 R_0 \text{ Volts/\% deviation}$$

where V_R is the internal reference voltage. For the choice of external components R_1 , R_0 , C_0 , C_1 and C_F , see the section on Design Instructions.



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Figure 5. Linear FM Detector Using RC2211 and an External Op Amp

Typical Performance Characteristics

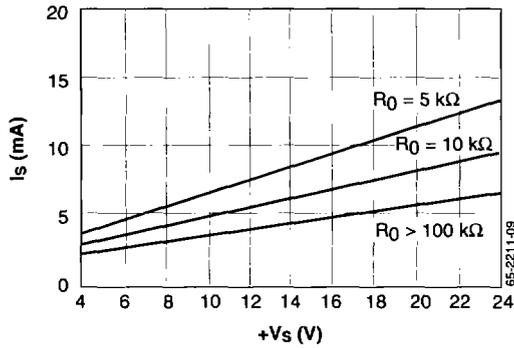


Figure 6. Supply Current vs. Supply Voltage (Logic Outputs Open Circuited)

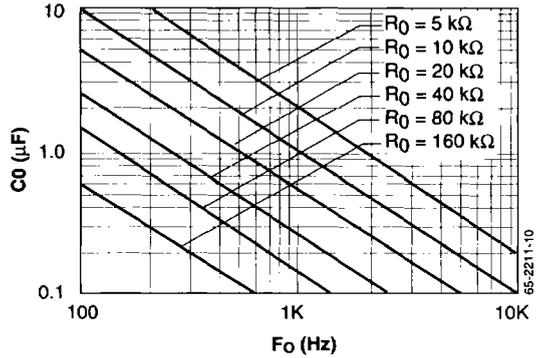


Figure 7. Timing Resistor with Timing Capacitor vs. VCO Frequency

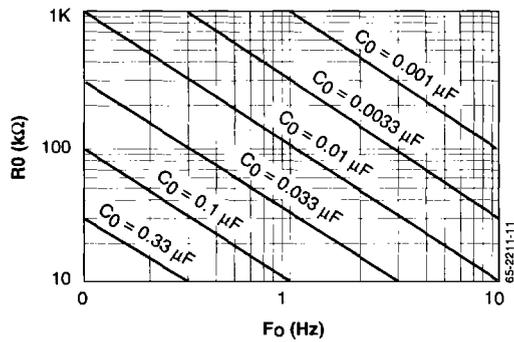


Figure 8. Timing Capacitor with Timing Resistor vs. VCO Frequency

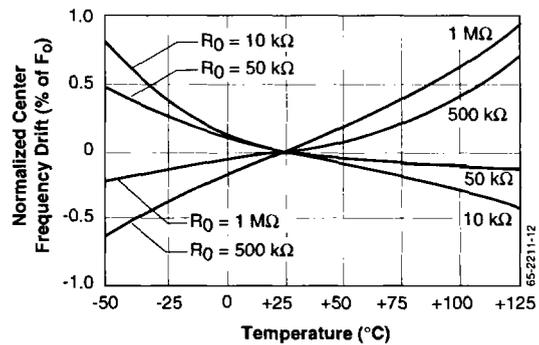


Figure 9. Center Frequency Drift vs. Temperature

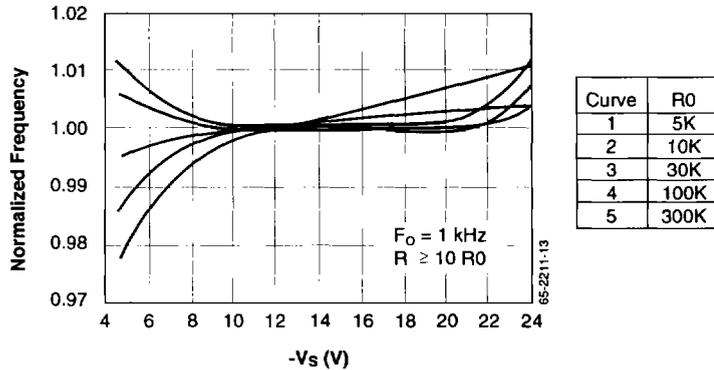
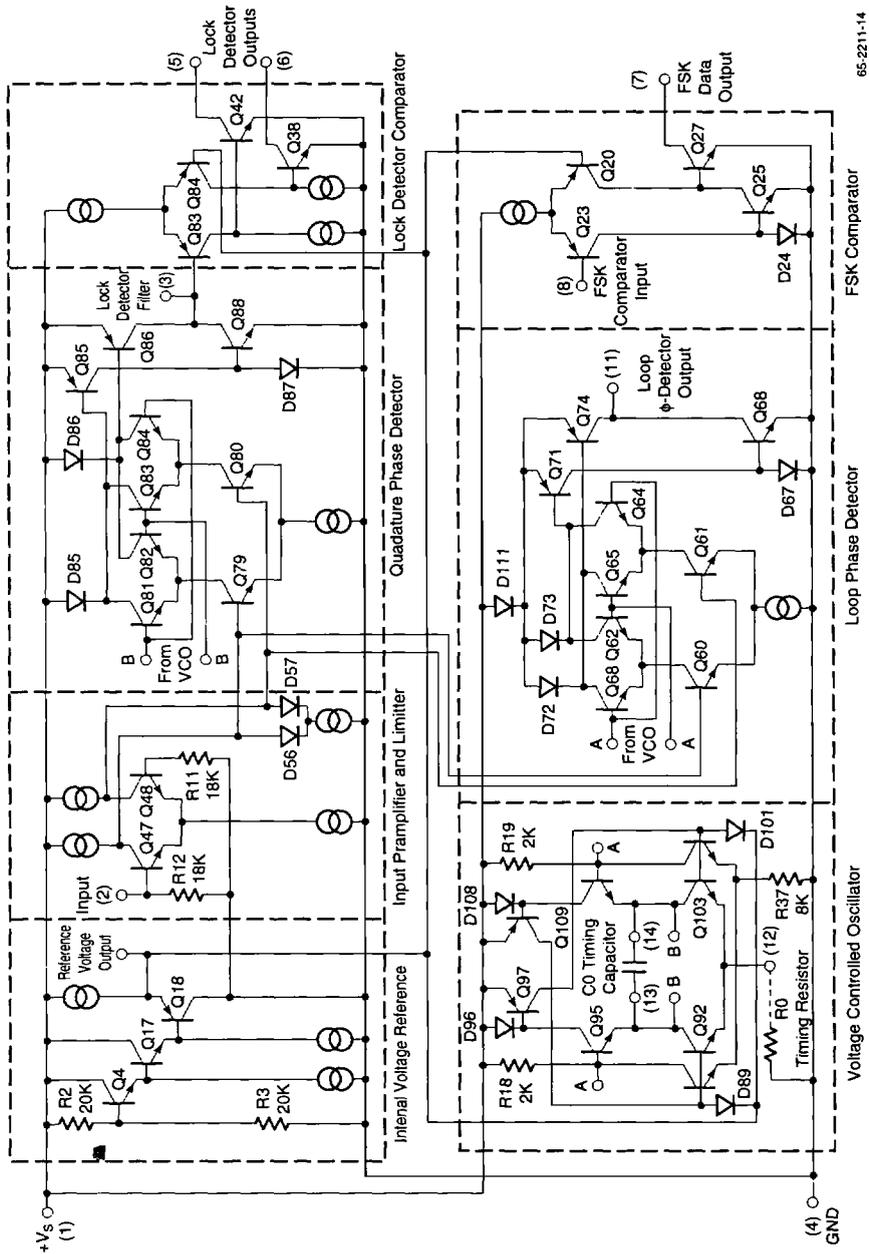


Figure 10. VCO Frequency vs. Supply Voltage

Schematic Diagram



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Ordering Information

Part Number	Package	Operating Temperature Range
RC2211N	N	0°C to +70°C
RV2211N	N	-25°C to +85°C
RM2211D	D	-55°C to +125°C
RM2211D/883B	D	-55°C to +125°C

Notes:

/883B suffix denotes MIL-STD-883, Par 1.2.1 Compliant Devices

N = 14-Lead Plastic DIP

D = 14-Lead Ceramic DIP