μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



FEATURES

- ♦ 2 × 4 bidirectional input/output stages at 24V
- ♦ Input/output mode programmable in 4-bit blocks
- Guaranteed high-side driving capability of 100mA_{dc} and 500mA_{peak} for pulse load
- ♦ Short-circuit-proof drivers with high dielectric strength
- ♦ Low saturation voltage of 0.6V/100mA and 2.0V/500mA
- ♦ Integrated flyback circuits
- PWM function with programmable duty cycle
- Flash mode for the outputs
- Power outputs can be disabled together
- Programmable current sources define logic levels and allow load monitoring
- ◆ Digital input filters with externally adjustable filtering times
- Can be bus operated due to the high-speed μP interface
- Programmable interrupt output
- Voltage and two-stage temperature monitoring

APPLICATIONS

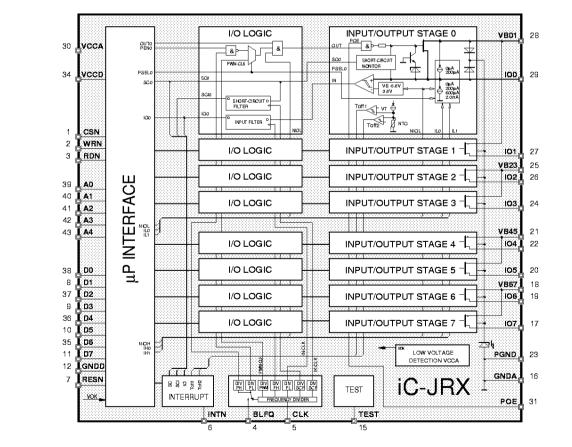
 Dual quad high-side driver as a bidirectional μP interface with digital filtering in industrial 24V applications

PACKAGES



PLCC44

BLOCK DIAGRAMM



iC-Haus GmbH Integrated Circuits Am Kuemmerling 18, 55294 Bodenheim

©1998

Tel. +49-6135-9292-0 Fax +49-6135-9292-192 http://www.ichaus.com

Rev A0

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 2/23

DESCRIPTION

iC-JRX is an 8-fold high-side driver with integrated control logic, internally divided into two independent blocks (nibbles). Both blocks can be individually set to input or output. The μP interface is made up of eight data, five address and three control pins. Two further clock inputs control internal sequences (input filter, pulse operation of the outputs). Starting with reset state, various register partitionings dependent on the selected operating mode are possible.

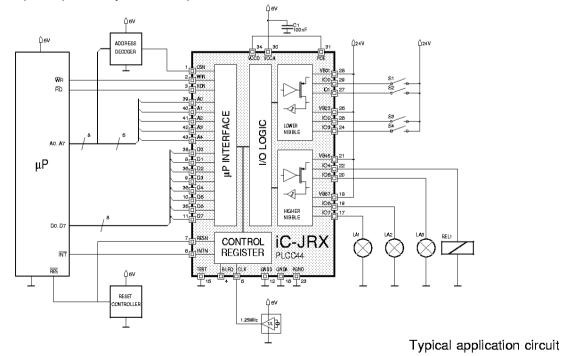
Input mode is used to log logic levels at 24V. An interrupt message can be generated when a signal at the inputs changes. Spurious signals are rejected by the device's adjustable digital filters. When the inputs are open the programmable pull-down current sets defined levels and acts as the bias current for switching contacts.

In output mode the power output stages can drive any desired load to GND (e.g. lamps, long cables or relays) at a continuous current of 100mA or 500mA in pulse operation. Spikes and flyback currents are discharged through the integrated flyback circuits. All output stages are short-circuit-proof and two-stage temperature monitoring (with interrupt messages) protects against thermal damage caused by large power dissipation. A short circuit at one of the outputs can cause an interrupt; the current short circuit status can be scanned via the μP interface. Pulse mode can be selected for each output, such as for indicator lamps in plugboards, in order to offload the control software used. The actual switching level of the output can be read out via the μP interface and be used to check for cable fractures with the pull-up currents. A PWM signal can also be switched to any selected output. All outputs can be switched off via a mutual disable input e.g. by a processor-independent watchdog circuit.

An interrupt pipeline which prevents the loss of interrupts allows reliable processing of interrupts using the applied control software.

With low voltage the voltage monitor resets all registers and in doing so switches off the power output stages.

Diodes protect all inputs and outputs against ESD. The device is also immune to burst transients according to IEC 1000-4-4 (4 kV; previously IEC 801-4).



μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS

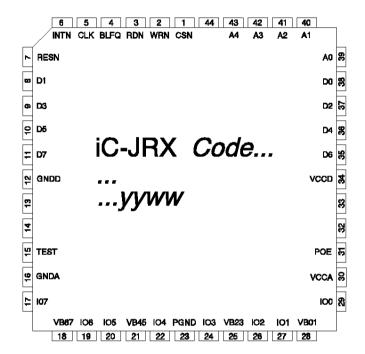


Rev A0, 3/23

PACKAGES PLCC44 to JEDEC Standard

PIN CONFIGURATION PLCC44

(top view)



PIN FUNCTIONS PLCC44

No.	Name	Fct.	Description	No.	Name	Fct.	Description
1	CSN	1	Chip Select	23	PGND		Ground (ESD protection circuitry)
2	WRN	1	Write Enable	24	IO3	В	I/O Stage 3
3	RDN	I	Read Enable	25	VB23		Power Supply Driver Stage 2+3
4	BLFQ	1	Clock Flash Mode	26	102	В	I/O Stage 2
5	CLK	1	Clock Filter and PWM Function	27	101	В	I/O Stage 1
6	INTN	0	Interrupt Message	28	VB01		Power Supply Driver Stage 0+1
7	RESN	1	Reset	29	100	В	I/O Stage 0
8	D1	В	Data Bus Bit 1	30	VCCA		5V Supply Voltage (analog section)
9	D3	В	Data Bus Bit 3	31	POE	1	Power Output Enable
10	D5	В	Data Bus Bit 5	32	n.c.		
11	D7	В	Data Bus Bit 7	33	n.c.		
12	GNDD		Ground (digital section)	34	VCCD		5V Supply Voltage (digital section)
13	n.c.			35	D6	В	Data Bus Bit 6
14	n.c.			36	D4	В	Data Bus Bit 4
15	TEST	В	Test Pin	37	D2	В	Data Bus Bit 2
16	GNDA		Ground (analog section)	38	D0	В	Data Bus Bit 0
17	107	В	I/O Stage 7	39	A0	1	Address Bus Bit 0
18	VB67		Power Supply Driver Stage 6+7	40	A1	1	Address Bus Bit 1
19	106	В	I/O Stage 6	41	A2	1	Address Bus Bit 2
20	IO5	В	I/O Stage 5	42	АЗ	1	Address Bus Bit 3
21	VB45		Power Supply Driver Stage 4+5	43	A4	I	Address Bus Bit 4
22	104	В	I/O Stage 4	44	n.c.		

Functions: I= Input, O= Output, B= bidirectional

External wiring VCCA, VCCD to +5V and GNDA, GNDD, PGND to 0V required.

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 4/23

PROGRAMMING

Registe	r Ove	ervie	W								
	A	\ddre	SS								
A(40)d	Α4	АЗ	A2	A1	A0	Write	Read				
0	0	0	0	0	0	-	Input Register ¹				
1	0	0	0	0	1	-	Change-of-input Message 2				
2	0	0	0	1	0	-	Interrupt Status Register				
3	0	0	0	1	1	-	Overcurrent Message 3				
4	0	0	1	0	0	-	Overcurrent Status				
5	0	0	1	0	1	-	Device ID				
6	0	0	1	1	0	Output	Register				
7	0	0	1	1	1	Flash Pu	lse Enable				
8	0	1	0	0	0	Change-of-input	Interrupt Enable ⁴				
9	0	1	0	0	1	Overcurrent I	nterrupt Enable				
10	0	1	0	1	0	Control Word	d 1 (I/O filters)				
11	0	1	0	1	1	Control Word 2	(I/O pin functions)				
12	0	1	1	0	0	Control Word 3 (f	lash pulse settings)				
13	0	1	1	0	1	Control World 4 (filter settir	ngs for overcurrent message)				
14	0	1	1	1	0	Control Word 5 (PWM	enable and pin selection)				
15	0	1	1	1	1	PWM	Register				
16	1	0	0	0	0		-				
•••							-				
26	1	1	0	1	0		-				
27	1	1	0	1	1	-	A/D Interface				
28	1	1	1	0	0		egister 1				
29	1	1	1	0	1		Test Register 2				
30	1	1	1	1	0	Test R	Test Register 3				
31	1	1	1	1	1	Test Cont	rol Register				

¹⁾ Reads the inputs or reads back the outputs, depending on I/O pin mode
2) For I/O pins in input mode (register is '0' in output mode)
3) For I/O pins in output mode (register is '0' in input mode)
4) Only writable in input mode

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 5/23

Control '	Control Word 1 (I/O filters) Add.: 10												
							1	eset entry: 00h					
	higher nil	bble			lower nik	lower nibble							
Bit Name	7 BYPH	6 -	5 FH1	4 FH0	3 BYPL	2 -	1 FL1	0 FL0					

higher nibble

Bit 7 BYPH	0	I/O filters a Bypass for		he I/O signals are rep	(r) I/O signals are reprocessed in their unfiltered state.							
Bit 54		FH1	FH0	Filter times								
FH10		0	0	14,5 × tc(CLK)	± 1 × tc(CLK)							
		0	1	896,5 × tc(CLK)	\pm 64 \times tc(CLK)							
		1	0	3.584,5 × tc(CLK)	\pm 256 \times tc(CLK)							
		1	1	7.168,5 × tc(CLK)	± 512 × tc(CLK)							

lower nibble

Bit 3 BYPL	0	I/O filters a Bypass for		he I/O signals are repr	rocessed in their unfiltered state.	(r)
Bit 10		FL1	FL0	Filter times		
FL10		0	•	14,5 × tc(CLK)	\pm 1 \times tc(CLK)	(r)
		0	1	896,5 × tc(CLK)	\pm 64 \times tc(CLK)	
		1	0	3.584,5 × tc(CLK)	\pm 256 \times tc(CLK)	
		1	1	7.168,5 × tc(CLK)	\pm 512 \times tc(CLK)	

^{&#}x27;-' Free memory location without a function. Status after a reset is '0' 'xx'h Indicates hexadecimal data for logic states. 'x' indicates binary data (r) Status after a reset

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 6/23

Control \	Control Word 2 (I/O pin functions) Add.: 11												
								reset entry: 00					
	higher ni	bble			lower nil	lower nibble							
Bit Name	7 NIOH	6 -	5 IH1	4 IH0	3 NIOL	2 -	1 IL1	O ILO					

higher nibble

Bit 7 NIOH	0	Input mode Output mo									
Bit 54		Current so	Current sources at I/O pins 47								
IH10		IH1		in input mode (sources low-side)	in output mode (sources high-side)						
		0 0		0μΑ	0μΑ						
		0	1	200μΑ	200μΑ						
			0	600μΑ	0μΑ						
		1	1	2mA	200μΑ	(r)					

lower nibble

Bit 3 NIOL	0		Input mode Output mode								
Bit 10		Current so	Current sources at I/O pins 03								
IL10		IL1	IL0	in input mode (sources low-side)	in output mode (sources high-side)						
		0 0 1	0 1 0	0μΑ 200μΑ 600μΑ	0μΑ 200μΑ 0μΑ						
		1	1 1	2mA	200μΑ	(r)					

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 7/23

Control \	Word 3 (flash	pulse settir	ngs)					Add.: 12	
							1	eset entry: 00h	
	higher nibb	ole			lower r	lower nibble			
Bit Name	7 NOBLFQ	6 NOCLK	5 PH1	4 PH0	3 -	2 -	1 PL1	0 PL0	

higher nibble

Bit 7 NOBLFQ	0		~	ed from the external clock signal at B ed from clock signal CLK	_FQ	(r)					
Bit 6 NOCLK	0		ation with the clock signal at CLK (all clock controlled actions are possible) (r) ation without the clock signal at CLK (filtering etc. deactivated)								
Bit 54		Flash frequ	ency for I/O	pins 47							
PH10		PH1	PH0	NOBLFQ= 0		NOBLFQ= 1					
		0	0	f(BLFQ)		f(CLK) / 2 ¹⁹					
		0	1	f(BLFQ) / 2		f(CLK) / 2 ²⁰					
			0	f(BLFQ) / 4		f(CLK) / 2 ²¹					
		1	1	f(BLFQ) / 16	(r)	f(CLK) / 2 ²³					

lower nibble

Bit 10	Flash frequ	Flash frequency for I/O pins 03								
PL10	PL1	PL0	NOBLFQ= 0	NOBLFQ= 1						
	0	0	f(BLFQ)	f(CLK) / 2 ¹⁹						
	0	1	f(BLFQ) / 2	f(CLK) / 2 ²⁰						
	1	0	f(BLFQ) / 4	f(CLK) / 2 ²¹						
	1	1	f(BLFQ) / 16 (r)	f(CLK) / 2 ²³						

Control W	Control Word 4 (filter settings for overcurrent message) Add.: 13											
							rese	t entry: 00h				
Bit	7	6	5	4	3	2	1	0				
Name	EOI	-	-	SCFH	BYPSCF	-	-	SCFL				

Bit 7 EOI	0	No effect "DELETE"s the interrupt message (change-of-input message; interrupt status register, overcurrent message), accepts successive interrupts from the pipeline, deletes the message at INTN when the pipel is empty; Bit automatically resets to '0'.	(r) line
Bit 4 SCFH	0	Overcurrent message with 2.3ms filtering (higher nibble) Overcurrent message with 4.6ms Filtering (higher nibble) Gives the filter times with the maximum clock frequency permitted at CLK, i.e. 1.25 MHz: 2.3ms from (2689,5 \pm 192)× t(CLK) and 4.6ms from (5378,5 \pm 384) × t(CLK) respectively	(r)
Bit 3 BYPSCF	0	Filters for the overcurrent message are active Bypass for the filters: overcurrent messages are reprocessed in their unfiltered state	(r)
Bit 0 SCFL	0	Overcurrent message with 2.3ms filtering (lower nibble) Overcurrent message with 4.6ms filtering (lower nibble)	(r)

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 8/23

Control V	Vord 5 (PWM enable and	l pin selectio	า)				Add.: 1
							res	set entry: 00
Bit Name	7	6 -	5	4 PWMEN	3 PWMPN	2 PWM ADR(2)	1 PWM ADR(1)	0 PWM ADR(0)
Bit 4 PWMEN	0	PWM "DISABLE PWM "ENABLE sources are swit	D": the output s	elected with PV	VMADR receiv	es the P W M s	ignal. The relev	ant current
Bit 3 PWMPN	0	PWM signal acti						(
Bit 20	<u>'</u>	PWMADR2	PWMADR1	PWMADR0	Selected I	/O pin		
PWMADR 20		1111	0 0 1 1 0 0	0 1 0 1 0 1	IO0 (ca IO1 IO2 IO3 IO4 IO5 IO6	ontrol line PSE	:L0= 1)	

							re	set entry: 00
Bit Name	7 PWM7	6 PWM6	5 PWM5	4 PWM4	3 PWM3	2 PWM2	1 PWM1	0 PWM0
Bit 70 PWM70	'00'h ''h 'FF'h	Duration of the Output stage '		n steps of 16× t ly)	,	signal. Output	selection and e	(nable are set via

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 9/23

	gister (re of inputs /	ad only) output feedba	ick					Add.: 0
							r	eset entry: 00h
Bit Name	7 IN7	6 IN6	5 IN5	4 IN4	3 IN3	2 IN2	1 IN1	0 INO
Bit 70 IN70	0	Input/Output	IOx reads '0' IOx reads '1'					(r)
11470			the state for IC	Ox (via I/O filter	or bypass).			

	on-Input M ages in Inp	essage (read ut mode	only)				re	Add.:
Bit Name	7 DCH7	6 DCH6	5 DCH5	4 DCH4	3 DCH3	2 DCH2	1 DCH1	0 DCH0
Bit 70 DCH70	0	Read access successive interrupt pipel	state at the inp had a change gates off chang terrupts which c ine. If this happ w. In this instar	of state enabled es to the regist occur during the ens, the messa	d for interrupt mer; the register read-out phase ge at INTN car	is reenabled or e and before a not be deleted	reset with EOI : by EOI, i.e. IN	are trapped by

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 10/23

Interrupt :	Status Regis	ster (read or	ıl y)					Add.: 2
							rese	et entry: 00h
	higher nibble				lower nibble			
Bit Name	7 DCHI	6 IET2	5 IET1	4 ISCI	3 -	2 ET2	1 ET1	0 SCS

higher nibble

overcurr	ent, exces	ssive temperature, change-of-input data (interrupts stored)	
		Read access gates off changes to the register; the register is reenabled only when reset via EOI. An successive interrupts for IET1 and IET2 which occur during the read-out phase and before a reset wi EOI are trapped (pipeline). If this happens, the message at INTN cannot be deleted by EOI, i.e. INTN constantly remains on low. In this instance, EOI fills the excessive temperatue message from the piper.	th J
Bit 7 DCHI	0	No message Interrupt through change-of-input message	(r)
Bit 6 IET2	0	No message Interrupt through excessive temperature level 2	(r)
Bit 5 IET1	0	No message Interrupt through excessive temperature level 1	(r)
Bit 4 ISCI	0	No message Interrupt through overcurrent message	(r)

lower nibble

overcur	rent status,	excessive temperature status (real time signals, at the time of readout)	
Bit 2 ET2	0	No error message Excessive temperature level 2 (shutdown)	(r)
Bit 1 ET1	0	No error message Excessive temperature level 1 (warning)	(r)
Bit 0 SCS	0	No error message Overcurrent status (e.g. caused by low-side short circuit)	(r)

Overcur	rent Messa	i ge (read onl	y)					Add.: 3
							re	eset entry: 00h
Bit Name	7 SCI7	6 SCI6	5 SCI5	4 SCI4	3 SCI3	2 SCI2	1 SCI1	0 SCI0
Bit 70 SCI70	0 1	Read access successive in an interrupt p remains on le	as had an over gates off chan nterrupts which pipeline. If this I	ges to the regis occur during th nappens, the mander, EOI fills the	ster; the registe e read-out phas essage at INTN	se and before a	only when reset a reset with EOI eted by EOI, i.e	•

SCIx reports for IOx.

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 11/23

Overcur	rent Statu	s (read only)						Add.: 4
							r	eset entry: 00h
Bit Name	7 SC7	6 SC6	5 SC5	4 SC4	3 SC3	2 SC2	1 SC1	0 SC0
Bit 70	0	No overcurre	ent	·			·	
SC70	1	Overcurrent	in output IOx, e	e.g. through a lo	ow-side short ci	rcuit		
			acts as error and for IOx pins in i				eal time, no reç	gister).

	<u> </u>	ion (read on					re	Add.: ! eset entry: 00h
Bit Name	7 -	6 -	5 DID5	4 DID4	3 DID3	2 DID2	1 DID1	0 DID0
Bit 50 DID50			riC-JRX: '00 0000 vith RESN= '0' an		Itage			(1

Output-F for I/O sta		output function	ו					Add.: 6
							re	set entry: 00h
Bit Name	7 OUT7	6 OUT6	5 OUT5	4 OUT4	3 OUT3	2 OUT2	1 OUT1	0 OUT0
Bit 70	0	High-side driv	ar "OFF"					(2)
OUT70	1		er "ON", i.e. no	rmally, IOx = '1	,			(1)
		OUTx switche	s the high-side	driver for IOx.				

		utput function					re	set entry: 00
Bit Name	7 PEN7	6 PEN6	5 PEN5	4 PEN4	3 PEN3	2 PEN2	1 PEN1	0 PEN0
Bit 70 PEN70	0	Flash pulse "D						ı

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 12/23

	i terrupt Enat nput function						Add.:
						re	eset entry: 00
7 IEN7	6 IEN6	5 IEN5	4 IEN4	3 IEN3	2 IEN2	1 IEN1	0 IEN0
0 1	"ENABLED" f	or interrupt: a h cannot be enabl	led for messagi		at the input IO	x triggers an int	(terrupt.
	ges with i	7 6 IEN7 IEN6 O "DISABLED" 1 "ENABLED" 1 Outputs IOx of	ges with input function 7 6 5 IEN7 IEN6 IEN5 0 "DISABLED" for interrupt 1 "ENABLED" for interrupt: a h Outputs IOx cannot be enabled	ges with input function 7 6 5 4 IEN7 IEN6 IEN5 IEN4 0 "DISABLED" for interrupt 1 "ENABLED" for interrupt: a hi→lo or lo→hi	7 6 5 4 3 IEN7 IEN6 IEN5 IEN4 IEN3 0 "DISABLED" for interrupt "ENABLED" for interrupt: a hi→lo or lo→hi change of state Outputs IOx cannot be enabled for messaging.	ges with input function 7 6 5 4 3 2 IEN7 IEN6 IEN5 IEN4 IEN3 IEN2 0 "DISABLED" for interrupt 1 "ENABLED" for interrupt: a hi→lo or lo→hi change of state at the input IO Outputs IOx cannot be enabled for messaging.	read of the state at the input function 7

Overcurre	ent Interrup	t Enable						Add.: 9
							res	set entry: 00h
Bit Name	7 SCEN7	6 SCEN6	5 SCEN5	4 SCEN4	3 SCEN3	2 SCEN2	1 SCEN1	0 SCEN0
Bit 70 0 "DISABLED" for interrupt (r) SCEN70 1 "ENABLED" for interrupt: a short-circuit at IOx triggers an interrupt.								

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 13/23

ABSOLUTE MAXIMUM RATINGS

Values beyond which damage may occur; device operation is not guaranteed.

Item	Symbol	Parameter	Conditions	Fig.			Unit
					Min.	Max.	
G001	VCCD VCCA	Supply Voltage VCCD, VCCA					٧
G002	VB	Supply Voltage VB			-0.3	30	٧
G003	V(IO)	Voltage at IO07	IOx= off		-10	30	٧
G004	Idc(IO)	Current in IO07		1	-500	100	mA
G005	lpk(IO)	Pulse Current in IOx	IOx= hi (*), τ= 2ms, T≥ 2s	2	-1.0		А
G006	lmax()	Current in VCCD, VCCA			-50	50	mA
G007	Imax(VB)	Current in VB01, VB23, VB45, VB67			-4	4	Α
G008	lc()	Current in Clamping Diodes CSN, WRN, RDN, A04, D07, RESN, CLK, BLFQ, POE	D07 with input function		-20	20	mA
G009	1()	Current in D07, INTN	D07 with output function		-25	25	mA
G010	llu()	Pulse Current in CSN, WRN, RDN, A04, D07, RESN, CLK, BLFQ, INTN, POE, IO07 (Latch-Up Strength)	pulse duration < 10μs, all in-/outputs open		-100	100	mA
E001	Vd()	ESD Susceptibility at all Pins	MIL-STD-883.D, Method 3015.7; HBM 100pF discharged through 1.5kΩ			2	kV
E002	Vb()	Permissible Burst-Transients at IO07	according to IEC 1000-4-4			4	kV
TG1	Tj	Junction Temperature			-40	150	°C
TG2	Ts	Storage Temperature			-40	150	°C

^(*) IOx= hi: pin set to output, active high, x= 0..7

THERMAL DATA

Operating Conditions: VCCD= VCCA= 5V $\pm 10\%$, VB= 24V $\pm 5\%$, GNDA= GNDD= PGND= 0V, alle inputs wired (to hi respectively to lo)

Item	Symbol	Parameter	Conditions	Fig.			Unit	
					Min.	Тур.	Max.	
T1	Та	Operating Ambient Temperature Range			0		70	°C
T2	Rthja		surface mounted on PCB, no additional cooling areas			55		K/ W

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 14/23

ELECTRICAL CHARACTERISTICS

Operating Conditions: VCCD= VCCA= 5V $\pm 10\%$, VB= 24V $\pm 5\%$, GNDA= GNDD= PGND= 0V, all inputs wired (to hi respectively to lo), Tj= 0..125°C unless otherwise noted.

ltem	Symbol	Parameter	Conditions	Tj	Fig.				Unit
				°C		Min.	Тур.	Max.	
Total	Device								
001	VCCA	Permissible Supply Voltage VCCA				4.5		5.5	٧
002	I(VCCA)	Supply Current in VCCA					7.5	13	mA
003	I(VCCA)	Supply Current in VCCA	no supply voltage VB					25	mA
004	VCCD	Permissible Supply Voltage VCCD				4.5		5.5	٧
005	I(VCCD)	Supply Current in VCCD (static)	all logic inputs lo= 0V or hi= VCCD				0.3	3	mA
006	I(VCCD)	Supply Current in VCCD (dynamic)	continously repeated read access: tlo(RDN)= thi(RDN)= 200ns; data word changes every other cycle between "00" and "FF", CL(D07)= 200pF					35	mA
007	I(VCCD)	Supply Current in VCCD	all logic inputs lo= 0.8V				80		mA
800	I(VCCD)	Supply Current in VCCD	all logik inputs hi= 2.0V				100		mA
009	VB	Permissible Supply Voltage VB (operating range)				22.8		25.2	٧
010	I(VB)	Supply Current in VB	POE= hi, IOx= hi, no load				8.5	14	mA
011	I(VB)	Supply Current in VB	IOx= off				2	4	mA
012	Vc()lo	ESD Clamp Voltage Io at VCCA, VCCD, VB	I()= -20mA			-1.4		-0.3	٧
013	Vc()hi	ESD Clamp Voltage hi at VCCA	I()= 20mA					11	٧
014	Vc()hi	ESD Clamp Voltage hi at VB	I()= 20mA			30	47	60	٧
015	Vc()lo	ESD Clamp Voltage lo at IOx	I()= -20mA			-30		-10	٧
016	Vc()hi	ESD Clamp Voltage hi at IOx	I()= 20mA			30	47	60	٧
I/O St	ages: Hig	h-Side Driver IO07							
101	Vs()hi	Saturation Voltage hi	Vs()hi= VB -V(IOx); I(IOx)= -10mA	1				0.2	٧
102	Vs()hi	Saturation Voltage hi	Vs()hi= VB -V(IOx); I(IOx)= -100mA	1				0.6	٧
103	Vs()hi	Saturation Voltage hi for pulse load	Vs()hi= VB -V(lOx); I(lOx)= -500mA, τ= 2ms, T≥ 2s	2				2.0	٧
104	lsc()hi	Overcurrent Cut-off	IOx= hi, V(IOx)= 0VB-3V			-1.8		-0.6	Α
105	It()scs	Threshold Current for Overcurrent Message				-1.2		-0.6	Α
106	Vc()lo	Free-wheeling Clamp Voltage	I(IOx)= -100mA			-15		-12	٧
107	SRhi()	Slew Rate hi	CL= 0100pF, RL= 240Ω1kΩ			15		40	V/µ
108	SRIo()	Slew Rate lo	CL= 0100pF, RL= 240Ω1kΩ			15		40	V/µ
109	tplh()	Propagation Delay until IOx: Io→hi	write cycle, WRN: lo→hi until V(lOx) > V0(lOx)+1V					5	μs
110	tphI()	Propagation Delay until IOx= off	write cycle, WRN= lo→hi until V(lOx) < 80% (VB-Vs(lOx)hi)					5	μs

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 15/23

ELECTRICAL CHARACTERISTICS

Operating Conditions: VCCD= VCCA= 5V $\pm 10\%$, VB= 24V $\pm 5\%$, GNDA= GNDD= PGND= 0V, all inputs wired (to hi respectively to lo), Tj= 0..125°C unless otherwise noted.

ltem	Symbol	Parameter	Conditions	Tj	Fig.				Unit
				°C		Min.	Тур.	Max.	
I/O S	tages: Cui	rrent Sources at IO07	•						
201	lpd()	Pull-down Current Source (200μΑ)	IOx with input function, IL1= IH1= 0, IL0= IH0= 1, V(IOx)= 3VVB			120	200	280	μА
202	lpd()	Pull-down Current Source (600μA)	IOx with input function, IL1= IH1= 1, IL0= IH0= 0, V(IOx)= 3VVB			400	600	800	μА
203	lpd()	Pull-down Current Source (2mA)	IOx with input function, IL1= IH1= 1, IL0= IH0= 1, V(IOx)= 3VVB			1.4	2.0	2.7	mA
204	lpu()	Pull-up Current Source (200μA) IOx with output function and IOx= off, IL0, IH0= 1; V(IOx)= -7VVB-2V		120	200	280	μА		
205	tp()Ion	Current Source Enable Time (pull-down and pull-up sources)	write cycle, WRN: lo→hi til I(IOx) > 90% lpd(IOx) or I(IOx) > 90% lpu(IOx)					5	μs
206	tp()loff	Current Source Disable Time (pull-down and pull-up sources)	write cycle, WRN: lo→hi til I(IOx) < 10% lpd(IOx) or I(IOx) < 10% lpu(IOx)					5	μs
207	lik()	Leakage Current	IOx with input function or output function with IOx= off and IL1, IH1, IL0, IH0= 0; V(IOx)= -7VVB			-20		20	μА
208	lik()	Leakage Current	logic see item 204; V(IOx)= -10V7V			-100		20	μА
209	llk()	Leakage Current	logic see item 204; V(IOx)= VBVB+0.4V			-20		100	μА
210	lik()	Leakage Current	logic see item 204; V(IOx)= VB30V				200	500	μА
211	IIk()	Leakage Current	no supply voltage VB					5	mA
I/O S	tages: Coi	mparator IO07							
301	Vin()	Permissible Input Voltage referenced to VB	V(VB)= 025.2V, (see also max. rating G003)					25.2	٧
302	Vt()hi	Threshold Voltage hi	IOx with input function					4.5	٧
303	Vt()lo	Threshold Voltage lo	IOx with input function			3.0			٧
304	Vt()hys	Hysteresis	IOx with input function, Vt()hys= Vt()hi -Vt()lo			100			mV
305	Vt()hi	Threshold Voltage hi referenced to VB	IOx with output function, Vt()hi= VB -V(IOx)			5.0			٧
306	Vt()lo	Threshold Voltage lo referenced to VB	IOx with output function, Vt()lo= VB -V(IOx)					6.7	٧
307	Vt()hys	Hysteresis	IOx with output function, Vt()hys= Vt()lo -Vt()hi			100			mV
308	tp(IOx -Dx)	Propagation Delay Input IOx to Data Output Dx	I/O filter inactive, CSN= Io, RDN= Io, A04= Io					10	μs

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 16/23

ELECTRICAL CHARACTERISTICS

Operating Conditions: VCCD= VCCA= 5V $\pm 10\%$, VB= 24V $\pm 5\%$, GNDA= GNDD= PGND= 0V, all inputs wired (to hi respectively to lo), Tj= 0..125°C unless otherwise noted.

tem	Symbol	Parameter	Conditions	Tj	Fig.				Unit
				°C		Min.	Тур.	Max.	
Therr	nal Shutdo	own							
401	Toff1	Over-Temperature Threshold Level 1: warning				105		130	°C
402	Toff1	Level 1 Release				100		125	°C
403	Thys1	Level 1 Hysteresis	Thys1= Ton1 -Toff1			2		7	°C
404	Toff2	Over-Temperature Threshold Level 2: shutdown				130		155	°C
405	Ton2	Level 2 Release				100		125	°C
406	Thys2	Level 2 Hysteresis	Thys2= Toff2 -Ton2			22		37	°C
407	ΔΤ	Temperatur Difference Level 2 to Level 1	ΔT= Toff2 -Toff1			20		30	°C
Bias	and Low V	oltage Detection							
501	VCCAon	Turn-on Threshold VCCA (Power-on release)				3.9	4.1	4.4	٧
502	VCCAoff	Undervoltage Threshold VCCA (Power-down reset)				3.8	4.0	4.3	٧
503	VCCAhys	Hysteresis	VCCAhys= VCCAon -VCCAoff			80	100	130	mV
504	toff	Power Down Time required for low voltage detection	VCCA= 2.5VVCCAoff			1			μs
505	tdoff	Propagation Delay until Reset after Low Voltage at VCCA						12	μs
μP In	terface, I/C	Logic, Frequency Divider, Inter	rupt						
701	Ilk(Dx)	Leakage Current in Dx	D07 with input function			-5		5	μА
702	li()	Input Current in Schmitt-Trigger Input CSN, WRN ,RDN, A04, RESN, CLK, BLFQ, D07	V()= 0VVCCD, D07 with input function			-1		1	μА
703	Vt()hi	Threshold Voltage hi at Schmitt-Trigger Input CSN, WRN, RDN, A04, RESN, CLK, BLFQ, D07	D07 with input function					2.2	٧
704	Vt()lo	Threshold Voltage lo at Schmitt-Trigger Input CSN, WRN, RDN, A04, RESN, CLK, BLFQ, D07	D07 with input function			0.8			٧
705	Vt()hys	Schmitt-Trigger Input Hysteresis CSN, WRN, RDN, A04, RESN, CLK, BLFQ, D07	Vt()hys= Vt()hi-Vt()lo; D07 with input function			300			mV
706	Vs()hi	Saturation Voltage hi at INTN	Vs()hi= VCCD -V(INTN); I(INTN)= -2mA					0.80	٧
707	Vs()lo	Saturation Voltage lo at INTN	I(INTN)= 100μA I(INTN)= 2mA					0.20 0.49	V V
708	Vs()hi	Saturation Voltage hi at Dx	Vs()hi= VCCD -V(Dx); I(Dx)= -4mA					0.80	٧
709	Vs()lo	Saturation Voltage lo at Dx	I(Dx)= 4mA					0.49	٧

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 17/23

ELECTRICAL CHARACTERISTICS

Operating Conditions: VCCD= VCCA= 5V $\pm 10\%$, VB= 24V $\pm 5\%$, GNDA= GNDD= PGND= 0V, all inputs wired (to hi respectively to lo), Tj= 0..125°C unless otherwise noted.

Item	Symbol	Parameter	Conditions	Tj	Fig.				Unit
				°C		Min.	Тур.	Max.	
μP In	terface, I/C	Logic, Frequency Divider, Inter	rupt (cont'd)						
710	Vc()hi	ESD Clamp Voltage hi at CSN, WRN, RDN, A04, RESN, CLK, BLFQ, D07, INTN	Vc()hi= V() -VCCD; D07 with input function, I()= 20mA			0.4		1.5	٧
711	Vc()lo	ESD Clamp Voltage lo at CSN, WRN, RDN, A04, RESN, CLK, BLFQ, D07, INTN	D07 with input function, I()= -20mA			-1.5		-0.4	٧
Input	POE								
F01	Vt()hi	Threshold Voltage hi						2.2	٧
F02	Vt()lo	Threshold Voltage lo				0.8			٧
F03	Vt()hys	Hysteresis	Vt()hys= Vt()hi -t()lo			300			mV
F04	Rpd()	Pull-Down Resistor				24		72	kΩ
F05	tw()lo	Disable/Enable Pulse Width				600			ns
F06	tsup()	Permissible Interference Pulse Width						100	ns
F07	td(POE- IOx)	Power Output Switch-off Delay	POE: hi \rightarrow lo until IOx disabled, ie. V(IOx)< 80% (VB -Vs(IOx)hi), RL= 240 Ω 1k Ω					5	μѕ
F08	Vc()hi	ESD Clamp Voltage hi	Vc()hi= V(POE) -VCCA; I(POE)= 20mA			0.4		1.5	٧
F09	Vc()lo	ESD Clamp Spannung lo	I(POE)= -20mA			-1.5		-0.4	٧
Swite	hing Char	acteristics							
801	td()	Permissible Cycle Duration at CLK				800			ns
802	tw()	Permis. Pulse Width Io at CLK				400			ns
803	td()	Permissible Cycle Duration at BLFQ				100			ms
804	tw()	Permis. Pulse Width Io at BLFQ				50			ms

ELECTRICAL CHARACTERISTICS: WAVEFORMS



IOxdc T T

Fig. 1: DC load Fig. 2: Pulse load, pulse duration 2ms

μΡ INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 18/23

OPERATING REQUIREMENTS: µP INTERFACE

Operating Cconditions: VCCD, VCCA= 5V \pm 10%, VB= 24V \pm 5%, GNDA= GNDD= PGND= 0V, Ta= 0..70°C, CL()= 150pF, input levels lo= 0.45V, hi= 2.4V, see Fig. 3 for reference levels

ltem	Symbol	Parameter	Conditions	Fig.			Unit
					Min.	Max.	
Data	Word Rea	d Timing					
l1	tAR1 tAR2	Setup Time: CSN, A04 set before RDN hi→lo		4	30		ns
12	tRA	Hold Time: CSN, A04 stable after RDN lo→hi		4	10		ns
13	tRD	Read Data Access Time: data valid after RDN hi→lo 4 120		120	ns		
14	tDF	Read Data Hold Time: ports high impedance after RDN lo→hi		4		65	ns
15	tRL	Required Read Signal Duration at RDN			50		ns
Data	Word Wri	te Timing					
16	tAW1 tAW2	Setup Time: CSN, A04 set before WRN hi→lo		4	30		ns
17	tDW	Write Data Setup Time: data valid before WRN lo→hi		4	100		ns
18	twa	Hold Time: CSN, A04 stable after WRN lo→hi		4	10		ns
19	twD	Write Data Hold Time: data valid after WRN lo→hi		4	10		ns
l10	tWL	Required Write Signal Duration at WRN		4	50		ns
Read	/Write Tim	ning					
l11	teye	Recovery Time between cycles: RDN lo→hi to RDN hi→lo, RDN lo→hi to WRN hi→lo, WRN lo→hi to WDN hi→lo, WRN lo→hi to RDN hi→lo		4	165		ns

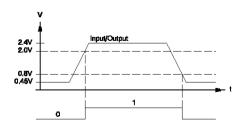


Fig. 3: Reference levels

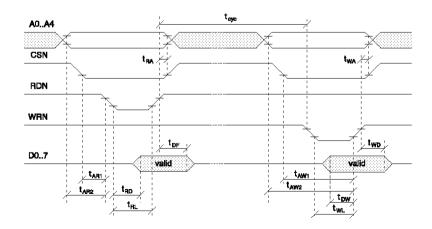


Fig. 4: Data word read/write timing

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 19/23

DESCRIPTION OF FUNCTIONS

iC-JRX is a bidirectional device which can analyze signals at the I/O pins and drive loads connected to ground. The input and output modes can be set in blocks of 4 bits (using nibbles).

I/O stages in input mode pass on the external signal via digital filtering which can be switched off as required by way of a bypass. Changes of level at any one input can generate an interrupt at the INTN port – providing that messaging is enabled. Individually programmable low-side current sources are available for each pin, enabling logic levels for the inputs to be defined (ranges 200μA, 600μA and 2mA).

I/O stages in output mode can switch currents of up to 500mA. A $200\mu\text{A}$ high-side current source can be activated to check the load for any interruptions. A PWM function and a flash mode for indicator lamps are integrated in the device, both of which can be selected for any chosen output pin. If overcurrent is determined at any of the outputs, caused for example by a short-circuit, this can be reported as an interrupt if suitably enabled. If the device exceeds normal operating temperature, an interrupt gives a temperature warning; if, following this, the device continues to overheat, the outputs are shutdown.

I/O stages in input mode

Input register (add. 0): reads the inputs

A hi level at IOx generates a hi signal at Dx. Any change to an input signal is accepted via digital filtering only after the chosen filter time has ended. Doing this, the input comparator of each I/O stage switches the count direction of a 3-bit counter. The counter output changes only when the final status is reached. The counters are reset to a value of 3 by a lo signal at the RESN reset input. The counter is clocked externally via the CLK pin.

The scaling factor for the clock frequency and the input filter bypass can be programmed separately for both nibbles (the bypass with BYPH or BYPL in control word 1). Switching the bypass permits operation without an external clock signal (see below).

After the change-of-input message has been enabled (add. 8) a change of level at one of the I/O pins is signaled via an interrupt to the microcontroller.

I/O stages in output mode

Input register (add. 0): reads the output feedback

A hi level at IOx generates a hi signal at Dx. Through this, the microcontroller can make a direct check of the switching state and, in conjunction with the 200µA high-side current source, can monitor the channel for any cable fractures. As with the input read, the read-back signals can be reprocessed in their filtered or unfiltered state.

Output register (add. 6): switches the various output stages on and off (for POE= 1)

Flash pulse enable (add. 7): enables flash mode

With this, each of the various output stages can be set to flash mode, providing the value of the corresponding output register is '1'. The flash frequency is derived from BLFQ or, alternatively, can be generated from CLK (via NOBLFQ in control word 3). Different flash frequencies can be set for both nibbles (ports 0..3 and 4..7).

PWM enable (add. 14)

A PWM signal for any chosen output stage can be activated with the aid of PWMEN in control word 5. The I/O stage is selected using PWMADR2..0. PWMPN determines the direction of the PWM signal (active hi or active lo). The shape of the PWM signal is given by the value of the PWM register (add. 15), multiplied by 16xtd(CLK).

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 20/23

Interrupts

Interrupt outputs at INTN can be triggered by a change of (filtered) input signal, by overcurrent, signaled at an I/O pin (e.g. due to a short circuit), or by exceeding maximum temperature levels (2 stages).

For each individual I/O stage, interrupt outputs can be caused by a change of input, or, with stages in output mode, also by a short circuit. The relevant interrupt enables determine which messages are stored and displayed. The display of interrupt messages caused by excessive temperature is not maskable; it is permanently enabled.

When an event occurs which is enabled to produce an interrupt output, pin INTN is set to '0'. An interrupt status register read-out (add. 2) enables the nature of the message to be determined and the I/O stage causing the interrupt to be located. Thus with a change-of-input message the initiating I/O stage is shown in the corresponding register (add. 1); with an overcurrent interrupt, the overcurrent message register (add. 3) pinpoints the I/O stage with a short circuit.

Interrupts are deleted by simply setting EOI in control word 4. This bit then automatically resets to '0'. If during operation the I/O mode is switched, i.e. from input to output mode, all interrupt messages are deleted via EOI.

To avoid interrupt messages caused by other sources in the time between the read-out of an interrupt register and the deletion of the current interrupt being overlooked, successive interrupts are stored in a pipeline. In the event of there being any successive interrupts, output INTN remains at '0' after the current interrupt has been deleted using EOI. The new interrupt source is shown in the interrupt status register and in the type-specific status registers.

Overcurrent messages

With an overload at one of the outputs the current in IOx is limited. In this instance an interrupt message is displayed, providing relevant interrupt enables have been set for overcurrent messages (add. 9) and the filter time set with control word 4 has elapsed. If this happens, ISCI is set in the interrupt status register (add. 2) and the relevant bit is set for the initiating I/O stage in the overcurrent message register (add. 3).

Under address 4 the current, unfiltered overcurrent status of each I/O stage can be read; an overall scan of all the I/O stages is also possible via bit SCS of the interrupt status register. This shows whether any of the I/O stages have overcurrent at the time of the readout. This short-circuit messaging allows permanent monitoring of the output transistors and clear allocation of the error message to the I/O stage affected.

Filtering of the overcurrent message can be shutdown via a bypass; this bypass can be activated for all I/O stages together using BYPSCF in control word 4 (add. 13).

Temperature monitoring

iC-JRX has a two-stage temperature monitor circuit.

Stage 1: A warning interrupt (INTN= 0) is generated if the first temperature level (Toff 1 at ca. 125°C)

is exceeded. Suitable measures to decrease the power dissipation of the driver can be

implemented via the microcontroller.

Stage 2: If the second temperature level is exceeded (Toff 2 at ca. 150°C), a second interrupt is

generated (INTN= 0). At the same time the output transistors and the I/O stage current sources are shutdown, the output register and flash mode enable deleted.

Once the temperature level has returned to below that of Toff1 the current sources are reactivated. The output register and flash pulse enable have to be respecified to activate the

output stages.

The interrupt status register (add. 2) gives information as to the stage of temperature interrupt but also on the current status of the temperature monitor. ET2 and ET1 statically indicate when Toff2 and Toff1 are exceeded, whereby the stored interrupt messages IET2 and IET1 and the display at INTN via EOI= 1 can be deleted (control word 4).

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 21/23

Low voltage detection

When the supply voltage at VCC is switched on, the output transistors are only released by the low voltage detector after the power-on enable VCCon has been reached. Should the supply voltage drop to VCCoff during operation, the I/O stages are disabled, i.e. the output transistors are turned off and the device reset (signal VOK). If the supply voltage should then rise to VCCon, iC-JRX is in its reset state.

Identification of the device

An identification code has been introduced to enable identification of device iC-JRX. Bit pattern '000000'b can be read out under address 5.

Reset

A reset (RESN= 0) sets the register entries to the reset values given in the tables. The output transistors and the current sources in the I/O stages are shutdown and all stages switched to input mode.

Operation without the BLFQ signal

Should no clock signal be available at pin BLFQ, iC-JRX can generate the flash pulse internally from the clock signal at pin CLK. To this end, NOBLFQ in control word 3 must be set to '1'. The flash period is then calculated from the clocking pulse at CLK by division by 2¹⁹.

Operation without the CLK signal

iC-JRX is operable without a clocking pulse at the CLK pin. With NOCLK in control word 3 the clocked filtering for the I/O signals and overcurrent messaging is deactivated. The device remains fully functional with one exception; the PWM cannot be activated, as this is dependent on CLK.

The same behavior can be obtained by setting BYPH and BYPL in control word 1 together with BYPSCF in control word 4; all filters are avoided by way of a bypass circuit. This has one disadvantage, namely that interferences in the load lines, for example, can lead to the unwanted display of interrupts.

Forced shutdown of output stages

The output stages can be forcibly shutdown at input POE. A '1' enables logic access to the drivers; an '0' disables this. With this, a processor-independent watchdog can lock the outputs in the event of error, for example. An integrated pull-down resistor increases safety.

up interface with 2×4 24V High-side drivers



Rev A0, 22/23

Pulse-width modulation

This function can be activated for any chosen I/O stage in output mode.

First the duty cycle is determined via the PWM register in 256 steps within one PWM period. Pulse direction and the address for the desired driver stage is selected via control word 5 (PWMPN, PWMADR2..0).

The PWM enable bit can now also be set via control word 5. With this enable, the current source and any active flash mode for the selected output are automatically switched off.

The set duty cycle is activated when a new PWM period is started.

A PWM signal is set at the selected output, whose frequency is determined by the clock signal at CLK and whose duty cycle follows the PWM register.

The following correlations apply:

$$f_{PWM} = \frac{f_{CLK}}{4096}$$
; $\Delta t_{PWM} = \frac{1}{f_{PWM} \times 256}$; $t_{PWMbo} = (PWMLEN + 1) \times \Delta t_{PWM}$

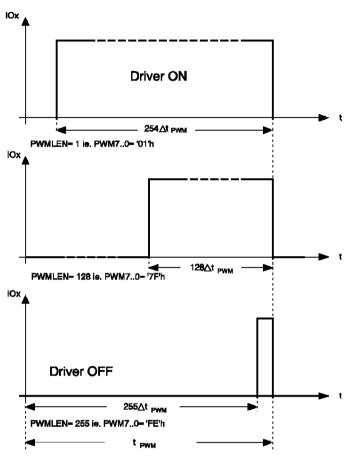


Fig. 5: PWM signal form

$$t_{PWMb} = (PWMLEN + 1) \times \Delta t_{PWM}$$

: Clock frequency CLK f_{CLK}

: Frequency for the PWM signal at IOx f_{PWM}

: Smallest possible pulse duration 'lo' (8µs with a 2MHz clock) Δt_{PWM}

: Pulse duration 'lo' (IOx= OFF with PWMPN= 1)

PWMLEN: Count for pulse duration 'lo' stored in register PWM7..0

Selectable Pulse	-Pause Rat	ios
PWM70	PWMPN	Output signal
20021-	0	Output stage "ON", Pin IOx= '1' (reset entry)
'00'h		Output stage "OFF", Pin IOx= '0'
1041L 2FF3L	0	Output pin IOx goes for (PWMLEN + 1) \times Δt_{PWM} to '0', and then for (255 - PWMLEN) \times Δt_{PWM} to '1'
'01'h 'FE'h	1	Output pin IOx goes for (PWMLEN + 1) \times Δt_{PWM} to '1', and then for (255 - PWMLEN) \times Δt_{PWM} to '0'
JEEN .	0	Output stage "OFF", Pin IOx= '0'
'FF'h	1	Output stage "ON", Pin IOx= '1'

μP INTERFACE WITH 2×4 24V HIGH-SIDE DRIVERS



Rev A0, 23/23

ORDERING INFORMATION

Type	Package	Order designation
iC-JRX	PLCC44	iC-JRX-PLCC44

For information about prices, terms of delivery, options for other case types, etc., please contact:

iC-Haus GmbH Am Kuemmerling 18 D-55294 Bodenheim

GERMANY

Tel +49-6135-9292-0 Fax +49-6135-9292-192 http://www.ichaus.com

This specification is for a newly developed product. iC-Haus therefore reserves the right to modify data without further notice. Please contact us to ascertain the current data. The data specified is intended solely for the purpose of product description and is not to be deemed guaranteed in a legal sense. Any claims for damage against us - regardless of the legal basis - are excluded unless we are guilty of premeditation or gross negligence.