Programmable switching cam encoder BME/BMF parallel

features

- 24 bit resolution, programmable
- 250 cams programmable to 16 signal outputs
- self-monitoring function
- binary code
- programmable:
 - direction CW/CCW
 - output logic normal/inverted
 - zero point and offset adjustment



general data	
voltage supply	10 - 30 VDC with reverse polarity protection
supply current no load	max. 50 mA (at 24 VDC)
max. resolution singleturn multiturn	12 Bit (1 step = 5' 16") 1 to 4096 programmable steps 12 Bit (4096 revolutions) programmable in Base 2
pulse tolerance	±1/2 step
cams	up to 250 cams programmable on 16 signal outputs
input signal	F/R-input, STORE/ENABLE, zero set input
accuracy	±0.03° @ 200 kHz ±0.05° @ 400 kHz
code switching speed for sampling	max. 400 kHz

mechanical data		
max. revolutions	mechanical 10,00 electrical 6000 /m	•
inertia torque rotor	2 x 10 ⁻⁶ kgm ²	
starting torque	≤0.010 Nm (no ≤ 0.015 Nm (with	, ,
max . shaft load	axial: 20 N	radial: 40 N
max. protection class	IP 65	
material	housing: steel flange: aluminum	
weight	approx. 600 g	

ambient conditions	
temperature range	-20 to +65 °C
relative humidity	max. 95% non condensing
vibration	DIN EN 60068-2-6 (≤ 100 m/s² / 16-2000 Hz)
shock	DIN EN 60068-2-27 (≤ 2000 m/s² / 6 ms)
noise immunity	DIN EN 61000-6-23
emitted interference	DIN EN 61000-6-4

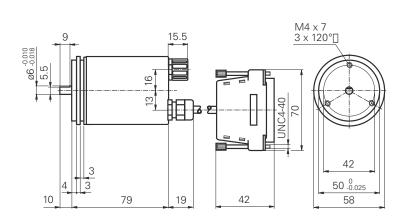




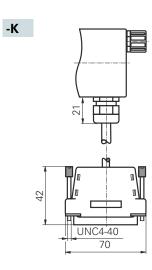
housing and connection dimensions

BME

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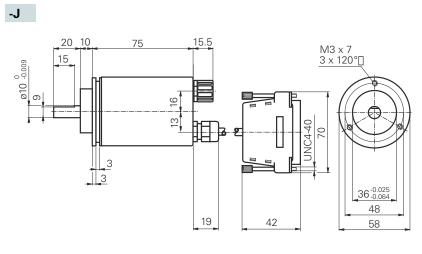


cable length 1 m

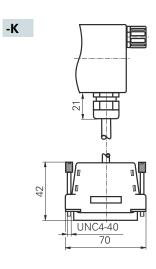


cable length 1 m

BMF



cable length 1 m



cable length 1 m

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assignment

Designation parallel				
connector 37-pin	signal	cable color		
1	S0	WH	white	
2	S1	BN	brown	
3	S2	GN	green	
4	S3	YE	yellow	
5	S4	GY	grey	
6	S5	PK	pink	
7	S6	BK	black	
8	S7	VT	violet	
9	S8	GY/PK	grey/pink	
10	S9	RD/BU	red/blue	
11	S10	WH/GN	white/green	
12	S11	BN/GN	brown/green	
13	S12	WH/YE	white/yellow	
14	S13	YE/BN	vellow/brown	
15	S14	WH/GY	white/grey	
16	S15	GY/BN	grey/brown	
17	-	WH/PK	white/pink	
18	-	PK/BN	pink/brown	
19	-	WH/BK	white/black	
20	D19	BN/BK	brown/black	
21	D20	GY/GN	grey/green	
22	D21	YE/GY	yellow/grey	
23	D22	PK/GN	pink/green	
24	D23	YE/PK	vellow/pink	
25	-	-	-	
26	_	_	-	
27	ZERO	YE/BU	yellow/blue	
28	ENABLE	BN/BU	brown/blue	
29	STORE	BN/RD	brown/red	
30	F/R	GN/BU	green/blue	
31	_	-	-	
32	_	_	-	
33	-	-	-	
34	GND Sense	WH/BU	white/blue	
35	+V Sense	WH/RD	white/red	
36	+Vs	RD	red	
37	GND	BU	blue	

Screen: In the case of encoders with cable output, the screen is connected to the housing internally.

signals parallel interface

1 - 16 S0 - S15	16 cam outputs Up to 250 cams can be programmed to these 16 outputs. For each data line, we recommend Pull-DOWN resistors for PNP and Pull-UP resistors for NPN, both with 4.7 k Ω values.
17 - 19 20 - 24 D19 - D23	not used factory diagnostic outputs These outputs may be assigned, at choice, to the functions preset 1, preset 2,
27 ZERO	speed monitoring or diagnosis. Reset input for setting a zero at any point within the programmed encoder resolution. The zero setting is triggered by a HIGH pulse imperatively after the sense of direction has been chosen (F/R). Assign to GND for maximum interference immunity after
28 <u>ENABLE</u>	zero setting. Pulse duration ≥ 100 ms. If this input is at LOW level, the output drivers will be activated. If HIGH potential is applied (or if open-circuited), the output drivers will turn to the HIGH-resistance state (Tristate).
29 <u>STORE</u>	When a LOW level is applied, the data of the absolute encoder is temporarily stored. If this input is connected to HIGH potential or if it remain closed, the current position data of the absolute encoder is switched through to the output drivers. This line must be used to ensure data readout in binary code.
30 F/ <u>R</u>	Input for counting up and down. If open- circuited, it is set to HIGH. HIGH means increasing output data if shaft rotates clock- wise when looking at the flange. LOW means increasing values if shaft rotates counter- clockwise when looking at the flange.
34 GND-Sense	
35 +Vs-Sense	This contact is connected internally to +Vs. If the sensor line is not to be used, this contact must be isolated (danger of short circuit).
36 +Vs 37 GND	Supply voltage of encoder. Ground contact of encoder with reference

BME BMF



inputs

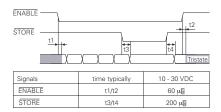
One control signal each for ENABLE for activation of the output driver, STORE for storing the output data, F/R for selection of positive direction of rotation and ZERO for zeroing in any position.

input voltage	(Vs = 10 - 30 VDC)
level HIGH	0.7 Vs up to Vs
level LOW	0 up to 0.3 Vs

wiring:

inputs with 10 k Ω against Vs, except zero setting input with 10 k Ω against GND.

signal characteristic STORE/ENABLE



outputs

16 outputs with $\overline{\text{STORE}}$ and tristate function ($\overline{\text{ENABLE}}$) and 5 special outputs.

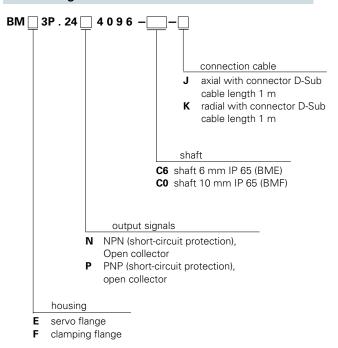
All outputs with short circuit protected PNP or NPN output levels

level HIGH (PNP)	\geq +Vs - 4.5 V (at I = -15 mA)
level LOW (NPN)	$\leq 3.5 \text{ V (at I} = 15 \text{ mA)}$
load HIGH (PNP)	≤ -20 mA
load LOW (NPN)	≤ 20 mA
tristate	≤ 200 µA

programming cable pin assignment

	5-Pol. EncSt.		PC-connector 9-Pol. D-Sub	
-	Pin 1	brown	_	-
RxD	Pin 2	white	Pin 3	Pin 2
GND	Pin 3	blue	Pin 5	Pin 7
P/R-Mode	Pin 4	black	Pin 5	Pin 7
TxD	Pin 5	gray	Pin 2	Pin 3
-	-	-	Br. 4 - 6	Br. 4 - 5
_	_	l_	Br 7-8	Br 6 - 20

order designation



programmingrequirements

- PC with RS 232-interface and Windows-operating
- Progeber software and handbook
- programming cable, connects encoder with PC

accessories

Type BME servo flange

mounting adapter	part nr. 117667
screws and servo clamps	part nr. 117668

Type BMF clamping flange

mounting angle part nr. 117698

Programming cable (length 2 m)

with 9-pin D-Sub connector	part nr. 117666
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Programming software

for PC with RS-232-Interface and	
operating system from DOS 3.2	part nr. 117665