

# 12-Bit 20MSPS Sampling Analog-to-Digital Converter IP Core

## nAD1220

### TSMC 0.35 $\mu$ 2P3M

#### FEATURES

- 2.8-3.6V power supply
- SINAD typ. 59dB for ( $f_{in} = 5\text{MHz}$ )
- Very low power (70mW@3.0V)
- Sample rate: > 20MSPS
- Internal Sample/Hold
- Differential input
- Low input capacitance

#### APPLICATIONS

- Imaging
- Test equipment
- Computer scanners
- Communications
- Set top boxes

#### GENERAL DESCRIPTION

The nAD1220 is a compact, high-speed, very low power 12-bit monolithic analog-to-digital converter, implemented in a 0.35 $\mu\text{m}$  CMOS process. It has 12-bit resolution with close to 10 effective bits, and more than 10 bit dynamic range for video signals. The converter includes sample and hold. The full-scale range can be set between  $\pm 0.6\text{V}$  and  $\pm 1.7\text{V}$  using external references. It operates from a single 2.8-3.6V supply - compatible with modern digital systems. Most converters in this performance range demand at least a +5V supply. Its low distortion and high dynamic range offers the performance needed for demanding imaging, multimedia, telecommunications and instrumentation applications. The conversion rate can be increased to 40MHz while keeping SINAD higher than 50dB. An evaluation kit is available, see ordering information below.

#### QUICK REFERENCE DATA

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$V_{DD}$	supply voltage		2.8	3.3	3.6	V
$P_D$	power dissipation	Ex. references		76		mW
DNL	differential nonlinearity	$f_{IN}=0.9991\text{MHz}$			$\pm 0.4$	LSB <sub>(10bit)</sub>
	differential nonlinearity	$f_{IN}=0.9991\text{MHz}$			$\pm 1$	LSB <sub>(12bit)</sub>
INL	integral nonlinearity	$f_{IN}=0.9991\text{MHz}$			$\pm 1$	LSB <sub>(10bit)</sub>
	integral nonlinearity	$f_{IN}=0.9991\text{MHz}$			$\pm 3$	LSB <sub>(12it)</sub>
$f_S$	conversion rate		20			MHz
N	resolution				12	bit

Table 1. Quick reference data

#### ORDERING INFORMATION

Type number	Name	Description	Version
nAD1220-CORE	CORE	nAD1220 hard-core; layout available in 0.35 $\mu\text{m}$ CMOS	c-1
nAD1220-KIT	KIT	nAD1220 evaluation kit with the nAD1220 on board	k-1

Table 2. Ordering information



## GENERAL DESCRIPTION (Continued)

The nAD1220 has a pipelined architecture - resulting in low input capacitance. Digital error correction of the 11 most significant bits ensures good linearity for input frequencies approaching Nyquist. The excellent linearity at the color subcarrier frequency makes the converter ideally suited for video. It is also well suited for demanding ultrasonic imaging and flow measurements. The nAD1220 is very compact - occupying less than  $3.2\text{mm}^2$  of die area in a standard dual poly  $0.35\mu\text{m}$  CMOS process. The fully differential architecture makes it insensitive to substrate noise. Thus it is ideal as a mixed signal ASIC macro cell. The modular architecture of the converter and the flexible external biasing scheme means that scaling in number of bits and sampling rate is easily achieved. Power consumption is roughly proportional to the number of bits and to the maximum sampling rate. Thus, nAD1220 is an excellent choice as the core of a product family of very low power high speed converters with resolutions ranging from 8 - 12 bits and sampling rates ranging from 1-40MHz.

## BLOCK DIAGRAM

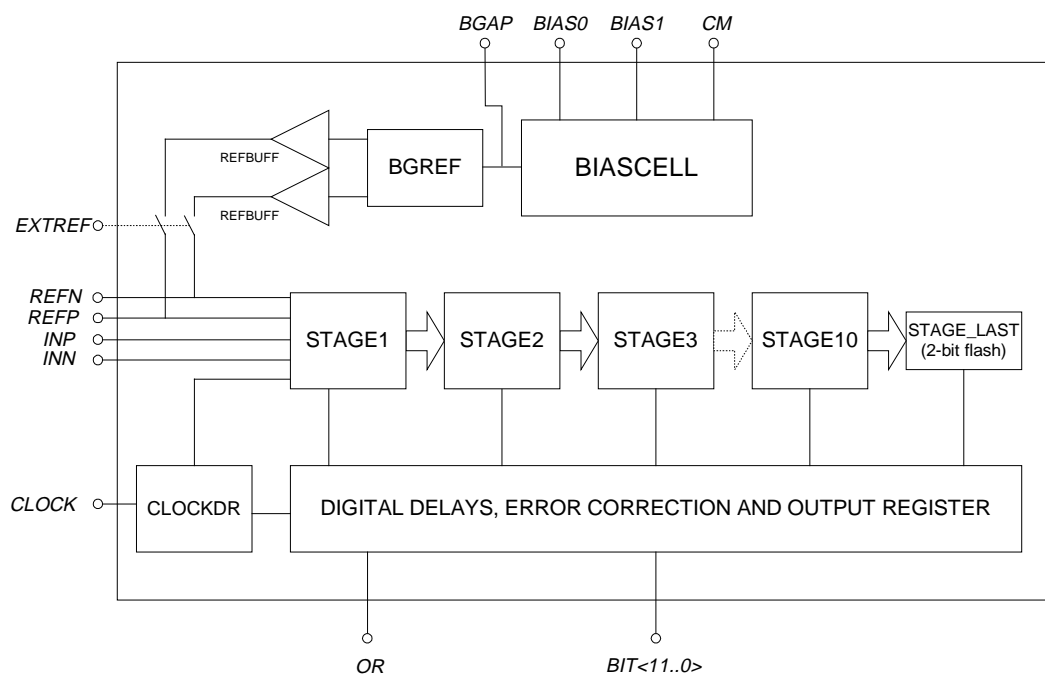


Figure 1. Block diagram nAD1220



## ELECTRICAL SPECIFICATIONS

(At  $T_A = 25^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ , Sampling Rate = 20MHz, Differential input, Input frequency = 4.4995MHz with a 50% duty cycle clock unless otherwise noted )

Symbol	Parameter (condition)	Test Level	Min.	Typ.	Max.	Units
<b>DC Accuracy</b>						
DNL	Differential Nonlinearity					
	$f_{IN} = 0.9991\text{ MHz}$	VI		$\pm 0.4$		LSB (10 bit)
				$\pm 0.6$		LSB (12bit)
INL	Integral Nonlinearity					
	$f_{IN} = 0.9991\text{ MHz}$	VI		$\pm 1.0$		LSB (10 bit)
				$\pm 3.0$		LSB (12bit)
	No Missing Codes	VI		Guaranteed		(12 bit)
$V_{OS}$	Midscale offset	V			$\pm 1$	% FSR
CMRR	Common Mode Rejection Ratio	V		55		DB
$\epsilon_G$	Gain Error	V		0.3		% FSR
<b>Dynamic Performance</b>						
SINAD	Signal to Noise and Distortion Ratio					
	$f_{IN} = 5\text{ MHz}$	VI	55	59		dB
	$f_{IN} = 10\text{ MHz}$	V		54		dB
SNR	Signal to Noise Ratio (without harmonics)					
	$f_{IN} = 5\text{ MHz}$	VI	57	60		dB
	$f_{IN} = 10\text{ MHz}$	V		56		dB
SFDR	Spurious Free Dynamic Range					
	$f_{IN} = 5\text{ MHz}$	VI	60	65		dB
	$f_{IN} = 10\text{ MHz}$	V		59		dB
DP	Differential Phase	V		0.2		degrees
DG	Differential Gain	V		0.5		%
PSRR	Power Supply Rejection Ratio	V		63		dB
<b>Analog Input</b>						
$V_{FSR}$	Input Voltage Range (Differential)	IV	$\pm 0.6$	$\pm 1$	$\pm 1.7$	V
$V_{CMI}$	Common mode input voltage	IV	1.2	1.65	1.9	V
$C_{INA}$	Input Capacitance (from each input to ground)	V		1.4		pF
<b>Reference Voltages</b>						
$V_{REFNO}$	Negative Input Voltage	IV		1.15		V
$V_{REFPO}$	Positive Input Voltage	IV		2.15		V
$V_{REFP} - V_{REFN}$	Reference input voltage range	IV	0.6	1.0	1.7	V
$V_{CM}$	Common mode output voltage ( $I_O = -1\mu\text{A}$ )	VI	1.3	1.65	1.8	V
<b>Digital Inputs</b>						
$V_{IL}$	Logic "0" voltage	VI			$20\% V_{DD}$	
$V_{IH}$	Logic "1" voltage	VI	$80\% V_{DD}$			
$I_{IL}$	Logic "0" current ( $V_I = V_{SS}$ )	VI			$\pm 1$	$\mu\text{A}$
$I_{IH}$	Logic "1" current ( $V_I = V_{DD}$ )	VI			$\pm 1$	$\mu\text{A}$
$C_{IND}$	Input Capacitance	V		1.8		pF
<b>Digital Outputs</b>						
$V_{OL}$	Logic "0" voltage ( $I = +2\text{ mA}$ )	VI		0.1	0.4	V
$V_{OH}$	Logic "1" voltage ( $I = -2\text{ mA}$ )	VI	$85\% V_{DD}$	$95\% V_{DD}$		V
$t_H$	Output hold time	IV		6		ns
$t_D$	Output delay time	IV	4	8	12	ns

(table continued on next page)



Switching Performance						
$f_s$	Conversion Rate	VI	20		TBD	MSPS
	Pipeline Delay (see timing diagram)	IV		7.5		Clocks
$\sigma_{AP}$	Aperture jitter	V		10		ps
$t_{AP}$	Aperture delay	V		5		ns
Power Supply						
$V_{DD}$	supply voltage	IV	2.8	3.3	3.6	V
$I_{DD}$	supply current 1)	VI		24	30	mA
$I_{DD}$	supply current (sleep mode, EXTREF "0")	VI		6.6		mA
$I_{DD}$	supply current (sleep mode, EXTREF "1")	VI		1.8		mA
$V_{SS}$	supply voltage			GND		
$AV_{DD}$ - $DV_{DD1}$	analog power - digital power pins	V	-0.2		+0.2	V
$DV_{DD1}$ - $DV_{DD2}$	digital power - output driver power	V	-0.2		+0.2	V
$P_D$	Power dissipation	VI		79	100	mW

Table 3. Electrical specifications

1) Power down ("zero") power consumption available for IP core.

### Test Levels

Test Level I: 100% production tested at +25°C

Test Level II: 100% production tested at +25°C and sample tested at specified temperatures

Test Level III: Sample tested only

Test Level IV: Parameter is guaranteed by design and characterization testing

Test Level V: Parameter is typical value only

Test Level VI: 100% production tested at +25°C. Guaranteed by design and characterization testing for industrial temperature range

## ABSOLUTE MAXIMUM RATINGS

### Supply voltages

$AV_{DD}$  ..... - 0.5V to +6V

$DV_{DD1}$  ..... - 0.5V to  $V_{DD} + 0.5V$

$DV_{DD2}$  ..... - 0.5V to  $V_{DD} + 0.5V$

### Temperatures

Operating Temperature....-55°C to +95°C

Storage Temperature..- 65°C to +125°C

### Input voltages

Analog In..... - 0.5V to  $AV_{DD} + 0.5V$

Digital In..... - 0.5V to  $V_{DD} + 0.5V$

$REF_P$  ..... - 0.5V to  $AV_{DD} + 0.5V$

$REF_N$  ..... - 0.5V to  $AV_{DD} + 0.5V$

CLOCK ..... - 0.5V to  $V_{DD} + 0.5V$

*Note: Stress above one or more of the limiting values may cause permanent damage to the device.*



## PIN FUNCTIONS

Pin Name	Description
IN <sub>P</sub> IN <sub>N</sub>	Differential input signal pins. Common mode voltage: 1.65V
REF <sub>P</sub> REF <sub>N</sub>	Reference pins. Bypass with 100nF capacitors close to the pins. See Application Information below.
EXTREF	Digital input: Reference select. EXTREF=1: Internal reference powered down, use external reference EXTREF=0: Internal reference is used
BIAS0, BIAS1	Digital inputs for max. sampling rate programming. BIAS1=0, BIAS0=0: Sleep mode (power save) BIAS1=0, BIAS0=1: Max. 5MHz sampling BIAS1=1, BIAS0=0: Max. 20MHz sampling BIAS1=1, BIAS0=1: Max. 30MHz sampling
CLOCK	Clock input
CM	Common mode voltage output.
BIT11 - BIT0	Digital outputs ( MSB to LSB)
BGAP	Band gap reference input / output voltage, nominally 2.413V
QI, S	Scan inputs. Connect to ground.
AV <sub>DD</sub>	Analog power pins. Should be connected to V <sub>DD</sub>
DV <sub>DD1</sub>	Digital power pins. Should be connected to V <sub>DD</sub>
DV <sub>DD2</sub>	Power pins for output drivers. Should be connected to V <sub>DD</sub>

Table 4. Pin functions.

## PIN ASSIGNMENT

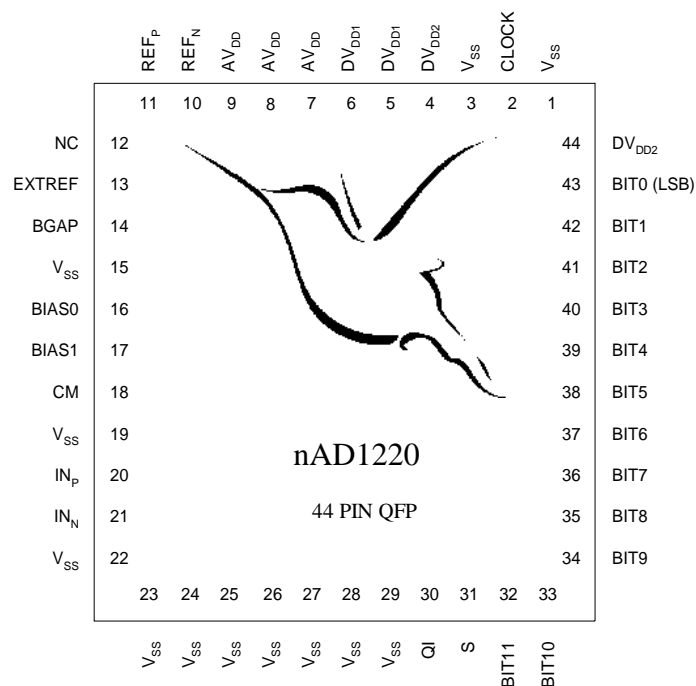


Figure 2. Pin assignment



## TIMING DIAGRAM

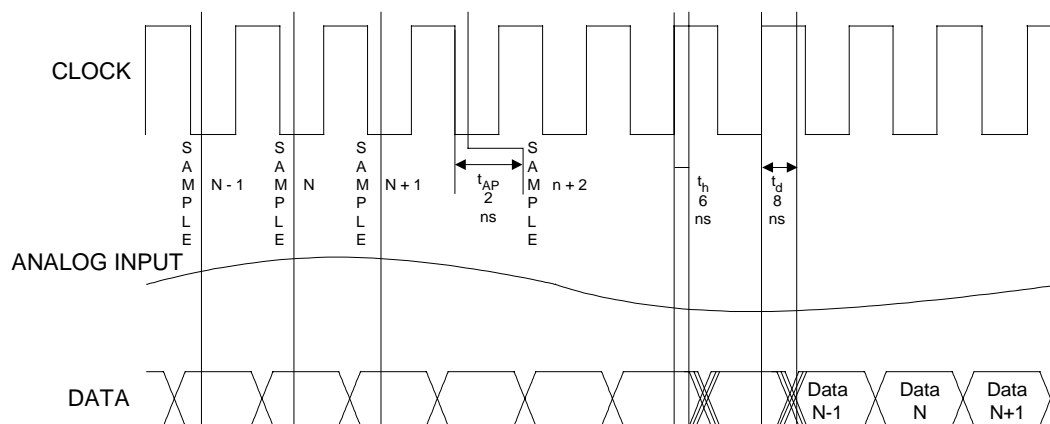
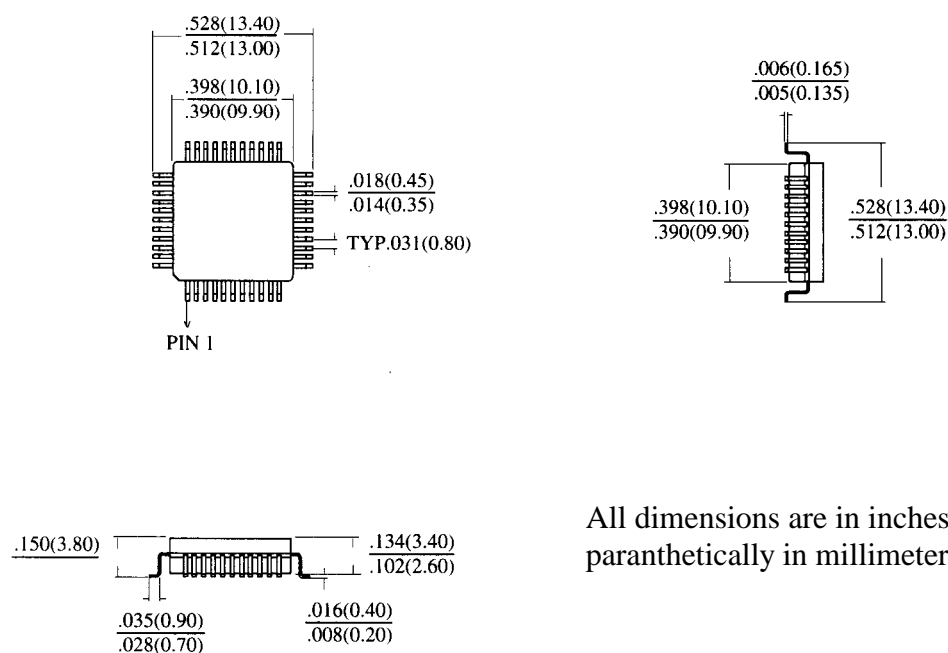


Figure 3. Timing diagram

## PACKAGE OUTLINE



All dimensions are in inches and  
paranthetically in millimeters.

Figure 5. Package outline

**DEFINITIONS**

<b>Data sheet status</b>	
Objective product specification	This datasheet contains target specifications for product development.
Preliminary product specification	This datasheet contains preliminary data; supplementary data may be published from Nordic VLSI ASA later.
Product specification	This datasheet contains final product specifications.
<b>Limiting values</b>	
Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Specifications sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.	
<b>Application information</b>	
Where application information is given, it is advisory and does not form part of the specification.	

Table 5. Definitions

**LIFE SUPPORT APPLICATIONS**

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Nordic VLSI ASA customers using or selling these products for use in such applications do so at their own risk and agree fully indemnify Nordic VLSI ASA for any damages resulting from such improper use or sale.



## APPLICATION INFORMATION

### References

The nAD1220 has a differential analog input. The input range is determined by the voltages  $V_P$  and  $V_N$  applied to reference pins  $REF_P$  and  $REF_N$  respectively, and is equal to  $\pm(V_P - V_N)$ . Externally generated reference voltages connected to  $REF_P$  and  $REF_N$  should be symmetric around 1.5V. The input range can be defined between  $\pm 0.6V$  and  $\pm 1.5V$ . Internal reference buffers exist – providing reference voltages at pins  $REF_P$  and  $REF_N$  equal to +2.00V ( $V_{REF_P}$ ) and +1.00V ( $V_{REF_N}$ ). These can be connected to  $REF_P$  and  $REF_N$  by connecting pin  $EXTREF$  to  $VSS$ . The references should be bypassed as close to the converter pins as possible using 100nF capacitors in parallel with smaller capacitors (e.g. 220pF) (to ground).

Series resistance from IP reference pins to pad window should be in the range 1 - 5 ohms.

### Analog input

The input of the nAD1220 can be configured in various ways - dependent upon whether a single ended or differential, AC- or DC-coupled input is wanted.

AC-coupled input is most conveniently implemented using a transformer with a center tapped secondary winding. The center tap is connected to the CM-node, as shown in Figure 1. In order to obtain low distortion, it is important that the selected transformer does not exhibit core saturation at full-scale. Excellent results are obtained with the Mini Circuits T1-6T or T1-1T. Proper termination of the input is important for input signal purity. A small capacitor (typ. 68pF) across the inputs attenuates kickback-noise from the sample and hold. A small capacitor (1nF) between CM and ground has also been proven to be advantageous.

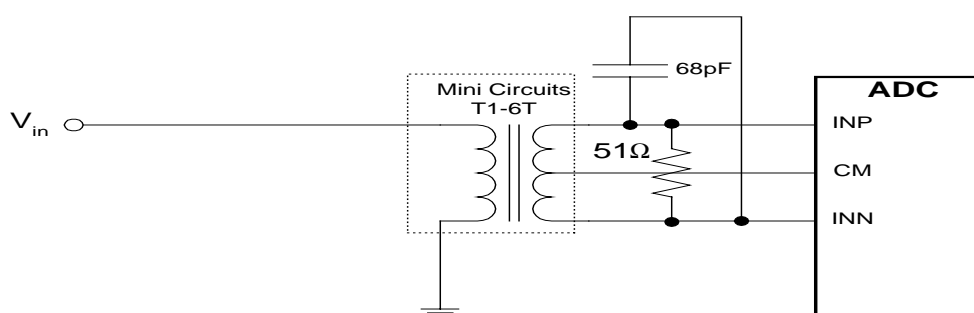


Figure 6. AC coupled input using transformer

If a DC-coupled single ended input is wanted, a solution based on operational amplifiers - as shown in Figure 7, is usually preferred. The AD826 is suggested for low distortion and video bandwidth. Lower cost operational amplifiers may be used if the demands are less strict.



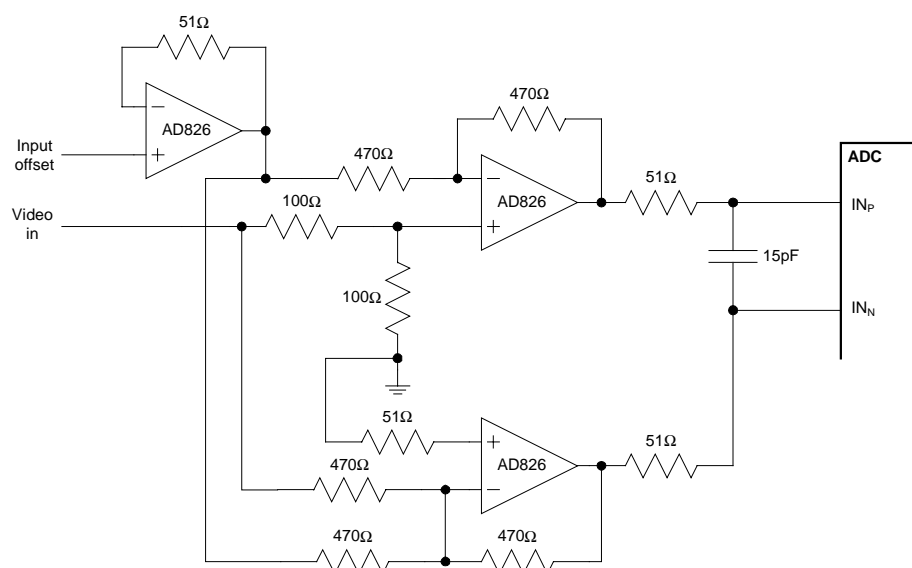


Figure 7. DC-coupled single ended to differential conversion (power supplies and bypassing not shown)

### Clock

The nAD1220 accepts a CMOS logic level clock at the CLK-node. The duty cycle of the clock should be close to 50%. Consecutive pipeline stages in the ADC are clocked in antiphase. With a 50% duty cycle, every stage has the same time for settling. If the duty cycle deviates from 50%, every second stage has a shorter time for settling - thus it operates less accurately, potentially causing degradation of SNR.

In order to preserve accuracy at high input frequency, it is important that the clock has low jitter and steep edges. Rise/fall times should be kept shorter than 2ns whenever possible. Overshoot should be avoided. Low jitter is especially important when converting high frequency input signals. Jitter causes the noise floor to rise proportionally to input signal frequency. Jitter may be caused by crosstalk on the PCB. It is therefore recommended that the clock trace on the PCB is made as short as possible.

### Digital outputs

The digital output data appears in offset binary code at CMOS logic levels. Full-scale negative input results in output code 000...0. Full-scale positive input results in output code 111...1. Output data are available 7.5 clock cycles after the data are sampled. The analog input is sampled one aperture delay ( $t_{AP}$ ) after the high to low clock transition. Output data should be sampled on the low to high clock transition, as shown in the timing diagram. Output data are invalid for the first 20 clock cycles after wake-up from power down mode.



### **PCB layout and decoupling**

A well designed PCB is necessary to get good spectral purity from any high performance ADC. A multilayer PCB with a solid ground plane is recommended for optimum performance. If the system has a split analog and digital ground plane, it is recommended that all ground pins on the ADC are connected to the analog ground plane. It is our experience that this gives the best performance. The power supply pins should be bypassed using 100nF surface mounted capacitors as close to the package pins as possible. Analog and digital supply pins should be separately filtered. One should make sure that the analog and digital supply voltages are equal.

### **Dynamic testing**

Careful testing using high quality instrumentation is necessary to achieve accurate test results on high speed A/D-converters. It is important that the clock source and signal source has low jitter. A spectrally pure, low noise RF signal generator - such as the HP8662A or HP 8644B is recommended for the test signal. Low pass filtering or band pass filtering of the input signal is usually necessary to obtain the required spectral purity (SFDR > 75dB). The clock signal can be obtained from either a crystal oscillator or a low-jitter pulse generator. Alternatively, a low-jitter RF-generator can be used as a clock source. At Nordic VLSI, the Marconi Instruments 2041A is used. The sinewave clock must then be applied to an ultra high speed comparator (e.g. AD9696) and a TTL to CMOS level shifter (e.g. 74LV04) before application to the converter. The most consistent results are obtained if the clock signal is phase locked to the input signal. Phase locking allows testing without windowing of output data. A logic analyzer with deep memory - such as the HP16500-series, is recommended for test data acquisition.



## **YOUR NOTES**



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