



## 1.0 ELECTRICAL CHARACTERISTICS

### 1.1 MAXIMUM RATINGS\*

V<sub>CC</sub> and input voltages w.r.t. V<sub>SS</sub> ..... -0.6V to + 6.25V  
 Voltage on  $\overline{OE}$  w.r.t. V<sub>SS</sub> ..... -0.6V to +13.5V  
 Voltage on A<sub>9</sub> w.r.t. V<sub>SS</sub> ..... -0.6V to +13.5V  
 Output Voltage w.r.t. V<sub>SS</sub> ..... -0.6V to V<sub>CC</sub>+0.6V  
 Storage temperature ..... -65°C to +125°C  
 Ambient temp. with power applied ..... -50°C to +95°C

**\*Notice:** Stresses above those listed under “Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TABLE 1-1: PIN FUNCTION TABLE

Name	Function
A0 - A10	Address Inputs
$\overline{CE}$	Chip Enable
$\overline{OE}$	Output Enable
$\overline{WE}$	Write Enable
I/O0 - I/O7	Data Inputs/Outputs
V <sub>CC</sub>	+5V Power Supply
V <sub>SS</sub>	Ground
NC	No Connect; No Internal Connection
NU	Not Used; No External Connection is Allowed

TABLE 1-2: READ/WRITE OPERATION DC CHARACTERISTICS

V <sub>CC</sub> = +5V ±10% Commercial (C): T <sub>amb</sub> = 0°C to +70°C Industrial (I): T <sub>amb</sub> = -40°C to +85°C						
Parameter	Status	Symbol	Min	Max	Units	Conditions
Input Voltages	Logic '1' Logic '0';	V <sub>IH</sub> V <sub>IL</sub>	2.0 -0.1	V <sub>CC</sub> +1 0.8	V V	
Input Leakage	—	I <sub>LI</sub>	-10	10	μA	V <sub>IN</sub> = -0.1V to V <sub>CC</sub> +1
Input Capacitance	—	C <sub>IN</sub>	—	10	pF	V <sub>IN</sub> = 0V; T <sub>amb</sub> = 25°C; f = 1 MHz
Output Voltages	Logic '1' Logic '0'	V <sub>OH</sub> V <sub>OL</sub>	2.4	0.45	V V	I <sub>OH</sub> = -400μA I <sub>OL</sub> = 2.1 mA
Output Leakage	—	I <sub>LO</sub>	-10	10	μA	V <sub>OUT</sub> = -0.1V to V <sub>CC</sub> +0.1V
Output Capacitance	—	C <sub>OUT</sub>	—	12	pF	V <sub>IN</sub> = 0V; T <sub>amb</sub> = 25°C; f = 1 MHz
Power Supply Current, Active	TTL input	I <sub>CC</sub>	—	30	mA	f = 5 MHz (Note 1) V <sub>CC</sub> = 5.5V;
Power Supply Current, Standby	TTL input TTL input CMOS input	I <sub>CC</sub> (S) <sub>TTL</sub> I <sub>CC</sub> (S) <sub>TTL</sub> I <sub>CC</sub> (S) <sub>CMOS</sub>	—	2 3 100	mA mA μA	$\overline{CE}$ = V <sub>IH</sub> (0°C to +70°C) $\overline{CE}$ = V <sub>IH</sub> (-40°C to +85°C) $\overline{CE}$ = V <sub>CC</sub> -0.3 to V <sub>CC</sub> +1 $\overline{OE}$ = V <sub>CC</sub> Other inputs equal V <sub>CC</sub> or V <sub>SS</sub>

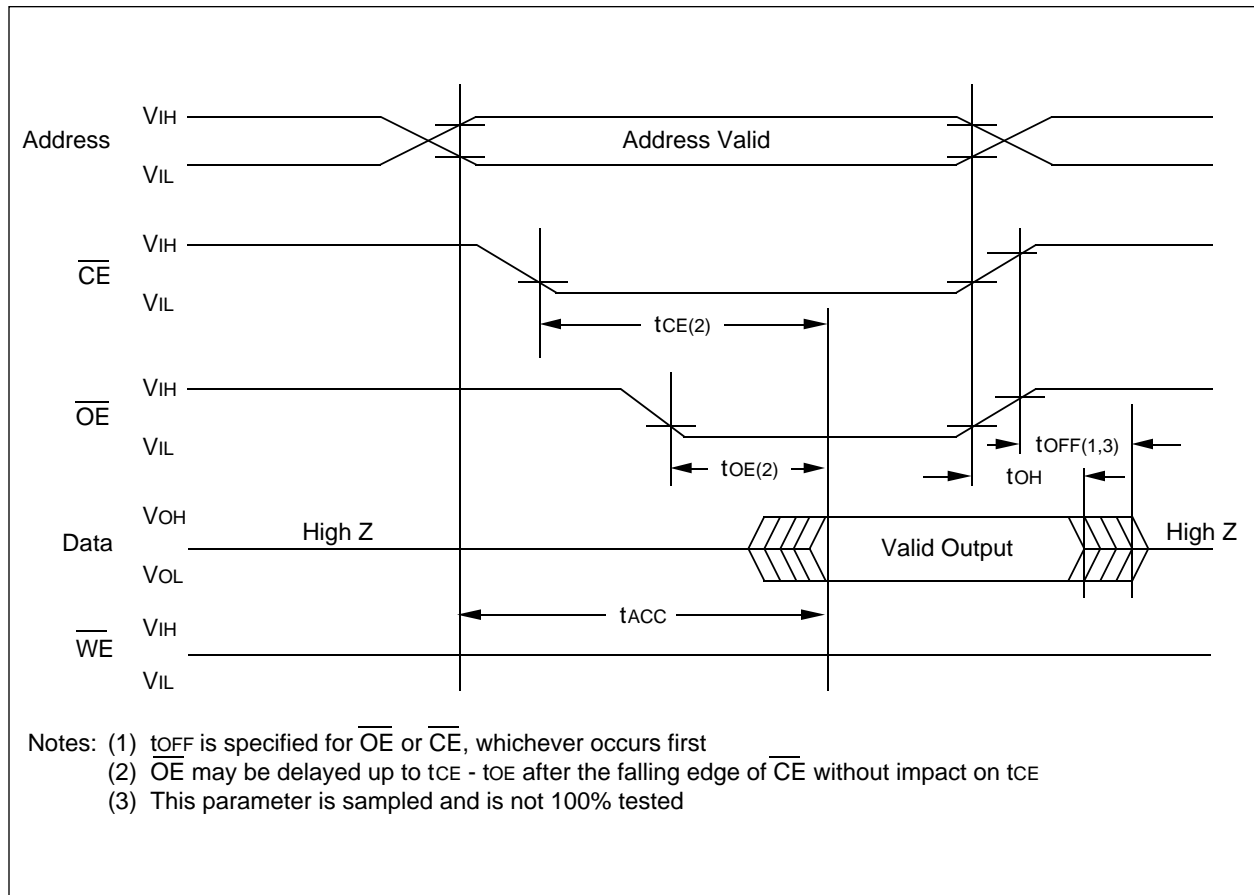
Note 1: AC power supply current above 5 MHz; 1 mA/MHz.

**TABLE 1-3: READ OPERATION AC CHARACTERISTICS**

		AC Testing Waveform:		V <sub>IH</sub> = 2.4V; V <sub>IL</sub> = 0.45V; V <sub>OH</sub> = 2.0V; V <sub>OL</sub> = 0.8V					
		Output Load:		1 TTL Load + 100pF					
		Input Rise and Fall Times:		20 ns					
		Ambient Temperature:		Commercial (C): Tamb = 0°C to +70°C Industrial (I): Tamb = -40°C to +85°C					
Parameter	Sym	28C16A-15		28C16A-20		28C16A-25		Units	Conditions
		Min	Max	Min	Max	Min	Max		
Address to Output Delay	t <sub>ACC</sub>	—	150	—	200	—	250	ns	$\overline{OE} = \overline{CE} = V_{IL}$
$\overline{CE}$ to Output Delay	t <sub>CE</sub>	—	150	—	200	—	250	ns	$\overline{OE} = V_{IL}$
$\overline{OE}$ to Output Delay	t <sub>OE</sub>	—	70	—	80	—	100	ns	$\overline{CE} = V_{IL}$
$\overline{CE}$ or $\overline{OE}$ High to Output Float	t <sub>OFF</sub>	0	50	0	55	0	70	ns	
Output Hold from $\overline{CE}$ or $\overline{OE}$ , whichever occurs first	t <sub>OH</sub>	0	—	0	—	0	—	ns	
Endurance	—	1M	—	1M	—	1M	—	cycles	25°C, V <sub>CC</sub> = 5.0V, Block Mode (Note)

Note: This parameter is not tested but guaranteed by characterization. For endurance estimates in a specific application, please consult the Total Endurance Model which can be obtained on our BBS or website.

**FIGURE 1-1: READ WAVEFORMS**



**TABLE 1-4: BYTE WRITE AC CHARACTERISTICS**

		AC Testing Waveform:		$V_{IH} = 2.4V$ and $V_{IL} = 0.45V$ ; $V_{OH} = 2.0V$ ; $V_{OL} = 0.8V$	
		Output Load:		1 TTL Load + 100 pF	
		Input Rise/Fall Times:		20 ns	
		Ambient Temperature:		Commercial (C):	$T_{amb} = 0^{\circ}C$ to $+70^{\circ}C$
				Industrial (I):	$T_{amb} = -40^{\circ}C$ to $+85^{\circ}C$
Parameter	Symbol	Min	Max	Units	Remarks
Address Set-Up Time	$t_{AS}$	10	—	ns	
Address Hold Time	$t_{AH}$	50	—	ns	
Data Set-Up Time	$t_{DS}$	50	—	ns	
Data Hold Time	$t_{DH}$	10	—	ns	
Write Pulse Width	$t_{WPL}$	100	—	ns	Note 1
Write Pulse High Time	$t_{WPH}$	50	—	ns	
$\overline{OE}$ Hold Time	$t_{OEH}$	10	—	ns	
$\overline{OE}$ Set-Up Time	$t_{OES}$	10	—	ns	
Data Valid Time	$t_{DV}$	—	1000	ns	Note 2
Write Cycle Time (28C16A)	$t_{WC}$	—	1	ms	0.5 ms typical
Write Cycle Time (28C16AF)	$t_{WC}$	—	200	$\mu s$	100 $\mu s$ typical

Note 1: A write cycle can be initiated by  $\overline{CE}$  or  $\overline{WE}$  going low, whichever occurs last. The data is latched on the positive edge of  $\overline{CE}$  or  $\overline{WE}$ , whichever occurs first.

2: Data must be valid within 1000ns max. after a write cycle is initiated and must be stable at least until  $t_{DH}$  after the positive edge of  $\overline{WE}$  or  $\overline{CE}$ , whichever occurs first.

**FIGURE 1-2: PROGRAMMING WAVEFORMS**

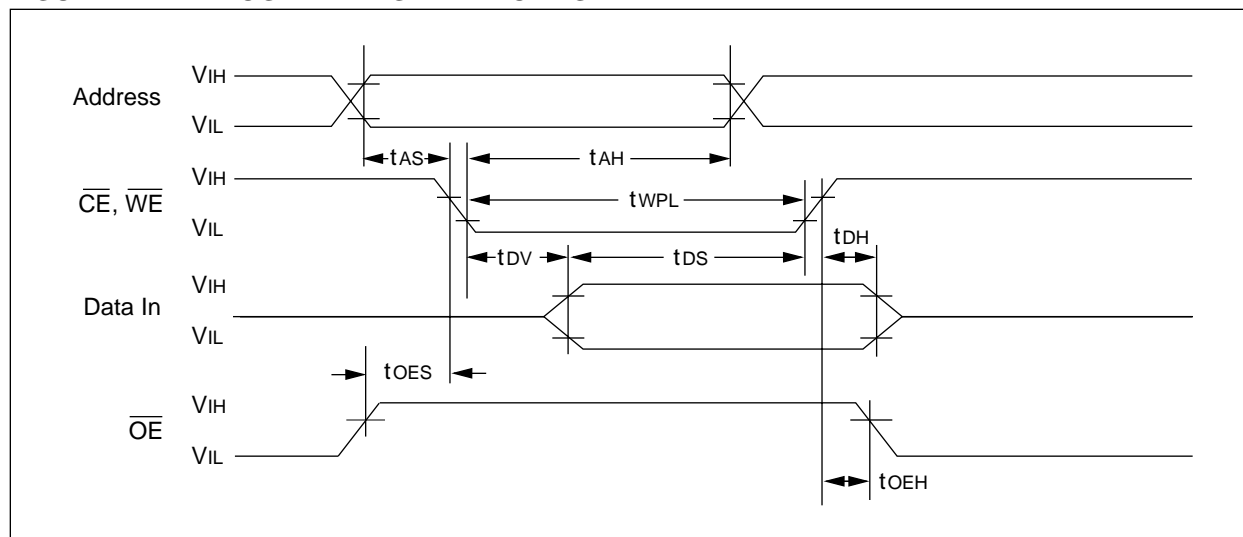


FIGURE 1-3: DATA POLLING WAVEFORMS

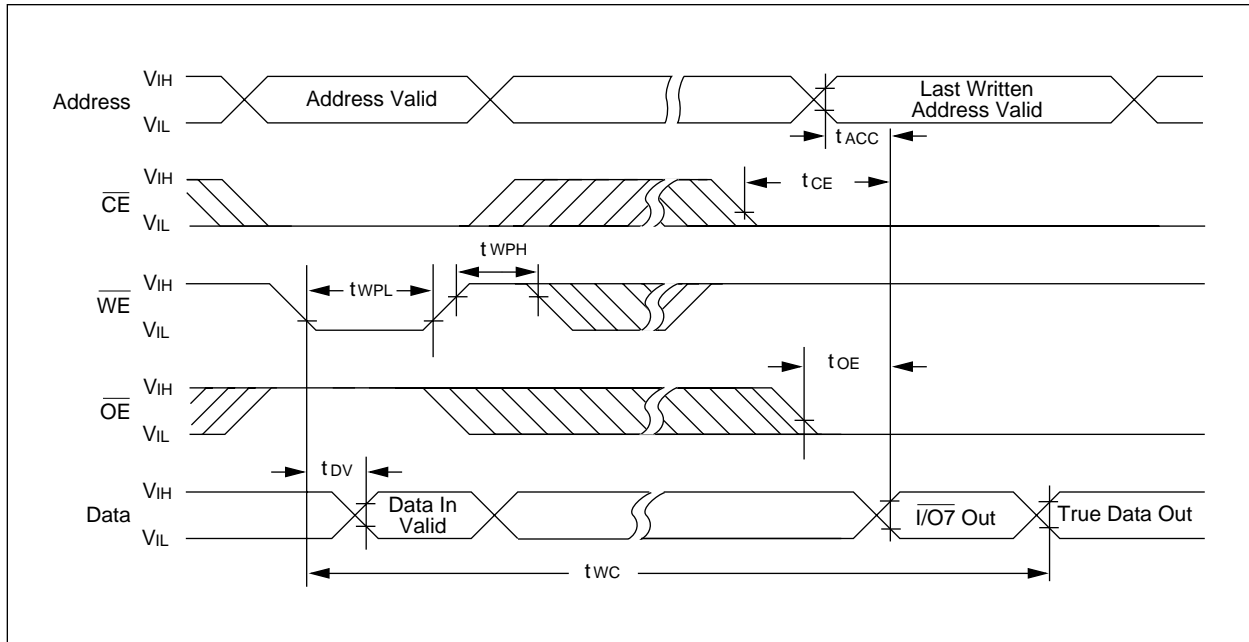


FIGURE 1-4: CHIP CLEAR WAVEFORMS

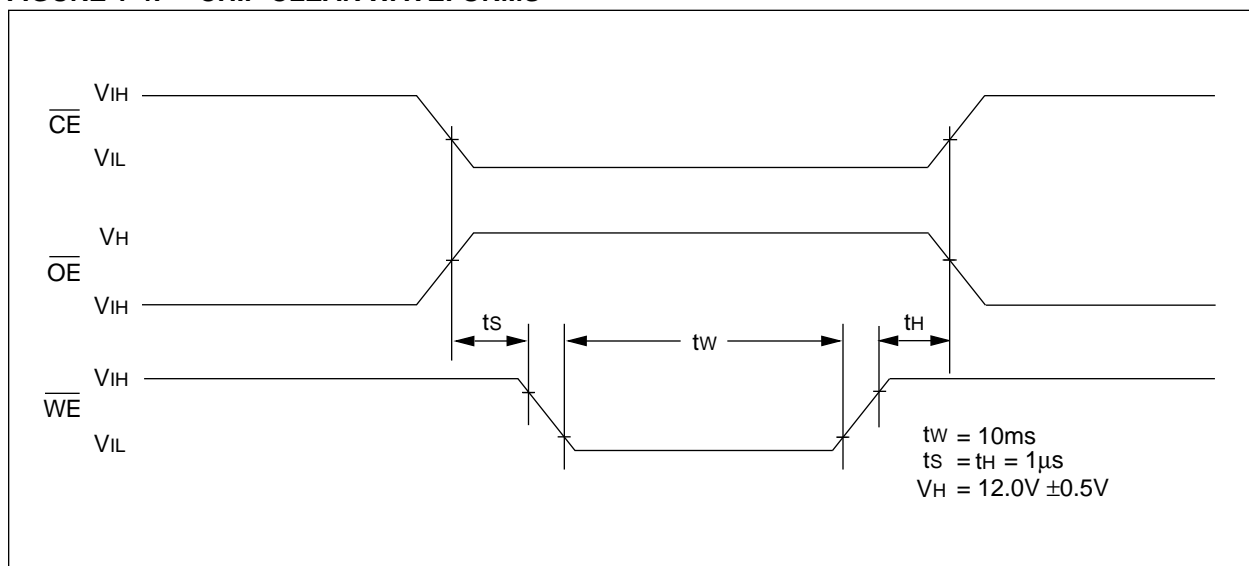


TABLE 1-5: SUPPLEMENTARY CONTROL

Mode	$\overline{CE}$	$\overline{OE}$	$\overline{WE}$	A9	Vcc	I/Oi
Chip Clear	VIL	VH	VIL	X	Vcc	
Extra Row Read	VIL	VIL	VIH	A9 = VH	Vcc	Data Out
Extra Row Write	*	VIH	*	A9 = VH	Vcc	Data In
Note 1: $V_H = 12.0\text{V} \pm 0.5\text{V}$ * Pulsed per programming waveforms.						

## 2.0 DEVICE OPERATION

The Microchip Technology Inc. 28C16A has four basic modes of operation—read, standby, write inhibit, and byte write—as outlined in the following table.

Operation Mode	$\overline{CE}$	$\overline{OE}$	$\overline{WE}$	I/O
Read	L	L	H	DOUT
Standby	H	X	X	High Z
Write Inhibit	H	X	X	High Z
Write Inhibit	X	L	X	High Z
Write Inhibit	X	X	H	High Z
Byte Write	L	H	L	DIN
Byte Clear	Automatic Before Each "Write"			

X = Any TTL level.

### 2.1 Read Mode

The 28C16A has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip enable ( $\overline{CE}$ ) is the power control and should be used for device selection. Output Enable ( $\overline{OE}$ ) is the output control and is used to gate data to the output pins independent of device selection. Assuming that addresses are stable, address access time ( $t_{ACC}$ ) is equal to the delay from  $\overline{CE}$  to output ( $t_{CE}$ ). Data is available at the output  $t_{OE}$  after the falling edge of  $\overline{OE}$ , assuming that  $\overline{CE}$  has been low and addresses have been stable for at least  $t_{ACC}-t_{OE}$ .

### 2.2 Standby Mode

The 28C16A is placed in the standby mode by applying a high signal to the  $\overline{CE}$  input. When in the standby mode, the outputs are in a high impedance state, independent of the  $\overline{OE}$  input.

### 2.3 Data Protection

In order to ensure data integrity, especially during critical power-up and power-down transitions, the following enhanced data protection circuits are incorporated:

First, an internal Vcc detect (3.3 volts typical) will inhibit the initiation of non-volatile programming operation when Vcc is less than the Vcc detect circuit trip.

Second, there is a  $\overline{WE}$  filtering circuit that prevents  $\overline{WE}$  pulses of less than 10 ns duration from initiating a write cycle.

Third, holding  $\overline{WE}$  or  $\overline{CE}$  high or  $\overline{OE}$  low, inhibits a write cycle during power-on and power-off (Vcc).

### 2.4 Write Mode

The 28C16A has a write cycle similar to that of a Static RAM. The write cycle is completely self-timed and initiated by a low going pulse on the  $\overline{WE}$  pin. On the falling edge of  $\overline{WE}$ , the address information is latched. On rising edge, the data and the control pins ( $\overline{CE}$  and  $\overline{OE}$ ) are latched.

### 2.5 Data Polling

The 28C16A features Data polling to signal the completion of a byte write cycle. During a write cycle, an attempted read of the last byte written results in the data complement of I/O7 (I/O0 to I/O6 are indeterminate). After completion of the write cycle, true data is available. Data polling allows a simple read/compare operation to determine the status of the chip eliminating the need for external hardware.

### 2.6 Electronic Signature for Device Identification

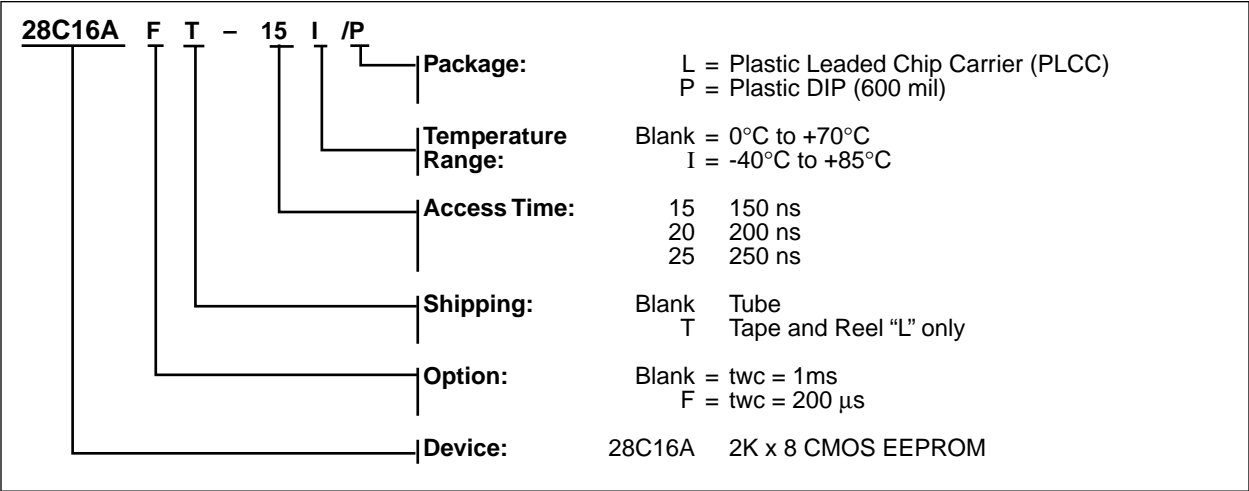
An extra row of 32 bytes of EEPROM memory is available to the user for device identification. By raising A9 to 12V  $\pm 0.5V$  and using address locations 7E0 to 7FF, the additional bytes can be written to or read from in the same manner as the regular memory array.

### 2.7 Chip Clear

All data may be cleared to 1's in a chip clear cycle by raising  $\overline{OE}$  to 12 volts and bringing the  $\overline{WE}$  and  $\overline{CE}$  low. This procedure clears all data, except for the extra row.

28C16A Product Identification System

To order or to obtain information, e.g., on pricing or delivery, please use the listed part numbers, and refer to the factory or the listed sales offices.





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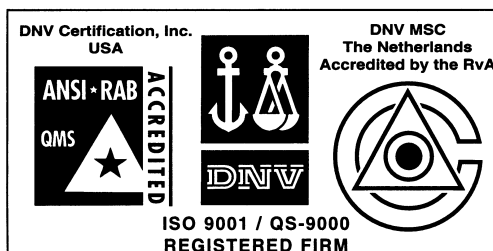
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Microchip received QS-9000 quality system certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona in July 1999. The Company's quality system processes and procedures are QS-9000 compliant for its PICmicro® 8-bit MCUs, KEELoc® code hopping devices, Serial EEPROMs and microperipheral products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001 certified.

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