SPECIFICATION

 Device Name
 : IGBT-IPM

 Type Name
 : 6MBP75RTB060

 Spec. No.
 : MS6M0652

Fuji Electric Co.,Ltd. Matsumoto Factory

	DATE	NAME	APPROVED		Evii Electric Co	144
DRAWN	Jun - 12- '02	K.Sekigara	•		Fuji Electric Co.,	Liu.
CHECKED	Jun-12-021	nishiaro	V 12	DWG.NO.	иссиосто	1 / b
CHECKED	Tun-12-102	K. Ganade	A.SE	DMC	MS6M0652	' 22

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Revised Records

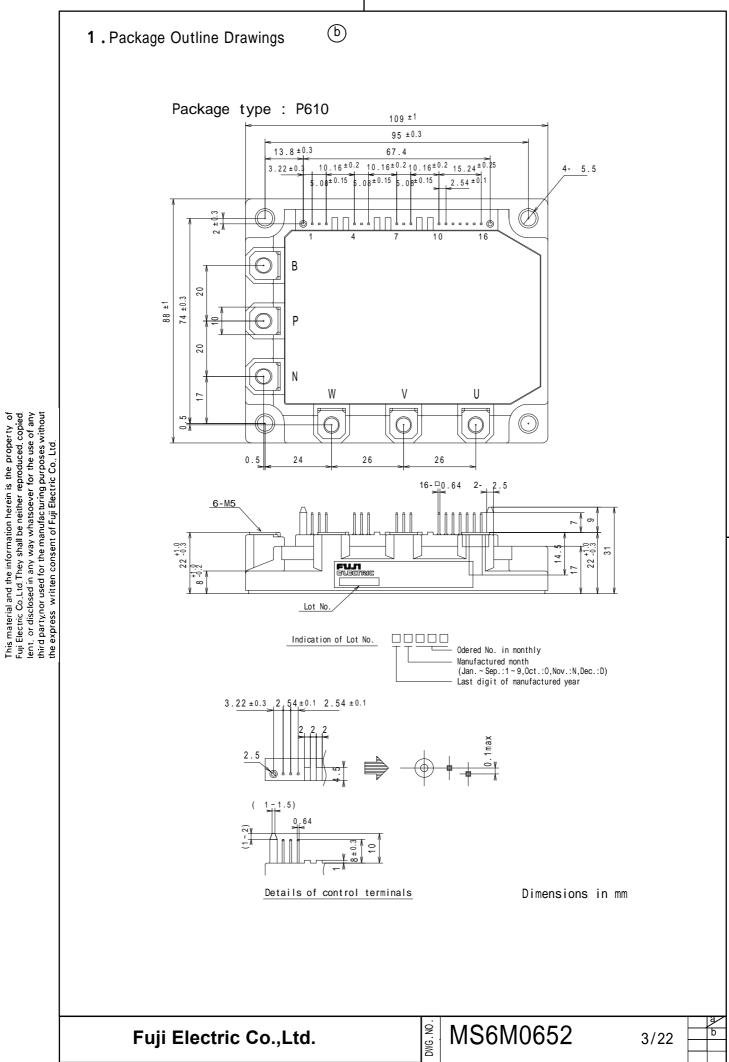
Date	Classi- fication	Ind.	Content	Applied date	Drawn	Check ed	Check ed	Appro ved
Jun-12-òz	Enactment	_		Issued date	K. Sekigawa	Nishura	K Yound	W.S.
Jul - 08-'02	Correction addition	a	Cottection: Ioc. Watthing (%2) (21/2) addition: total vs Ir (18/22)					
09. Apr. 3003	Revision	Ь	Cottection: Ioc. Watthing (%2) (31/2) addition: totalth vs Ir (18/2) Reliability Test Items	09. Apr.	N. Trahala	T. Myas.la	K. Yamada	7. Fuji'him
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2. Pin Descriptions

Main circuit

Symbol	Description
Р	Positive input supply voltage.
U	Output (U).
V	Output (V).
W	Output (W).
N	Negative input supply voltage.
В	No contact.

Control circuit

Symbol	Description
GNDU	High side ground (U).
VinU	Logic input for IGBT gate drive (U).
VccU	High side supply voltage (U).
GNDV	High side ground (V).
VinV	Logic input for IGBT gate drive (V).
VccV	High side supply voltage (V).
_	
GNDW	High side ground (W).
VinW	Logic input for IGBT gate drive (W).
VccW	High side supply voltage (W).
GND	Low side ground.
Vcc	Low side supply voltage.
VinDB	No contact.
VinX	Logic input for IGBT gate drive (X).
VinY	Logic input for IGBT gate drive (Y).
VinZ	Logic input for IGBT gate drive (Z).
ALM	Low side alarm signal output.
	GNDU VinU VccU GNDV VinV VccV GNDW VinW VccW GND Vcc VinDB VinX VinY VinZ

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4 . Absolute Maximum Ratings

Tc = 25unless otherwise specified.

Items				Min.	Max.	Units
		DC	VDC	0	450	V
Bu	s Voltage	Surge	VDC(surge)	0	500	V
(b	etween terminal P and N)	Shortoperating	Vsc	200	400	V
Со	llector-Emitter Voltage *1		Vces	0	600	V
		DC	lc		75	Α
nverter	Collector Current	1ms	Icp		150	Α
l N		Duty74.9% *2	-lc		75	Α
	Collector Power Dissipation	One transistor *3	Pc		198	W
Su	Supply Voltage of Pre-Driver *4			-0.5	20	V
Inp	ut Signal Voltage *5		Vin	-0.5	Vcc+0.5	V
Inp	ut Signal Current		lin		3	mA
Ala	rm Signal Voltage *6		VALM	-0.5	Vcc	V
Ala	rm Signal Current *7		IAM		20	mA
Jur	nction Temperature		Tj		150	
Ор	erating Case Temperature		Topr	-20	100	
Sto	orage Temperature		Tstg	-40	125	
Isolating Voltage			Vice		A C 2 E 0 0	V
(Te	erminal to base, 50/60Hz sine v	vave 1min.) *8	Viso		AC2500	V
Sci	rew Torque	Terminal (M5)			2.5	Nm
		Mounting (M5)			3.5	Nm

Note

- *1 : Vces shall be applied to the input voltage between terminal P and U or V or W, N and U or V or W.
- *2 : 125 /FWD Rth(j-c)/(lc × VF MAX)=125/0.855/(75 × 2.6) × 100=74.9%
- *3 : Pc=125 /IGBT Rth(j-c)=125/0.63=198W
- *4: VCC shall be applied to the input voltage between terminal No.3 and 1, 6 and 4, 9 and 7, 11 and 10
- *5: Vin shall be applied to the input voltage between terminal No.2 and 1, 5 and 4, 8 and 7, 13,14,15 and 10.
- *6: VALM shall be applied to the voltage between terminal No.16 and 10.
- *7: IALM shall be applied to the input current to terminal No.16.
- *8 : 50Hz/60Hz sine wave 1 minute.

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5 . Electrical Characteristics

, Vcc = 15V unless otherwise specified.

5.1 Main circuit

	Item	Symbol	Conditi	ons	Min.	Тур.	Max.	Units
	Collector Current at off signal input	ICES	Vce = 600V Vin terminal op	en.	-	-	1.0	mA
nverter	Collector-Emitter	V05 ()	To - 75 A	Terminal	-	ı	2.4	V
l Ve	saturation voltage	VCE(sat)	Ic = 75A	Chip	-	2.0	-	V
	Forward voltage of	\ /F	T 75 A	Terminal	-	ı	2.6	V
	FWD	VF	-Ic =75A	Chip	-	1.6	-	V
Tu	rn-on time	ton	VDC = 300V, Tj=125		1.2	ı	-	
Tu	rn-off time	toff	Ic = 75A Fig.1	, Fig.6	-	ı	3.6	
Re	verse recovery time	trr	V _{DC} = 300V IF = 75A Fig.	1 , Fig.6	-	-	0.3	us
En	aximum Avalanche ergy non-repetition)	Pav	internal wiring inductance = Main circuit wir inductance = 8	ring	40	ı	-	mJ

5.2 Control circuit

Item	Symbol	Conditions	Min.	Тур.	Max.	Units	
Supply current of P-side pre-driver (one unit)	Ісср	Switching Frequency: 0 ~ 15kHz	-	-	18	mA	
Supply current of N-side pre-driver	Iccn	Tc = -20 ~ 125 Fig.7	-	-	65	mA	
	Vin(th)	ON	1.00	1.35	1.70	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	
Input signal threshold voltage		OFF	1.25	1.60	1.95	V	
Input Zener Voltage	Vz	Rin = 20k	-	8.0	-	V	
		Tc = -20 Fig.2	1.1	-	-	ms	
Alarm Signal Hold Time	tALM	Tc = 25 Fig.2	-	2.0	-	ms	
		Tc = 125 Fig.2	-	-	4.0	ms	
Limiting Resistor for Alarm	RALM		1425	1500	1575		

5.3 Protection Section (Vcc = 15V)

	Item	Symbol	Conditions	Min.	Тур.	Max.	Units
a	Over Current Protection Level of Inverter circuit	loc	Tj=125	113	1	ı	Α
	Over Current Protection Delay time	tdoc	Tj=125	-	5	-	us
	SC Protection Delay time	tsc	Tj=125 Fig.4	-	•	8	us
	IGBT Chips Over Heating Protection Temperature Level	TjOH	Surface of IGBT Chips	150	1	1	
	Over Heating Protection Hysteresis	TjH		ı	20	ı	
	Over Heating Protection Temperature Level	TcOH	VDC=0V,IC=0A CaseTemperature	110	1	125	
	Over Heating Protection Hysteresis	TcH		ı	20	ı	
	Under Voltage Protection Level	VUV		11.0	ı	12.5	V
	Under Voltage Protection Hysteresis	VH		0.2	0.5	1	

6. Thermal Characteristics (Tc = 25)

Item			Symbol	Min.	Тур.	Max.	Units
Junction to Case	las santan	IGBT	Rth(j-c)	-	-	0.63	
Thermal Resistance *9	Inverter	FWD	Rth(j-c)	ı	-	0.855	/W
Case to Fin Thermal Resistance with Compound		Rth(c-f)	-	0.05	-		

7. Noise Immunity (Vdc=300V, Vcc=15V, Test Circuit Fig 5.)

Item Conditions		Min.	Тур.	Max.	Units
Common mode	Pulse width 1us,polarity ±,10 minuets	± 2.0			kV
rectangular noise	Judge: no over-current, no miss operating	± 2.0	-	-	KV
Common mode	Rise time 1.2us, Fall time 50us				
lightning surge	Interval 20s, 10 times	± 5.0	-	-	kV
lightning surge	Judge: no over-current, no miss operating	3.0			

8. Recommended Operating Conditions

Item	Symbol	Min.	Тур.	Max.	Units
DC Bus Voltage	VDC	ı	ı	400	V
Power Supply Voltage of Pre-Driver	Vcc	13.5	15.0	16.5	V
Screw Torque (M5)	-	2.5	-	3.0	Nm

9. Weight

	Item	Symbol	Min.	Тур.	Max.	Units
١	Weight	Wt	ı	450	ı	g

^{*9: (}For 1device , Case is under the device)

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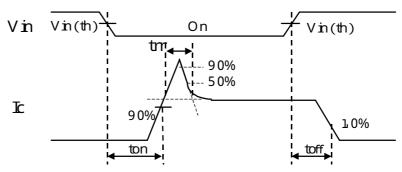
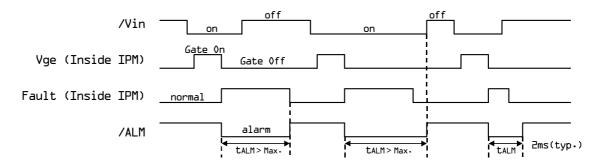


Figure 1. Switching Time Waveform Definitions



Fault: Over-current, Over-heat or Under-voltage

Figure 2. Input/Output Timing Diagram

Necessary conditions for alarm reset (refer to to in figure 2.)

This represents the case when a failure-causing Fault lasts for a period more than tALM. The alarm resets when the input Vin is OFF and the Fault has disappeared.

This represents the case when the ON condition of the input Vin lasts for a period more than tALM. The alarm resets when the Vin turns OFF under no Fault conditions.

This represents the case when the Fault disappears and the Vin turns OFF within tALM. The alarm resets after lasting for a period of the specified time tALM.

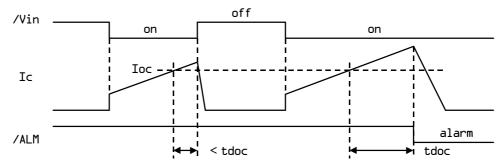


Figure 3. Over-current Protection Timing Diagram

Period: When a collector current over the OC level flows and the OFF command is input within a period less than the trip delay time tdoc, the current is hard-interrupted and no alarm is output.

Period: When a collector current over the OC level flows for a period more than the trip delay time tdoc, the current is soft-interrupted. If this is detected at the lower arm IGBTs, an alarm is output.

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Figure.4 Definition of tsc

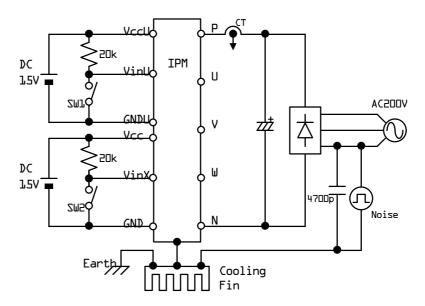


Figure 5. Noise Test Circuit

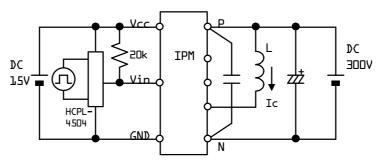


Figure 6. Switching Characteristics Test Circuit

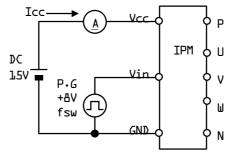


Figure 7. Icc Test Circuit

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10. Truth table

10.1 IGBT Control

The following table shows the IGBT ON/OFF status with respect to the input signal Vin. The IGBT turn-on when Vin is at "Low" level under no alarm condition.

Input (Vin)	Output (IGBT)
Low	ON
High	OFF

10.2 Fault Detection

- (1) When a fault is detected at the high side, only the detected arm stops its output. At that time the IPM doesn't any alarm.
- (2) When a fault is detected at the low side, all the lower arms stop their outputs and the IPM outputs an alarm of the low side.

	IGBT			Alarm Output		
	Fault	U-phase	V-phase	W-phase	Low side	ALM
	ОС	0FF	*	*	*	Н
High side	UV	OFF	*	*	*	Н
U-phase	TjOH	OFF	*	*	*	Н
III ale ali da	ОС	*	0FF	*	*	Н
High side	UV	*	0FF	*	*	Н
V-phase	ТjОН	*	0FF	*	*	Н
III ale ali da	ОС	*	*	0FF	*	Н
High side	UV	*	*	OFF	*	Н
W-phase	ТjОН	*	*	OFF	*	Н
	ОС	*	*	*	0FF	L
Low side	UV	*	*	*	0FF	L
	ТjОН	*	*	*	0FF	L
Case Temperature	ТсОН	*	*	*	OFF	L

^{*:} Depend on input logic.

11. Cautions for design and application

- 1. Trace routing layout should be designed with particular attention to least stray capacity between the primary and secondary sides of optical isolators by minimizing the wiring length between the optical isolators and the IPM input terminals as possible. フォトカプラとIPMの入力端子間の配線は極力短くし、フォトカプラの一次側と二次側の浮遊容量を小さくしたパターンレイアウトにして下さい。
- 2. Mount a capacitor between Vcc and GND of each high-speed optical isolator as close to as possible. 高速フォトカプラの Vcc-GND 間に、コンデンサを出来るだけ近接して取り付けて下され
- 3. For the high-speed optical isolator, use high-CMR type one with tpHL, tpLH 0.8μs. 高速フォトカプラは tpHL,tpLH 0.8us, 高 CMR タイプをご使用ください。
- 4. For the alarm output circuit, use low-speed type optical isolators with CTR 100%. アラーム出力回路は、低速フォトカプラ CTR 100%のタイプをご使用ください。
- 5. For the control power Vcc, use four power supplies isolated each. And they should be designed to reduce the voltage variations.

制御電源 Vcc は 絶縁された4電源を使用してください。また、電圧変動を抑えた設計として下さい。

- Suppress surge voltages as possible by reducing the inductance between the DC bus P and N, and connecting some capacitors between the P and N terminals
 P-N 間の直流母線は出来るだけ低インダクタンス化し、P-N 端子間にコンデンサを接続するなどしてサージ
- 7. To prevent noise intrusion from the AC lines, connect a capacitor of some 4700pF

AC ラインからのノイズ侵入を防ぐために、3相各線 - アース間に4700pF程のコンデンサを接続して下さい

between the three-phase lines each and the ground.

- 8. At the external circuit, never connect the control terminal GNDU to the main terminal U-phase, GNDV to V-phase, GNDW to W-phase, and GND to N-phase. Otherwise, malfunctions may be caused.
 - 制御端子 GNDUと主端子U相、制御端子 GNDVと主端子V相、制御端子 GNDWと主端子W相 制御端子 GNDと主端子Nを外部回路で接続しないで下さい。誤動作の原因になります。
- 9. Take note that an optical isolator's response to the primary input signal becomes slow if a capacitor is connected between the input terminal and GND.

入力端子-GND 間にコンデンサを接続すると、フォトカプラー次側入力信号に対する応答時間が長くなりますのでご注意ください。

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電圧を低減して下さい。

10. Taking the used isolator's CTR into account, design with a sufficient allowance to decide the primary forward current of the optical isolator.

フォトカプラの一次側電流は お使いのフォトカプラの CTR を考慮し十分に余裕をもった設計にして下さい。

11. Apply thermal compound to the surfaces between the IPM and its heat sink to reduce the thermal contact resistance.

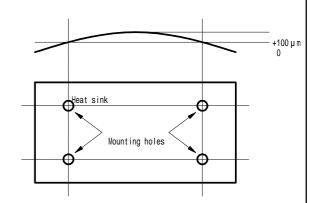
接触熱抵抗を小さくするために、IPMとヒートシンクの間にサーマルコンパウンド塗布して下さい。

12. Finish the heat sink surface within roughness of $10\mu m$ and flatness (camber) between screw positions of 0 to +100 μm . If the flatness is minus, the heat radiation becomes worse due to a gap between the heat sink and the IPM. And, if the flatness is over

 $+100\mu m$, there is a danger that the IPM copper base may be deformed and this may cause a dielectric breakdown.

ヒートシンク表面の仕上げは 粗さ 10um 以下、ネジ位置間での平坦度(反り)は 0~100um として下さい。平坦度がマイナスの場合、ヒートシンクと IPM の間に隙間ができ放熱が悪化します。また、平坦度が+100um 以上の場合IPMの銅

ペースが変形し絶縁破壊を起こす危険性があります。



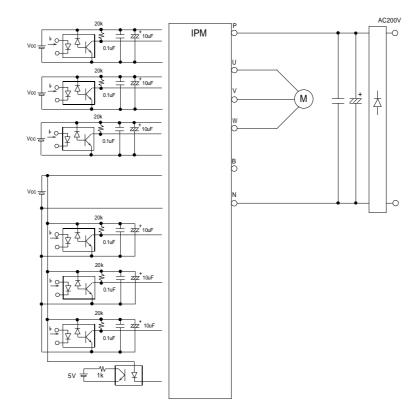
13. This product is designed on the assumption that it applies to an inverter use. Sufficient examination is required when applying to a converter use. Please contact Fuji Electric Co.,Ltd if you would like to applying to converter use.

本製品は、インバータ用途への適用を前提に設計されております。コンバータ用途へ適用される場合は、十分な 検討が必要です。もし、コンバータへ適用される場合は御連絡ください。

14. Please see the Fuji IGBT-IPM R SERIES APPLICATION MANUAL and Fuji IGBT MODULES N SERIES APPLICATION MANUAL .

『富士 IGBT-IPM R シリーズ アプリケーションマニュアル』及び『GBT モジュール N シリーズ アプリケーションマニュアル』を御参照ください。

12. Example of applied circuit 応用回路例



13. Package and Marking 梱包仕様

Please see the MT6M4140 which is packing specification of P610 & P611 package . P 6 1 0 , 6 1 1 梱包仕様書 M T 6 M 4 1 4 0 を御参照ください。

- 14. Cautions for storage and transportation 保管、運搬上の注意
 - Store the modules at the normal temperature and humidity (5 to 35°C, 45 to 75%).
 常温常湿(5~35 、45~75%)で保存して下さい。
 - Avoid a sudden change in ambient temperature to prevent condensation on the module surfaces. モジュールの表面が結露しないよう、急激な温度変化を避けて下さい。
 - Avoid places where corrosive gas generates or much dust exists.
 腐食性ガスの発生場所、粉塵の多い場所は避けて下さい。
 - Store the module terminals under unprocessed conditions モジュールの端子は未加工の状態で保管すること。.
 - Avoid physical shock or falls during the transportation.
 運搬時に衝撃を与えたり落下させないで下さい。
- 15. Scope of application 適用範囲

This specification is applied to the IGBT-IPM (type: 6MBP75RTB060). 本仕様書は、IGBT-IPM (型式: 6MBP75RTB060)に適用する。

1 6 . Based safety standards **準拠安全規格** UL1557

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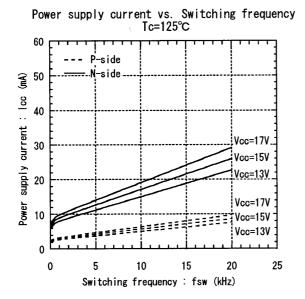
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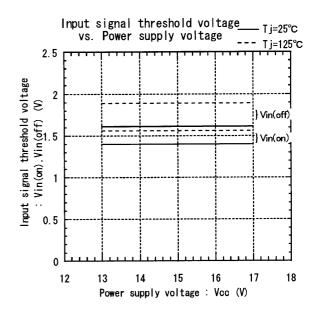
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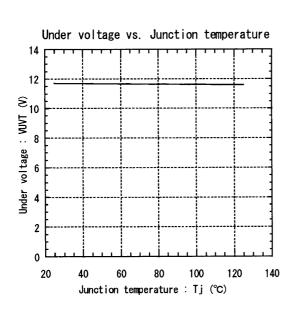
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1 7 . Characteristics

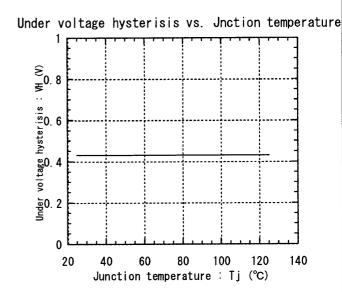
17-1. Control Circuit Characteristics (Respresentative)

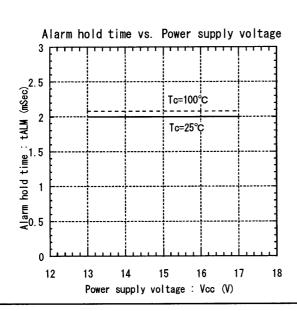


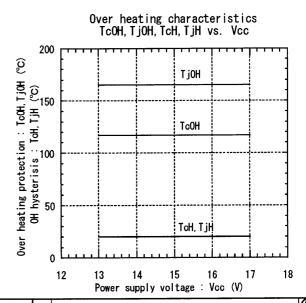




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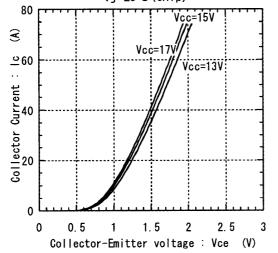


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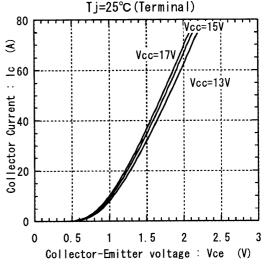
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17-2. Main Circuit Characteristics (Representative)

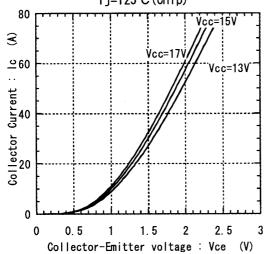
Collector current vs. Collector-Emitter voltage Tj=25°C (Chip)



Collector current vs. Collector-Emitter voltage



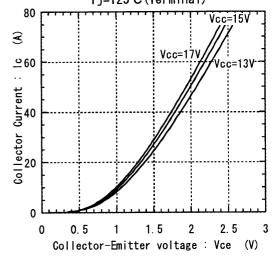
Collector current vs. Collector-Emitter voltage Tj=125°C (Chip)



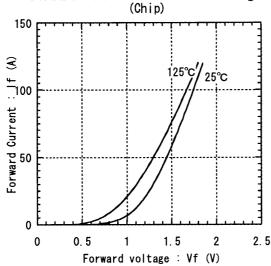
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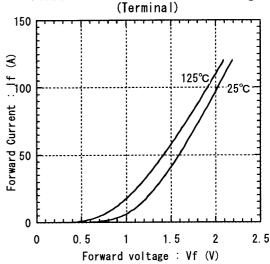
Collector current vs. Collector-Emitter voltage Tj=125°C (Terminal)



Forward current vs. Forward voltage (Chip)



Forward current vs. Forward voltage



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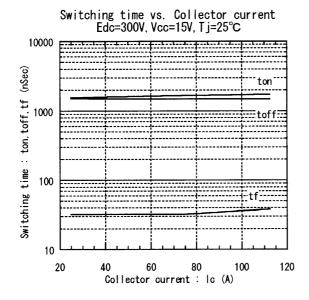
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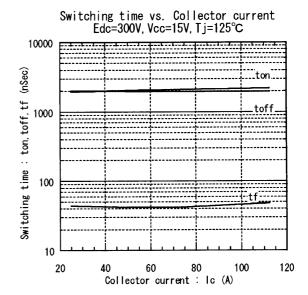
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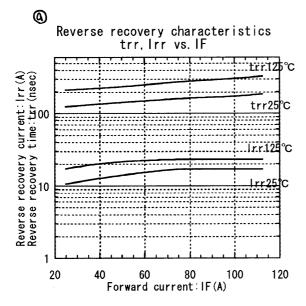
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18. Reliability Test Items

Test cate- gories	e- Test items ies		Test r	methods and conditions	Reference norms EIAJ ED-4701	Number of sample	Accept- ance number
	1	Terminal strength 端子強度 (Pull test)	Pull force Test time	: 40 N (main terminal) 10 N (control terminal) : 10 ±1 sec.	Test Method 401 Method	5	(1:0)
	2	Mounting Strength 締付け強度		: 2.5 ~ 3.5 N·m (M5) : 10 ±1 sec.	Test Method 402 method	5	(1:0)
ests	3	Vibration 振動	Sweeping time Acceleration Sweeping direction	: 10 ~ 500 Hz : 15 min. : 100 m/s ² : Each X,Y,Z axis : 6 hr. (2hr./direction)	Test Method 403 Condition code B	5	(1:0)
Mechanical Tests	4	Shock 衝擊	Maximum acceleration Pulse width Direction		Test Method 404 Condition code B	5	(1:0)
N	5	Solderabitlity はんだ付け性	Test time	: 235 ±5 : 5.0 ±0.5 sec. : 1 time be Immersed in solder ne body.	Test Method 303 Condition code A	5	(1:0)
	6	Resistance to soldering heat はんだ耐熱性	Solder temp. Immersion time Test time	: 260 ±5 : 10 ±1sec. : 1 time be Immersed in solder	Test Method 302 Condition code A	5	(1:0)
	1	High temperature storage 高温保存	Storage temp.	: 125 ±5 : 1000 hr.	Test Method 201	5	(1:0)
	2	Low temperature storage 低温保存	Storage temp.	: -40 ±5 : 1000 hr.	Test Method 202	5	(1:0)
	3	Temperature humidity storage 高温高湿保存	Storage temp. Relative humidity	: 85 ±2 : 85 ±5% : 1000hr.	Test Method 103 Test code C	5	(1:0)
Tests	4	Unsaturated pressure cooker プレッシャークッカー	Test temp. Atmospheric pressure Test humidity	: 120 ±2	Test Method 103 Test code E	5	(1:0)
Environment Tests		Temperature cycle 温度サイクル	Test temp. Dwell time Number of cycles	: Minimum storage temp40 ±5 Maximum storage temp. 125 ±5 Normal temp. 5 ~ 35 : Tmin ~ Tn ~ Tmax ~ Tn 1hr. 0.5hr. 1hr. 0.5hr. : 100 cycles	Test Method 105	5	(1:0)
	6	Thermal shock 熱衝擊	Test temp. Fluid used Dipping time	: High temp. side 100 -5 Low temp. side 0 -0 : Pure water (running water) : 5 min. par each temp.	Test Method 307 method Condition code A	5	(1:0)
			Transfer time Number of cycles	: 10 sec. : 10 cycles			

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Test cate- gories	Test items	Tesi	Reference norms EIAJ ED-4701	Number of sample	Accept- ance number	
sts	1 High temperature reverse bias 高温逆パイアス	Test temp. Bias Voltage Bias Method Test duration	: Ta = 125 ±5 (Tj 150) : VC = 0.8×VCES : Applied DC voltage to C-E Vcc = 15V : 1000 hr.	Test Method 101	5	(1:0)
Endurance Tes	2 Temperature humidity bias 高温高湿パイアス	Test temp. Relative humidity Bias Voltage Bias Method Test duration	: 85 ±2 : 85 ±5 % : VC = 0.8×VCES Vcc = 15V : Applied DC voltage to C-E : 1000 hr.	Test Method 102 Condition code C	5	(1:0)
	3 Intermitted operating life (Power cycle) 断続動作	ON time OFF time Test temp. Number of cycles	: 2 sec. : 18 sec. : Δ Tj=100 ±5deg Tj 150 , Ta=25 ±5 : 15000 cycles	Test Method 106	5	(1:0)

19. Failure Criteria

Item	Charac	teristic	Symbol	Failure criteria		Unit	Note
				Lower limit	Upper limit		
Electrical	Leakage current		ICES	-	USL×2	mΑ	
characteristic	Saturation voltage		VCE(sat)	-	USL×1.2	V	
	Forward volta	ige	VF	-	USL×1.2	V	
	Thermal	IGBT	Rth(j-c)	-	USL×1.2	/W	
	resistance	FWD	Rth(j-c)	-	USL×1.2	/W	
	Over Current Protection Alarm signal hold time Over heating Protection Isolation voltage		loc	LSL×0.8	USL×1.2	Α	
			tALM	LSL×0.8	USL×1.2	ms	
			TcOH	LSL×0.8	USL×1.2		
			Viso	Broken i	nsulation	-	
Visual	Visual inspection						
inspection	Peeling		-	The visual sample		-	
	Plating						
and the others							

LSL: Lower specified limit. USL: Upper specified limit.

Note: Each parameter measurement read-outs shall be made after stabilizing the components at room ambient for 2 hours minimum, 24 hours maximum after removal from the tests. And in case of the wetting tests, for example, moisture resistance tests, each component shall be made wipe or dry completely before the measurement.

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Warnings

- This product shall be used within its absolute maximum rating (voltage, current, and temperature). This product may be broken in case of using beyond the ratings.
 製品の絶対最大定格(電圧,電流,温度等)の範囲内で御使用下さい。絶対最大定格を超えて使用すると素子が破壊する場合があります。
- 2. Connect adequate fuse or protector of circuit between three-phase line and this product to prevent the equipment from causing secondary destruction.
 万一の不慮の事故で素子が破壊した場合を考慮し、商用電源と本製品の間に適切な容量のヒューズ 又はブレーカーを必ず付けて 2 次破壊を防いでください。
- 3. When studying the device at a normal turn-off action, make sure that working paths of the turn-off voltage and current are within the RBSOA specification. And ,when studying the device duty at a short-circuit current non-repetitive interruption, make sure that the paths are also within the avalanche proof(PAV) specification which is calculated from the snubber inductance, the IPM inner inductance and the turn-off current. In case of use of IGBT-IPM over these specifications, it might be possible to be broken.

通常のターンオフ動作における素子責務の検討の際には、ターンオフ電圧・電流の動作軌跡が RBSOA 仕様内にあることを確認して下さい。また、非繰返しの短絡電流遮断における素子責務の検討に際しては、スナバーインダクタンスとIPM内部インダクタンス及びターンオフ電流から算出されるアバランシェ耐量(PAV)仕様内である事を確認して下さい。これらの仕様を越えて使用すると、素子が破壊する場合があります。

4. Use this product after realizing enough working on environment and considering of product's reliability life. This product may be broken before target life of the system in case of using beyond the product's reliability life.

製品の使用環境を十分に把握し、製品の信頼性寿命が満足できるか検討の上、本製品を適用して下さい。製品の信頼性寿命を超えて使用した場合、装置の目標寿命より前に素子が破壊する場合があります。

a) 5. If the product had been used in the environment with acid, organic matter, and corrosive gas (For example: hydrogen sulfide, sulfurous acid gas), the product's performance and appearance can not be ensured easily.

酸・有機物・腐食性ガス(硫化水素, 亜硫酸ガス等)を含む環境下で使用された場合、製品機能・外観などの保証は致しかねます。

- 6. Use the product within the power cycle curve (Technical Rep.No.: MT6M4057) 本製品は、パワーサイクル寿命カーブ以下で使用下さい(技術資料 No.: MT6M4057)
- 7. Never add mechanical stress to deform the main or control terminal.

The deformed terminal may cause poor contact problem.

主端子及び制御端子に応力を与えて変形させないで下さい。 端子の変形により、接触不良などを引き起こす場合があります。

- 8. According to the outline drawing, select proper length of screw for main terminal. Longer screws may break the case.
 - 本製品に使用する主端子用のネジの長さは、外形図に従い正しく選定下さい。ネジが長いとケースが破 損する場合があります。
- 9. If excessive static electricity is applied to the control terminals, the devices can be broken. Implement some countermeasures against static electricity. 制御端子に過大な静電気が印加された場合、素子が破壊する場合があります。取り扱い時は静電気対 策を実施して下さい。

Caution

Fuji Electric is constantly making every endeavor to improve the product quality and 1. reliability. However, semiconductor products may rarely happen to fail or malfunction. To prevent accidents causing injuly or death, damage to property like by fire, and other social damage resulted from a failure or malfunction of the Fuji Electric semiconductor products, take some measures to keep safety such as redundant design, spread-fire-preventive design, and malfunction-protective design...

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- 2. The application examples described in this specification only explain typical ones that used the Fuji Electric products. This specification never ensure to enforce the industrial property and other rights, nor license the enforcement rights.
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- 3. The product described in this specification is not designed nor made for being applied to the equipment or systems used under life-threatening situations. When you consider applying the product of this specification to particular used, such as vehicle-mounted units, shipboard equipment, aerospace equipment, medical devices, atomic control systems and submarine relaying equipment or systems, please apply after confirmation of this product to be satisfied about system construction and required reliability.

本仕様書に記載された製品は 人命にかかわるような状況下で使用される機器あるいはシステムに用いられ ることを目的として設計・製造されたものではありません。本仕様書の製品を車両機器、船舶、航空宇宙、医 療機器 原子力制御 海底中継機器あるいはシステムなど 特殊用途へのご利用をご検討の際は システム 構成及び要求品質に満足することをご確認の上、ご利用下さい。

If there is any unclear matter in this specification, please contact Fuji Electric Co., Ltd.