ID240E01 4MB Flash Memory Card

(Model No.: ID240E01)

Spec No.: EL105110

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ID240E01

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ID240E01 2

1. General Descriptions

SHARP

The SHARP ID240E01 is a 4MB Flash Memory PC Card conforms to PCMCIA Release 2.0 and is offered to customers giving aim to confirm an external shape or electrical performances of the card. Before mass production, we will create a new product name dedicated for a customer and also present a specification which implies customer's request including panel design.

2. Features

4MB Flash Memory Card 2.1 Type -

(Conforms to PCMCIA Rel.2.0)

2.2 Memory Capacity

Common Memory 4M words × 8 bits or 2M words × 16 bits

EEPROM Model 2k words × 8 bits read/write Attribute Memory

Note) We have another type of attribute memory as follows,

No EEPROM Model. (5 words × 8 bits read only in card's control circuit.)

Sample card name: ID240E02. Customers can choose one model from two.

Supply Voltage 2.3

> Read Cycle $V_{CC} = 5 \pm 0.5 \text{V}, V_{PP1}, V_{PP2} = 0 \sim 1.5 \text{V}$

Read/Program/Erase Cycle $V_{CC} = 5 \pm 0.5 \text{V}, V_{PP1}, V_{PP2} = 12.0 \text{V} \pm 0.6 \text{V}$

Erase Unit Block

(64k bytes/byte access, 128k bytes/word access)

2.5 Program/Erase Cycles 100,000 cycles

2.6 Interface Parallel I/O Interface

2.7 **Function Table** See Function Table in page. 6

2.8 **External Dimensions** $54 \times 85.6 \times 3.3$ mm

2.9 Pin Connections See Pin Connections in page. 4

2.10 Type of Connector Conforms to PCMCIA Re1.2.0 Card Use Connector

(Card connector: JC20-J68S-NB3 JAE or FCN-568J068-G/0 Fujitsu

or ICM-C68S-TS13-5035A JST)

2.11 Average Weight 30g

0 to 60℃ 2.12 Operating Temp Range

2.13 Storage Temp Range -20 to 65℃

2.14 External Appearance External appearance shall be free of any dirt, cratches and abnor-

malities that could adversely affect sales.

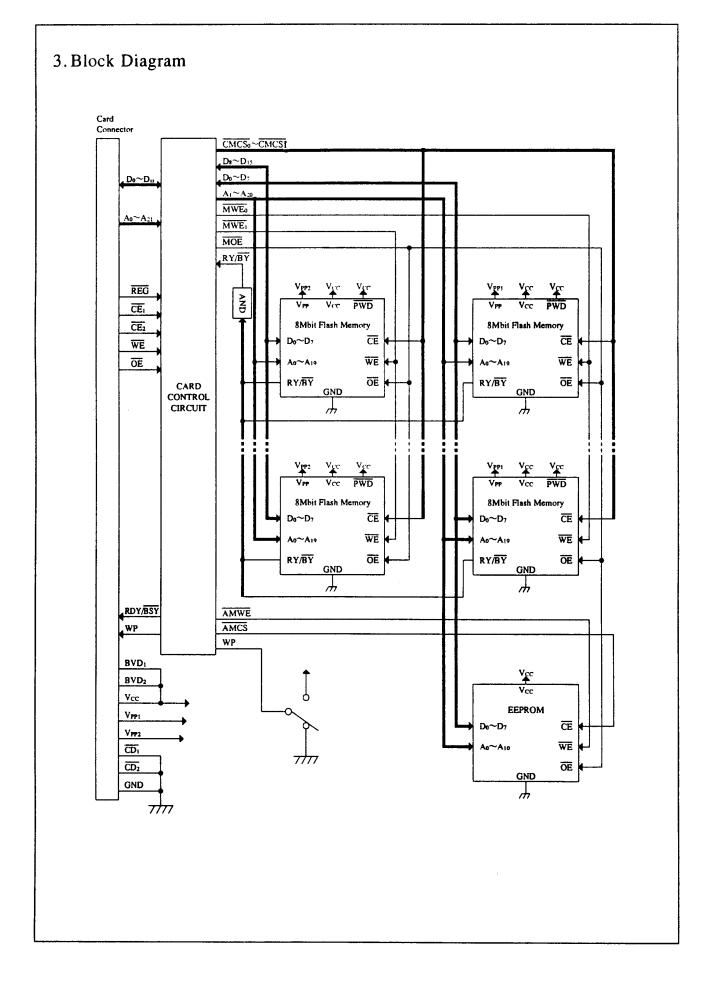
2.15 Manufacturer's Code The manufacturer's code shall be printed on the memory card di-

rectly or on the seal which is then attached to the memory card.

2.16 Brand Name The user's brand name will be used.

2.17 Not designed or rated radiation hardened.







4. Pin Connections

PIN	SIGNAL	PIN	SIGNAL	PIN	SIGNAL	PIN	SIGNAL
1	GND	18	V_{pp_1}	35	GND	52	V_{PP2}
2	D_3	19	A ₁₆	36	$\overline{\text{CD}}_{1}$	53	A ₂₂ (NC)
3	D_4	20	A ₁₅	37	D_{11}	54	A ₂₃ (NC)
4	D_5	21	A ₁₂	38	D ₁₂	55	A ₂₄ (NC)
5	D_6	22	A ₇	39	D ₁₃	56	A ₂₅ (NC)
6	D_7	23	A_6	40	D_{14}	57	NC
7	CE i	24	A ₅	41	D_{15}	58	NC
8	A ₁₀	25	A ₄	42	$\overline{\text{CE}}_2$	59	NC
9	. ŌĒ	26	A ₃	43	NC	60	NC
10	A ₁₁	27	A ₂	44	NC	61	REG
11	A ₉	28	A ₁	45	. NC	62	BVD_2
12	A ₈	29	A ₀	46	A ₁₇	63	BVD_1
13	A ₁₃	30	D_0	47	A ₁₈	64	D_8
14	A ₁₄	31	D _i	48	A ₁₉	65	D ₉
15	WE/PGM	32	D_2	49	A ₂₀	66	D_{i0}
16	RDY/BSY	33	WP	50	A ₂₁	67	$\overline{\mathrm{CD_2}}$
17	$V_{\rm cc}$	34	GND	51	V_{cc}	68	GND

Pin Descriptions:

D₀~D₇ Data Bus (Input/output)

D₈~D₁₅ Data Bus (Input/output)

A₀~A₂₂ Address Bus (Input)

 \overline{CE}_1 , \overline{CE}_2 Card Enable (Input)

02[, 02]

OE Output Enable (Input)

WE/PGM Write Enable/Program (Input)

 $\overline{\text{CD}}_1$, $\overline{\text{CD}}_2$ Card Detect (Output) (Card Inserted Detection Signal)

WP Write Protect (Output) (in write protect mode, the WP output signal is "HIGH")

V_{PPI} Program/Erase Power Supply (Even Byte)

V_{PP2} Program/Erase Power Supply (Odd Byte)

REG Register Select (Input)

BVD₁, BVD₂ Battery Voltage Detect (Always "HIGH")

RDY/BSY Ready/Busy (Output)



5. Function

5.1 Memory Block

5.1.1 Memory Configuration

8Mbits Flash Memory × 4 Devices.

5.1.2 Memory Erase Unit

Block Erase

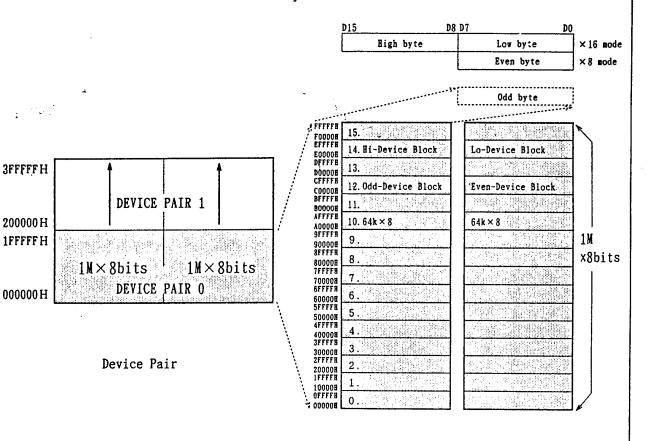
Block:

Byte Mode

64k bytes

Word Mode

128k bytes



Block Pair

;

5.2 Function Table

\overline{CE}_{i}	$\overline{\text{CE}}_2$	A _o	WE	ŌĒ	REG	V_{PP1}	V_{PP2}	V_{cc}	Operation	D_0 - D_7	D ₈ -D ₁₅	Status
Н	Н	×	×	×	Н	V_{PPL}	V_{PPL}	V_{cc}		Hi-Z	Hi-Z	Standby
L	Н	L	H	L	Н	V_{PPL}	V_{PPL}	V_{cc}	Read (×8)	Do (Even)	Hi-Z	Byte
L	Н	Н	Н	L.	Н	V_{PPL}	V_{PPL}	V_{cc}	Read (×8)	Do (Odd)	Hi-Z	Byte
L	L	×	Н	L	Н	V_{PPL}	V_{PPL}	V_{cc}	Read (×16)	Do (Even)	Do (Odd)	Word
Н	L	×	Н	L	Н	V_{PPL}	V_{PPL}	V_{cc}	Read (×8)	Hi-Z	Do (Odd)	Byte
L	×	×	×	Н	Н	V_{PPL}	V_{PPL}	V_{cc}	Outpu Disable	Hi-Z	Hi-Z	Byte
Н	L	×	×	Н	H	V_{PPL}	V_{PPL}	V_{cc}	Outpu Disable	Hi-Z	Hi-Z	Byte
L	H	L	L	Н	Н	V_{PPH}	V_{PPX}	V_{cc}	Program (×8)	Di (Even)	Don't care	Byte
L	Н	ιH	L	H	Н	V_{PPX}	V_{PPH}	V_{cc}	Program (×8)	Di (Odd)	Don't care	Byte
L	L	×	L	Н	Н	V _{PPH}	V_{PPH}	V_{cc}	Program (×16)	Di (Even)	Di (Odd)	Word
. Н	L	×	L	Н	H	V_{PPX}	V_{PPH}	V_{cc}	Program (×8)	Don't care	Di (Odd)	Byte
L	Н	L	Н	L	Н	V_{PPH}	V_{PPX}	V_{cc}	Verify (×8)	Do (Even)	Hi-Z	Byte
L	Н	H	H	L	Н	V_{PPX}	V_{PPH}	V_{cc}	Verify (×8)	Do (Odd)	Hi-Z	Byte
L	L	×	Н	L	Н	V_{PPH}	V_{PPH}	V_{cc}	Verify (×16)	Do (Even)	Do (Odd)	Word
Н	L	×	H	L	Н	V_{PPX}	V_{PPH}	V_{cc}	Verify (×8)	Hi-Z	Do (Odd)	Byte
L	Н	Н	L	L	Н	V_{PPH}	V_{PPX}	V_{cc}	*1 Prohibited		_	
L	H	L	L	L	Н	V_{PPX}	V_{PPH}	V_{cc}	*1 Prohibited	_		-
L	L	×	L	L	Н	V_{PPH}	V_{PPH}	V_{cc}	*1 Prohibited			_
Н	L	×	L	L	Н	V_{PPX}	V_{PPH}	V_{cc}	*1 Prohibited			

*1. Do not use this mode as it will result in write errors.

Н : High L : Low × : Don't Care

: Input Data Di

Do : Output Data Hi-Z : High Impedance

: 4.5 ∼ 5.5V V_{cc}

 V_{PPL} : $0.0 \sim 1.5 V$

 V_{PPH} : 11.4 \sim 12.6 V

 $V_{PPX} : V_{PPL} \text{ or } V_{PPH}$

Caution: When the write Protect switch is in protect-mode, the WP signal is "HIGH" and write operation are not allowed.

5.3 Software Command (8/16 Bits Operation ():16 Bits Operation)

Command	Bus Cycles	F	irst Bus Cyc	le		Second I	Bus Cycle	
Command	Dus Cycles	Operation	Address	Data	Operation	Address	Data Input	Data Output
Read Array/Reset	1	Write	RA	FFH/ (FFFFH)		_		
Read Intelligent Identifier	3	Write	DA	90H/ (9090H)	Read	IA	_	IID
Read Status Register	2	Write	DA	70H/ (7070H)	Read	DA		SRD
Clear Status Register	1	Write	DA	50H/ (5050H)			`	
Erase Setup/Erase Confirm	2	Write	BA	20H/ (2020H)	Write	ВА	D0H/ (D0D0H)	
Erase Suspend/Erase Resume	2	Write	ВА	B0H/ (B0B0H)	Write	BA	D0H/ (D0D0H)	_
Byte Write Setup/Write	2	Write	WA	40H/ (4040H)	Write	WA	WD	
Alternate Byte Write Setup/Write	2	Write	WA	10H/ (1010H)	Write	WA	WD	

Note) 1. This Table shows the basic from of Erase, Verify and Program Verify.

Refer Programming Flowchart, Erase Algorithm in detail.

2. Bus operations are defined in function table in page.

3. IA: Device Identifier Address IID

IID: Device Identifier Data

			IA				
	DA	8Bits (Even Device)	8Bits (Odd Device)	16Bits	Byte (8Bits)	Word (16Bits)	
Manufacturer Code	000000H∼1FFFFFH	000000Н	000001H	000000Н	89H	8989H	
Device Code	000000H∼1FFFFFH	000002H	000003Н	000001H	A2H	A2A2H	

RA : Read Address

WA: Write Address

WD: Write Data

DA : Device Address (Any Address in device is acceptable.)

BA : Erase Block Address (Erase Size is 64k Bytes.)

SRD: Status Register Data

4. Either 40H (4040H) or 10H (1010H) are recognized by the WSM as the Byte Write Setup Command.



a) Read Array/Reset Command: (FFH/FFFFH)

By writing this command, device. Devices pair become read mode. The device remains enable for reads until the Command User Interface contents are altered.

b) Intelligent Identifier Command: (90H/9090H):

After writing this command into the Command User Interface, a read cycle retrieves the manufacturer Code and device Code. To terminate the Operation, it is necessary to write another valid command into the register.

c) Read Status Register Command: (70H/7070H):

By Writing this command, the Status Register may be read at any time to determine when a byte or block erase operation is complete, and whether that operation completed successfully.

Refer to Status Register definition in page. 9. After writing this command, all subsequent read operations output data from the Status Register, until another valid command is written to the Command User Interface.

d) Clear Status Register Command: (50H/5050H)

Status bits which show error, the Erase Status (SR. 5), Byte Write Status (SR. 4) bits and the V_{PP} Status bit (SR. 3) can be reset by the Clear Status Machine Register Command.

e) Erase Setup/Erase Command: (20H/2020H) (D0H/D0D0H): Erase is executed one block (64kB for 1 device, 128kB for 2 devices) at a time.

This command is functional when $V_{PP} = V_{PPH}$ and an Erase Setup Command is first written to the Command User Interface, followed by the Erase Confirm Command. After that, the device automatically outputs Status Register data when read.

The CPU can detect the completion of the erase event by analyzing the output of the RDY/BSY pin, or the WSM Status bit of the Status Register. When erase is completed, the Erase Status bit should be checked. If erase error is detected, the Status Register should be cleared.

f) Erase Supend/Erase Resume Command: (B0H/B0B0H) / (D0H/D0D0H)

The Erase Suspend command allows block erase interruption in order to read data from another block of memory. The device continues to output Status Register data when read, after the Erase Suspend Command is written. Polling the WSM Status and Erase Suspend Status bits will determine when the erase operation has been suspended. RDY/\overline{BSY} pin will also transition to V_{OH} . At this point, a Read Array Command can be written to the Command User Interface to read data from blocks other than that which is suspended. V_{PP} must remain at V_{PPH} while device is in Erase Suspend.

Erase Resume Command, at which time the WSM will continue with the erase process. The Erase Suspend Status and WSM Status bits of the Status Register will be automatically cleared and RDY/ \overline{BSY} pin will return to V_{OL} . After the Erase Resume is written, the device automatically output Status Register data when read.

g) Byte Write Setup/Write Command: (40H/4040H) or (10H/1010H)

This command is functional when $V_{PP} = V_{PPH}$ and an Byte Write Setup Command is first written to the Command User Interface, followed by a second write specifying the address and data to be written. The WSM then take over, controlling the byte write and write verify algorithms internally. After the two command byte sequence is written to it, the device automatically outputs Status Register data when read. The CPU can detect the completion of the byte write event by analyzing the output of the RDY/ \overline{BSY} pin, or the WSM Status bits of the Status Register.

5.4 Status Register

The memory devices in this card have Status Register which shows state of the device.

Byte Access × 8 Bits

bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
SR.7	SR.6	SR.5	SR.4	SR.3	SR.2	SR.1	SR.0
WSMS	ESS	ES	BWS	VPPS	RFU	RFU	RFU

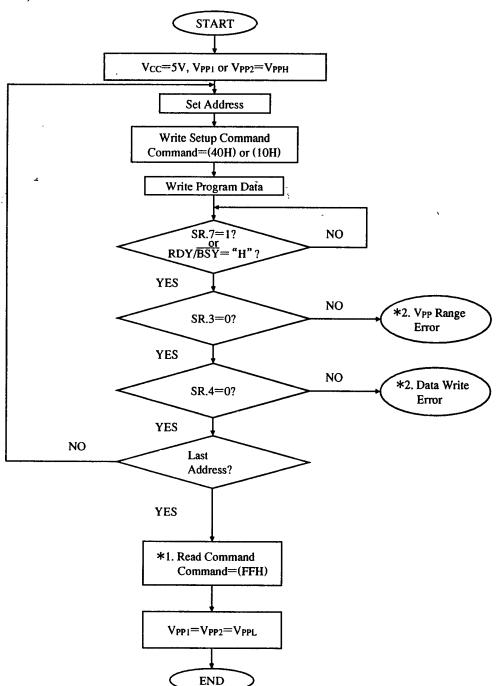
Register	Contents
SR.7=Write State Machine Status	
1 = Ready	When set "1" s, read, erase, data write is acceptable.
0=Busy	
· SR.6=Erase Suspend Status	
1=Erase Suspend	Check whether Erase Suspend Command is executed or not.
0=Erase In Progress/Completed	of not.
SR.5=Erase Status	G . "1" 1 C !! . T
1 = Error In Block Erase	Set "1" s when fail to Erase. Reset by the Clear Status Register Command.
0=Successful Block Erase	Reset by the clear diatus Register Command.
SR.4=Byte Write Status	Cas "1" - when fall as Posts With
1 = Error In Byte Write	Set "1" s when fail to Byte Write. Reset by the Clear Status Register Command.
0=Successful Byte Write	Reset by the clear status register command.
$SR.3 = V_{PP}$ Status	Set "1" s when V _{PP} , which is needed in Byte Write or
1=V _{PP} Low Detect; Operation Abort	Erase operation, is below V _{PPH} . Reset by the Clear
$0 = V_{PP} OK$	Status Register Command.
SR.2~SR.0=Reserved for Future Use	

Word Access × 16 bits

bit15	bit8	bit7							bit0
SR.15 SR.14 SR.13 SR.12 SR.11 SR.10	SR.9 SR.8	SR.7	SR.6	SR.5	SR.4	SR.3	SR.2	SR.1	SR.0
Odd Byte device				E	ven By	te devic	·e		•

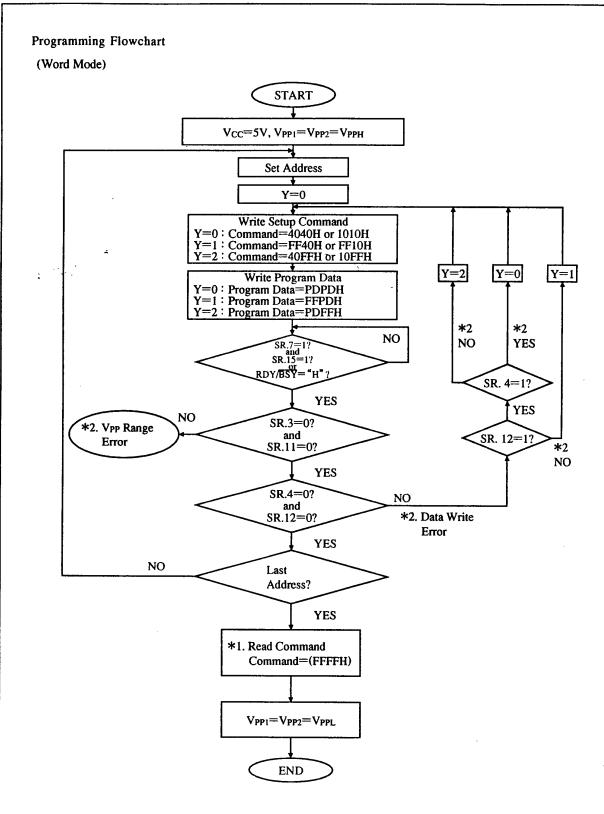
5.5 Programming Flowchart

(Byte Mode)



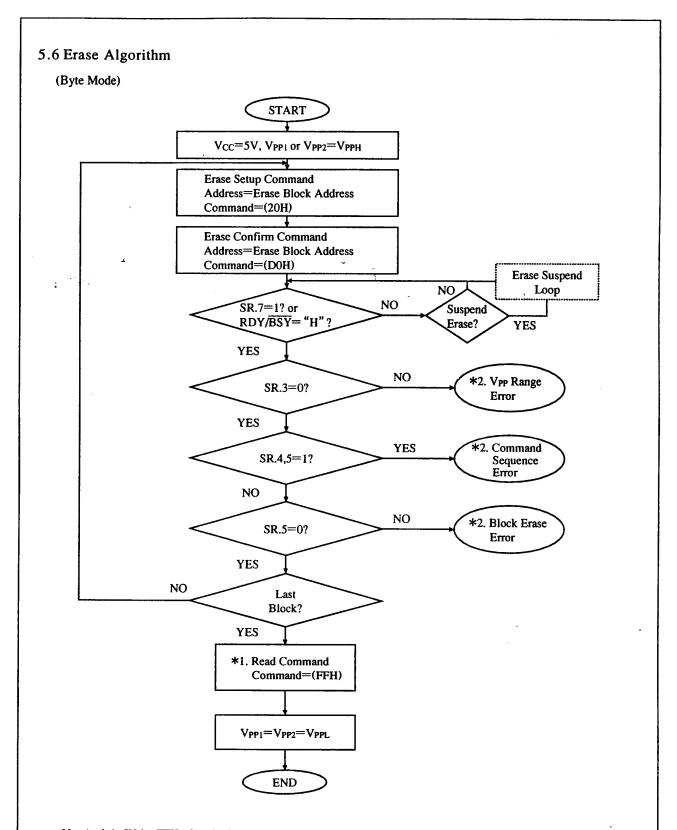
Note) * 1. Write FFH after the last block write operation to reset the device to Read Array Mode.





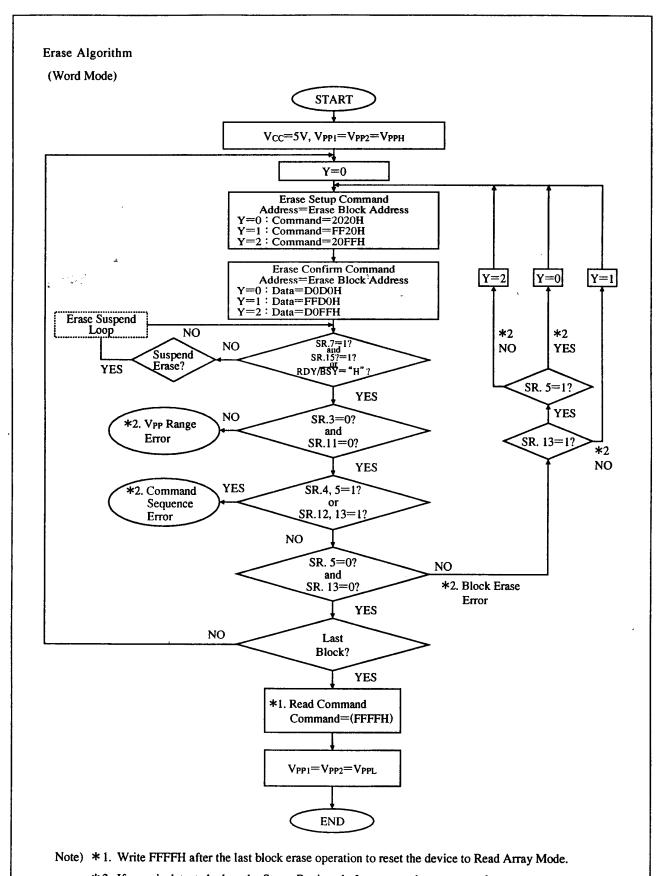
Note) * 1. Write FFFFH after the last block write operation to reset the device to Read Array Mode.





Note) * 1. Write FFH after the last block erase operation to reset the device to Read Array Mode.







6. Absolute Maximum Ratings

PARAMETER	SYMBOL	RATING	UNIT
Supply Voltage	V_{cc}	-0.3 to 7.0	V
Input Voltage	V _{IN}	-0.3 to $V_{cc}+0.3$ (Max: 7.0)	V
Output Voltage	V _{out}	-0.3 to $V_{cc} + 0.3$ (Max : 7.0)	V
Operating Temperature	T _{OPR}	0 to +60	$^{\circ}$
Storage Temperature	T _{STG}	-20 to+65	°C

7. Recommended Operating Conditions

PARAMETER	SYMBOL	Min.	Max.	UNIT
Operating Temperature	T _{OPR}	0	+60	$^{\circ}$
Supply Voltage	V _{cc}	, 4.5	5.5	V
Input Voltage High	V _{IH}	3.5	V _{cc} +0.3	V
Input Voltage Low	V _{IL}	-0.3	1.5	V

8. Capacitance

PARAMETER	SYMBOL	Min.	TYP	Max.	UNIT	CONDITION
Input Capacitance	C _{IN}	_	17	_	pF	$V_{cc} = 5V \pm 10\%$
Input/Output Capacitance	C _{io}	_	17		pF	f=1MHz, Ta=25℃

9. Read Operation

9.1 DC Characteristics

 $(V_{CC}=4.5\sim5.5V, Ta=0\sim60°C)$

PAR	AMETER	SYMBOL	Min.	TYP	Max.	UNIT	CONDITION	
Operating	High Temperature	V _{cc}	4.5		5.5	v		
Voltage	Low Temperature	V CC	4.5		5.5	v		
Current	Static Operatin Current	I _{sb}	-		2.0	A	X16, Address:	
Consumption * 1	Dynamic Operating Current	I_{cc}		_	80	mA	PingPong	
Input Voltage	Input Voltage Level High	V _{IH}	3.5		$V_{cc} + 0.3$	v	V _{cc} =4.5~5.5V	
input voltage.	Input Voltage Level Low	V_{IL}	-0.3	_	1.5	V		
Input Current	$A_0 \sim A_{20}, D_0 \sim D_{15}$	T	-10		70	A		
Input Current	\overline{CE}_1 , \overline{CE}_2 , \overline{OE} , \overline{WE} , \overline{REG}	$I_{l,1}$	-70	-	10	μΑ	$V_i = V_{cc}, 0V$	
Output Voltage	High	V _{oн}	V _{cc} ~0.5	. —	_	v	$I_{OH} = -2mA (*^2)$ $I_{OH} = -4 \mu A (*^3)$	
	Low	V _{oL}			0.4	`	I _{OL} =4mA	

PingPong: Scan the target address, with accessing the target and another address alternately.

- *1 (1) Static Operating Current: With the memory card's voltage at 5.5V and the \overline{CE}_1 , \overline{CE}_2 \overline{OE} , \overline{WE} and \overline{REG} signals "HIGH" ($V_{IH} = V_{CC} = 0.2V$), A_0 signal "LOW" ($V_{IL} \le 0.2V$) the current consumption is measured with the output open.
 - (2) Dynamic Operating Current: With the memory card's V_{CC} at 5.5V and V_{PP1} = V_{PP2} at 12.6V, current consumption during access is measured with the output open.
 (Access time: 200ns) The current depends on addressing.
- *2 D₀~D₁₅
- *3 BVD₁, BVD₂, RDY/BSY, WP

9.2 AC Characteristics ($V_{CC}=4.5\sim5.5V$, $V_{PP}=0.0\sim1.5V$, $Ta=0\sim60^{\circ}C$)

Testing Conditions:

Input Pulse Level : 0.8~3.5V
 Input Rise/Fall Time : 10ns
 Input/Output Timing Reference Level : 1.5V

4) Output Load : 1TTL+C_L (100pF) (including scope and jig capacitance)

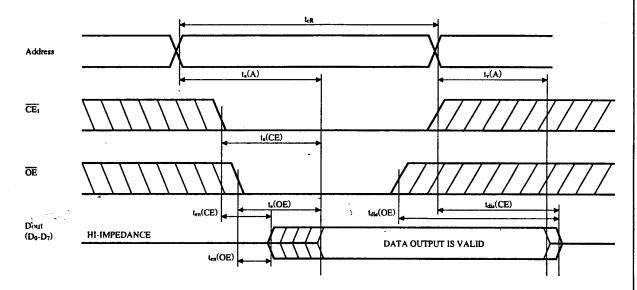
9.2.1 Read Cycle

 $(V_{CC}=4.5\sim5.5V, V_{PP}=0.0\sim1.5V, Ta=0\sim60^{\circ}C)$

PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Read Cycle Time	t _{AVAV}	t _{eR}	200	_	
Address Access Time	t _{AVQV}	t _a (A)		200	1
Card Enable Access Time	t _{ELQV}	t _a (CE)		200	1
Output Enable Access Time	t_{GLQV}	t _a (OE)		100	1
Output Disable Time from CE∗	t _{EHQV}	t _{dis} (CE)	_	90	ns
Output Disable Time from OE*	t _{GHQZ}	t _{dis} (OE)	_	90	1
Output Enable Time from CE	t _{ELQX}	t _{en} (CE)	5	_	1
Output Enable Time form OE	t_{GLQX}	t _{en} (OE)	5		1
Data Valid from Add Change		t _v (A)	0		1

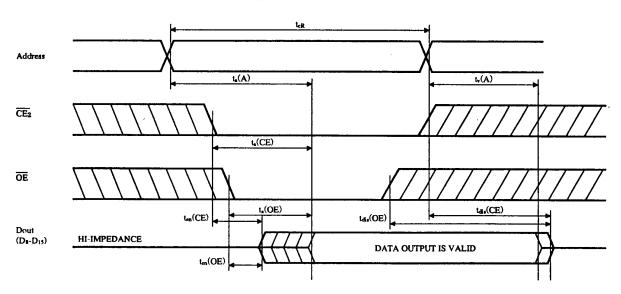
^{*} Time until output becomes floating. (The output voltage is not defined.)

ORead CYCLE (1) ($\overline{CE}_2 = V_{IH}$ Fixed), 8bits Output



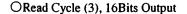
- Note) 1. WE="HIGH", during a read cycle.
 - 2. Either "HIGH" or "LOW" in diagonal areas.
 - 3. The output data becomes valid when last interval, t_a (A), t_a (CE) or t_a (CE) have concluded.

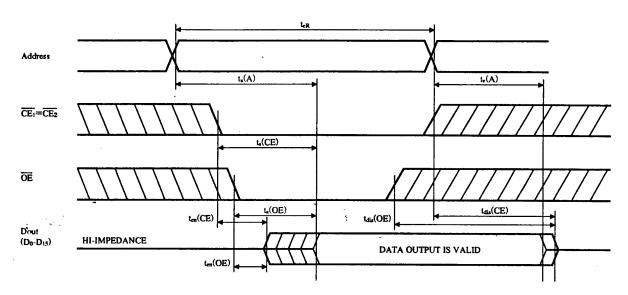
ORead Cycle (2) ($\overline{CE}_1 = V_{IH}$ Fixed), 8Bits Output



- Note) 1. WE="HIGH", during a read cycle.
 - 2. Either "HIGH" or "LOW" in diagonal areas.
 - 3. The output data becomes valid when last interval, t_a (A), t_a (CE) or t_a (CE) have concluded.







- Note) 1. WE="HIGH", during a read cycle.
 - 2. Either "HIGH" or "LOW" in diagonal areas.
 - 3. Change $\overline{CE_1}$ and $\overline{CE_2}$ at the same time.
 - 4. The output data becomes valid when last interval, t, (A), t, (CE) or t, (CE) have concluded.

10. Programming Operation

10.1 DC Characteristics

1	$V_{\alpha\alpha}=4$	5~55	VV.	=11	4~12	6V	$T_9 = 0$	~60°C)
1	V CC 7		V . V t	D II.	7 12.	υν.	1 a – \	, -000

PARAMET	ER	SYMBOL	Min.	Max.	UNIT	CONDITION
37 37	Read	V_{PPL}	0	1.5		
V _{PP1} , V _{PP2} operating Voltage	Program	V_{pph}	11.4	12.6	v	
V _{PP1} , V _{PP2} operating	Read	l _{SB2}		1.6		Input open
Current (×16 Mode)	Program	I_{pp}	—	20	mA	RMS
V _{cc} operating	Standby	I _{sbi}	_	2]	Input open
Current	Program	I_{cc}		75		RMS
Input Voltage		V_{iL}	-0.3	1.5		
input voitage		V_{IH}	3.5	$V_{\infty}+0.3$	v	
Output Voltage During Verify		V _{oL}	_	0.4]	I _{oL} =4mA
		V_{OH}	V_{cc} -0.5			$I_{OH} = -2mA$

- Note) 1. Power on V_{cc} before power on V_{cc} , power off V_{cc} after power off V_{pp} .
 - 2. Keep V_{PP} including its overshoot, below 13V.
 - 3. Card insertion or removal while applying $V_{PP}=12V$ may cause a loss of integrity.
 - 4. Do not turn on or turn off during \overline{CE} ="LOW".
 - 5. If V_{IH} goes above $V_{CC}+0.3V$, normal operation is not assured.

10.2 AC Characteristics ($V_{CC}=4.5\sim5.5V$, $V_{PP}=11.4\sim12.6V$, $T_a=0\sim60^{\circ}C$)

Testing Conditions:

1) Input Pulse Level

: 0.8~3.5V

2) Input Rise/Fall Time

: 10ns

3) Input/Output Timing Reference Level

: 1.5V

4) Output Load

: 1TTL+C_L (100pF) (including scope and jig capacitance)

10.2.1 Program Cycle

WE Controlled

 $(V_{cc}=4.5\sim5.5V, V_{PP}=11.4\sim12.6V, Ta=0\sim60^{\circ}C)$

		(, ()	· FF	,	
PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Write Cycle Time	t _{AVAV}	t _{eW}	200		
Address Setup Time	tavwl	t,u (A)	20		
Write Recovery Time	twhax	t _{rea} (WE)	30	_	
Data Setup Time for WE	t _{DVWH}	t,u (D-WEH)	60		
Data Hold Time	t _{whDX}	t _h (D)	30		
Write Recovery Before Read	t _{wHGL}		10	_	
Card Enable Setup time for WE	t _{ELWH}	t _{su} (CE-WEH)	140		ns
Address Setup for WE	t _{AVWH}	t _{su} (A-WEH)	140		
Card Enable Hold Time	t _{when}		15	_	
Write Pulse Width	twlwh	t _w (WE)	120		
Write Pulse Width High	twhwL	tw (WEH)	30	_	
WE High to RDY/BSY Going Low	twirl			150	
Duration of write					
operation	t _{WHQV1}		4.8		μς
V _{PP} Setup to WE Going High	t _{vpwH}		100	_	
V _{PP} Hold from Valid SRD, RDY/BSY High	t _{QVVL}		0	_	ns

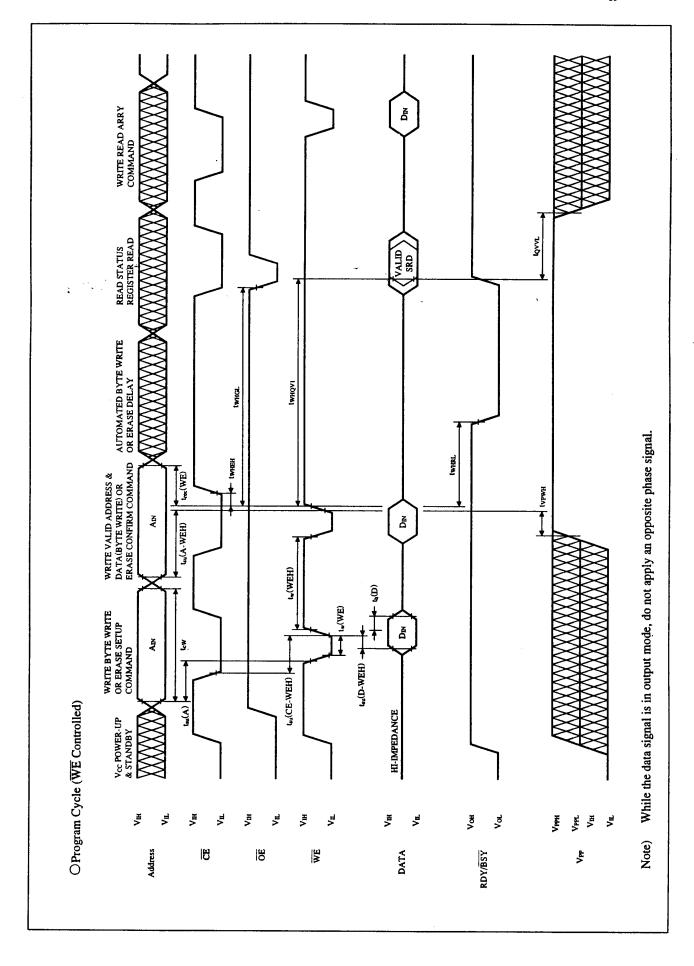
CE Controlled

 $(V_{cc}=4.5\sim5.5V, V_{pp}=11.4\sim12.6V, Ta=0\sim60^{\circ}C)$

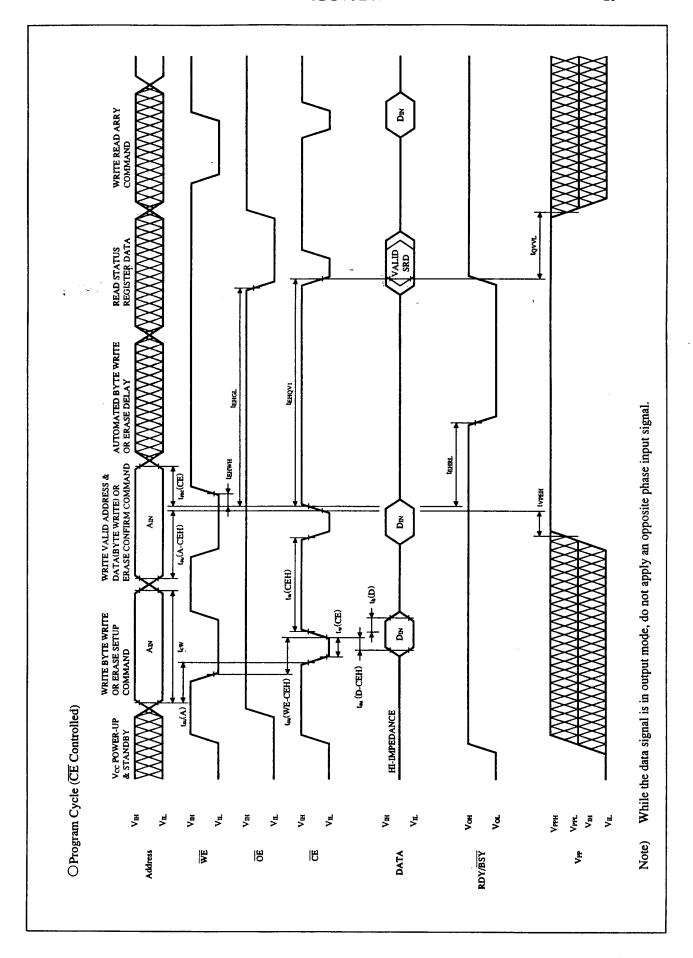
CL Condoned		(700 7.5 5.5 7, 1	v pp 11.—	12.0 V, 1a	0 · 00 C,
PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Write Cycle Time	t _{AVAV}	t _{eW}	200		
Address Setup Time	t _{AVEL}	t _{su} (A)	20	— .	1
Write Recovery Time	t _{ehax}	t _{rec} (CE)	30	-	1
Data Setup Time for CE	t _{DVEH}	t _{su} (D-CEH)	60		1
Data Hold Time	t _{EHDX}	t _h (D)	30	_] .
Write Recovery Before Read	t _{EHGL}		10		1
Write Enable Setup time for CE	t _{wleh}	t _{su} (WE-CEH)	140		ns
Address Setup for CE	t _{aveh}	t _{su} (A-CEH)	140		
Write Enable Hold Time	t _{EHWH}		0		
Write Pulse Width	t _{ELEH}	t _w (CE)	120	_	
Write Pulse Width High	t _{EHEL}	tw (CEH)	30	<u> </u>	
WE High to RDY/BSY Going Low	t _{EHRL}		_	150	
Duration of write operation	t _{EHQV1}		4.8	_	μs
V _{PP} Setup to WE Going High	t _{VPEH}		100		
V _{PP} Hold from Valid SRD, RDY/BSY High	t _{QVVL}		0		ns

1. Set \overline{CE}_1 , \overline{CE}_2 , \overline{OE} and \overline{WE} "HIGH", when V_{PP} changes from V_{PPL} to V_{PPH} or vice versa.









11. Erase Operation

11.1 DC Charactristics

 $(V_{cc}=4.5\sim5.5V, V_{pp}=11.4\sim12.6V, Ta=0\sim60^{\circ}C)$

 $(V_{cc}=4.5\sim5.5V, V_{PP}=11.4\sim12.6V, Ta=0\sim60°C)$

0

			(100 7.5	3.3 V, V	pp 11.4 12.0 v, 1a 0 -00 C	
PARAME	TER	SYMBOL	Min.	Max.	UNIT	CONDITION
v v	Read	V_{PPL}	0	1.5		
V _{PP1} , V _{PP2} Operating Voltage	Program	$V_{\tiny exttt{PPHE}}$	11.4	12.6	v	
V V	Standby	I _{SB2}		1.6		I/O open
V _{PP1} , V _{PP2} Operating Current (×16 Mode)	Erase	I_{pp}	_	20	mA	RMS
	Erase Suspend	I _{PPS}		1.6	1	$\overline{CE_1}$, $\overline{CE_2} = V_{IH}$, RMS
V _{cc} Operating	Standby	I _{SB1}		2.0		I/O open
Current	Erase	I _{CCE}		75		RMS
(×16 Mode)	Erase Suspend	I _{CCES}	-0.3	22 -	1 1	$\overline{CE_1}$, $\overline{CE_2} = V_{IH}$, RMS
Input Voltage		V _{IL}	3.5	1.5	l _v l	
		V _{IH}	_	$V_{cc} + 0.3$]	
Output Voltage		VoL	$V_{cc}-0.5$	0.4] [I _{oL} =4mA
During Verify		V _{OH}				$I_{OH} = -2mA$

Note) Power on V_{cc} before power on V_{pp} , power off V_{cc} after power off V_{pp} . Keep V_{pp} including its overshoot, below 13V. Card insertion or removal while applying $V_{pp} = 12V$ may cause a loss of integrity. Do not turn on or turn off during $\overline{CE} = \text{`LOW''}$.

If V_{IH} goes above $V_{CC}+0.3V$, normal operation is not assured.

11.2 AC Characteristics ($V_{CC}=4.5\sim5.5V$, $V_{PP}=11.4\sim12.6V$, $Ta=0\sim60^{\circ}C$)

Testing Conditions:

Input Pulse Level : 0.8~3.5V
 Input Rise/Fall Time : 10ns
 Input/Output Timing Reference Level : 1.5V

4) Output Load : 1TTL+C_L (100pF) (including scope and jig capacitance)

11.2.1 Erase Cycle

V_{PP} Hold from Valid SRD, RDY/BSY High

WE Controlled

PARAMETER SYMBOL SYMBOL (PCMCIA) Min. Max. UNIT Write Cycle Time 200 t_{AVAV} t_{cW} Address Setup Time t_{su} (A) 20 t_{AVWL} Write Recovery Time t_{rec} (WE) 30 twhax Data Setup Time for WE t_{su} (D-WEH) t_{DVWH} 60 Data Hold Time $t_h(D)$ 30 t_{whDX} Write Recovery Before Read 10 twHGL กร Card Enable Setup time for WE t_{ru} (CE-WEH) 140 telwh Address Setup for WE t_{su} (A-WEH) 140 tAVWH Card Enable Hold Time 15 twhen Write Pulse Width tw (WE) twlwh 120 Write Pulse Width High tw (WEH) 30 t_{whwl} WE High to RDY/BSY Going Low twhrl. 150 Duration of Erase twHQV2 operation 0.3 V_{PP} Setup to WE Going High 100 tvPWH

tovvl

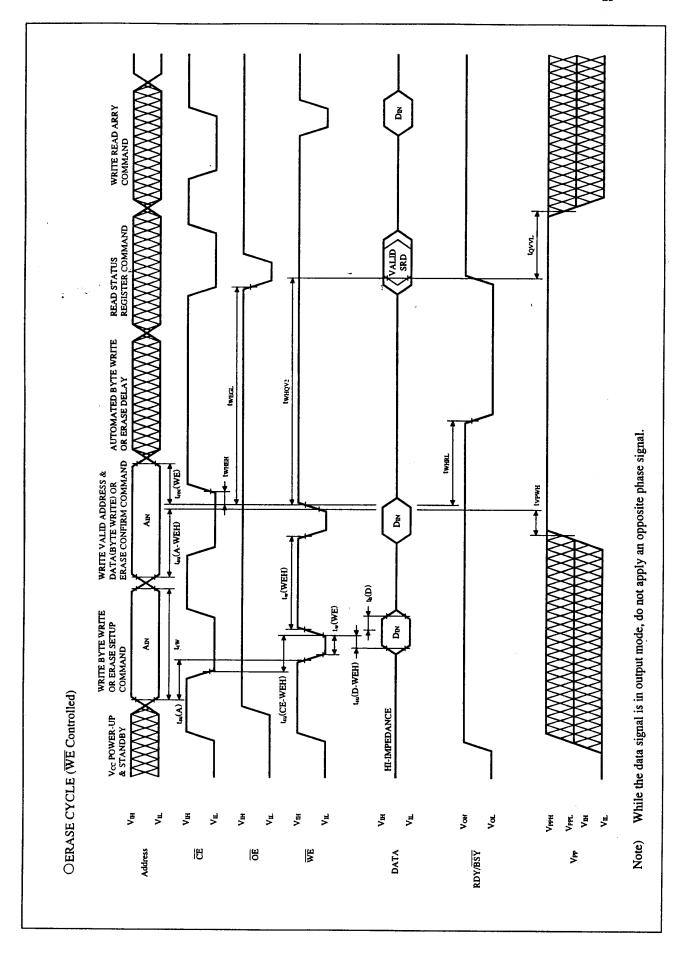
ᅋ	Con	torol	hai

 $(V_{cc}=4.5\sim5.5V, V_{PP}=11.4\sim12.6V, Ta=0\sim60^{\circ}C)$

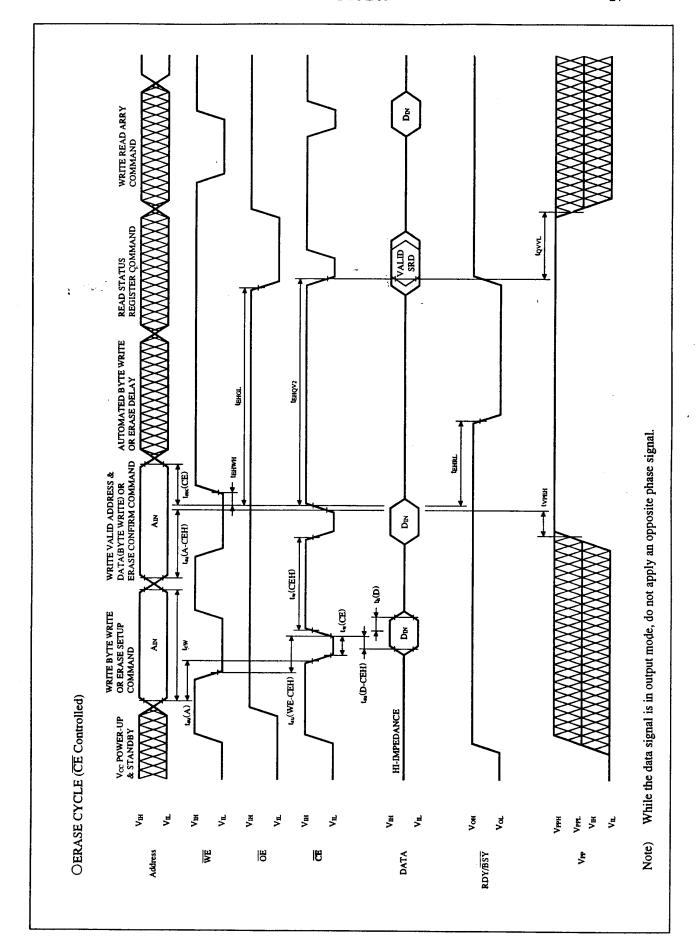
PARAMETER	SYMBOL	SYMBOL (JEIDA)	T	Mari	
	STMBOL	31 MBOL (JEIDA)	Min.	Max.	UNIT
Write Cycle Time	t _{AVAV}	t _{cW}	200		
Address Setup Time	t _{avel}	t _{su} (A)	20	_	
Write Recovery Time	t _{EHAX}	t _{rec} (CE)	30	_	
Data Setup Time for CE	t _{DVEH}	t _{su} (D-CEH)	60	_	
Data Hold Time	t _{EHDX}	t _h (D)	30		
Write Recovery Before Read	t _{EHGL}		10		
Write Enable Setup time for CE	t _{WLEH}	t _{su} (WE-CEH)	140	_	ns
Address Setup for CE	t _{aveh}	t _{su} (A-CEH)	140		
Write Enable Hold Time	t _{EHWH}		0		
Write Pulse Width	t _{ELEH}	t _w (CE)	120		
Write Pulse Width High	t _{ehel}	t _w (CEH)	30		
WE High to RDY/BSY Going Low	t _{EHRL}			150	
Duration of Erase operation	t _{EHQV2}	-	0.3		s
V _{PP} Setup to WE Going High	t _{vpeh}		100	_	
V _{PP} Hold from Valid SRD, RDY/BSY High	t _{QVVL}		0		ns

^{1.} Set \overline{CE}_1 , \overline{CE}_2 , \overline{OE} and \overline{WE} "HIGH", when V_{PP} changes from V_{PPL} to V_{PPH} or vice versa.







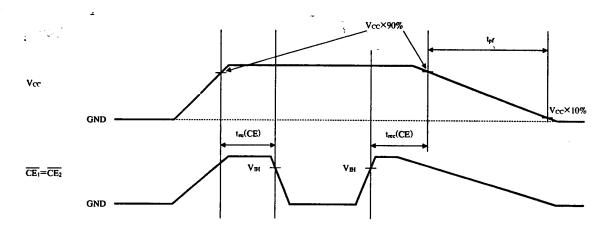


12. Block Erase and Data Write Characteristics

$(V_{CC}=4.5\sim5.5V_{c}$	$V_{PP}=11.4\sim12.6$	6V, Ta=0~60°C)
, ,,	· FF ·	··, · · · · · · · · ·

PARAMETER	Min.	Тур.	Max.	UNIT
Block Pair Erase Time	_	1.0	10	
Block Pair				s
Write Time		0.4	2.1	

13. Voltage Timing (Ta=25℃)



3.5V < VIH < Vcc+0.3

PARAMETER	SYMBOL	Min.	Max.	UNIT
CE Setup Time	t _{su} (CE)	4.0	-	ms
CE Recovery Time	t _{ree} (CE)	1.0	_	μs
V _{CC} Falling Time	tpf	3.0	300	ms

Note) 1. When V_{CC} (4.5~5.5V) is applied to the memory card and you are inserting or removing the card, \overline{CE}_1 , \overline{CE}_2 should both be high-impedance. At such a time, other signal line should also be hi-impedance. After inserting the memory card, do not access it during the \overline{CE} setup time (minimum of 4ms).

(During this time, neither $\overline{CE_1}$ nor $\overline{CE_2}$ = "LOW".)

2. When V_{CC} is turn on, if the condition (for example, V_{CC} rising time. etc) is not sufficient to as specified, it is possible that device's Status Register is not cleared or device not becomes to Read Array Mode. To prevent these, it is recommended that using software command, reset the Status Register or set the device to Read Array Mode.

ex.

Reset the Status Register 50H (5050H)
Set to Read Array Mode FFH (FFFFH)



14. Attribute Memory

The attribute memory holds the attribute information of the card such as the type of card, bit configuration, speed and so on.

EEPROM Model

Card has 2k bytes of EEPROM attribute memory. To read the attribute memory, set REG = "LOW" and perform a read with the same access timming as common memory read.

For this operation, access time is 300ns maximum. To allow 2k bytes of attribute memory, even addresses from 0 to 4096 are reserved. Since only the even-numbered bytes are used, reading odd-numbered bytes will result in invalid data.

Note) We have another type of attribute memory as follows,

No EEPROM Model. (Model no ID240E02:5 bytes device informations in even address 0 to 8, read only in card's control circuit, with the same access timming as common memory read.)

14.1 Attribute Memory Read/Write Function Chart

$\overline{CE_i}$	CE ₂	A ₀	WE	ŌĒ	REG	MODE	D ₀ ~D ₇	D ₈ ~D ₁₅	STAATUS
Н	Н	X	X	X	X		High-Z	High-Z	Standby
L	. H	L	Н	L	L	Read (×8)	D ₀ (even byte)	High-Z	Byte Access
L	Н	Н	H	L	L		High-Z	High-Z	Standby
L	L	X	Н	L	L	Read (×8)	D ₀ (even byte)	High-Z	Byte Access
Н	L	X	Н	L	L		High-Z	High-Z	Standby
L	Н	L	L	Н	L	Write (×8)	D ₁ (even byte)	×××	Byte Access
L	Н	Н	L	Н	L		×××	×××	Standby
L	L	X	L	Н	L	Write (×8)	D ₁ (even byte)	×××	Byte Access
H	L	X	L	Н	L		×××	×××	Standby
L	х	X	Н	L	L	Attribute Memory Address 0~8	D ₀	High-Z	Byte Access

H: High

L : Low

X: High/Low not applicable

Di: Input Data

Do: Output Data

Hi-Z: High Impedance

×××: Don't Care

Notes: 1) When the write protect switch is in protect-mode, the WP output signal is "HIGH" and write operations (including attribute memory) are not allowed.

2) A₀-A₁₁ are attribute memory address. Addresses after A₁₂ are not decoded, so care should be taken.

14.2 AC Characteristics ($V_{CC}=4.5V\sim5.5V$, $Ta=0\sim60^{\circ}C$)

Testing Conditions

1) Input Pulse Level

: 0.8~3.5V

2) Input Rise/Fall Time

: 10ns

3) Input/Output Timing Reference Level

: 1.5V

4) Output Load Capacitance

 $: 1TTL + C_{L} (100pF)$

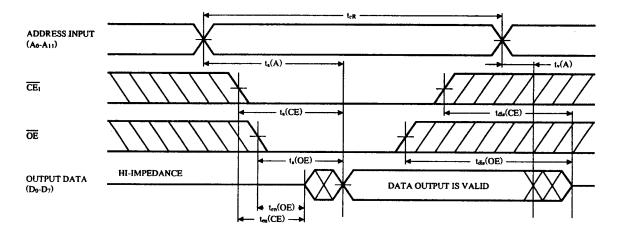
(including scope and jig capacitance)

14.3 Attribute Memory Read Cycle

$(V_{cc}=4.5\sim5.5V,$	To-On-KORC)
$(v_{CC} + J_{CC} + J_{CC})$, 1a-0 ~00C)

PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Read Cycle Time	t _{CR}	t _{cR}	300		
Address Access Time	t _{ACC}	t _a (A)	-	300	1
Card Enable Access Time	t _{CE}	t _a (CE)		300	1
Output Enable Access Time	t _{OE}	t _a (OE)		150	1
Output Disable Time from CE		t _{dis} (CE)		100	ns
Output Disable Time from OE	t _{DF}	t _{dis} (OE)	_	100	1
Output Enable Time from CE		t _{en} (CE)	5	_	Ì
Output Enable Time from OE		t _{en} (OE)	5	_	1
Data Valid from Add Change	t _{oh}	t _v (A)	0		

OAttribute Memory Read Cycle



- Note: 1. To read attribute memory, \overline{REG} ="LOW", \overline{WE} ="HIGH" and either \overline{CE}_2 ="LOW" or else \overline{CE}_2 ="HIGH" and A_0 ="LOW".
 - 2. The output data becomes valid when last interval, t_a (A), t_a (CE)or t_a (OE)have concluded.

14.4 Attribute Memory Write Cycle

WE Controlled

 $(V_{cc}=4.5V\sim5.5V, Ta=0\sim60^{\circ}C)$

PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Write Cycle Time	t _{wc}	t _{cW}	10		ms
Write Pulse Width	t _{wp}	t _w (WE)	180		
Address Setup Time	t _{AS}	t _{su} (A)	10		1
Data Setup Time for WE	t _{DS}	t _{su} (D-WEH)	100		1
Card Enable Setup Time	t _{CES}	t _{su} (CE)	0		1
Output Enable Setup Time	t _{OES}	t _{su} (OE-WE)	45		ns
Address Hold Time	t _{AH}		260		1
Write Hold Time	t _{CH}		0		
Output Enable Hold Time	t _{OEH}		70		
WE HIGH Hold Time	t _{weh}	3	9.9		ms
Data Hold Time	t _{DH}	t _h (D)	80 .		ns

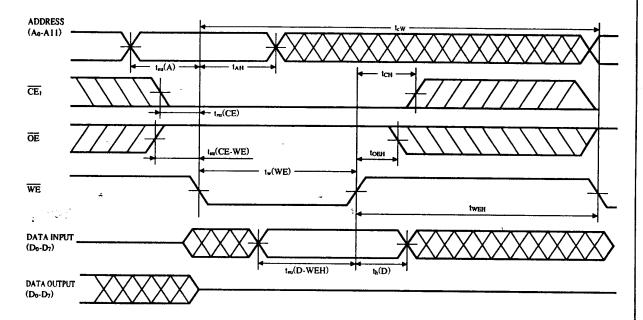
CE Controlled

 $(V_{CC}=4.5V\sim5.5V, Ta=0\sim60^{\circ}C)$

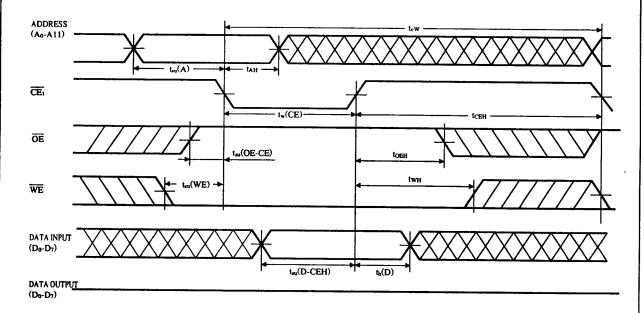
PARAMETER	SYMBOL	SYMBOL (PCMCIA)	Min.	Max.	UNIT
Write Cycle Time	t _{wc}	t _{cw}	10		ms
Write Pulse Width	t _{wp}	t _w (CE)	210		
Address Setup Time	t _{AS}	t _{su} (A)	10		1
Data Setup Time for CE	t _{DS}	t _{su} (D-CEH)	100		1
Write Enable Setup Time	t _{wes}	t _{su} (WE)	0		1
Output Enable Setup Time	t _{OES}	t _{su} (OE-CE)	45		ns
Address Hold Time	t _{AH}		260		Ì
Write Hold Time	t _{wH}		0	T —	İ
Output Enable Hold Time	t _{OEH}		70		
CE HIGH Hold Time	t _{CEH}		9.9		ms
Data Hold Time	t _{DH}	t _h (D)	80	_	ns



OAttribute Memory Write Cycle (WE Controlled)



OAttribute Memory Write Cycle (CE Controlled)



Note: 1. To write attribute memory, \overline{REG} ="LOW" and either \overline{CE}_2 ="LOW" or else \overline{CE}_2 ="HIGH" and A_0 = "LOW"

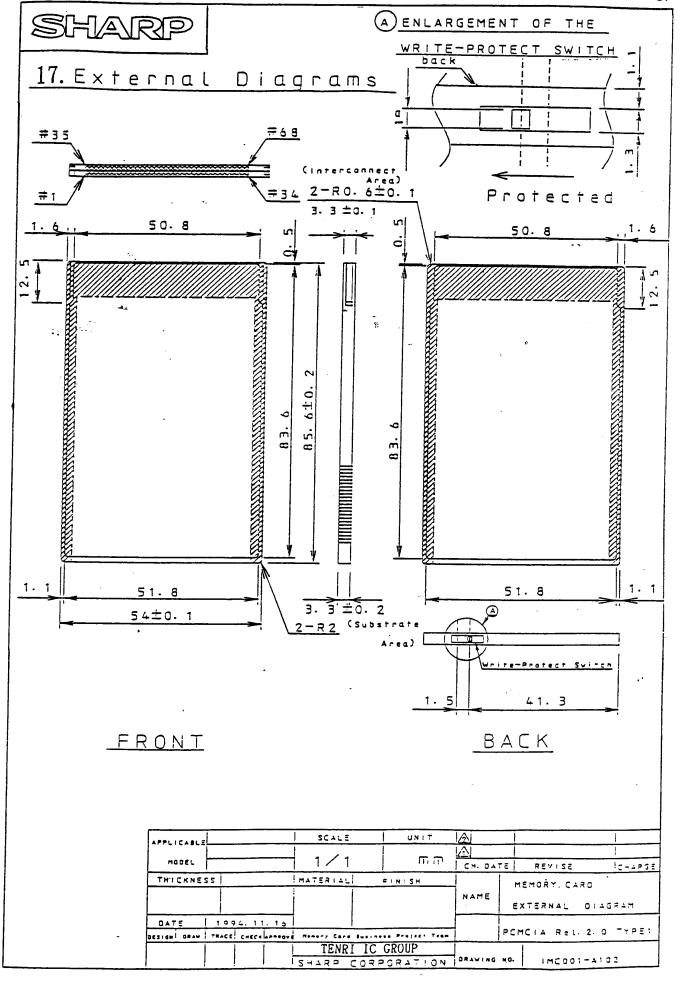
15. Specification Changes

Specifications may be changed upon discussion and agreement between both parties.

16. Othes Precautions

0	Permanent damage occures if the memory card is stressed beyond Absolute Maximum Ratings. Operation beyond
	the Recommended Operating Conditions is not recommended and extended exposure beyond the Recommended
	Operating Conditions may affect device reliability.

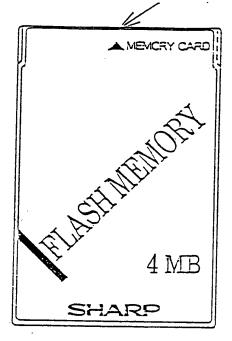
- O Writing to the memory card can be prevented by switching on the write protect switch on the end of the memory card.
- O Avoid allowing the memory card connectors to come in contact with metals and avoid touching the connectors, as the internal circuits can be damaged by static electricity.
- O Avoid storing in direct sunlight, high temperatures (do not place near heaters or radiators), high humidity and dusty areas.
- O Avoid subjecting the memory card to strong physical abuse. Dropping, bending, smashing or throwing the card can result in loss of function.
- O When the memory card is not being used, return it to its protective case.
- O Do not allow the memory card to come in contact with fire.



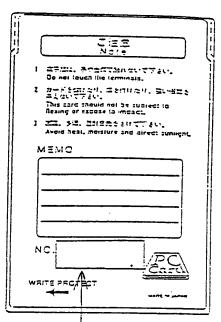


19. EXTERNAL APPEARANCES

CONNECTOR SIDE

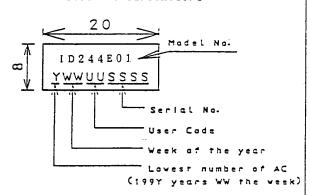


FRONT PANEL



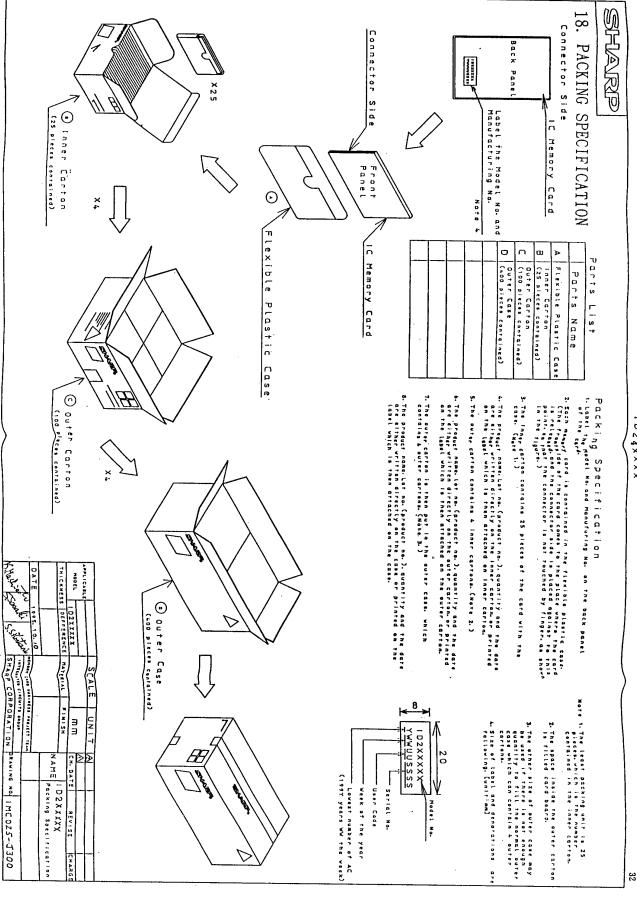
LABELING POSITION BACK PANEL

LABEL SIZE AND DENOTATIONS



APPLICABLE	ID244E01	SCALE	UNIT	12		
HODEL			mm	CH. DATE	REVISE	 CHARGE
THICKNESS	DEFFERENCE	MATERIAL	FINISH	NAME		
DATE	1995. 10. 10					
	asabi S.Shritariu	HEMORY CARD BUSI	HESS PROJECT TEAM			
Phone K	S. S	SHARP COR	PORATION	PRAWING NOT		





4 MB, PCMCIA, Flash Card, ID240E01

SPECIFICATIONS ARE SUBJECT TO CHANGE WITHOUT NOTICE.

Suggested applications (if any) are for standard use; See Important Restrictions for limitations on special applications. See Limited Warranty for SHARP's product warranty. The Limited Warranty is in lieu, and exclusive of, all other warranties, express or implied. ALL EXPRESS AND IMPLIED WARRANTIES, INCLUDING THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR USE AND FITNESS FOR A PARTICULAR PURPOSE, ARE SPECIFICALLY EXCLUDED. In no event will SHARP be liable, or in any way responsible, for any incidental or consequential economic or property damage.



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