

PPSM

3.1	PPSM Initialization and Applic
	PPSM Initialization
	Task Registration
3.2	PPSM Application Programmi
	Active Area Registration .
	Messages from PPSM . .
3.3	Data Representation
3.4	Naming Convention
	Procedure
	Constants and Labels . .
	Local Variables
	Global Variables
	Local Pointer Variables . .
	Global Pointer Variables .

Part II

Writing PPSM Applications

Chapter 4	Pen Input Handling
4.1	Active Area
	Icon Area
	Input Area
4.2	Creating an Active Area. . . .
4.3	Removing an Active Area . .
4.4	Suspending an Active Area .
4.5	Active Area Enquiry
4.6	Put Active Area to Front of Lis
4.7	Pen Echoing
4.8	Pen Color and Pen Size
4.9	Creating a Control Active Are
4.10	Removing a Control Active Ar
4.11	Push Active Area List into Bac
4.12	Pop Active Area List to Foreg



Motorola Semiconductor

Document Number	PPSM Version	Re
PDAPSM01U18-10	2.0	Noveml
PDAPSM01U18-11	2.1	May 13
PDAPSM03SPM1-10	3.0	March 5
PDAPSM03SPM1-11	3.1	Novem
PDAPSM03SPM1-12	3.11	Apirl 20

Copyright © 1995-1999 by Motorola, Inc.

Produced by DragonBall Operation, WSSG, Motorola

Fax: (852) 2666-6551

Email: portable@email.sps.mot.com

Website: <http://www.apspg.com/products/ppsm/ppsm>

Motorola reserves the right to make any modificat
thereof for any reason whatsoever without further
liability arising out of the application or use of this p
convey nor license under its patent rights or copy
all or any portion of this product. Motorola products
as components in systems intended for surgical in
support or sustain life, or for any other application
create a situation where personal injury or death r
products for such unintended or unauthorized app
and its officers, employees, subsidiaries, affiliate
costs, damages, and expenses, and reasonable at
claim of personal injury or death associated with s
claims alleges that Motorola was negligent regardi
and  are registered trademarks of Motorola, Inc

Table of Contents

Table of Contents .
Preface

Part I
PPSM
Architecture

Chapter 1 Introduction

1.1 What is PPSM?

1.2 Strengths and Feature

1.3 Software Developmen

1.4 Hardware Developmen

Chapter 2 PPSM System Over

2.1 Interrupt Handling

2.2 Error Handling

2.3 I/O Devices

Pen Input

Screen Format

Hardware Cursor

2.4 Data Storage

2.5 Font Management

2.6 Memory Management

2.7 Power Management

Direct Control

Automatic Control

2.8 Task Management

PPSM Tasks

Application State T

Task Swapping

2.9 Timer Management

Chapter 3 PPSM Programmin



11.2	Power Modes	Chapter 5	Character Input Me
11.3	System Internal Modes	5.1	Soft Keyboard
	Initialization Mode		Starting Soft Keybo
	System Mode		Auto-Key-Repeat
	Wake-up Mode		Terminating Soft K
11.4	Application Modes		Suspend Soft Key
	Normal Mode	5.2	Handwriting Recogniti
	Doze Mode		The Input Pad Mec
	Sleep Mode		Starting Handwriti
11.5	Power Management Tools . .		Terminating Handv
	Setting Duty Cycle	Chapter 6	Using Graphics To
	Setting Doze Period	6.1	Display Screen Forma
	Setting Sleep Period		LCD Display Scree
	Going Into Doze Mode . .		Panning Display S
	Going Into Sleep Mode . .		
11.6	I/O Ports Control	6.2	Screen Initialization .
	Disabling I/O Port Before		LCD Display Scree
	Enabling I/O Port After Do		Screen Resolution
	Disabling I/O Port Before	6.3	Sample LCD Display S
	Enabling I/O Port After Sle	6.4	1 bit-per-pixel Graphi
Chapter 12			Drawing Operators
Chapter 13	UART Communication Su	6.5	2 bits-per-pixel Graphi
			Drawing Operators
13.1	UART Communication Archite	6.6	Graphics Tools
	UART hardware flow cont	6.7	Get LCD Display Scree
	UART Interface Constrai	6.8	Get LCD Display Scree
	UART Interface Interrupt I	6.9	Get Panning Screen V
13.2	UART Configurations	6.10	Get Panning Screen H
	Configuring the UART . .	6.11	Set Pattern Fill
	Inquiring the UART Config	6.12	Set Dot Width
	Setting Data Transmissior	6.13	DisplayMove
	Setting Data Transmissior	6.14	Direct All Graphics Ou
13.3	Sending Data to the UART . .	6.15	Change Panning Scree
	Initiating a Send Request	6.16	Fill the whole Panning
	Terminating a Send Requ	6.17	Draw a Dot
13.4	Receiving Data from the UAR	6.18	Draw a Horizontal Line
	Initiating a Receive Reque	6.19	Draw a Vertical Line .
	Reading Received Data .		
	Terminating a Receive Re		
	Setting Data Reception Ti		



6.20	Draw a Line		Creating text temp
6.21	Draw a Rectangle		Deleting text templ
6.22	Draw a Circle	8.4	Text Properties
6.23	Draw an Ellipse		Setting Text Displa
6.24	Draw an Arc		Setting Text Outloc
6.25	Draw a Vector from a List of F	8.5	Setting Font Attrib
6.26	Put a Rectangular Area on Pa		Text Mapping
	Special cases of PutRec()		Displaying text . . .
6.27	Save a Rectangular Area from	8.6	Removing text . . .
6.28	Exchange a Rectangular area		Text character cursor p
6.29	Fill a Rectangular Area		Setting the charact
6.30	Inverse a Rectangular Area .		Reading the chara
6.31	Hardware Cursor	Chapter 9	Timer Management
	Set Hardware Cursor Size	9.1	Reading System Date
	Set Hardware Cursor Pos	9.2	Setting System Date a
	Set Hardware Cursor Stat	9.3	Reading Clock Alarm
	Get Hardware Cursor Stat	9.4	Setting Clock Alarm .
	Set Hardware Cursor Blin	9.5	Clearing Clock Alarm
	Turn Hardware Cursor Off	9.6	Setting Periodic Alarm
6.32	Display Other Region of Pann	9.7	Setting Timeout
6.33	Get LCD Display Origin on Pa	9.8	Setting Input Timeout
6.34	Allocate memory for Panning	9.9	Continuous Reference
Chapter 7	Database Management . .	9.10	Read The Reference T
7.1	Data Format	9.11	Set Reference Timer A
	Formatted Data	9.12	Compute Reference T
	Unformatted Data	Chapter 10	Memory Manage
7.2	The Database Manipulation T	10.1	Allocating Memory . .
7.3	Creating and Editing a Datab	10.2	Freeing Memory
7.4	Searching and Retrieving Dat	10.3	Reallocating Memory
7.5	Navigating along a Record Lis	10.4	Copying Memory . . .
Chapter 8	Text Display Managemen	10.5	Inquiring Memory . . .
8.1	Text Representation	Chapter 11	Power Management
8.2	Text Display Area	11.1	Power Control Module
8.3	Text Templates		



21.3	ClearRec
21.4	ClearScreen
21.5	CursorGetOrigin
21.6	CursorGetPos
21.7	CursorGetStatus
21.8	CursorInit
21.9	CursorOff
21.10	CursorSet
21.11	CursorSetBlink
21.12	CursorSetOrigin
21.13	CursorSetPos
21.14	CursorSetStatus
21.15	DisplayMove
21.16	DrawArc
21.17	DrawCircle
21.18	DrawDot
21.19	DrawEllipse
21.20	DrawHorz
21.21	DrawLine
21.22	DrawRec
21.23	DrawVector
21.24	DrawVert
21.25	ExchangeRec
21.26	GetDisplayX
21.27	GetDisplayY
21.28	GetLogicalX
21.29	GetLogicalY
21.30	GetScreenMem
21.31	InvRec
21.32	LCDContrast
21.33	LCDRefreshRate
21.34	LCDScreenMove

13.5	UART hardware flow c Enabling RTS/CTS Disabling RTS/CTS
13.6	Data reception with ha Pause data recept Continue data rece
13.7	Data transmission with Pause data transm Continue data tran

Chapter 14

Task Management

14.1	Main Task
	System Task
14.2	Sub-task
	Sub-task Manager
14.3	Task Switching
14.4	Message Broadcasting
14.5	Task Control
14.6	Task Swapping Exampl
14.7	Creating a Task
14.8	Creating a Task with S
14.9	Creating a Sub Task .
14.10	Starting a Task
14.11	Termination of a Task
14.12	Task Reinitialization .
14.13	Task Hook
14.14	Stop task swapping .

Chapter 15

Inter-Task Messagi

15.1	Message Passing ... With Delayed Task With Immediate Ta With Immediate Ta Message Passing
15.2	Message Structure .
15.3	Sending Message ...
15.4	Advanced Sending Me



15.5	Deleting Message for Current
15.6	Deleting Message for any Tas
15.7	Receiving Message
Chapter 16	Interrupt Handling
16.1	System Interrupts
	IRPT_AUDIO
	IRPT_PEN
	IRPT_INPUT_STATUS
	IRPT_ICON
	IRPT_KEY
	IRPT_RTC
	IRPT_TIMER
	IRPT_HWR
	IRPT_UART
16.2	Device Interrupts
	User Defined Interrupt Ha
	Device Interrupt Identifiers
	Application Access to Har
	Request and Release Inte
16.3	Message Handling
	Example
Chapter 17	Using System Tools
17.1	PPSM Initialization
	Motorola Logo
Chapter 18	Audio Tools
18.1	Audio Playing
18.2	Tone playing
18.3	Wave playing (DragonBall-EZ
18.4	Stop the audio playing

Part III **API Toolset**

Chapter 19	Pen Input Tools
19.1	ActiveAreaDisable

19.2	ActiveAreaEnable
19.3	ActiveAreaRead
19.4	ActiveAreaSuspend
19.5	ActiveAreaToFront
19.6	ActiveListPop
19.7	ActiveListPush
19.8	AreaEchoDisable
19.9	AreaEchoEnable
19.10	ActiveAreaPosition
19.11	CtrlIconDisable
19.12	CtrlIconEnable
19.13	IconScanOff
19.14	IconScanOn
19.15	PenCalibration
19.16	PenEchoParam
19.17	PenGetInput
19.18	PenSetInputMax
19.19	PenSetInputOrg
19.20	PenSetRate
19.21	ScanningOff
19.22	ScanningOn

Chapter 20	Character Input To
20.1	AdvOpenInputPad
20.2	AdvOpenSoftKey
20.3	CloseInputPad
20.4	CloseSoftKey
20.5	OpenInputPad
20.6	OpenSoftKey

Chapter 21	Graphics Tools
21.1	ChangePanning
21.2	ChangeWindow



28.4	TaskCreate
28.5	TaskHook
28.6	TaskReInit
28.7	TaskStart
28.8	TaskTerminate

Chapter 29 Inter-Task Messaging Tools

29.1	AdvMessageDelete
29.2	AdvSendMessage
29.3	MessageDelete
29.4	SendMessage

Chapter 30 Interrupt Handling Tools

30.1	IrptGetData
30.2	IrptRelease
30.3	IrptRequest
30.4	IrptSendData

Chapter 31 System Tools

31.1	PPSMInit
31.2	ReadSMVersion

Chapter 32 Audio Tools

32.1	AdvAudioPlayWave (DragonE
32.2	AudioInUse
32.3	AudioPlayTone
32.4	AudioPlayWave (DragonBall-I
32.5	AudioStopTone
32.6	AudioStopWave (DragonBall-

Part IV System Integrator's

21.35	PutChar
21.36	PutRec
21.37	SaveRec
21.38	SetDotWidth
21.39	SetPatternFill

Chapter 22 Database Management Tools

22.1	DBAdd
22.2	DBAddRecord
22.3	DBAddRecToTop ...
22.4	DBAppendRecord ...
22.5	DBChangeStdData ...
22.6	DBChangeUnfData ...
22.7	DBDelete
22.8	DBDeleteRecord ...
22.9	DBGetFirstRecID ...
22.10	DBGetNextRecID ...
22.11	DBGetPrevRecID ...
22.12	DBReadData
22.13	DBReadTotalNumber
22.14	DBReadTotalNumberF
22.15	DBReadUnfData ...
22.16	DBRecordSecret ...
22.17	DBSearchData
22.18	DBSecretFlag
22.19	DBSetRecordSecretFI
22.20	DBSetSecretFlag ...

Chapter 23 Text Tools

23.1	TextCreate
23.2	TextDelete
23.3	TextMap
23.4	TextReadCursor ...



23.5	TextSetCursor	25.2	Lfree
23.6	TextSetDisplay	25.3	Lmalloc
23.7	TextSetFont	25.4	Lrealloc
23.8	TextSetOutlook	25.5	MoveBlock
23.9	TextSetup	25.6	TaskMemUsed
23.10	TextUnmap	25.7	TaskStackAvail
		25.8	TotalMemSize
		25.9	TotalMemUsed
Chapter 24	Timer Tools	Chapter 26	Power Management
24.1	AlarmClear	26.1	SetDozeMode
24.2	AlarmClearId	26.2	SetDozePeriod
24.3	AlarmRead	26.3	SetDutyCycle
24.4	AlarmReadId	26.4	SetSleepMode
24.5	AlarmSet	26.5	SetSleepPeriod
24.6	AlarmSetId		
24.7	DateTimeRead	Chapter 27	UART Communication
24.8	DateTimeSet	27.1	UARTConfigure
24.9	DeleteTimer	27.2	UARTFlowCtrl
24.10	InputTimeout	27.3	UARTInquire
24.11	RefFineTimeAlarm	27.4	UARTRcvCtrl
24.12	RefFineTimeAlarmId	27.5	UARTReadData
24.13	RefFineTimeDiff	27.6	UARTReceive
24.14	RefFineTimeRead	27.7	UARTSend
24.15	RefTimeAlarm	27.8	UARTSendAbort
24.16	RefTimeAlarmId	27.9	UARTSendCtrl
24.17	RefTimeDiff	27.10	UARTSetDelay
24.18	RefTimeRead	27.11	UARTTimeout
24.19	SetPeriod		
24.20	SetPeriodId	Chapter 28	Task Handling Tools
24.21	Timeout	28.1	AdvTaskCreate
24.22	TimeoutId	28.2	AppSwap
		28.3	SubTaskCreate
Chapter 25	Memory Management Tools		
25.1	Lcalloc		



Guide

Chapter 33	How to make ROM
33.1	Boot Strap Code (boot 68K Start-up Chip Selects Peripheral Devices
33.2	Linker Supplications F
33.3	Generating S-Record Loader Options . . Loader Commands
Chapter 34	Device Drivers . . .
34.1	System Configuration Boot Strap Driver (User Interrupt Han
34.2	Pen Input Device Drive Pen Initialization . Pen Interrupt Enab Pen Interrupt Disal Pen Read Device
34.3	Pen Calibration(PenIn
34.4	LCD Device Drivers (l 1 bit/pixel Initializa 2 bits/pixel Initializa
34.5	Handwriting Recogniti Handwriting Recog Handwriting Recog Process One Strok Initiate Character F
34.6	Font Driver (font.c) . . Font Library Inform Font Library or Fon Font Accessing . .
34.7	UART Device Driver (u Sending the BREA
34.8	Power Management D Enabling I/O ports Disabling I/O ports Enabling I/O ports

Disabling I/O ports when c

Chapter 35	Linker Specification File .
35.1	.SPC File for a RAM-only Sys
35.2	.SPC File for a ROM-RAM Sy
35.3	For SingleStep Debugging Sy
Chapter 36	Trap Usage in PPSM
36.1	PPSM Tools Calling Structure
36.2	TRAP Implementation
	Application
	Stub Library
	TRAP Service Handler . .

Appendices

A	Error Code Definition
B	List of References.
C	Index of PPSM Tools

Preface

<i>What is PPSM?</i>	Personal Portable System designed specifically for operating system enable such as advanced pager instruments, organizers,
<i>Audience & Purpose</i>	The first three parts of th ing to learn the importan trates on a specific aspe
	The forth part of this man for building and configuri
<i>Part I</i>	"PPSM Architecture" des
<i>Part II</i>	"Writing PPSM Applicatio application development This part is targeted part tools. Therefore, the tool tools for writing PPSM ap
<i>Part III</i>	"API Toolset" details the larly to those experience ming methodology. Ther alphabetical order for qu
<i>Part IV</i>	"System Integrator's Gui and configure PPSM sys
<i>Appendices</i>	At the end of the manual information.

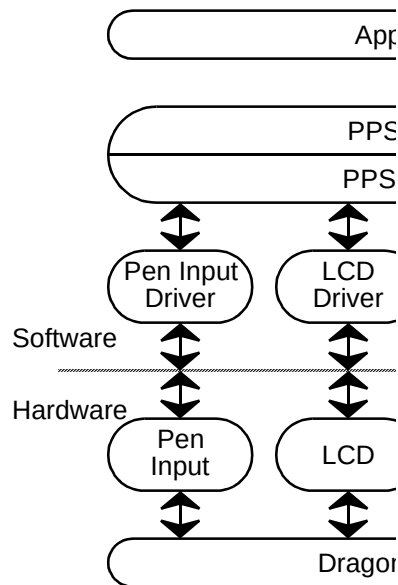


Figure 1-1 Architecture

Part I

PPSM

Architecture

1.2 Strengths and Features

PPSM is modularly designed to shield the developer from the hardware, providing a good toolset for the application developer to use in their specific product design. Performance is optimized for an effective system which requires \

Strengths:

- SPEEDS up application
- COMPACT ROM size per application
- MODULAR Software Architecture
- PEN-CENTRIC
- Third party applications support
- MULTILINGUAL HANDWRITING
- BITMAP FONTS, Infrared
- Application code is compact
- Microsoft Windows based application development

Features:

- Pen / touch panel input support
- 32-bit Real Time Operating System
- Real Time Interrupt Handling
- Power Management
- 16-bit text data representation



Chapter 1 Introduction

1.1 What is PPSM?

Personal Portable System is designed specifically for an operating system enable such as advanced pager instruments, organizers,

PPSM is a real time 32-bit interrupt-driven, e.g. applications. Because PPSM is configurable, and easy to development process.

The PPSM Tools consist of System and Communication a sophisticated User-Interface API for LCD based products provides the basic control and the UART.

The PPSM kernel does not devices are controlled by supplying the appropriate integrators greater flexibility changing the core of the the DragonBall™ family



2.2 Error Handling

Unless otherwise specified, all P completion. A value other than P has occurred.

Each error code uniquely defines

Refer to *Appendix A - Error Code*

2.3 I/O Devices

This section describes the LCD c

Figure 2-2 shows the screen forr areas:

- Pen Input Area
- Display Screen
- Panning Screen

(xInputOrigin, yInputOrigin)
(-59,-29)

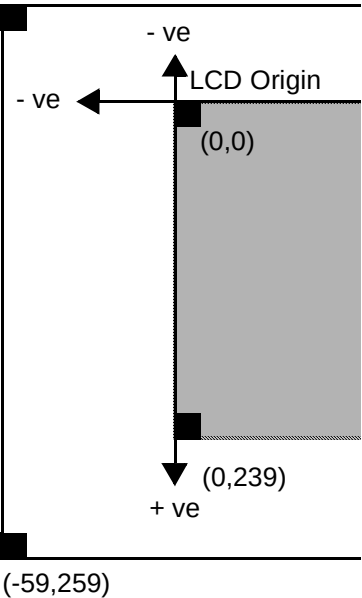


Figure 2-2 An exa

- High Level API T
- Multiple grey lev
- LCD hardware c

1.3 Software Develop

ANSI C is the main prog implementation of low lev and hardware device driv PC running under Windo Debugger, from Software level and instruction deb simulator running on the

1.4 Hardware Develo

The M68328 and M68EZ the reference developme used is a 10-bit compone direction.

For details on the hardw *Manual V2.0 and M68EZ*

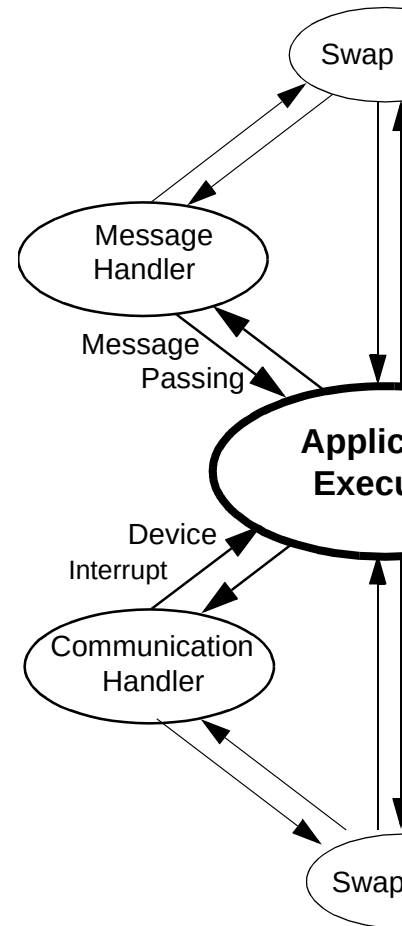


Chapter 2 PPSM System

2.1 Interrupt Handling

An application will always either be the active task, interrupt. An application conditions:

- Interrupt from pe
- Interrupt from a
- Interrupt from po
- Interrupt from tin
- Interrupt from m





choose to control the system's p
PPSM's automatic power manag

2.7.1 Direct Control

A set of tools provide the applica
during Normal mode:

- switch into any of the po
- the duty cycle of the proc

2.7.2 Automatic Control

A set of tools are available for the
management features provided t

- to switch automatically to
is idle
- to control user defined I/
saving modes

2.8 Task Management

Each application running on PPS
tasks can be actively running at :

2.8.1 PPSM Tasks

There are two types of PPSM tas
task) and tasks that are spawnec

2.8.1.1 Main Task

Most applications fall into the ma
each other. There cannot be mor
created by the system tool TaskC
created, it can be started in one :

- By using the system tool
- By pressing the applicati
- By messages sent by an

2.8.1.2 Sub-task

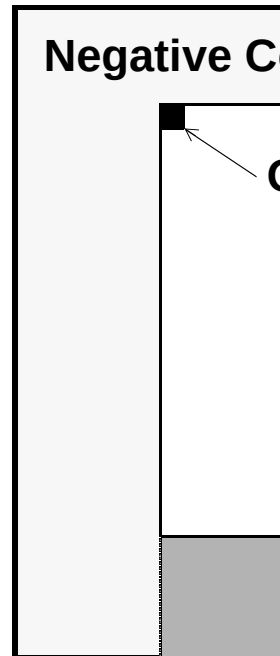
Sub-task, on the other hand, can
that generated the sub-task. Mes
and its parent. Sub-task uses the
started with the system tool Sub

Sub-tasks are tied to the parent t

2.3.1 Pen Input

2.3.1.1 Pen Input Area

This is the touch sensitiv
touch panel is the same
(0,0) or the origin, is at th
see from *Figure 2-3*, the
have a negative value. P
allows applications to im
writing area.



Fig

If the LCD display screen
coordinates from the per

2.3.1.2 Active area

An active area is defined
application or an action v
an icon, or an action butt

Active areas are classifie
to *Section 4.1 - Active A*



2.3.2 Screen Format

2.3.2.1 LCD Display Screen

The display screen is the LCD di
images. The LCD module can ha
graphics, giving black and white
Display data, such as graphics a
screen area.

2.3.2.2 Panning Screen

The Panning Screen is an extens
is to allow applications to write d
Although applications can write t
screen unless this area is being i
areas on the panning screen will
with the LCD display screen.

2.3.3 Hardware Cursor

The maximum hardware cursor s
task swapping, the hardware cur
origin on panning screen in curre
status, position, size and the offs
used.

2.4 Data Storage

Databases are the main means c
is available in PPSM to support c

PPSM database are in global da
tasks.

When a database is created, PP
the application. Application will n
subsequent access to that partic
any limit in number of database r
limitation in creating these datab.

The PPSM database tools provic
and search for particular data. Ac
record list. In particular, the tool I
DBGetPrevRecID() are meant to
sophisticated searching algorithn
example usage of each database
Management and Chapter 21 - L

2.5 Font Management

PPSM supports 8x10 En
Chinese bitmap fonts, an
are included in PPSM. T
System integrators need
these fonts.

The font bitmap lookup c
33.6 - Font Driver (font.c)
access to these fonts for

2.6 Memory Management

PPSM provides a set of m
memory space. A heap is
allocate memory from the
provided by the compiler

Four memory managem

- Lcalloc()
- Lmalloc()
- Lrealloc()
- Lfree()

PPSM also provides a s
time memory size.

Three memory inquiry to

- TaskMemUsed()
- TotalMemUsed()
- TotalMemSize()
- TaskStackAvail()

The size of the largest ch
be known by calling Lma

The size of the heap me
available in the hardware
ROM? on how memory s

For SingleStep Debuggin
further description in hov

2.7 Power Management

PPSM utilizes the power
power management tool



handler assignment. It must be c
can also perform the pen to scre
system start-up.

3.1.2 Task Registration

An application is treated as a tas
application task on the system m
application can make use of the

When integrating the individual a
integrator must first call one of th
are two types of tasks, main task
and Section 13.2 - Sub-task). Th
memory and stack required for e
memory system.

Associated with each main applic
This launch icon's position on the
tool. The application is put to the
selected by the pen input device.

When writing an application task
alone procedure as PPSM resou
implementation of tasks allow a r
independently and linked togethe

For details of the task creation to
Task, Section 13.8 - Creating a i
13.9 - Creating a Sub Task.

After all applications have been r
by calling the tool TaskStart(). Th
the system will be started when t
pressed.

3.2 PPSM Application Proc

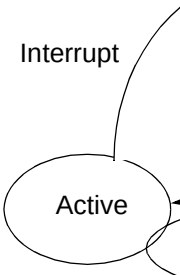
This section describes the gener
PPSM environment. The typical i
Figure 3-2. After the application i
areas with PPSM, it would contin
events. When an event occurs, tl
loop back to IrptGetData() to wai

terminated, the sub-task
the input pad and pannin

2.8.2 Application State T

Application tasks have th
application.

- Active
- Suspended
- Stopped



Figure

2.8.2.1 Active State

This is the state when an
hardware resources are

2.8.2.2 Suspended S

An application task is pu
during active state execu
mode, will become the ac
the registers that are use

The suspended task will
otherwise it will be put in

2.8.2.3 Stopped State

An application changes t
application is selected. In
bitmap image are stored

A task will exit from the s



selected. It will continue executi
state.

2.8.3 Task Swapping

Task swapping is performed by F
A task swapping is executed whe
application, needs to become ac
receives an interrupt, such as tim

For example, when an applicatio
that is actively running will be put
active.

2.9 Timer Management

PPSM maintains a reprogramma
January, 1997 upon start up. Thi
never stops.

A set of timer tools are available
programmer to set system clock,
application.

Chapter 3 PPSM Program

PPSM programming mai

- PPSM initializati
- Individual PPSM

3.1 PPSM Initialization

A PPSM system must fir
be assigned and used. S
individual PPSM applica
PPSM organizer may co
scheduler and calculator

Figure 3-1 shows a typic
initialized, then applicati
with PPSM individually. T
application which is chos

Figure 3

3.1.1 PPSM Initialization

The PPSMInit() tool perfo



- OK
- UNKNOWN

3.4.3 Local Variables

All local variables start with lower case names. There are no underscores.

Example 3-3 Local variable

- xPos
- yPos
- dataLen
- temp
- rate

3.4.4 Global Variables

Same as local variables, except they start with upper case "G".

Example 3-4 Global variable

- gCurrentTask
- glrptMask
- gSystemClock

3.4.5 Local Pointer Variables

All local pointer variables start with "p" followed by lower case variable names. There are no underscores.

Example 3-5 Local pointer variable

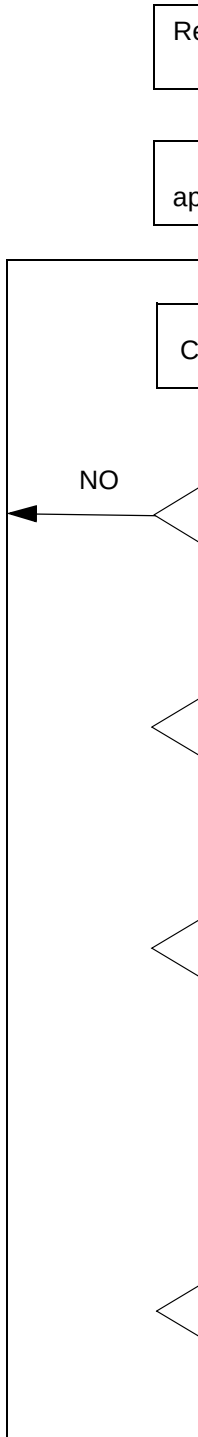
- pSourceAddr
- pDestAddr
- pTaskTable
- pReturnSize

3.4.6 Global Pointer Variables

Same as local pointer variables, except they start with upper case "GP" followed by lower case "gp".

Example 3-6 Global pointer variable

- gpSysList
- gpPhoneBook
- gpSrcMem



3.2.1 Active Area Register

PPSM is designed as a p



regions defined in PPSM as activ
for applications to receive pen in
need to monitor the hardware co
sampling, maximizing processor

An active area is defined as a rec
messages are generated to the a
areas only generate messages to
example of an active area is an i
area.

When application needs to perfor
register each active area with PF
All remaining areas on the input j
any information to the application
please refer to *Chapter 4 - Pen I
Methods*.

3.2.2 Messages from PPSM

PPSM application should take a
When external events occur, suc
automatically intercepts and inte
from the application, such as an i
UART, PPSM will package the d
to the waiting application's interr
Handling). However, if the event
pressing of input panel that is no
power saving mode, the event is
message sent to the application.

Upon receiving soft interrupt mes
act upon the nature of the mess
types for different types of interr
Section 15.2 - Device Interrupts)

Application tasks can receive the
IrptGetData(). The application ta
program's flow to check for any i
IrptGetData).

3.3 Data Representation

PPSM is a 32-bit system. *Table .*

Table 3-1 Data

Data Type	
U8	
P_U8	ur

Table 3

Data Type
S8
P_S8
U16
P_U16
S16
P_S16
U32
P_U32
S32
P_S32
STATUS
TEXT
P_TEXT
P_VOID

3.4 Naming Conventions

For consistency, a set of
software development. T

3.4.1 Procedure

All procedure names are
the name will be in upper

Example 3-1 Proced

- PenInit()
- PagerCheck()
- DrawDot()

3.4.2 Constants and Labels

All constants and labels

Example 3-2 Consta

- DISPLAY_MODI
- DEFAULT_MOD



Upon release, either by pen-up o
touch panel, another soft interrup
event. This type of area is desigr

4.1.2 Input Area

Input area is an area where writir
will monitor the area with the giv
rate, pen echoing and pen positio
Three modes of operation are av
CONFINED or CONTINUOUS.

4.1.2.1 Stroke Mode

Drawing on STROKE type of inp
coordinate integers to the applic
usually with a pen-up. This list co
pen-input device. When the pen
then the stroke data ends.

4.1.2.2 Confined Mode

CONFINED mode is very much I
input moves out of the defined ar
outside the region are truncated t
area. This means a stroke will nc

4.1.2.3 Continuous Mode

Drawing on CONTINUOUS type
x and y coordinates to the applic
panel. With this type of input, sof
The last input point will be a set o
of area must ensure the soft inter
very significant.

4.2 Creating an Active Ar

STATUS **ActiveAreaEnable**
S16 ySrc, S16 x

This tool creates a new active ar
the new area to the caller. Once
returned to the application.

The argument type is used to sp
required. Mode specifies the inp

Example 4-1 Create an acti

```
49  U32  nextWinId; /* NextWin'
```

Part II Writing PPSM Applica



Chapter 4 Pen Input Handling

The Pen Input Tools enable you to:

- define active areas
- control ink echo

Refer to *Section 6.2.2 - 3*

4.1 Active Area

Active area provides an interface for the PPSM to receive samples from the touch pen. The PPSM samples the touch pen constantly. PPSM uses the samples to determine pen utilization.

An active area is defined by a set of coordinates. When an interrupt message is generated, the PPSM checks the active area. An example of this is an active area for a button.

Active areas are only "active" when the pen is in the corresponding pen up state. The PPSM generates a "B", and one of its sub-tasks is to check the active areas "C" and "D". When a user moves the pen across the active areas "A" and "B", the PPSM generates a "D". By the time the pen moves across them, "D" will receive message.

If active areas are overlapped, the PPSM will receive pen messages.

There are two types of active areas. The PPSM has three different modes of operation.

Type	
ICON_AREA	N/A
INPUT_AREA	STROKES
	CONTOUR
	CONTOUR

4.1.1 Icon Area

Icon area is for the purpose of generating a soft interrupt either from a pen-down or a pen-up. The PPSM generates a soft interrupt when the pen is in the pen-down state.



```

114 if ( CtrlIconEnable(&abortRc
115     != PPSM_OK )
116     return (PPSM_ERROR);

```

4.10 Removing a Control A

STATUS CtrlIconDisable(U:

Remove the control icon from PF
no longer generate icon interrupt

4.11 Push Active Area List

STATUS ActiveListPush(vo

PPSM maintains a stack for stori
the active areas that have been c
and a new list begins. A new list
area created will belong to the ne

This tool allow applications to cre
original active areas when the te

Example 4-7 Push active ar

```

/* Push all existing active ar
If (rv = ActiveListPush())
{
    /* error */
    return (rv);
}

/* create new set of active ar
GenerateNew();

/* Call subroutine */
ScratchPad();

/* restore original active are
if (rv = ActiveListPop())
{
    /* error */
    return (rv);
}

```

4.12 Pop Active Area List t

STATUS ActiveListPop(voi

PPSM maintains a stack for stori
least recently pushed in active a
tool must be called after an Activ
Otherwise, an error will be return

```

.
.
104 /* Create an active
105 * as specified belo
106 */
107
108 if (ActiveAreaEnabl
109     NE
110     != PPSM_OK)
111     return PPSM_ERROR;
112

```

4.3 Removing an Ac

STATUS ActiveArea

Removes a valid active a
tool must be a valid activ
ActiveAreaEnable tool. T
area.

Once removed, the regio
identifier will no longer re

Example 4-2 Remov

```

74     U32     backId;
.
.
.
262         if ( Acti
263         return (P

```

4.4 Suspending an A

STATUS ActiveArea

Activate or deactivate a v
it can be suspended from

To suspend, call this tool
active area no longer se
writing in the region.

To re-enable the active a

Example 4-3 Suspen

```

if ((rv = ActiveAreaSu
{
    /* error */
    return (rv);
}

```

Example 4-4 Re-enal

```

if ((rv = ActiveAreaSu
{
    /* error */
    return (rv);
}

```



4.5 Active Area Enquiry

STATUS **ActiveAreaRead**(U
xDest, P_S16 y)

Given a valid active area identifier, this function returns the active area.

Example 4-5 Enquire coord

```
85  U32      id, size;
86  P_U16    inData;
87  S16      xSrc, ySrc, xDest, y
.
.
.
180          ActiveAreaRead(id,
```

4.6 Put Active Area to Front

STATUS **ActiveAreaToFront**

Given the active area identifier, this function inserts the active area into the active area linked list and inserts the element into the active area linked list.

Once the element is at the front of the active area linked list, the function returns the active area identifier if there are other active areas.

4.7 Pen Echoing

STATUS **AreaEchoEnable**(I

STATUS **AreaEchoDisable**(I

For input active areas, echoing can be enabled when input active areas are valid. When a valid active area identifier is generated, the function returns the active area identifier.

4.8 Pen Color and Pen Size

STATUS **PenEchoParam**(U

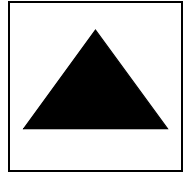
PPSM allows the application developer to set the pen color. This tool only sets the echo color for other applications within the system.

4.9 Creating a Control Area

STATUS **CtrlIconEnable**(P

A pre-defined group of direction codes is used to create a control area.

purpose of scrolling. The function returns the icon area. Two sets of direction codes are used to create a control area.



An identifier is returned to the application developer.

Icon Type
PPSM_ICON_8_UP
PPSM_ICON_8_DOWN
PPSM_ICON_8_LEFT
PPSM_ICON_8_RIGHT
PPSM_ICON_8_DONE
PPSM_ICON_16_UP
PPSM_ICON_16_DOWN
PPSM_ICON_16_LEFT
PPSM_ICON_16_RIGHT
PPSM_ICON_16_DONE

Example 4-6 Create

```
80  U32      sendButton
.
.
.
102 /* create control button
103 if ( CtrlIconEnabled
104     != PPSM_OK )
105     return (PPSM_ERROR)
106
107 if ( CtrlIconEnabled
108     != PPSM_OK )
109     return (PPSM_ERROR)
110
111 if ( CtrlIconEnabled
112     != PPSM_OK )
113     return (PPSM_ERROR)
```




```
        break;
    /* Close keyboard
    case IRPT_ICON:
        if (id == C
            Clos
            break
    /* no more interr
    default:
        break;
    } /* switch */
} /* while */
```

5.2 Handwriting Recognit

The handwriting recognition input row by column format layout (refr

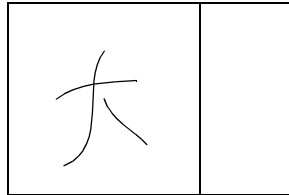


Figure 5-3 An Example I

It serves as an interface between recognition engine. It captures th handwriting input, and passes the processing. (Refer to *Figure 5-4* through the input pad).

Chapter 5 Character Inp

PPSM supports two type input from the user. Ther numeric input, and an inp support any coded langu

This chapter describes th Input Tools provided by P

5.1 Soft Keyboard

A default QWERTY soft any position within the p for upper case letters an letters and symbols (refe layouts by pressing one

1	2	
Q	W	
A	S	
SHIFT	Z	

Figure 5

!	@	:
q	w	
a	s	
SHIFT	Z	

Figure 5

As an alternative, an use column and row in numb defined return keycode a



For both of the above keyboards.
S16) of the pen on the key is also

Only one soft keyboard can be o

5.1.1 Starting Soft Keyboard C

STATUS **OpenSoftKey**(U16

OpenSoftKey() opens the soft, o
keyboard (as shown in *Figure 5-*
upper-left corner position specific
PPSM saves the display area cov
keys automatically. The soft keyt

When the user presses a key on i
be returned to the calling applica
application calls IrptGetData(). (F
IRPT_KEY interrupt message is i
ASCII code returned is of type TE
byte.

Example 5-1 Open soft key

```
118  /* open soft keyboard for in
119  if ( OpenSoftKey(KEYBD_X, KE
120  return (PPSM_ERROR);
```

STATUS **AdvOpenSoftKey**(
keyHeight, U16
bitmap)

AdvOpenSoftKey() opens the so
configurable details.

- Location of the soft keyb
- Width and height of the k
- Number of rows and col
- The return code of each
- The bitmap user interfac

The return codes are defined in a
array is from top left key across t
bottom right key. The contents of
AdvOpenSoftKey() has been call
or it must fit to cover the entire sc
this soft keyboard must be (keyV
number of pixels. For the NULL p
screen.

Example 5-2 Open soft key

```
/* 7, 8, 9, 4, 5, 6, 1, 2, 3, *, (
static const U16 keyMap[] = {55, 56
```

```
/* open user specified soft
/* with 10x10 key size and
/* 7 8 9 */
/* 4 5 6 */
/* 1 2 3 */
/* * 0 # */
if ( AdvOpenSoftKey(KEYBD_
return (PPSM_ERROR);
```

5.1.2 Auto-Key-Repeat

Continually pressing a ke
first and second returned
to be 20. The time durati
AUTO_REPEAT_RATE.
tick. For example, a 32H
sec, then, for every 5/32

5.1.3 Terminating Soft K

STATUS **CloseSoftK**

CloseSoftKey() closes th
or AdvOpenSoftKey(). Pl
soft keyboard automatica

5.1.4 Suspend Soft Keyb

STATUS **ActiveList**

STATUS **ActiveList**

ActiveListPush() pushes
current task into backgro
and soft keyboard of the
that is currently being us
list. For more details, ple

Example 5-3 Display

```
if (rv = OpenSoftKey(S
{
/* error */
return (rv);
}
while (running)
{
switch(IrptGetD
{
/* Any ke
case IRPT
/*
Di
/*
x=
y=
Di
```

Us

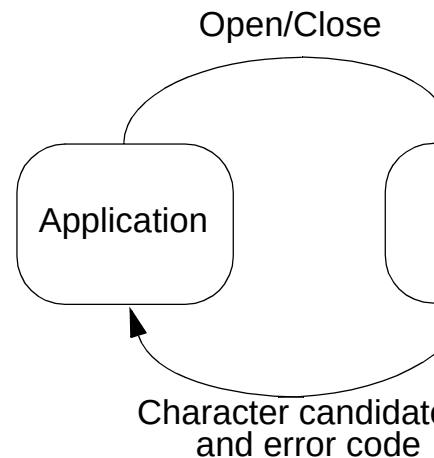


Figure 5-4 Data f

5.2.1 The Input Pad Mech

The user writes a charac
system proceeds to reco
different box, or when a
whichever occurs first. T
entered, independent of
mechanism to determine
(e.g. the user clicks on a

The input pad is a subtas
messages, IRPT_HWR,
recognized. Each individ
IRPT_HWR interrupt me
returns the recognized c
input pad. (Refer to Sect

Only ONE instance of the
parent and sub-tasks). If
attempt to open the input
fail. If the user switches t
in the current task. The h
area is cleaned if the are

5.2.2 Starting Handwritin

STATUS **OpenInput**
U16 are

An application can open



application needs to specify the x and y position of the input pad, the number of rows and columns of the input pad box (in units of pixel). If the input pad is not at the specified location and that the specified layout fits within the screen, the input pad is moved to the specified location ready for use.

The area of the panning screen covered by the input pad when the function is called. Any changes to the input pad when the function is called will not be recognized.

The default length of timeout for the input pad.

STATUS AdvOpenInputPad
numCol, U16 array
echoWidth, U32
stackSize)

AdvOpenInputPad is similar to the OpenInputPad function. It allows the user to configure the following details. It allows the user to:

- position of the input pad
- number of rows and columns of the input pad
- the width and the height of the input pad
- the echo ink colour and the echo width
- the length of time out after the input pad is closed
- the sampling rate of the input pad
- if the system should clear the input pad when a character is written
- the stack size for the input pad

5.2.3 Terminating Handwriting

STATUS CloseInputPad(void)

CloseInputPad() closes the input pad. After the input pad is closed, the OpenInputPad() or AdvOpenInputPad() function will be required to open the input pad. The original image covered by the input pad will be restored. The input pad flag has been set to be 1(TRUE).

Example 5-4 Display character

```
/* open an input pad at location (x, y)
   being 64x64 pixels each
if (rv = OpenInputPad(50, 50,
{
    /* error */
    return (rv);
}
while (running)
{
    switch(IrptGetData((P_USR1 & 0x00000000)))
    {
        /* Any icon press
```

```
case IRPT_ICON:
    /* Code for icon
recognized character
DisplayKeyChar
break;

/* Close keyboard
case IRPT_ICON:
    if (id == 0)
        CL
        break;
    /* no more input
        break;
} /* switch */
} /* while */
```



6.2.2 Screen Resolution

LCD display screen resolution is hardware. This is normally a fixed panel resolution must be equal to cannot point at every pixel of the

6.3 Sample LCD Display S

The following two figures show e hardware platform.

The LCD Display Screen area ha and 320 pixels wide by 200 pixel

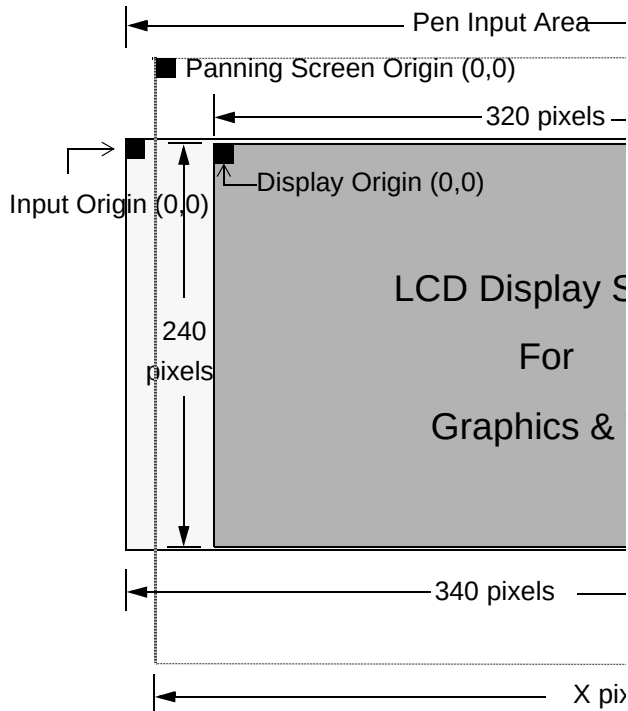


Figure 6-2 320x240 LCD Pane

Chapter 6 Using Graph

PPSM supports LCD mo hardware cursor, hardwa

The Graphics Tools enab

- draw lines and s
- display and man
- swap bitmap ima
- control and resto
- control hardware
- set grey levels
- get information a
- change the pann
- direct all drawing area
- hardware cursor
- allocate memory
- set dot width in p arc and vector
- set pattern fill me
- draw vector by c

This chapter will describ hardware cursor control

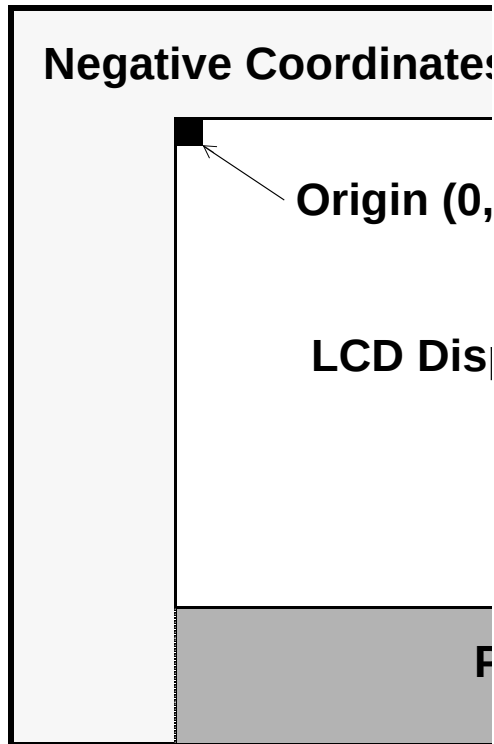


Figure 6-1 Generic Screen Layout

6.1 Display Screen Format

Figure 6-1 shows the general screen layout with three major areas:

- Pen Input Area
- LCD Display Screen
- Panning Display Screen

6.1.1 LCD Display Screen

The Display Screen is the region where the application displays output data. Its size will be 200 pixels high or 320 pixels wide.

The LCD module is capable of 1 bit per pixel and WHITE, LIGHT GRAY, DARK GRAY, and BLACK.

pixel.

The reference coordinate system for the screen is the top-left corner, the Display Origin (0,0). The origin is associated with the LCD Display Screen.

6.1.2 Panning Display Screen

The Panning Screen is a screen that allows applications to pan the LCD display screen. Although applications can pan the LCD display screen unless this area is used for other areas on the panning screen, the panning screen is associated with the LCD display screen.

Panning Screen has a size of 200 pixels by 200 pixels. It has a different origin. It is configured as follows:

- The maximum number of pixels is 200 pixels by 200 pixels.
- In 1 bit per pixel mode, the width and height are divisible by 16 and the maximum of 2048 pixels.
- The height of the screen is 200 pixels that is available for panning.

6.2 Screen Initialization

Because every hardware configuration is different, a calibration procedure is required when initializing the screen. The calibration of the alignment is required for the screen.

Screen initialization is implemented as follows:

Example 6-1 Initialization

```
57 main()
58 {
59     .
60     .
61     .
62     /* Initialize PPSM v
63     PPSMInit(TRUE);
```

6.2.1 LCD Display Screen

The touch panel can be used to pan the LCD display screen. The tools will only return LCD coordinates outside the LCD display screen or even greater than the screen size.



PutRec(), and ClearRec().

The following tables show the gr
is applied.

X is the existing grey level on the
and R is the final grey level on sc

AND_STYLE

Table 6-6 R = >

X	Y
00	00
01	00
10	00
11	00
00	01
01	01
10	01
11	01
00	10
01	10
10	10
11	10
00	11
01	11
10	11
11	11

OR_STYLE

Table 6-7 R =

X	Y
00	00
01	00
10	00
11	00
00	01

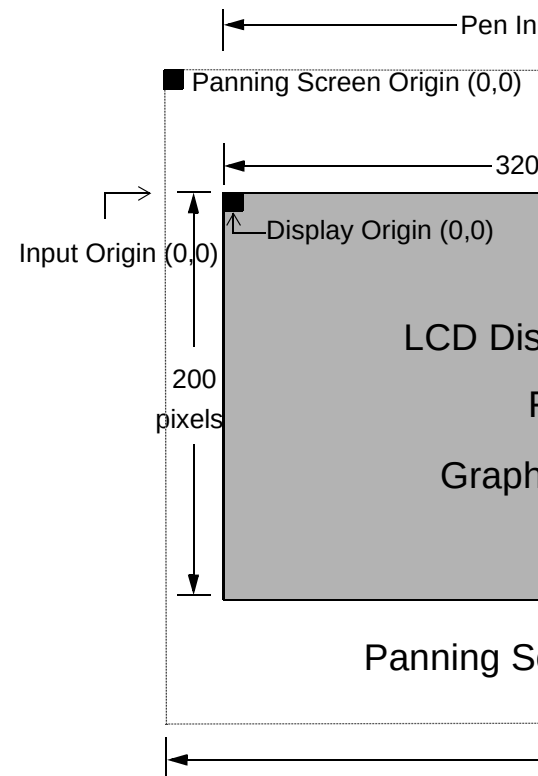


Figure 6-3 320x200

6.4 1 bit-per-pixel G

The graphics routines wi
panning screen.

The byte and bit within b



BLACK (

The above image will be
0x8A88 in hexadecimal.



6.4.1 Drawing Operators

PPSM supports drawing operators: DrawLine(), DrawCircle(), DrawEPutRec(), and ClearRec().

The following tables show the grey level that is applied.

X is the existing grey level on the screen and R is the final grey level on screen.

AND_STYLE

Table 6-1 R = X AND Y

X	Y
0	0
1	0
0	1
1	1

OR_STYLE

Table 6-2 R = X OR Y

X	Y
0	0
1	0
0	1
1	1

EXOR_STYLE

Table 6-3 R = X EXOR Y

X	Y
0	0
1	0
0	1
1	1

REPLACE_STYLE

Table 6-4

X	Y
0	0
1	0
0	1
1	1

INVERT_STYLE

Table 6-5

X
0
1

6.5 2 bits-per-pixel Color

The graphics routine will accept four colors: DARK GREY and BLACK.

The byte and bit within a byte are:



BLACK (11)

LIGHT GRAY (01)

The above image will be stored in memory in binary and 0xD08CC4.

6.5.1 Drawing Operators

PPSM supports drawing operators: DrawLine(), DrawCircle(), DrawEPutRec(), and ClearRec().



6.9 Get Panning Screen V

U16 **GetLogicalX**(void)

GetLogicalX() returns to the caller the current application.

The panning screen width is dynamically recommended to use this tool to purposes.

6.10 Get Panning Screen H

U16 **GetLogicalY**(void)

GetLogicalY() returns to the caller the current application.

The panning screen height is dynamically recommended to use this tool to purposes.

6.11 Set Pattern Fill

STATUS **SetPatternFill**(U16
fillSpace)

This routine allows application programmer. These settings include the pattern, the background grey level, and the fill called, the settings will be applied. DrawEllipse(), and DrawArc().

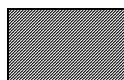
The pattern will be drawn with the DrawRec(), DrawCircle(), DrawE

The argument *fillSpace* lets application between the pattern lines. The si

There are 8 fill patterns available



1



2



5



6

Table 6

X	
01	
10	
11	
00	
01	
10	
11	
00	
01	
10	
11	

EXOR_STYLE

Table 6-8

X	
00	
01	
10	
11	
00	
01	
10	
11	
00	
01	
10	
11	
00	
01	
10	
11	



REPLACE_STYLE

Table 6-9 F

X	Y
00	00
01	00
10	00
11	00
00	01
01	01
10	01
11	01
00	10
01	10
10	10
11	10
00	11
01	11
10	11
11	11

INVERT_STYLE

Table 6-10 R =

X	
00	
01	
10	
11	

6.6 Graphics Tools

The following sections explain ea

Top left corner of the panning sc
Top left corner of the LCD display

origin. All co-ordinates g
screen origin. There is n

Some of the graphics rou
argument in calling the r
drawing 5 dots with spec
Those graphics routines
DrawVert(), DrawLine() a

DrawDot(), DrawHorz(),
DrawEllipse(), DrawArc()
which is described above

For all the following exam
LCD display screen size
(50, 50) from panning sc

6.7 Get LCD Display

U16 GetDisplayX(v

GetDisplayX() returns to
LCD display panel being

When writing an applicat
numbers for the width of
flexible to run on differen

6.8 Get LCD Display

U16 GetDisplayY(v

GetDisplayY() returns to
LCD display panel being

When writing an applicat
numbers for the height o
run on different LCD pan

Example 6-2 Get LCD

```

362 STATUS DrawTextIcon(P
363                     U16 font,
364 {
365
366     U16     xDest, yDe
.
.
.
375     /* Check to see if
376     if ( (xSrc < 0) ||
377         (yDest >= GetDi
378         return PPSM_ERR

```

equals to FALSE to c
screen to the task's c

Example 6-5 Use ChangePa panning screen

```
#include <ppsm.h>
#include <errors.h>
#include <proto.h>

PAN_SCREEN newScreen;

STATUS TestApp()
{
    /* use the common panning sc
    ChangePanning(&newScreen, FA

    /* draw a circle with center
    DrawCircle(BLACK, 100, 100,

}

main()
{
    U32 taskId;
    P_U8 newPanning;

    PPSMInit(FALSE);

    /* create a common panning s
    newPanning = (P_U8)GetScreen

    newScreen.panAddress = (U32)
    newScreen.displayScreenAddr
    newScreen.horzSize = 640;
    newScreen.vertSize = 400;
    newScreen.displayX0Origin = 0
    newScreen.displayY0Origin = 0
    newScreen.regPOSr = 0;
    newScreen.regPSW = 80; /* as
                                PSW

    /* destroy the system panning
    */
    ChangePanning(&newScreen, FA

    /* clear whole panning scree
    ClearScreen(WHITE);

    /* draw a circle with center a
    screen */
    DrawCircle(BLACK, 100, 100,

    /* create a new task with no
    AdvTaskCreate(&taskId, (P_V0I

    TaskStart(taskId);
}
```

In the example above, both the s
the same panning screen. So wh
system task or task TestApp() wi

If a panning screen is shared am
screen in one of the task can als

The pattern fill mode 0 w

6.12 Set Dot Width

STATUS SetDotWid

After this routine is called
DrawDot(), DrawHorz(),
DrawEllipse(), DrawArc()

If the dot width is larger t
thick arc and thick vector

Example 6-3 Set dot

```
160 * Drawing1 - Draw a l
161 *           Both hav
162 *           drawn as
.
.
.
170 SetDotWidth(6, 0);
171 SetPatternFill(2, WH
```

6.13 DisplayMove

STATUS DisplayMo

This function is to set the
screen. It sets the displa
function is called, the new

6.14 Direct All Graphi

STATUS ChangeWi
P_U16 c

Run-time computation in
Users may see the graph
ChangeWindow() allows
routines to an off-screen
on the LCD display scree
generated, it can be disp
that the image is display

ChangeWindow() assum
values are supposed to k

Example 6-4 Use Ch

```
U32 oldScreen1, oldScr
U16 oldWidth1, oldHeig
```



```
U16 oldWidth2, oldHeight2;
U32 tempScreen = (U32)GetScre

/* Direct all graphic routine
   tempScreen with width 64 pi
ChangeWindow(tempScreen, 64, 6

/* This may be any routine for
   be drawn or drawing anythin
DoCalculation();

/* Direct all graphic routine
ChangeWindow(oldScreen1, oldWi
   &oldHeight2);
```

6.15 Change Panning Scre

STATUS **ChangePanning**(P
P_PAN_SCRE

ChangePanning() allows applica
another memory area during run
panning screen is still needed or

P_PAN_SCREEN is a pointer to
elements:

Table 12-11

Name
<i>panAddress</i>
<i>horzSize</i>
<i>vertSize</i>
<i>displayXOrigin</i>
<i>displayYOrigin</i>

Table

Name
<i>displayScreenAddr</i>
<i>regPOSR</i>
<i>regPSW</i>

Upon start-up, *panAddress*
displayXOrigin and *disph*
bits per pixel display or *h*

When DisplayMove() is c
modified so that the syst
position within the word t

When ChangeWindow()
changed so that all graph
and image processing.

If all or several tasks in a
memory, the following st

- 1) In main()
 - call GetScre
 - panning scre
 - call Change
 - for each tas
 - AdvTaskCre
 - the task with
- 2) for each correspo
screen
 - during initial

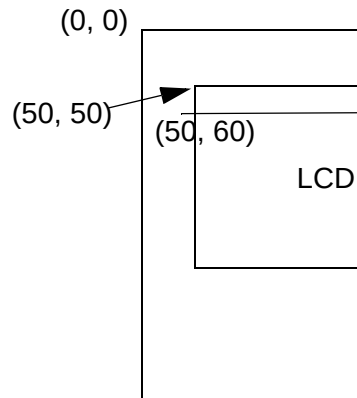


Figure 6-9 Screen

Example 6-12 Draw a thick

```
STATUS ret;

/* set dot width to 4 */
ret = SetDotWidth(4, 0);

if (ret !=PPSM_OK)
return ret;

/* draw a black horizontal line
ret = DrawHorz(BLACK, 60, 60,

if (ret != PPSM_OK)
return ret;
```

In the above example, a thick ho

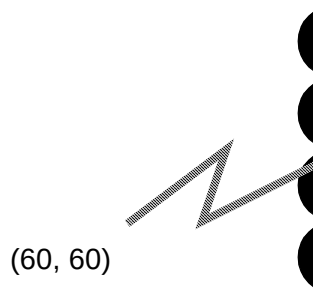


Figure 6-10 Screen

6.19 Draw a Vertical Line

```
STATUS DrawVert(U16 grey
dotLine, U16 sty
```

This routine will draw a vertical li

6.16 Fill the whole Pa

STATUS ClearScre

This routine will fill the w

Example 6-6 Fill the

```
STATUS ret;

/* fill the whole pann
ret = ClearScreen(WHIT
```

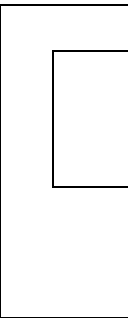


Figure 6-11

6.17 Draw a Dot

STATUS DrawDot(L

This routine will draw a c

If dot width is 1, a pixel w
be drawn with top left pix
the dot width is greater th
value of (dot width - 1)/2
ordinate, (xPos, yPos).

Example 6-7 Draw a

```
STATUS ret;

/* draw a dot at (52,
ret = DrawDot(BLACK, 5
```

The calling of DrawDot(E
panning screen. As the L
on screen is at (2, 2) in c
have a dot which is very

Example 6-8 Draw a

```
STATUS ret;
```

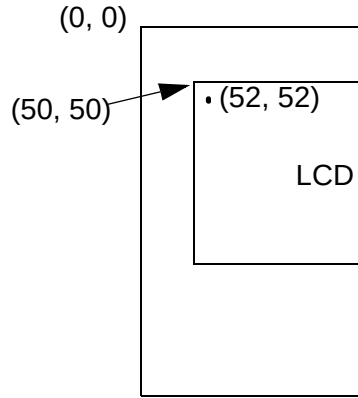


Figure 6-5 Sc

```
/* set dot width to 2 */
SetDotWidth(2, 0);

/* draw a dot at (52, 52) */
ret = DrawDot(BLACK, 52, 52, R
```

When the dot width equals 2, a s

(52, 52)

Figure 6-6 Sc

Example 6-9 Draw a dot wit

```
STATUS ret;

/* set dot width to 3 */
SetDotWidth(3, 0);

/* draw a dot at (52, 52) */
ret = DrawDot(BLACK, 52, 52, R
```

When the dot width is 3, a circle
drawn.

(52, 52)

Figure 6-7 Sc

Example 6-10 Draw a dot w

```
STATUS ret;
```

```
/* set dot width to 4 */
SetDotWidth(4, 0);

/* draw a dot at (52, 52) */
ret = DrawDot(BLACK, 52, 52, R
```

When the dot width is 4, a circle
drawn.

(52, 52)

Figure 6-8 Sc

6.18 Draw a Horizontal Line

STATUS DrawHorz(STATUS dotLine,

This routine will draw a horizontal line.

If the dot width is greater than the line width, the line is truncated of (dot width - line width) lines below it. The length of the line is 2 pixels to the left of the starting point.

If the width of the horizontal line is 0, the line is not drawn.

Example 6-11 Draw a horizontal line

```
STATUS ret;

/* draw a black horizontal line */
ret = DrawHorz(BLACK, 52, 52, R
```

In this example, the dot width is 0, REPLACE_STYLE) will be used on panning screen. Only the line is displayed.



Example 6-17 Draw a recta

```
STATUS ret;

/* draw a black rectangle with i
   at (500, 400) */
ret = DrawRec(BLACK, 310, 250,
```

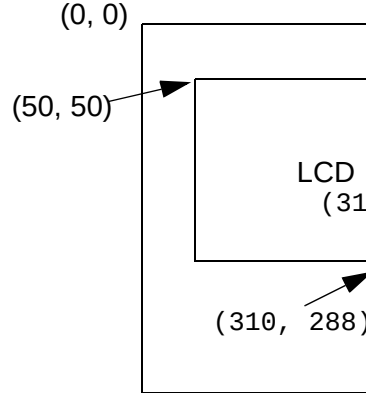


Figure 6-15 Sc

In this example, the dot width is 1
400, 0, REPLACE_STYLE) will d
and bottom right corner at (500, .
horizontal line from (310, 250) to
(310, 289) will be seen on the LC

Example 6-18 Draw a recta fill pattern mode 1

```
STATUS ret;

/* set dot width to 3 */
ret = SetDotWidth(3, 0);

if (ret !=PPSM_OK) return ret;

/* set pattern fill mode to 1
ret = SetPatternFill(1, WHITE,

if (ret !=PPSM_OK) return ret;

/* fill a rectangle from top l
ret = DrawRec(BLACK, 310, 250,
```

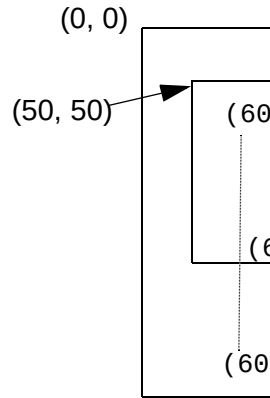
If the dot width is greater
truncated of (dot width - .
at right. The height of ea
pixels above the source

If the height of the vertic

Example 6-13 Draw a

```
STATUS ret;

/* draw a black vertic
ret = DrawVert(BLACK,
```



Figure

In this example, the dot v
REPLACE_STYLE) will
screen. However, only th
which is (60, 60) to (60, 2
drawn in the form of 2 BL
pixels, and so on.

Example 6-14 Draw a

```
STATUS ret;

/* set dot width to 4
ret = SetDotWidth(4, 0);

if (ret !=PPSM_OK)
return ret;

/* draw a black thick
ret = DrawVert(BLACK,

if (ret != PPSM_OK)
return ret;
```



In the above example, a thick ver

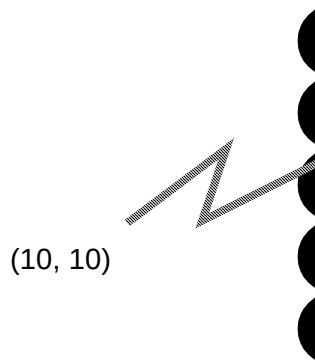


Figure 6-12 Sc

6.20 Draw a Line

STATUS **DrawLine**(U16 gre,
yDest, U16 dotL

This routine will draw a line from

If dot width is greater than 1, eac
a thick square dot. Each of the th
truncated (dot width - 1)/2 pixels
pixels to the left and (dot width)/2
line is then generated by overlap

Example 6-15 Draw a black

```
STATUS ret;

/* draw a black line from (60,
ret = DrawLine(BLACK, 60, 240,
```

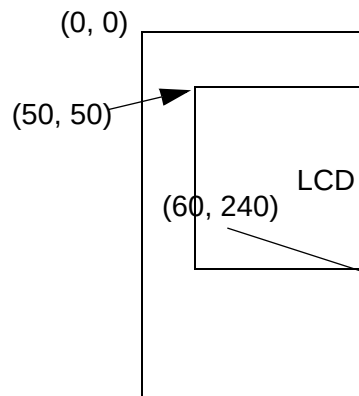


Figure 6-13 Sc

In this example, the dot v
470, 0, REPLACE_STYL
panning screen. Howeve
be seen.

Example 6-16 Draw a

```
STATUS ret;

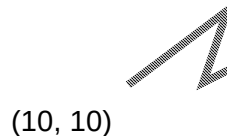
/* set dot width to 4
ret = SetDotWidth(4, 0

if (ret !=PPSM_OK)
return ret;

/* draw a black thick
ret = DrawLine(BLACK,

if (ret != PPSM_OK)
return ret;
```

In the above example, a



Figure

6.21 Draw a Rectangle

STATUS **DrawRec**(U
yDest, U

This routine draws a rect
corner at (xDest, yDest).

If the dot width is greater
inside the rectangle and

If both fill pattern mode a
which is not covered by r

If fill pattern mode is set
rectangle border will be f

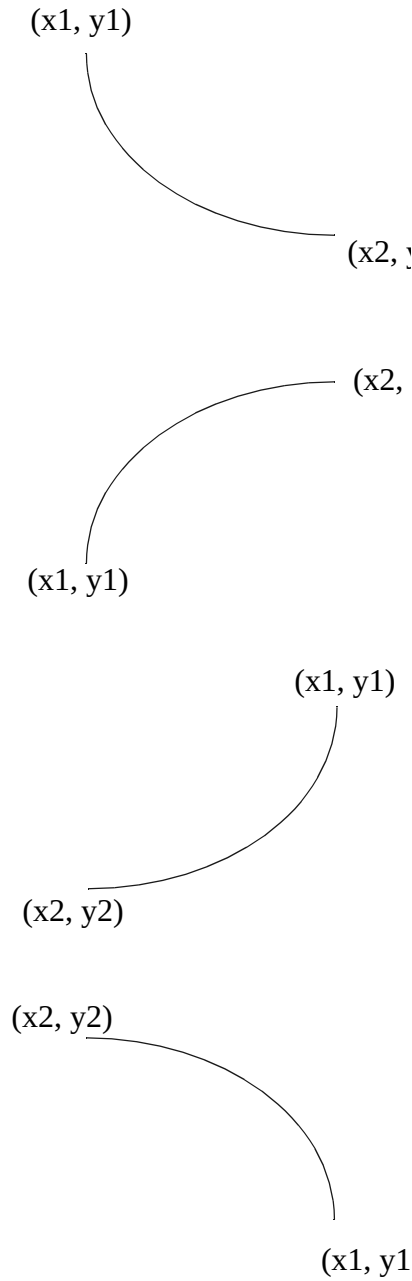
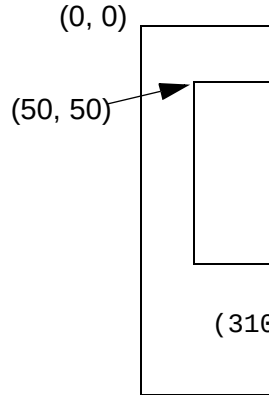


Figure 6-19 Cases

If the dot width is greater than 1, i
inside the arc and (dot width)/2 li

If both fill pattern mode and bord
not covered by the border of the

If fill pattern is set and border is o
filled.



Figure

In this example, the dot v
DrawRec(BLACK, 310, 2
with top left corner at (30
screen. However, only a
will be seen on the LCD

6.22 Draw a Circle

STATUS DrawCircle
U16 styl

This routine will draw a c
radius and grey level.

If the dot width is greater
inside the circle and (dot

If both fill pattern mode a
which is not covered by l

If fill pattern mode is set
border will be filled.

Example 6-19 Draw a

```
STATUS ret;  
  
/* draw a black outline  
ret = DrawCircle(BLACK
```

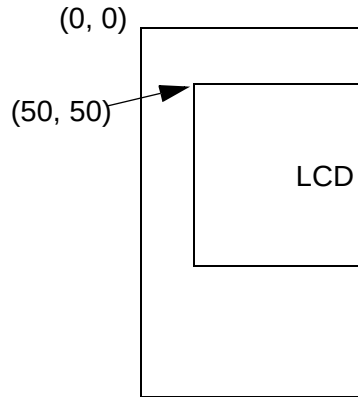
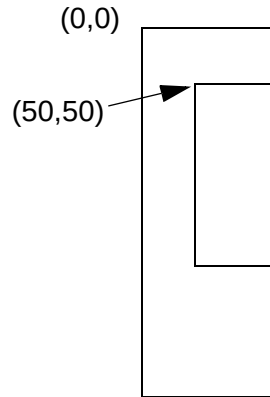


Figure 6-17 Sc

In this example, the dot width is :
150, REPLACE_STYLE) will draw
As the circle is drawn outside the
LCD.



Figure

In this example, the dot v
150, 100, REPLACE_ST
longest distance on y ax
distance on x axis from c

6.23 Draw an Ellipse

STATUS **DrawEllipse**(U16 c
xLength, U16 yL

This routine will draw a ellipse ce
size.

If the dot width is greater than 1, i
inside the ellipse and (dot width),

If both fill pattern mode and bord
is not covered by the border will

If fill pattern mode is set and bord
border will be filled.

Example 6-20 Draw an ellip

```
STATUS ret;

/* draw an ellipse with center
   length 100 */
ret = DrawEllipse(BLACK, 560,
```

6.24 Draw an Arc

STATUS **DrawArc**(L
style)

This routine will draw an

DrawArc() will draw a qu
DrawArc(BLACK, x1, y1,
will be drawn according t



The following will be seen on LC

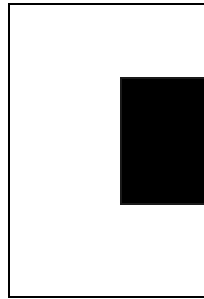


Figure 6-25 Sc

Example 6-26 When LCD Di
ary of the panning scree

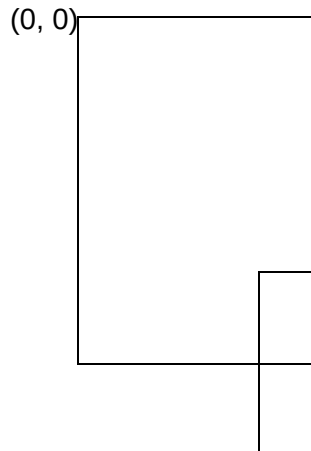


Figure 6-26 Scr

The following will be seen:

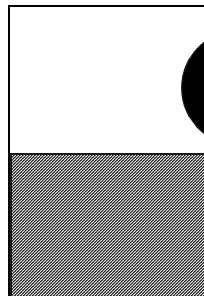
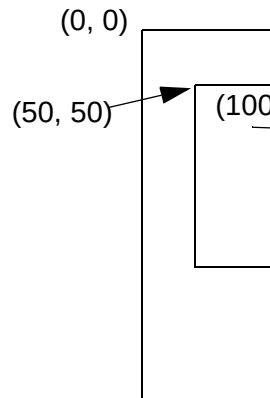


Figure 6-27 Sc

The pattern of the noise part of th
that follows the panning screen.
0, the noise will appear as a blan

Example 6-21 Draw a

```
STATUS ret;  
  
/* draw an arc from (2  
ret = DrawArc(BLACK, 2
```

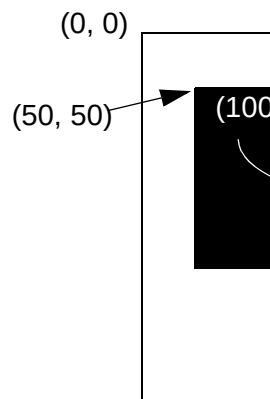


Figure

In this example, the dot v
50, OR_STYLE) will draw
The arc is actually a qua
distance of 141 pixels in
center is determined by r
of the first point which is

Example 6-22 Draw a

```
/* draw an arc from (3  
ret = DrawArc(BLACK, 3
```



Figure

In this example, the dot v
the calling of DrawArc() i
a black background.



6.25 Draw a Vector from a

STATUS **DrawVector**(U16 *g*
pointPtr, U16 *sty*)

This routine will draw lines to cor
whether the first point and last po

6.26 Put a Rectangular Are

STATUS **PutRec**(P_U8 *bitm*
U16 *style*, U16 *r*)

This routine puts an image from

PutRec() supports style such as
and AND_STYLE. There is error
the value of *bitmap*.

Example 6-23 Put a bitmap

```
/* put an image on panning scr
height 480 */
ret = PutRec(bitmap, 0, 0, 640
```

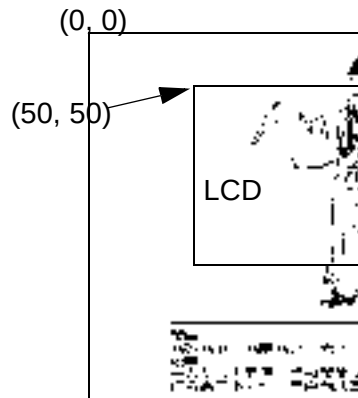


Figure 6-22 Sc

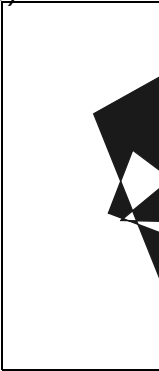
The calling of PutRec(bitmap, 0,
image from the memory area poi

6.26.1 Special cases of Pu

The following are the fev

Example 6-24 Displa setting

Two similar images will b
(0, 0)



Figure

Example 6-25 LCD D panning screen

(0, 0)

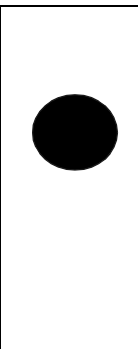


Figure 6



```
/* set hardware cursor width t
CursorInit(15, 15);

/* turn on the hardware cursor
CursorSetStatus(PPSM_CURSOR_ON
```

The above will create a cursor at
and will turn the cursor on.

6.31.2 Set Hardware Cursor Pos

```
STATUS CursorSetPos(U16
```

This routine will set the hardware

**Example 6-32 When the har
other position:**

```
/* set hardware cursor positio
CursorSetPos(15, 150);
```

This will change cursor to new p

6.31.3 Set Hardware Cursor Stat

```
STATUS CursorSetStatus(l
```

This routine will change the hard
PPSM_CURSOR_OFF, PPSM_C
PPSM_CURSOR_REVERSED.

Table 6-1

Status name
PPSM_CURSOR_OFF
PPSM_CURSOR_ON
PPSM_CURSOR_REVERSED

**Example 6-33 When hardw
it needs to be on with re**

```
U16 x, y;

/* turn on hardware cursor in
CursorSetStatus(PPSM_CURSOR_RE
```

6.31.4 Get Hardware Cursor Sta

```
STATUS CursorGetStatus(l
```

This routine will return the curren
of the following states: PPSM_C

memory is invalid, a bus

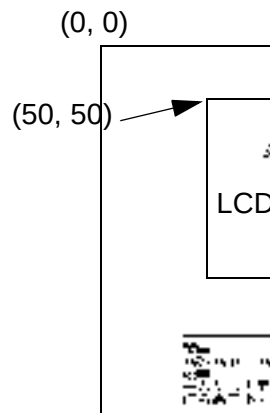
6.27 Save a Rectangu

```
STATUS SaveRec(P  
U16 res
```

This routine saves an im

Example 6-27 Save a

```
/* save the portion of  
width 320 and h  
ret = SaveRec(bitmap,
```



Figure

The calling of SaveRec(l
display image into memo

6.28 Exchange a Rec

```
STATUS Exchangel  
rese
```

This routine exchanges i

Example 6-28 Save a

```
/* exchange the image  
and height 120  
ret = ExchangeRec(bitm
```

This example swaps the
rectangular region from t
169). After this call, *bitm*
region (50, 50) to (369, 1
displayed on the rectang



6.29 Fill a Rectangular Area

STATUS **ClearRec**(U16 *grey*,
height, U16 *style*)

This routine fills a rectangular area

Example 6-29 Fill a rectangular area

```
STATUS ret;  
  
/* fill a rectangular area with  
   161 */  
ret = ClearRec(BLACK, 300, 240
```

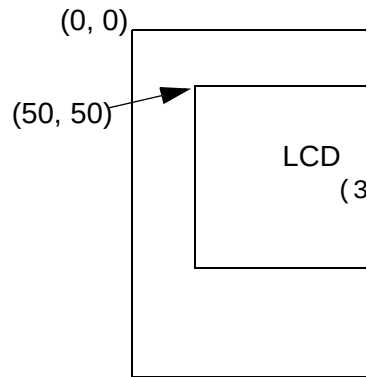


Figure 6-29 Sc

This example fills the rectangular area of the panning screen with width 261 pixels

6.30 Inverse a Rectangular Area

STATUS **InvRec**(U16 *xSrc*, U16 *ySrc*, U16 *width*, U16 *height*)

This routine will inverse the grey level of the area at (xSrc, ySrc) and bottom right corner

Example 6-30 Inverse a rectangular area

```
STATUS ret;  
  
/* inverse a rectangular area with  
   height 100 */  
ret = InvRec(250, 200, 200, 10
```

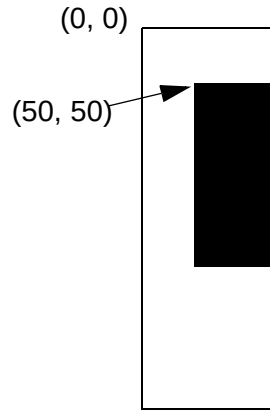


Figure 6-30 Sc

In this example, the LCD screen is white. After invoking the routine, the screen is black. The routine is 200) and 200 pixels wide. The routine is 200) and 200 pixels wide. The routine is 200) and 200 pixels wide.

6.31 Hardware Cursor

When there is no hardware cursor, the application requires to set the cursor status. The routine is CursorSetStatus(PPSM_

When hardware cursor is enabled, the application should call CursorOff(). If the hardware cursor is enabled, the application has to set the cursor character. The routine is CursorSetStatus(PPSM_

When hardware cursor is disabled, the application should call CursorSetStatus(PPSM_

A application can change the hardware cursor status from the application by calling of functions to change the hardware cursor status. The routine is CursorSetStatus(PPSM_

6.31.1 Set Hardware Cursor

STATUS **CursorInit**(U16 *width*, U16 *height*)

This routine will change the hardware cursor status from the application by calling of functions to change the hardware cursor status. The routine is CursorSetStatus(PPSM_

Example 6-31 When hardware cursor is enabled

```
/* set hardware cursor  
CursorSetPos(150, 158)
```



Table 7-1 Predefined fie

Field Index	
DB_COMPANY	Co
1,2,3,4,5	5 a

7.1.2 Unformatted Data

Unformatted data is data that has only one unformatted data field a one of the following eight types c

- type 0 text (ASCII code
- type 1 decompressed F
- type 2 compressed PP
- type 3 mixed text and g
- type 4 reserved
- type 5 text followed by
- type 6 text followed by
- type 7 text followed by

PPSM will keep track of the size record information field.

7.2 The Database Manipu

PPSM provides a set of tools to c they can be grouped together in

- 1) Operate at the database
 - Add or delete a data
 - Inquire the total num environment.
 - Set or clear the data
 - Interrogate the data
- 2) Operate at the individual
 - Add or delete a reco
 - Add a blank record t
 - Append a blank reco
 - Write or read format
 - Write or read unform
 - Get the ID of the firs
 - Get the ID of the pre
 - Search for a record i
 - Set or clear the reco
 - Interrogate the recor
 - Inquire the total num

PPSM_CURSOR_REVE

Example 6-34 When

```
U16 status;  
  
/* get the hardware c  
CursorGetStatus(&stat
```

6.31.5 Set Hardware Curs

STATUS CursorSet

This routine will set the h of blinks per 10 seconds

6.31.6 Turn Hardware Cur

STATUS CursorOff

This routine will turn off t hardware cursor again, t and follows by calling Cu

6.32 Display Other Re

STATUS CursorSet

STATUS LCDScreen

These two routines toget different regions of the p two routines must be use replaced by DisplayMove

Example 6-35 Displa

```
U16 x=50, y=50;  
  
/* set the LCD display  
CursorSetOrigin(x, y);  
  
/* change the hardware  
top left corner  
LCDScreenMove(x, y);
```

The LCD Display screen screen with top left corne

6.33 Get LCD Display

STATUS CursorGet

This routine will return th



panning screen.

Example 6-36 Get LCD disp

```
U16 x, y;  
  
/* get the position of LCD dis  
CursorGetOrigin(&x, &y);
```

6.34 Allocate memory for F

P_VOID GetScreenMem(U1

This routine will allocate memory
the size of the new panning scre
is available, it will return NULL.

Example 6-37 Allocate men

```
P_U8 screenPtr;  
  
/* allocate memory for panning  
screenPtr = (P_U8)GetScreenMem
```

Chapter 7 Database Ma

PPSM supports global d
type may be formatted o

The Database Tools ena

- create and delet
- add and delete r
- store, retrieve ar
- search for partic
- get status about

This chapter gives some
getting up to speed fast.
power reset, all databas
to save the database inf

7.1 Data Format

PPSM database tools su

7.1.1 Formatted Data

Formatted data means t
in *Table 7-1*, will be usec
predefined. Other Forma
need arise. When a new
seven by default. PPSM
record. The number of m
PPSM at compile time, c
Formatted Data, not Unf

There is a size limit of 60

Table 7-1 Predet

Field Index
DB_LAST
DB_FIRST
DB_HOME
DB_OFFICE
DB_ADDRESS
DB_FAX



database.

7.3 Creating and Ed

Whenever a record is cre
Application will need to u
particular record.

The following example ill
memory variables which
formatted data field in a

Note that user must have
calling DBAdd(). It is imp
access to the database r

Note also that in the exa
creation of the next reco
because of the linked list
retrieve the record that w
ID. However, for those fr
memory variable to keep

Example 7-1 Create a n number of records

```
/* Database identifier
U32 gAddBkDBaseID;
/* Data to be wr
TEXT grec1LName[5]={ 'A
TEXT grec1FName[4]={ 'K
TEXT grec1Phone[9]={ '2
TEXT grec1Add[17]={ '1

/* Data to be wr
TEXT grec2LName[8]={ 'A
TEXT grec2FName[4]={ 'J
TEXT grec2Phone[9]={ '6
TEXT grec2Add[17]={ '1

STATUS buildDBase
{
    STATUS ret;
    U32 recID;
    S32 numRec;

    ret = DBAdd(&gAc
    if(ret != PPSM_C
        /* Add Rec
        DBAddRecord(gAc
        DBChangeStdData
        DBChangeStdData
        DBChangeStdData
        DBChangeStdData

        /* Add Rec
        DBAddRecord(gAc
        DBChangeStdData
        DBChangeStdData
        DBChangeStdData
        DBChangeStdData
        /* Read bac
```



```
DBReadTotalNumberRecord
}
```

7.4 Searching and Retrieval

The following example uses the `DBSearchData` function to search for a particular record. It is a good programming practice to check the return value of `DBSearchData` ensuring that a match is found before proceeding with the next operation.

Example 7-2 Search a database and retrieve record data

```
/* Global database identifier
U32 gAddBkDBaseID;
/* This is the search key */
TEXT grec1FName[4]={'K','e','n','n'}
STATUS searchRec(void)
{
    STATUS ret;
    U32 recID;
    /* Pointers to the formatted data field
    P_TEXT tempLname, tempFname;

    /* Search for a record in the database
    ret = DBSearchData(gAddBkDBaseID, grec1FName, tempLname, tempFname);

    if (ret != PPSM_OK) return ret;
    /* recID now is the record ID
    /* We can now access the record data
    DBReadData(gAddBkDBaseID, recID, tempLname, tempFname);
    DBReadData(gAddBkDBaseID, recID, tempLname, tempFname);
    DBReadData(gAddBkDBaseID, recID, tempLname, tempFname);
    /* tempLname, tempFname, tempMname, tempDname,
    data field stored in tempDataOut;
    } /* end searchRec() */
```

```
STATUS ret;

/* Get the first record
ret = DBGetFirstRecord(gAddBkDBaseID, &recID, &tempDataOut);

/* Check if the data was found
if (ret == PPSM_ERROR) return ret;

/* Read back data
DBReadData(gAddBkDBaseID, recID, tempLname, tempFname);
.
/* Do something here
.
/* Get next record
while(srchToken)
{
    DBGetNextRecID(gAddBkDBaseID, &recID, &tempDataOut);
    /* The RecID pointer is now the next record ID
    if(botFlag == 1)
    /* Read back data
    DBReadData(gAddBkDBaseID, recID, tempLname, tempFname);
    .
    /* Do something here
    .
    /* Continue searching
    RecId = nextRecID;
} /* end while loop
} /* end of seqAccessofRec() */
```

7.5 Navigating along a Record

The following example uses the `DBGetNextRecID` function to navigate sequentially. It is assumed that a record already existed. Initially, the first while loop is set up to access records by using the `botFlag` passed to the function. If `botFlag` is set to 1, it signifies that the current record is the first record in the database.

Example 7-3 Use the record list to navigate sequentially

```
/* Global database identifier
U32 gAddBkDBaseID;

STATUS seqAccessofRec(void)
{
    U32 RecId,nextRecId;
    S32 srchToken = 1;
    U16 botFlag = 0;
    P_TEXT stdDataOut;
```

8.4.2.1 Text output style

The output style defines an oper: image at a specified display loca bitmap can replace, OR with, AN replace the existing image.

Table 8-1 Supported

Output Styles	
REPLACE_STYLE	Re
OR_STYLE	Or
AND_STYLE	An
EXOR_STYLE	Ex
INVERSE_STYLE	Inv

8.4.2.2 Text Grey Levels

Depending on the hardware syst supported. For details about the *Graphics* and *Section 6.5 - 2 bits*

Table 8-2 Supported

Grey Level Values	
BLACK	Bla
DARK_GREY	Da
LIGHT_GREY	Lig
WHITE	Wh

8.4.3 Setting Font Attributes

STATUS **TextSetFont**(U32 t

Font attributes includes font type (e.g. outline) that's related to a p.

A font attribute data structure, ca desired values in order for these attributes will take effect when te these new values set. The follow ppsm.h:

```
typedef struct
{
    U16      type;
    U16      width;
    U16      height;
    U16      attrib;
```

Chapter 8 Text Display

Applications must map th an area on the display so seen. This chapter descr the display of text on the

PPSM supports 16-bit te coded languages. The d Asian and English chara scalable and bitmap font fonts with size 8 x 10 and ISV.

8.1 Text Representa

Both ASCII and Asian ch TEXT) system-wide. For Chinese, both GB and B

The most significant byte zero-extended ASCII and most significant byte whi byte.

8.2 Text Display Are

Text can be displayed an 2.3.2.2 - *Panning Screen* row by column format on

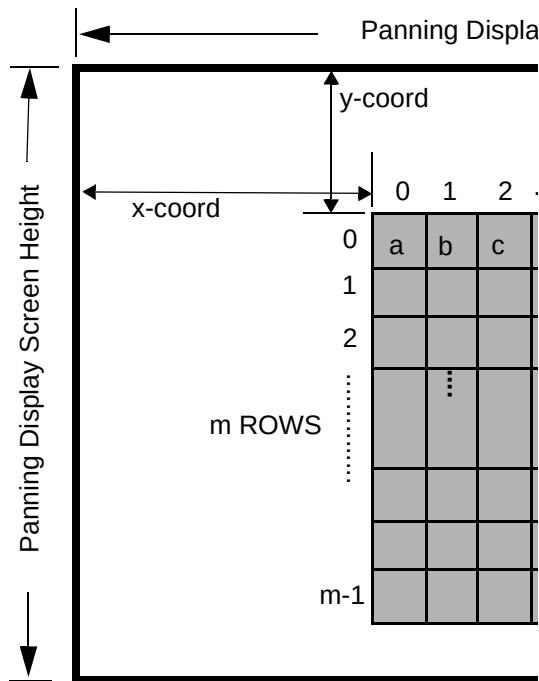


Figure 8-1 A Text Display

8.3 Text Templates

A text template refers to a collection of text properties displayed. These text properties include style, coordinates and size of the cursor. These text templates are flexible for applications to change in an efficient manner. Applications can, at their discretion, on an as-needed basis, use a cursor indicator showing where the text

8.3.1 Creating text templates

`STATUS TextCreate(P_U32`

A text template needs to be created. An unsigned 32-bit text template identifier is created. This text template identifier is the created text template. Refer to the text template properties when a text template is

Example 8-1 Create a text template

```
336 U32 tId; /* textId for the
337
338 if(TextCreate(&tId) != PPSM_
```

```
339 return PPSM_ERROR;
340
```

8.3.2 Deleting text templates

`STATUS TextDelete`

When a text template is deleted, the up space that is being used is returned by `TextCreate()`.

Example 8-2 Delete a text template

```
352 /* Delete the text v
353 if(TextDelete(tId) !=
354 return PPSM_ERROR;
```

8.4 Text Properties

Text properties describe the panning display screen. The text template, include the position of the text characters, the font size, the text display area. Refer to the text display area of a text template when it

8.4.1 Setting Text Display

`STATUS TextSetDisplay`
`U16 height`

The text display layout of the panning display screen. The boundary of the panning display screen, the upper left corner, and the number of characters. The size of the text display area is related to the size of the selected text display area. The range of 0 and one less than the number of characters can display.

In *Figure 8-1*, the text display area is 3 columns in size. This text display area is what the user wishes.

8.4.2 Setting Text Outlook

`STATUS TextSetOutlook`

The text outlook of a text template. The text template to be displayed on the text display area. The text template take effect on subsequent text display. The text template modified.



8.6 Text character cursor

The character cursor position de
will be displayed next. This posi
specified in the given text templa
through one less than the size of

In *Figure 8-1*, the range of valid c
the current cursor position is 3 at

8.6.1 Setting the character curs

STATUS **TextSetCursor**(U32

Setting the character cursor posi
template to the given value. Sub:
character cursor position.

Example 8-5 Set character

```
53 static U32 gTextId, gTmpTextId
.
.
.
279 /* Clear the text on
280 TextUnmap(gText
281 TextSetCursor(g
```

8.6.2 Reading the character cu

STATUS **TextReadCursor**(L

Applications can inquire the curre
specified by a text template. The
will be displayed next.

Example 8-6 Set and read t

```
U32 tId; /* text tem
TEXT moto[] = {'M', 'o', 't',
*/
U16 len; /* # chars to be
U16 curPos; /* cursor positio
.
.
.
/* create a text template */
TextCreate(&tId);

/* calculate # chars to be dis
len = Strlen(moto);

/* set up text properties. */
TextSetup(tId, LARGE_NORMAL_FO

/* set current character cursor
*/
TextSetCursor(tId, len);

/* display "Motorola" using th
```

P_U8

bi

} FONTATTR, *P_FONTATT

8.4.3.1 Font Types

Eight font types are supp
English fonts. Large Nor
Normal is 16 x 16 Chine
as GB Normal (for backv
in BIG5 code format. BIG

Table 8-3 Support

Output Styles
SMALL_NORMAL_FONT
SMALL_ITALIC_FONT
LARGE_NORMAL_FONT
LARGE_ITALIC_FONT
GB_NORMAL_FONT
CHINESE_NORMAL_FO
BIG5_NORMAL_FONT
BIG5_VARIABLE_FONT

Note: Asian fonts

8.4.3.2 Font Sizes

If a scalable font engine
an application to specify
template. The minimum
particular scalable font e

All the other font types a
and height of those font

8.4.3.3 Special font a

No other special font attr
modify the font attributes

reserved for future extensions are

Table 8-4 Text

Text Properties
(x,y)-coordinate of the origin (top left text display area)
Width of text display area in number of characters
Height of text display area in number of lines
Character cursor position relative to display area
Font type
Font width
Font height
Special font attributes
Text grey level value
Text output style

Example 8-3 Setting text pr

```

U32      tId;                                /* t */
                                                /* t */
TEXT     moto[] = {'M', 'o', 't', 'o', 'r', 'i', 's', 't', 'i', 'c', 's'};
                                                /* t */
                                                2
U16      len;                                /* # */
FONTATTR fontAttr;                          /* f */
.
.
.
/* create a text template */
TextCreate(&tId);

/* calculate # chars to be displayed */
len = Strlen(moto);

/* subsequent text displayed with the
   length of moto character:
   position zero. */
TextSetDisplay(tId, 102, 0, len);

/* subsequent text displayed with the
   the existing image on screen */
TextSetOutlook(tId, EXOR_STYLE);

/* set up font attributes */
fontAttr.type = BIG5_VARIABLE;
fontAttr.width = fontAttr.height;
fontAttr.attrib = 0;

/* subsequent text displayed with the
   type of size 20x20 pixel */
TextSetFont(tId, &fontAttr);

/* delete unused text template */

```

```
TextDelete(tId);
•
•
•
```

8.5 Text Mapping

Mapping functions are provided for mapping display screen area to a template.

8.5.1 Displaying text

STATUS TextMap(U

The given text is displayed
character cursor position
described by the specified

There is no word-wrap function for characters of a word that do not fit in the text display area. Text display area ends at the end of the text display area, or when *numC* is mapped, or when *numC* is on panning screen, character is available position, or (the character is at the end of the template) without returning any error.

Example 8-4 Display

```

333 STATUS DisplayString(
334 {
335     U16 len; /* length
336     U32 tId; /* textId
337     .
338     .
339     .
340
341     /* get the string length
342     if (len = Strlen(string))
343     {
344         /* Set up the text
345         if(TextSetup(tId, string, len))
346             return PPSM_ERROR;
347
348         /* Map the text
349         if(TextMap(tId, string, len))
350             return PPSM_ERROR;

```

8.5.2 Removing text

STATUS TextUnmap

The unmapping of text m and size of the text display template.

```
TextMap(tId, (P_TEXT)m)

/* read current character
   case) */
TextReadCursor(tId, &
.
.
.
```

```
TextReadCursor(tId, &c)
.
```

9.4 Setting Clock Alarm

9.5 Clearing Clock Alarm

9.6 Setting Periodic Alarm

RTC_PERI_NONE	Dis
RTC_PERI_SECOND	Se
RTC_PERI_MINUTE	Min
RTC_PERI_HOUR	Ho
RTC_PERI_MIDNIGHT	Mi



Chapter 9 Timer Manag

PPSM uses one Dragon reference timer and the s microseconds and the sy tools are included for app alarm, clock alarm and ti

PPSM manages all the ti specific time-out or alarm appropriate alarm time o interrupt to notify the app

The system default time

Two types of interrupt me

- IRPT_RTC
- IRPT_TIMER

IRPT_RTC message is s

IRPT_TIMER message i

If the timeout or alarm ha alarm task, the timer or a current task are handled

9.1 Reading System

STATUS DateTimeR
P_U16 /

Read the system date and

9.2 Setting System

STATUS DateTimeS
U16 sec

Set the system date and

9.3 Reading Clock A

STATUS AlarmReac
P_U16 /



RTC_PERI_NO_SECOND

RTC_PERI_NO_MINUTE

RTC_PERI_NO_HOUR

RTC_PERI_NO_MIDNIGHT

9.7 Setting Timeout

STATUS Timeout(U

STATUS TimeoutId

General time-out tool. PR
caller once the time-out
immediately disable the
timeout set by reference
which will be returned in

IRPT_TIMER is the inter
occurs.

9.8 Setting Input Tim

STATUS InputTimee

Set the repetitive time-ou
routine is an explicit time

Once this time-out is acti
immediately after a valid
next pen input occurs, P
otherwise, the time-out p
time-out because once a
after each pen input stok

IRPT_TIMER is the inter
returned in IrptGetData()
timer set by Timeout(), T

To cancel the input time-
argument.



9.9 Continuous Reference

PPSM provides a continuous 32-value wraps around about every condition, making it transparent to either a resolution of 1 millisecond tools allow the user to make use stamping and time-out.

Note that there are two sets of timer 100 microsecond resolution. The sets of tools should NOT be mixed. The 100 microsecond resolution tools cannot be used in the 100 millisecond resolution timer.

The millisecond resolution timer is used for the 100 microsecond resolution tools.

9.10 Read The Reference Timer

U32 RefTimeRead(void)

U32 RefFineTimeRead(void)

Read the reference timer value. The function returns the current reference timer value, as returned by RefTimeRead(), or in 100 microsecond resolution.

9.11 Set Reference Timer / Alarm

STATUS RefTimeAlarm(U32 time)

STATUS RefFineTimeAlarm(U32 time)

STATUS RefTimeAlarmId(PID alarmId)

STATUS RefFineTimeAlarmId(PID alarmId)

Set the alarm time, using the reference timer. When using this tool, the input time will generate an alarm interrupt to the user. The alarmId output from this function: alarmId is reached.

9.12 Compute Reference Time Difference

U32 RefTimeDiff(U32 begin, U32 end)

U32 RefFineTimeDiff(U32 begin, U32 end)

Compute the difference in time between two reference timer values. The difference is in millisecond resolution. The function returns the difference in time as RefFineTimeDiff().

Example 9-1 Timer Management

```

U32      (*TimeRead)();

STATUS   (*TimeAlarm)(U32 time);
U32      (*TimeDiff)(U32 begin, U32 end);

/*
 * RefTimer
 */
STATUS   RefTimer(void)
{
    /*
     * Initialize the reference timer
     */
    gOldTime = 0;
    gNewTime = 0;
    gDiffTime = 0;

    /*
     * Set up the reference timer
     * to start the timer
     */
    if (gUnit == MILLI_SECONDS)
    {
        /*
         * Assign the reference timer function
         */
        TimeRead = RefTimeRead;
        TimeAlarm = RefTimeAlarm;
        TimeDiff = RefTimeDiff;
    }
    else if (gUnit == MICRO_SECONDS)
    {
        TimeRead = RefFineTimeRead;
        TimeAlarm = RefFineTimeAlarm;
        TimeDiff = RefFineTimeDiff;
    }
    SetUnit(MILLI_SECONDS);

    if (*inData == 1)
    {
        /*
         * Start the reference timer
         */
        if (id == 1)
        {
            /*
             * Start the reference timer
             */
            gOldTime = TimeRead();
            gNewTime = TimeRead();
            gDiffTime = TimeDiff(gOldTime, gNewTime);
            DisarmAlarm(id);
        }
        /*if ready to start the reference timer*/
    }
}
/*while*/
}/*RefTimer*/

```



are driven by the system clock, p
without sacrificing peripheral res

Chapter 10 Memory Man

11.2 Power Modes

Figure 11-1 shows the state diag
defined in PPSM.

System Internal Modes:

- Initialization mode
- System mode
- Wake-up mode

Application Modes:

- Normal mode
- Doze mode
- Sleep mode

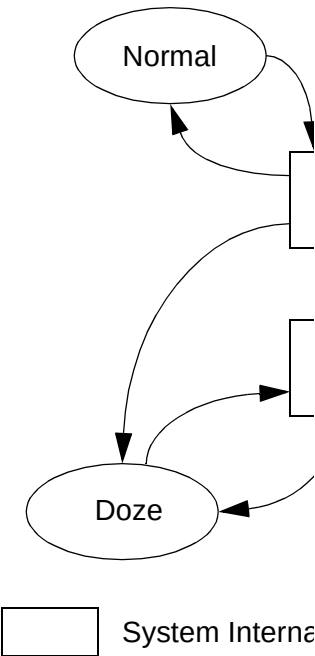


Figure 11.

11.3 System Internal Mode

Initialization, System and Wake-t

In order for PPSM to ma
management tools provid
its own memory tools tha
allocate memory from the
PPSM is specified in the
Specification File).

Note: For allocatin
allocation fu
Graphics To

10.1 Allocating Memo

`void *Lmalloc(U32 s`

`void *Lcalloc(U32 si`

Memory can be allocated
a pointer to a block of av
returned to the caller is n
Lcalloc() is used. No aut
when used by the caller.
through Lmalloc() can be

If no memory is left in the

The actual size of memo
requested by user. A hea
memory management. N
use the required size of r
value is not NULL.

10.2 Freeing Memory

`void Lfree(void *ptr)`

When an application finis
memory can be recycled
into the system heap and

The pointer passed into
Lmalloc() ,Lcalloc() or Lr



10.3 Reallocating Memory

void *Lrealloc(void *src, U32

Moving of memory. This routine r
system from one location to anot
content from the old location to tl
it back into the system heap. The
the system memory.

10.4 Copying Memory

STATUS MoveBlock(P_U32

Copying memory from one region
area. It performs memory copy ir

10.5 Inquiring Memory

STATUS TaskMemUsed(U3

U32 TotalMemUsed(void)

U32 TotalMemSize(void)

S32 TaskStackAvail(void)

Memory allocated to the applicat
time. PPSM returns to the caller
the task with the given task ident
bytes of memory allocated to the
PPSM returns the number of byt
through Lmalloc(), Lcalloc() or Lr

PPSM returns to the caller the to
current task when calling TaskSta
has not been used up, negative \

User can inquire the size of the l
Lmalloc() with input flag LARGE!

Chapter 11 Power Manag

PPSM utilizes the power
power management tool

The Power Management

- switch to one of
- control the duty
Normal mode
- switch automatic
idle
- control user defi
transition

Applications can choose

- control the syste
- use the PPSM's

By default, the system w
message waiting to be s
period and sleep period

11.1 Power Control M

PPSM makes use of the
efficiency. It allows the a
software control. System
the CPU via the PCM. B
the CPU core from a mir
referred to as the CPU c

- While the CPU c
application, the c
- While the CPU c
recognition appli
100% duty cycle

The PCM uses a period

- For example, wit
period of time, th
clock cycles), fol

Please refer to the MC68
PCM.

When using the PCM to
Phase Locked Loop rem



mode.

- If a Wake-up condition is time-out countdown for S countdown and return th

This automatic Sleep mode time-mode until the Sleep mode perio tion.

11.4.3.3 Waking up from Sle

Any one of the following internal Sleep mode. The interrupts are:

- Pen Interrupt
- Real Time Clock Alarm,
- External Interrupts from and PWM

For Mid-night interrupt, system w date and time and then go back t system will wake up from Sleep r

11.5 Power Management T

11.5.1 Setting Duty Cycle

U16 SetDutyCycle(U16 per

This tool allows the application t mode. Applications within a syste PPSM automatically changes the becomes active.

11.5.2 Setting Doze Period

STATUS SetDozePeriod(U1

Sets the countdown period, in ur mal mode to Doze mode. A valu going into Doze mode automatica A value of zero will bring back the setting is to go to doze mode whi rent task to be handled.

11.5.3 Setting Sleep Period

STATUS SetSleepPeriod(U:

Sets the countdown period, in ur

Applications need not be are included in this chap agement. All of these are where PPSM takes contr swapping, message pas

11.3.1 Initialization Mode

This is the power on or s PPSM occur in this mode PPSM is initialized, unles

11.3.2 System Mode

PPSM performs all of its power module controlling frequently invoked, only ning, for example, to han To minimize the actual ti regardless of its set valu leaves System mode, it v

11.3.3 Wake-up Mode

This is invoked either fro Sleep mode, only interna refer to Section 11.4.2.3 from Sleep for the Wake

In Wake-up mode, the sy

- which of the inte
- where the interr
- which applicatio
- which mode the

For example, mid-night i

- 1) Go into Wake-up
- 2) Determine that t
- 3) Update the syste
- 4) Go directly back

11.4 Application Mod

Normal, Doze and Sleep that an application sees



11.4.1 Normal Mode

In this mode, applications can manage the CPU duty cycle value, please Phase Locked Loop is on, all peripheral Application is actively executing

PPSM is designed as an event driven monitoring the calls to the system

- When there are interrupt with interrupt messages. application accordingly.
- When there is no more interrupt message, IRPT_NONE is

11.4.2 Doze Mode

In this mode, the CPU is disabled, Real Time Clock, Timer and other peripherals are disabled. S CPU for more activities.

There are two ways for application

- direct system call
- automatic time-out

11.4.2.1 Direct System Call

Application can go into Doze mode refer to *Section 11.5.4 - Going Into* the system into Doze mode immediately

11.4.2.2 Automatic Time-out

Application can set a time-out period Normal mode. When PPSM detects either from the pen, timers, real time period countdown. When this time mode.

PPSM uses IRPT_NONE as an interrupt and is ready to go into Doze mode

However, if a Wake-up condition doze time-out countdown is reset

This automatic Doze mode time-out mode until the Doze mode period expires.

11.4.2.3 Waking up from

Any one of the following Doze mode in MC68328

- Pen Interrupt
- Real Time Clock
- Timer 1 and Timer
- External Interrupt

For MC68EZ328, whatever wake up the system.

The kind of interrupt to wake up the system is available() and restored in Power

The system can also be waked up by a message() to send message

For Mid-night interrupt, system and time and then go back to system will wake up from Doze

11.4.3 Sleep Mode

In this mode,

- CPU, Phase Locked Loop disabled.
- Only the Real Time

This is the mode where power consuming parts of the system

There are two ways for application

- direct system call
- automatic time-out

11.4.3.1 Direct System

Application can go into Sleep mode refer to *Section 11.5.5 - Going Into* the system into Sleep mode

11.4.3.2 Automatic Time

Application can set a time-out period Sleep mode.

When PPSM puts the system into Sleep time-out countdown

- When this time-out



mode to Sleep mode. A
mode.

11.5.4 Going Into Doze Mode

VOID SetDozeMode

System goes directly to
up condition is met.

11.5.5 Going Into Sleep Mode

VOID SetSleepMod

System goes directly to S
up condition is met.

11.6 I/O Ports Control

For those I/O ports that a
required as PPSM does
system integrator will ne
to disable and enable the
sitions.

11.6.1 Disabling I/O Port E

VOID PortDozeDisa

Just before PPSM goes i
defined I/O ports that are
code to disable the I/O p

11.6.2 Enabling I/O Port A

VOID PortDozeEna

When PPSM wakes up f
user defined I/O ports th
their own I/O initialization

11.6.3 Disabling I/O Port E

VOID PortSleepDis

Just before PPSM goes i
defined I/O ports that are
code to disable the I/O p



11.6.4 Enabling I/O Port After SI

VOID **PortSleepEnable**(VOI

When PPSM wakes up from Sle
user defined I/O ports that are nc
their own I/O initialization code ir

Chapter 12



Chapter 12 UART Comm

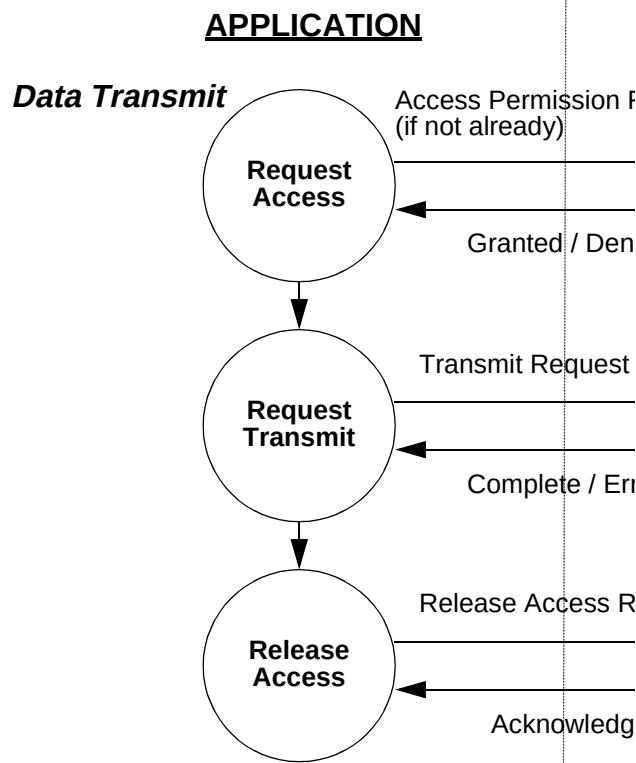


Figure 12-2 UART Communication

PPSM supports serial co
IrDA mode. A set of inter
data through the UART.

12.1 UART Communi

The UART interface tools
receive data serially with
and *Figure 12-2* for an o
between a calling applica
transmission.

PPSM monitors the use
and IrptRelease() (refer
tools will have effect only
to access the UART. The

Once permission is gran
or receive data through t
receive operation. The sa
UART hardware is config

12.1.1 UART hardware flo

In PPSM v3.11, data con
communication devices
RTS is asserted automa
hardware flow control is
sender, receiver needs t
it's RTS pin. When Drag
asserting RTS pin. Thus
communication device a

Three APIs are availabl
UARTFlowCtrl(), UARTR
be enabled or disabled b
UARTSendCtrl(), PPSM
transmission respectively

An API, UARTSendAbor
send buffer and number
API can abort the transm

12.1.2 UART Interface Constraints

Only one task in the system can inquire current settings, an error attempts to use the UART interface

Applications swapping is inhibited. Once a data transmission or reception application, pen touches on application, prevents data loss due to super request.

The enforcement of these constraints is implemented by the `Device` class, initiating a request only when it is necessary for the device to perform data transmission or reception is

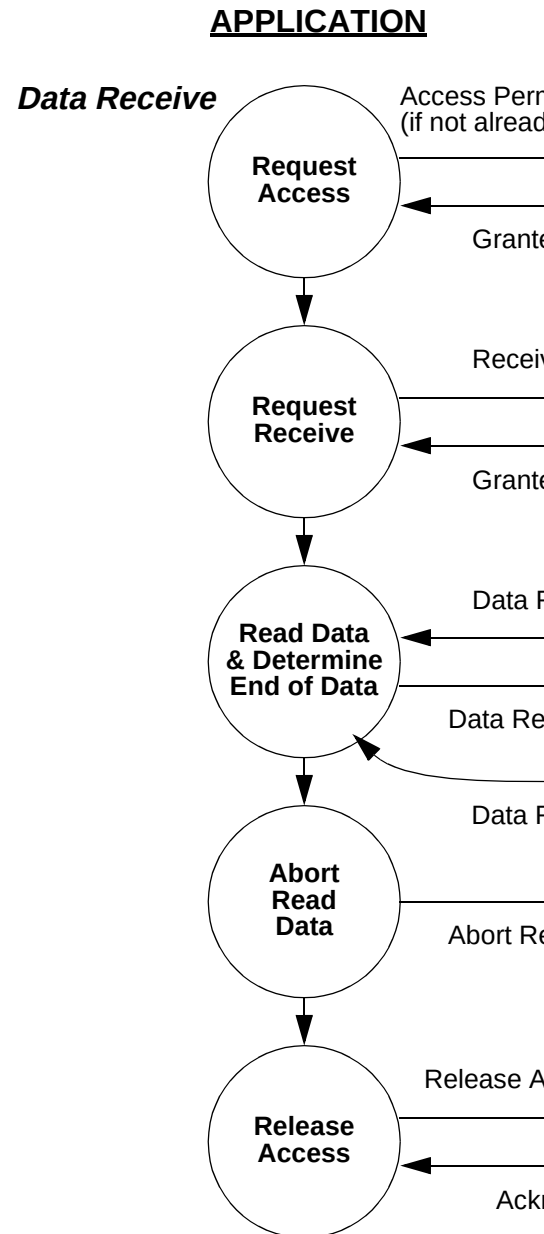


Figure 12-1 UART Commu



mode, various baud rates, parity settings, and data transmission t normal mode, the minimum and l per second) and 115200 bps res mode, only the 115200 bps baud

There is no default UART config UART is configured properly by c communication.

Please note that the application i before it can configure the UART regarding the usage of IrptReque

12.2.1 Configuring the UART

STATUS **UARTConfigure**(U
U8 charLen)

Applications can use UARTConfi settings. Any on-going data trans transmission time out reset to the approximation to the specified ba

Table 12-2 shows the list of conf corresponding selection flag to b 26.1 - *UARTConfigure* for details

Table 12-2 UART Coi

Configurations
Operating Mode
Baud Rate
Parity

APPLICATION

**Data Receive
with RTS/CTS
flow control**

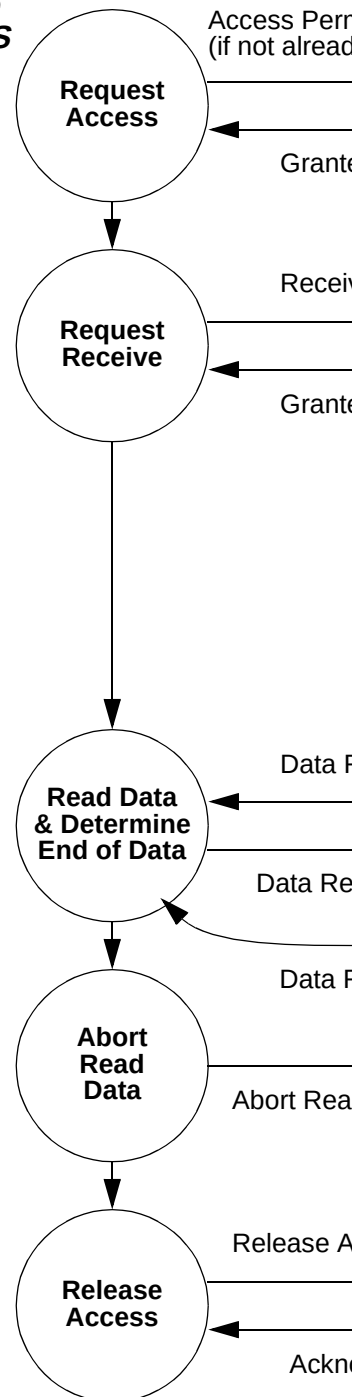


Figure 12-3 UART Communication Archi

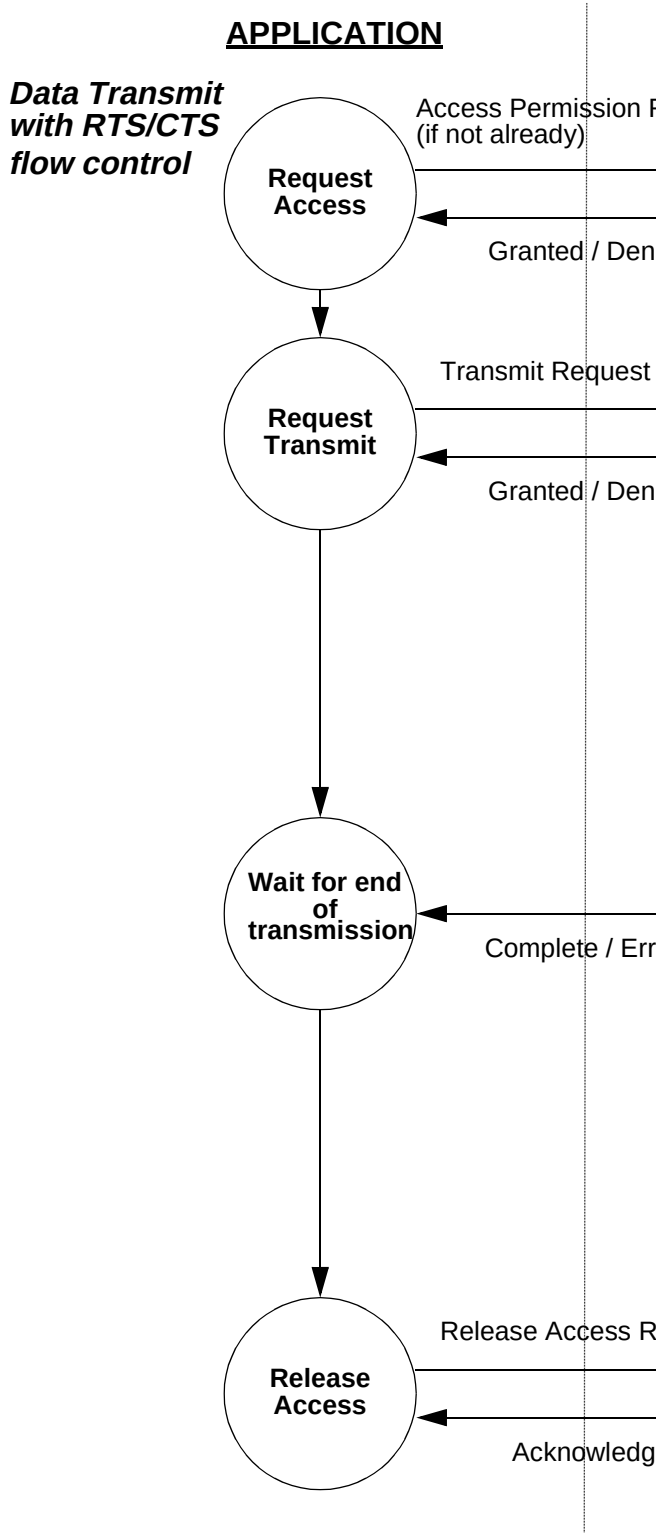


Figure 12-4 UART Communication Architecture

12.1.3 UART Interface Inter

The UART interface com
returned by IrptGetData(
Interrupt Handling for de

After an application is gr
transmission request. As
IRPT_UART interrupt me
following circumstances.

- An error conditio
UART_ERROR,
the calling applic
- UART_ERR
once the tra
- UART_ERR
receive.
- UART_ERR
receive.
- UART_ERR
receive.
- UART_ERR
data before
- Data has been r
data, UART_DA
application.
- Data send requ
data, UART_DA
application.

Table 12-1 shows the ne
with it during IrptGetData

Table 12-1 UART

Interrupt Message
IRPT_UART

12.2 UART Configura

PPSM allows application



12.4.1 Initiating a Receive Request

Applications can receive data by initiating receive requests. A receive request is initiated when the following is true:

- the application has permission to receive data (see *Chapter 15 - Interrupt Handling*)
- there is no other on-going receive request

Actual data receiving does not happen until `UARTReceive()` returns success. After receiving data, the application can start waiting for data or handle other interrupts (e.g. power saving).

For power saving reason, system can suspend data reception, it is recommended to call `UARTReceive()`.

Note: Application swapping may cause a receive request.

12.4.2 Reading Received Data

When PPSM has received data from the hardware, an interrupt message with message data will be generated. The calling application can read the received data at any time.

As PPSM is receiving data from the hardware, an interrupt message will arise:

- a frame error generated
- a parity error generated
- an overrun error when PPSM is behind in reading the received data

In any of the above error conditions, an interrupt message with message data will be generated. These error related interrupt messages will be generated to the application, and does NOT stop the application. The calling application should determine the error condition (see *Section 15.1.9 - IRPT_UART* for details).

If RTS/CTS is enabled, RTS pin will be asserted when `UARTReadData()` is called.

12.4.3 Terminating a Receive Request

A receive request will be terminated when:

- If a timed out error condition occurs, PPSM will post the message data `UART_EF_TIMEOUT`.

Table 12-2 UART Configuration

Configuration
Number of Stop Bits
Character Length

12.2.2 Inquiring the UART Configuration

`void UARTInquire(PPSM *ppsm, unsigned short *stopBits)`

`UARTInquire()` provides the current configuration settings of the UART. The corresponding configuration settings are returned in the `stopBits` parameter. The actual baud rate is not returned.

Note: UARTInquire() does not return the UART access status.

12.2.3 Setting Data Transmission Timeout

`STATUS UARTTimeOut(PPSM *ppsm, unsigned short timeout)`

The data transmission timeout is the time out for the hardware UART interrupt. If the timeout is reached, the hardware UART will be deadlocking itself when the interrupt is not cleared.

If RTS/CTS is enabled, a timeout will occur if the application will receive a timeout error. If CTS is asserted, the timeout interval between two hardware UART interrupts is the timeout.

The range of time out value is:

- Zero means disabled
- 1 to 60,000 means the number of UART interrupts

12.2.4 Setting Data Transmission Status

`STATUS UARTSetData(PPSM *ppsm, unsigned short data)`

In order to communicate with the hardware, transmitting data in a burst mode is required. The accuracy of transmission is determined by the time interval between each transmission (UART interrupts). In *Example 1*, the UART is connected to HyperTerminal. The time interval between each UART hardware interrupt is the timeout.



The range of delay values suppo

- UART_TXDELAY_CLEA
transmission
- 1 to 60,000 means allow
hardware UART interrup

Example 12-1 Setting delay

```
.....
IrptRequest(IRPT_UART_FL
/* Enable RTS/CTS flow c
UARTFlowCtrl(UART_RCTS_E
/* Configure UART */
UARTConfigure( UART_NORM
EIGHT_BIT_CHAR);
/* Set a 600 us delay be
_UARTSetDelay(UART_TXHAL
/* release irpt */
IrptRelease(IRPT_UART_FL
.....
```

12.3 Sending Data to the U

STATUS UARTSend(U8 ser

Refer to *Figure 12-2* and *Figure*
architecture.

12.3.1 Initiating a Send Request

Applications can send data ou
initiate send requests. A send
following are true:

- the application has perm
Chapter 15 - Interrupt H
- there is no other on-go

Actual data sending does not ha
UARTSend() returns success for
interrupts and start sending data
handle other interrupts (e.g. pen

The calling application cannot m
entire course of the send reques

If RTS/CTS hardware flow contr
UART when CTS pin is asserted

For power saving reason, system
transmission speed is reduced. F
disable the Doze mode before ca
12-2.

*Note: Application swappin
data transmission.*

Example 12-2 Initiati

```
.....
IrptRequest(IRP
SetDozePeriod(P
UARTSend(UART_S
.....
```

12.3.2 Terminating a Send

A send request will be te

- After PPSM finis
interrupt messag
calling applicatio
(Refer to *Section*
interrupt messag
- If a timed out err
data, PPSM will
message data U
This marks a fail
determine the re
after time out ha
- An application a
UARTSend() or

The calling application s
IrptRelease() as soon as

It is recommended to for
or a transmission is com

*Note: Application s
completed o*

Example 12-3 Termin

```
.....
/* Abort send. S
/* .. sent in g
UARTSendAbort(U
IrptRelease(IRP
SetDozePeriod(0
.....
```

12.4 Receiving Data f

STATUS UARTRece

STATUS UARTReac

Refer to *Figure 12-1* and
architecture.

This marks a fail
should determin
is aborted after t

- An application a
UARTReceive()

The calling application s
is not needed anymore.

It is recommended to for
reception or a reception

Note: Application s
terminated.

12.4.4 Setting Data Recep

If RTS/CTS is enabled, a
time out error depends o
application will not receiv
is off. On the other hand,
if no data arrived within t
programmer is prefer to s
UARTReceive() to avoid

Example 12-4 Setting

```
.....  
IrptRequest(IRPT_UART_  
UARTTimeout(1000); /*  
UARTReceive(UART_RECEI  
RefTimeAlarmId(&RxAlar  
.....  
if(*inData==UAR  
{ DeleteTim  
UARTReadD  
.....  
}
```

12.5 UART hardware

12.5.1 Enabling RTS/CTS

Applications can enable
UARTFlowCtrl(UART_R
when calling RTS/CTS fl
returned to the applicatio

12.5.2 Disabling RTS/CTS

Applications can disable
UARTFlowCtrl(UART_R
after disabled hardware



ignored by the system. RTS is as

12.7.2 Continue data trans

Applications can continu
UARTSendCtrl(UART_R
Error code PPSM_ERR_
enabled.

12.6 Data reception with ha

12.6.1 Pause data reception

After RTS/CTS hardware flow co
data reception once internal UAF
resumed after data is read out by
CTS remain negated is longer th

Applications can pause data rece
enabled. Error code PPSM_ERR
is not enabled. Applications can
UARTRcvCtrl(UART_RCTS_CO

There will be no receive timeout
Because the purpose of UARTRcvCtrl
in dead loop when transmitting or
RefTimeAlarmId(). The receive t
resumed by calling UARTRcvCtr

12.6.2 Continue data reception

Applications can continue data re
UARTRcvCtrl(UART_RCTS_PA
Error code PPSM_ERR_RCTS_
enabled.

12.7 Data transmission wit

12.7.1 Pause data transmission

Applications can pause data tran
enabled. Error code PPSM_ERR
is not enabled. Applications can
UARTSendCtrl(UART_RCTS_C

There will be no transmit timeout
Because the purpose of UARTTi
in dead loop when transmitting or
RefTimeAlarmId(). The transmit
resumed by calling UARTSendC



needs to be swapped in later by SWAP_TASK_BACK_LATER, then while it's swapped out.

If the current task is parent task and system will check whether there is no more main task to be swapped in may due to the subtask is on.

If the current task is subtask and system will check whether there is subtask queue. If not, system will see whether they need to be swapped in more message or task to swap in queue to see whether it needs to

Task switching can be disabled by function to stop task swapping with other critical operations. If the App number of times of AppSwap(TR) again.

13.4 Message Broadcastin

If the application programmer stops a global list, message can be broadcast AdvSendMessage() with or without

13.5 Task Control

If the application programmer stops a global list, the task swapping system AdvSendMessage() with or without task swapping queue will not be swapping queue, nothing can be swapping queue, AdvSendMessage() queue. The earlier the task is put the task will be swapped in.

In task swapping, PPSM will check before checking the sub tasks of

The system will always check to be handled within the family and swapped. Sometimes the message in current immediately to other member of the memory for the last message next IrptGetData() is called. And that task will be next IrptGetData

Chapter 13 Task Management

Each application running on PPSM tasks:

- main task - application
- sub-task - task the sub task.

The task management to

- Create a main task
- Start execution of
- Terminate execu

This chapter describes how PPSM tasks.

Message passing or task and any other main task the panning screen parameter task will affect the panning belonging to the same m

13.1 Main Task

Most applications fall into each other. There cannot They are created by the main task is created, the

- By using the sys
- By pressing the
- By messages se

13.1.1 System Task

System task is a special terminated since creation defined in SPC file so it can be deleted and replaced method:

Example 13-1 Sharing variable

```
/* Global variable for
U32 gPanScreen;

STATUS TaskApp()
```



```

{
    PAN_SCREEN tempScreen;

    tempScreen.panAddress =
    tempScreen.horzSize = 166
    tempScreen.vertSize = 24
    tempScreen.displayXOrig
    tempScreen.regPOSR = 0;
    tempScreen.regPSW = temp
    is set to 2 bits/pixel a

    /* Set the panning scree
    ChangePanning(tempScreer

    while(1)
    {
        ....
    }
}

main()
{
    U32 taskAppId;
    PAN_SCREEN tempScreen;

    /* PPSM Initialization */
    PPSMInit(FALSE);

    /* Get screen memory */
    gPanScreen = (U32)GetScr

    /* Assign panning screer
    tempScreen.panAddress =
    tempScreen.horzSize = 166
    tempScreen.vertSize = 24
    tempScreen.displayXOrig
    tempScreen.regPOSR = 0;
    tempScreen.regPSW = temp

    /* Delete the default sys
    to system task */
    ChangePanning(tempScreer

    /* Create a main task w
    AdvTaskCreate(taskAppId,
    0, NULL);

    TaskStart(taskAppId);
}

```

13.2 Sub-task

Sub-task, on the other hand, can that generated the sub-task and task can create multiple sub-task order they are created initially. Hc task is swapping in or out by usir

Sub-task uses the display resour and can only be created with the

Sub-tasks are tied to the parent t terminated, the sub-task will be s the input pad properties from the input pad among the main task a

13.2.1 Sub-task Management

When the active area of the current task.

The IrptGetData() tool is pending among a main t current main or sub-task task or its sub tasks, task

If there are multiple sub-most recently swapped c system is ready to restart of the queue.

13.3 Task Switching

When the task is started task application. When the current Program Counter resume execution from v

Example 13-2 Task s

1 → TaskApp1()

```

{
    TaskInit();

    while(TRUE)
    {
        switch(I
        .....
        .....
    }
}

```

At arrow 1, TaskApp1() is also started for the first t TaskApp1() is swapped l

If the task is swapped by being SWAP_TASK or S

If the task is swapped by parameter being SWAP_ immediately. It will be sw task are handled. If the t parent of the other family

All tasks to be swapped swapped out will be put a



This tool launches a task that has `AdvTaskCreate()`. This routine needs no argument and begins execution of the application caller from executing `main()` to start the first task.

Example 13-4 Start a task

```
59    U32    SlideTask;
.
.
.
91    /* Slide is the default task
92    TaskStart(SlideTask);
```

13.11 Termination of a Task

STATUS TaskTerminate(U32 taskID)

Termination of a task. The task ID and memory associated with the task are freed, such as stack memory explicitly allocated by the task threads going to be freed by the system threads. That area can be freed by

A task cannot terminate itself. If it does, it will either.

13.12 Task Reinitialization

STATUS TaskReInit(U32 taskID)

This tool will set the reinit flag in the task. When the task is swapped in, it will start application programmer needs to swapping using `TaskHook()`.

In task swapping, the PC and stack task is not executed.

This function must be called immediately when the task is created. This function reinitialization at anytime but can

13.13 Task Hook

STATUS TaskHook(U32 taskID)

This tool will hook the entryCallback task. When the task is swapped in the registers. When the task is swapped

13.6 Task Swapping

```
TaskAppA()
{
    SubTaskCreate(&
    SubTaskCreate(&
    AdvSendMessage(
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}

TaskAppB()
{
    SubTaskCreate(&
    SubTaskCreate(&
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}

SubTaskAppA1()
{
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}

SubTaskAppA2()
{
    .....
    AdvSendMessage(
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}

SubTaskAppB1()
{
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}

SubTaskAppB2()
{
    .....
    AdvSendMessage(
    AdvSendMessage(
    AdvSendMessage(
    .....
    while(1)
    {
        IrptGetDa
        .....
    }
}
```



}

Task swapping sequence is A->E

When task A is created, it will create subtasks. If subtasks wouldn't be executed until AdvSendMessage() with SWAP_IrptGetData() so the next task is created. In IrptGetData() of task command is SWAP_TASK_BACK be executed in sequence. In subtask is B. In IrptGetData() of task Then in IrptGetData() of subtask SWAP_TASK_LATER is called for system will check for next subtask IrptGetData() of subtask B2. In Irpt will check for the parent after check and then A1 in IrptGetData() of task swapping task to A1 in subtask E subtask in other family, the parent

13.7 Creating a Task

```
STATUS TaskCreate(P_U32
                  S16 xDest, S16
```

PPSM needs to know the existing access PPSM resources. The memory once for each application. PPSM memory space required to run the each application with the coordinate application is put to the foreground not start the execution of the application the user does not want to have a width or height to be zero(xSrc = application icon to be created.

By default, a screen is created with physical size as the dimension for specified in the Linker Specification File.

A 2K byte of memory is allocated

13.8 Creating a Task with S

```
STATUS AdvTaskCreate(P_
                    ySrc, S16 xDest,
                    screenWidth, U1
```

Creation of a new PPSM task. TI

same manner as the existing allows the caller to specify required by the application settings for the panning

- PPSM_SCREEN
- PPSM_SCREEN
screenHeight and
However, if either
screenHeight, is
the linker specifying

A default of 512 byte of memory argument is negative.

Example 13-3 Create

```
57 main()
58 {
59     U32    SlideTask;
60     U32    UartDemoTask,
61     .
62     .
63     .
64     /* Create the UART
65     * and a panning screen
66     */
67     if (AdvTaskCreate(&
68         src_y[UART_ICON],
69         PPSM_SCREEN_NEW, 0
70         return(PPSM_ERROR);
```

13.9 Creating a Sub T

```
STATUS SubTaskC
U16 nur
```

Creating a sub-task. Any task is itself a sub-task, the parent (ie. the calling task) has already created to the head of the sub-task a parent task can create

This routine accepts various into the sub-task by PPSM input arguments.

Subtask will be started with handled and there is no the IrptGetData() routine

13.10 Starting a Task

```
STATUS TaskStart(
```



In the above example, task B will then task C will be put after task system will swap to task B. When swap to task C.

Note: If UARTSend() or Ux can be happened in aborted. It is applied this chapter.

14.1.1 With Delayed Task Swap

```
TaskApp1(
{
    TaskInit();

    while(TRUE)
    {
        switch(IrptGetDa
        {
            .....
            SendMessage(TaskAp
            .....
        }
    }
}
```

In the diagram above, TaskApp1 TaskApp2(). However, the active be active until it executes IrptGet swapped back in as in arrow 2. M IrptGetData() of TaskApp2() as ir

The task swapping happens whe

This will happen if SendMessage SWAP_TASK_LATER are used. task swapping queue if the target queue otherwise.

14.1.2 With Immediate Task Swa

In AdvSendMessage(), if the flag swapping will happen inside Adv touching the panel.

14.1.3 With Immediate Task Swa

In AdvSendMessage(), if the flag passing and task swapping will h the pen is not touching the panel the task swapping queue. So wh current task will be swapped bac

before storing the register one input parameter func task id. for the task just s be the task id. for the tas

e.g. STATUS Entry(U32

This function can be call the task, the entry routine function.

Example 13-5 TaskH

```
VOID EntryR(U32 oldId,
{
    .....
}

VOID ExitR(U32 nextId,
{
    .....
}

Task1()
{
    Task1Init();
    TaskHook(task1I
    EntryR(0);

    While(1)
    ....
}
```

If TaskHook() is called o automatically once the ta

13.14 Stop task swapp

void AppSwap(U16

If *flag* is FALSE, no task SendMessage() or AdvS the message will be sent executed. This function v FALSE several times, the before task swapping is



Chapter 14 Inter-Task M

PPSM supports asynchron provided tools. This tool different parent tasks.

The sender task sends o structure using the tool S task identifier of the task

The receiving task receiv the same way as other in this message by the app

The messaging tool enab

- notify other appli
- pass data betwe
- swap to the spee

The format of the data pa receiver must have their PPSM only performs the application task of the ar

The AdvSendMessage() without message passing

This can be used to send are called to send messa the system is in doze mo

14.1 Message Passin

Message can be sent be SendMessage() will send the target task once all n AdvSendMessage() has message sent to the targ can be used to send mes as a purely message pas

Example 14-1 Multip

```
TaskA( )
{
    .....
    SendMessage( tas
    SendMessage( tas
    .....
}
```



14.1.4 Message Passing v

In AdvSendMessage(), i
passing only and no task

14.2 Message Structu

A pre-defined structure is

```
typedef struct _MESSAG
{
    U16 me
    U16 me
    U32 mi
    P_VOID da
    U16 si
    U16 re
} PPSM_MESSAGE,
```

Name
<i>messageType</i>
<i>message</i>
<i>misc</i>
<i>data</i>
<i>size</i>

14.3 Sending Messag

STATUS SendMess

This tool sends a messa

not known, this tool cannot be us

All data that the sender wants to structure. No protocol or data for receiver must have a mutual und transferred.

14.4 Advanced Sending M

STATUS **AdvSendMessage**

This is similar to SendMessage()
The *flag* can control whether the also controls whether the current in target task are handled.

If *msg* is NULL, this is a task swa

If *flag* is NO_TASK_SWAP, this i control.

14.5 Deleting Message for

STATUS **MessageDelete(U**

This is for deleting all messages parameter such as IRPT_PEN, Il

14.6 Deleting Message for

STATUS **AdvMessageDelet**

This is for deleting messages in :
The short data here refers to the timer, etc. If *taskId* is 0xFFFFFFFF messages in main task queue wi the *taskId* is 0xFFFFFFFF and th matching *type* and *shortData* in c 0xFFFF, all messages with match

If *type* is 0xFFFF and *shortData* i will be deleted.

14.7 Receiving Message

STATUS **IrptGetData(P_U32**

This tool is used to receive the m receive the standard software int

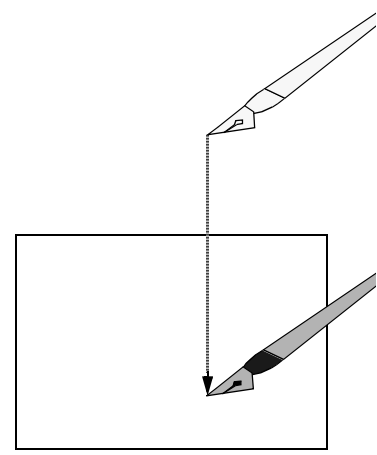
The arguments returned
the MESSAGE structure

IrptGetData	Data Type
<i>return value</i>	STATUS
<i>sData</i>	P_U32
<i>data</i>	P_U32*
<i>size</i>	P_U32

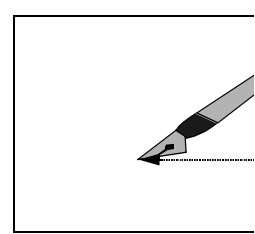
Example 14-2 Receiv

```
73 STATUS UartDemo()  
74 {  
75     P_U16         inData;  
76     U8            selected;  
77     U32           size, id;  
78     .  
79     .  
134 while (1)  
135 {  
136     switch (IrptGett  
137     {  
138         case IRPT_UART:  
139             switch (*inDa  
140             {  
141                 case UART_D  
142                 .  
143                 /* Data h
```

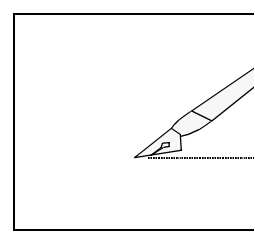

Chapter 15 Interrupt Han



PPSM_ICON_TOUCH and
PPSM_INPUT_TOUCH



PPSM_ICON_D



PPSM_ICON_DRAC

Figure 15-2 ICON ar

15.1.5 IRPT_KEY

PPSM provides a soft keyboard .
activated, a keyboard is displaye
keys on the soft keyboard will res
to the application. The message
was pressed. The ASCII code re
zero extended in high byte and tl

PPSM maintains a set of
internal hardware events
aware of the characteris
real time clock. The kern
event and send them to

PPSM maintains a uniqu
hardware interrupt occur
stored into this software
PPSM and the applicatio
if the application is slow
time interrupt of the perip

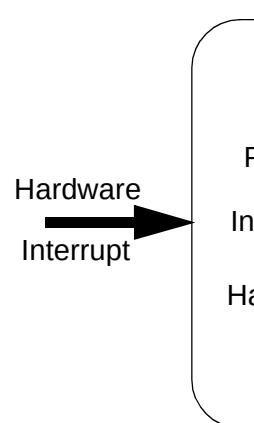


Figure 1

PPSM has two distinct ty

- System interrupt
- User defined inte

15.1 System Interrupt

These are interrupts that
developers can make us
hardware resources such

Table 15-1 shows the lis



to the application.

Table 15-1 :

Interrupt Identifier	Inte
IRPT_AUDIO	PPSM / indicati
IRPT_HWR	Handwr
IRPT_ICON	Icon inp
IRPT_INPUT_STATUS	Pen inp
IRPT_KEY	Soft key
IRPT_NONE	No inter
IRPT_PEN	Pen inp
IRPT_RTC	System
IRPT_TIMER	Timer ti
IRPT_UART	UART c
IRPT_USER	User

15.1.1 IRPT_AUDIO

It is a message generated from a the user has called AudioStopTo stops, this interrupt is sent to the AudioPlayWave() to indicate that

15.1.2 IRPT_PEN

It is a message generated from a an active area as pen area on th when pen input sequence occurs coordinates of the pen input poin

The data message returned by If pair of 16-bit words in the list rep point on the touch panel. There v of (-1,-1) signals the end of the li

15.1.3 IRPT_INPUT_STATUS

This message is sent to the appl beginning and the end of each p example, when an active area cr

together with the pen sta coordinates are sent; the touch panel, this messag coordinate to report the p aware of the pen action s area, or it is a pen down returned. Figure 15-2 sho

Table 15-2 Me

Message
PPSM_INPUT_TOUCH
PPSM_INPUT_DRAG
PPSM_INPUT_PEN_UP
PPSM_INPUT_DRAG_UP

messages.

15.1.4 IRPT_ICON

Icon area is for the purpo from the pen interrupt ha a soft interrupt with its id interrupts will be generat drag in, and one interrup for buttons, and selection

Table 15-3 shows the m

Table 15

Message
PPSM_ICON_TOUCH
PPSM_ICON_DRAG
PPSM_ICON_PEN_UP
PPSM_ICON_DRAG_UP



Table 15-6 Interrupt I

Interrupt Handler	
SPI Slave	IRPT_S
IRQ1	IRPT_I
IRQ2	IRPT_I
IRQ3	IRPT_I
IRQ6	IRPT_I
INT0 - INT7	IRPT_I
WatchDog	IRPT_V
PWM	IRPT_F
UART	IRPT_U
User Defined	IRPT_U

The IRPT_USER is intended for i
defined interrupt messages to inf
their own meanings to this mess:

Example 15-1 Request an I

```
203          /* request usag  
204          if ( IrptReques  
205              return (PPSM_  
.  
.  
.  
216          /* Release the  
217          IrptRelease(IRP
```

15.3 Message Handling

STATUS IrptSendData(U16

STATUS IrptGetData(P_U32

User can send messages, with or
using IrptSendData(). This tool c

When an application requested a
handler, any messages sent by I
directed to that application, until

IrptSendData() appends the mes
application's software interrupt b
message via the system tool Irpt
messages.

15.1.6 IRPT_RTC

This is the clock alarm. V
message will be generat
No data is included in thi

15.1.7 IRPT_TIMER

Time-out message. This
out period is reached. No

15.1.8 IRPT_HWR

PPSM provides an input
5 - Character Input Meth
resultant characters gene
message. The data pass
character candidates and

15.1.9 IRPT_UART

When an application is g
UART Communication S
report UART data trans

A 16-bit message data is
have one of the following

Table 15-

Message
UART_DATA_SENT
UART_DATA_RECEIVED
UART_ERROR

15.2 Device Interrupt

PPSM supports another



devices. The list of device interrupt

Table 15-5 Interrupt I

Interrupt Source	Interrupt
SPI Master	IRPT_SPI
SPI Slave	IRPT_SPI
IRQ1	IRPT_IRQ
IRQ2	IRPT_IRQ
IRQ3	IRPT_IRQ
IRQ6	IRPT_IRQ
INT0 - INT7	IRPT_INT
WatchDog	IRPT_WD
PWM	IRPT_PW
UART	IRPT_UA
User Defined	IRPT_US

15.2.1 User Defined Interrupt Ha

For each of the external interrupt their own handler. The generic, c device library. These are:

- SPI Master
- SPI Slave(DragonBall or
- IRQ6
- IRQ3
- IRQ2
- IRQ1
- INT0 - INT7
- Watch Dog
- PWM
- UART

Each of the stub handler is associ _IRQ6IrptHandler is associated v external interrupt event occurs, F handler as part of the interrupt h

For system that uses any of the handler such that integration into

For PPSM source licensee, if _U DNO_UART_HANDLER" needs that the internal PPSM UART int

15.2.2 Device Interrupt Ide

The device interrupt identifier handlers to send soft interrupt much like the system peripheral IrptSendData(), to allow handlers to the application

For example, user install message to the application event, or to pass data from

15.2.3 Application Access

By isolating the interrupt have access to the same only be registered with a application is requesting first application making t handler until it is release

To control access conflict hardware concurrently, a

- IrptRequest()
- IrptRelease()

15.2.4 Request and Release

U32 IrptRequest(U32 STATUS IrptRelease

When an application task it must first request for successfully registers with are directed to the register handler.

One application task can handlers in the system, b attached to one single ap release the handler after

To request or release a h the interrupt tools to specify values representing indiv

Table 15-6 Im

Interrupt Handler
SPI Master



16.1.1 Motorola Logo

Depending on the physical LCD s
the LCD display during pen calib

For LCD display that is larger tha
standard logo will be displayed. 7
Figure 16-2.

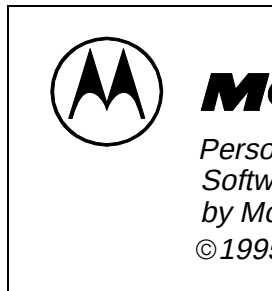


Figure 16-2

For LCD display that is larger tha
than 280 pixels by 150 pixels, a s
Motorola logo will be 104 pixels l

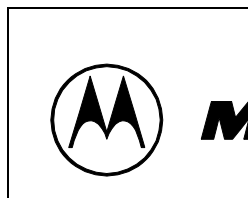


Figure 16-3

For LCD display that is smaller th
Motorola logo will be drawn.

15.3.1 Example

Assuming that an applica
PPSM, when the user de
sent to the application im

```
shortMessage = COMMAND  
messageSize = 4;  
messageData = pInData;  
IrptSendData( IRPT_IRQ6,
```

The application retrieve t

```
switch (IrptGetData( &  
.  
.  
.  
case IRPT_IRQ6:  
    /* IRQ6 event  
    if (event == CO  
    .  
    .  
    .  
    default;
```

In the above example, th
application:

Table 15-7

IrptSendData	
Argument	
<i>irptType</i>	IRPT_IRQ6
<i>sData</i>	shortMessage
<i>data</i>	messageData
<i>size</i>	messageSize

Chapter 16 Using System

PPSM provides additional
resources.

16.1 PPSM Initializati

STATUS **PPSMInit**(U

PPSM needs to be initial
PPSM tools can be calle
devices initialization and
display.

A device driver (PenInit.c
the touch panel origin and
This function should call
coordinate of origin is the
screen coordinate. The c
touch panel in terms of o

Org - (-10, -10) —

Touch Panel —

Figur

The default touch panel
pixels by 240 pixels (phy
An offset of 100 (in A/D
the edge of the touch pa

The caller of CalibratePe
logoFlag is FALSE, no lo
cross-hairs (one at top ri
displayed on the LCD sc
hairs, in no particular or

Example 16-1 Initiali

```
62  /* Initialize PPSM v  
63  PPSMInit(TRUE);
```



```
        /* Display message to indicat
        ....
        break;
case IRPT_ICON:
    /* Click icon to stop the wav
    rv = AudioStopWave();
    ....
    break;
}
```

Chapter 17 Audio Tools

17.1 Audio Playing

PPSM supports two type
hardware limitation, the v

The audio tools have the

- Only one wave f
- A wave file or to
Modulation) mod
- An interrupt "IRP
called AudioPlay
playing has finis

17.2 Tone playing

STATUS **AudioPlayTone**
autoRepeat)

PPSM supports tone pla
PWM module. Tone play
and changeable frequen
resolution, the tone frequ

Name
<i>toneData</i>
<i>toneSize</i>
<i>toneDuration</i>



Name
<i>autoRepeat</i>

Example 16-1 PPSM tone p

```
/* 100Hz, 1000Hz, 500Hz and 600Hz
U16 toneData[] = {100, 1000, 500,

/* Play a melody with 4 different
#ifdef EZ328
    AudioPlayTone((P_U16)toneData,
#else
    AudioPlayTone((P_U16)toneData,
#endif
```

To stop the tone playing, a user c
Tools are currently being used, a

*Note: This is impossible to play a
of duration, since the duration of
duration.*

17.3 Wave playing (Dragon

PPSM audio tools can play back
that can be generated by many a
two PPSM audio tools - AdvAudi

AdvAudioPlayWave() is provided
want to have advanced configura
module. For most cases, AudioP

STATUS **AudioPlayWave**(P_U8

Name
<i>waveData</i>
<i>waveSize</i>
<i>samplingRate</i>

Example 16-2 PPSM wave p

```
/* Some PWM wave data */
U16 waveData[] = {...};
```

```
/* Play a melody with 100
AudioPlayWave((P_U8)waveDa
```

STATUS **AdvAudioPlay**
repeat, U8 clkssel)

Name
<i>waveData</i>
<i>waveSize</i>
<i>prescaler</i> (see DragonBa manual)
<i>repeat</i> (see DragonBa manual)
<i>clkssel</i> (see DragonBa manual)

The sampling rate can b
SamplingRate = ((16.58MHz)/

For more detail informati

Example 16-3 PPSM

```
/* Some PWM wave data */
U16 waveData[] = {...};

/* Play a melody with 100
/* 16kHz = 16.58Mz/(2 x 1
AdvAudioPlayWave((P_U8)wav
```

The device driver functio
TRUE for proper wave p
his/her own PWM interr
playing tools, the _PWM

17.4 Stop the audio p

An audio stops after it ha
AudioStopWave(). After
called AudioPlayTone() c
finished.

Example 16-4 Stopp

```
/* Some PWM wave data */
U16 waveData[] = {...};

/* Play a melody with 100
AudioPlayWave((P_U8)waveDa

switch( IrptGetData((P_U32
{
case IRPT_AUDIO:
```




Parameter

Name
<i>areald</i>
<i>code</i>
<i>mode</i>
<i>xSrc</i>
<i>ySrc</i>
<i>xDest</i>
<i>yDest</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID
PPSM_ERR_AREA_CODE
PPSM_ERR_COORDINATE
PPSM_ERR_NO_MEMORY

Part III

API Toc

18.3 ActiveAreaRead

Syntax



Chapter 18 Pen Input To

18.1 ActiveAreaDisab

Syntax

STATUS ActiveArea

Description

Removes an active
specifies the entry th
obtained from the Ac
creates the active ar

Parameter

Name
<i>areald</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_

18.2 ActiveAreaEnab

Syntax

STATUS ActiveArea
S16 yS

Description

Creates and enables
area. An active area
where a software inte
the area when the
returned to the appli

Active areas can be
the boundary of the
display area are the
display area, echoin



18.8 AreaEchoDisable

Syntax

STATUS AreaEchoDisable(
xSrc, ySrc, xDest, yDest, PPSM_OK, PPSM_ERR_AREA_ID)

Description

Disables active area pixel ec
selected pixels will not be
disabled for all active input a

Parameter

Name
areald

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

18.9 AreaEchoEnable

Syntax

STATUS AreaEchoEnable(
xSrc, ySrc, xDest, yDest, PPSM_OK, PPSM_ERR_AREA_ID)

Description

Enables active area pixel ec
selected pixels will be echoer
all active input area by defau

Parameter

Name
areald

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

STATUS ActiveArea
xDest, P

Description

Reads the area coord
identifier *areald* spec

Parameter

Name
areald
xSrc
ySrc
xDest
yDest

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

18.4 ActiveAreaSusp

Syntax

STATUS ActiveArea
xSrc, ySrc, xDest, yDest, PPSM_OK, PPSM_ERR_AREA_ID)

Description

Suspend or re-enabl
active area is susperr
will remain in the ac
again respond to per

Parameter

Name
areald



Name
<i>flag</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

18.5 ActiveAreaToFront

Syntax

STATUS **ActiveAreaToFron**

Description

Given the active area identifi
area linked list and insert the

Once the element is at the fr
pen input if other active area

Parameter

Name
<i>areald</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

18.6 ActiveListPop

Syntax

STATUS **ActiveListPop**(voic

Description

Pops the top backg
stack. The active list
top background activ

Parameter

Name
None

Return Value

Name
PPSM_OK
PPSM_ERROR

18.7 ActiveListPush

Syntax

STATUS **ActiveList**

Description

Pushes the current
creates a new empt
these areas is disabl
to the new active list

The number of activ
stored internally in a

Parameter

Name
None

Return Value

Name
PPSM_OK
PPSM_ERR_ACTIVE



Return Value

Name
None

18.14 IconScanOn

Syntax

void IconScanOn(void)

Description

Switches on system applicat
by default.

Parameter

Name
None

Return Value

Name
None

18.15 PenCalibration

Syntax

STATUS PenCalibration(U1

Description

This function performs per
peninit.c of the device driver |
different calibration method
default driver will clear the sc
pen calibration are captured.

Parameter

Name
logoFlag

18.10 ActiveAreaPosit

Syntax

STATUS ActiveArea
S16 yDe

Description

This function will cha
by areald.

Parameter

Name
areald
xSrc
ySrc
xDest
yDest

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_
PPSM_ERR_COORD

18.11 CtrlIconDisable

Syntax

STATUS CtrlIconDis

Description

Removes a predefin
must be a valid activ



Parameter

Name
<i>iconId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AREA_ID

18.12 CtrlIconEnable

Syntax

STATUS CtrlIconEnable(P_

Description

Adds a predefined icon area
anywhere on the applicati
specifies the position of the i
to the caller.

Parameter

Name
<i>iconId</i>
<i>xSrc</i>
<i>ySrc</i>

Name
<i>iconType</i>

Return Value

Name
PPSM_OK
PPSM_ERR_ICON_
PPSM_ERR_COORD
PPSM_ERR_AREA_

18.13 IconScanOff

Syntax

void IconScanOff(v

Description

Switches off system
current task.

Parameter

Name
None



For MC68EZ328 only

Sampling Period
samplingPeriod>= 250
250>samplingPeriod>=125
125>samplingPeriod>= 62
62>samplingPeriod>= 31
31>samplingPeriod>= 15
15>samplingPeriod>= 7
7>samplingPeriod>= 3
3>samplingPeriod>= 1

Return Value

Name
PPSM_OK
PPSM_ERR_PEN_RATE

18.21 ScanningOff

Syntax

void **ScanningOff**(void)

Description

Switches off touch panel sc
active areas will not respons

Parameter

Name
None

Return Value

Name
None

18.22 ScanningOn

Syntax

void **ScanningOn**(void)

Return Value

Name
PPSM_OK

18.16 PenEchoParam

Syntax

STATUS **PenEchoP**

Description

This tool allows the
system pen echoing

Parameter

Name
<i>echoCol</i>
<i>echoWidth</i>

Return Value

Name
PPSM_OK
PPSM_ERR_COLOUR
PPSM_ERROR

18.17 PenGetInput

Syntax

STATUS **PenGetInp**

Description



Returns a single pair of X and Y coordinates for a point. A set of -1 will be returned if the point is outside the panel range, i.e. pen up.

Parameter

Name
<i>xPos</i>
<i>yPos</i>

Return Value

Name
PPSM_OK

18.18 PenSetInputMax

Syntax

STATUS PenSetInputMax(S

Description

It allows the user to define the maximum coordinate in terms of screen system is doing calibration
CalibratePen(U16 logoFlag)

Parameter

Name
<i>x</i>
<i>y</i>

Return Value

Name
PPSM_OK

18.19 PenSetInputOrg

Syntax

STATUS PenSetInputOrg(S

Description

It allows the user to define the origin of the coordinate system in terms of screen display. This is useful when doing calibration/re-calibration of the device (logoFlag) at the device.

Parameter

Name
<i>x</i>
<i>y</i>

Return Value

Name
PPSM_OK

18.20 PenSetRate

Syntax

STATUS PenSetRate(S

Description

To allow user to define the sampling period set in a task. The effect after at least one period.

Parameter

Name
<i>samplingPeriod</i>



Name
timeOut
samplingTime
areaClean
stackSize

Return Value

Name
PPSM_OK
PPSM_ERR_INPUT_PAD_OF
PPSM_ERR_INPUT_PAD_WI
PPSM_ERR_INPUT_PAD_HE
PPSM_ERR_INPUT_PAD_X_
PPSM_ERR_INPUT_PAD_Y_
PPSM_ERR_PEN_RATE
PPSM_ERR_PAN_INIT
PPSM_ERR_NO_MEMORY
PPSM_ERR_TMOUT_VALUE

Description

Switches on touch p
all application active

Parameter

Name
None

Return Value

Name
None

19.2 AdvOpenSoftKey

Syntax

```
STATUS AdvOpenSoftKey(  
    keyHeight, U16 |  
    bitmap)
```

Description

Opens a soft keyboard modu
but with advanced configurat

- location of the soft keybc



Chapter 19 Character In

19.1 AdvOpenInputPa

Syntax

STATUS AdvOpenI
numCol,
echoWid
stackSiz

Description

Opens the input p
OpenInputPad() but
specify:

- position of the in
- number of rows
- the width and the
- the echo ink col
- the length of tim
- the sampling rat
- if the system sho
- character is writt
- the stack size fo

Parameter

Name
xPos
yPos
numRow
numCol
areaWidth
areaHeight
echoCol
echoWidth



Name
PPSM_ERR_INPUT_PAD_OF
PPSM_ERR_INPUT_PAD_X_
PPSM_ERR_INPUT_PAD_Y_
PPSM_ERR_INPUT_PAD_WI
PPSM_ERR_INPUT_PAD_HE
PPSM_ERR_NO_MEMORY

- width and height
- number of rows
- the return code o
- the bitmap of the

Parameter

Name
xPos
yPos
keyWidth
keyHeight
numRow
numCol
keyMap
bitmap

19.6 OpenSoftKey

Syntax

STATUS **OpenSoftKey**(U16

Description

Opens a soft keyboard modu

A soft keyboard is drawn at t
keyboard is opened, key-
generated to the application
pressed. Each individual k
message.

Only one soft keyboard is :
covered by the pseudo keyb
will be restored upon closing
system is a snap-shot of the
changes to this area by the a

Parameter

Name
xPos
yPos

Return Value

Name
PPSM_OK
PPSM_ERR_SKBD_X_POS

Return Value

Name
PPSM_OK
PPSM_ERR_SKBD_
PPSM_ERR_PAN_IN
PPSM_ERR_INPUT_ EN
PPSM_ERR_SKBD_
PPSM_ERR_SKBD_
PPSM_ERR_NO_ME

19.3 CloseInputPad

Syntax

STATUS **CloseInputPad**(voi

Description

Closes the handwritten char

The input pad image is remo
handwriting recognition mes
system to the application. 7
restored by the system.

Parameter

Name
None

Return Value

Name
PPSM_OK
PPSM_ERR_PEN_INIT
PPSM_ERR_INPUT_PAD_CL

19.4 CloseSoftKey

Syntax

STATUS **CloseSoftKey**(voi

Description

Closes the soft keyboard mo

The soft keyboard image is
pressed messages (IRPT_k
application. The original ima
system.

Parameter

Name
None

Return Value

Name
PPSM_OK

Name
PPSM_ERROR

19.5 OpenInputPad

Syntax

STATUS **OpenInputPad**(
U16 are

Description

Opens the input pad

The input pad is draw
input pad has *numR*
box is of size *areaS*

Once the input pad
(IRPT_HWR) are g
recognized. Each m
message.

Only one input pad
covered by the input
restored upon closin
system is a snap-sh
changes to this area
input pad needs to b

The default length of

Parameter

Name
<i>xPos</i>
<i>yPos</i>
<i>numRow</i>
<i>numCol</i>
<i>areaSize</i>

Return Value

Name
PPSM_OK

Name
<i>newPanning</i>
<i>flag</i>
<i>oldPanning</i>

Name
PPSM_OK

Name
PPSM_ERR_SKBD_
PPSM_ERR_SKBD_
PPSM_ERR_NO_ME



Chapter 20 Graphics Tools

All coordinates mentioned

- The range of val
Screen Width - 1
- The range of val
- The range of val

20.1 ChangePanning

Syntax

STATUS **ChangePa**
P_PAN_

Description

This function chang
The panning screen
16 for 1 bit/pixel disp

Return Value

Name
PPSM_ERR_PAN_INIT
PPSM_ERROR
PPSM_OK

Hint

The LCD display origin is the screen relative to the pannin

20.6 CursorGetPos

Syntax

STATUS **CursorGetPos**(P_I

Description

Returns the coordinate (*xP task. If this function is called no more information about ci

Parameter

Name
<i>xPos</i>
<i>yPos</i>

Return Value

Name
PPSM_ERR_CURSOR_INIT
PPSM_ERR_PAN_INIT
PPSM_ERROR
PPSM_OK

20.2 ChangeWindow

Syntax

STATUS **ChangeWi**
P_U16 d

Description

This tool will direct a will be changed on divisible by 8 for 2 b The original settings

Parameter

Name
<i>addr</i>
<i>width</i>
<i>height</i>
<i>oldAddr</i>
<i>oldWidth</i>
<i>oldHeight</i>

Return Value

Name
PPSM_OK

Name
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT

Hint

This is used for displaying in
image can be plotted in othe
the image is drawn, it car
ChangeWindow() and PutRe

20.3 ClearRec

Syntax

STATUS **ClearRec**(U16 *grey*
height, U16 *style*

Description

Fills the given area with grey

Parameter

Name
<i>greyLevel</i>
<i>xSrc</i>
<i>ySrc</i>
<i>width</i>
<i>height</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT

Name
PPSM_ERR_LCD_S

Hint

If (*xSrc*, *ySrc*) is (5, 2)
rectangle with top le
LCD with specified g

20.4 ClearScreen

Syntax

void **ClearScreen**(U

Description

Fills the whole pannin

Parameter

Name
<i>greyLevel</i>

Return Value

Name
None

20.5 CursorGetOrigin

Syntax

STATUS **CursorGet**

Description

Returns the coordinat

Parameter

Name
<i>xPos</i>
<i>yPos</i>



Name
PPSM_ERR_CURSOR_INIT
PPSM_ERROR

20.12 CursorSetOrigin

Syntax

STATUS **CursorSetOrigin**(L

Description

Sets the LCD display screen

Parameter

Name
<i>xPos</i>
<i>yPos</i>

Return Value

Name
PPSM_ERR_PAN_INIT
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_OK

Hint

This must be used with LCD:

20.13 CursorSetPos

Syntax

STATUS **CursorSetPos**(U16

Description

Sets the top left corner posi

20.7

CursorGetStatus

Syntax

STATUS **CursorGet**

Description

Returns the status o

Parameter

Name
<i>status</i>

Return Value

Name
PPSM_ERR_CURSC
PPSM_OK

20.8

CursorInit

Syntax

STATUS **CursorInit**

Description

Changes hardware
cursorHeight. The w

Parameter

Name
<i>cursorWidth</i>
<i>cursorHeight</i>



Return Value

Name
PPSM_ERR_PAN_INIT
PPSM_ERR_CURSOR_INIT
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT
PPSM_OK

Hint

If the cursor is large, program

20.9 CursorOff

Syntax

STATUS **CursorOff**(void)

Description

Turns off the hardware curso

Parameter

Name
None

Return Value

Name
PPSM_ERR_CURSOR_INIT
PPSM_OK

20.10 CursorSet

Syntax

STATUS **CursorSet**(U16 xP

Description

Sets the top left cor
current task must ha
panning screen. Ho
exceeds the panning

Parameter

Name
<i>xPos</i>
<i>yPos</i>

Return Value

Name
PPSM_ERR_PAN_IN
PPSM_ERR_CURSCO
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_OK

20.11 CursorSetBlink

Syntax

STATUS **CursorSet**

Description

This will set the hard
number of blinks per
cursor is set on by c

Parameter

Name
<i>frequency</i>

Return Value

Name
PPSM_ERR_PAN_IN

STATUS **DrawCircle**(U16 *gx*, U16 *gy*, U16 *radius*, U16 *style*)

Description

Draws a circle centered at (*xCenter*, *yCenter*) with a radius of *radius* pixels. The circle is drawn with the specified *style*.

If dot width is greater than 1, the circle is drawn with a thick border.

If both fill pattern mode and border mode are set, the circle is filled with the specified fill pattern and has a border.

If fill pattern mode is set and border mode is not, the circle border will be filled.

Parameter

Name
<i>greyLevel</i>
<i>xCenter</i>
<i>yCenter</i>
<i>radius</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_GREY
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_RADIUS
PPSM_ERR_LCD_STYLE

20.18 DrawDot

Syntax

STATUS **DrawDot**(U16 *gx*, U16 *gy*, U16 *greyLevel*, U16 *style*)

Description

Outputs a dot with grey level *greyLevel* at (*xCenter*, *yCenter*) with indicated style.

Parameter

Name
<i>xPos</i>
<i>yPos</i>

Return Value

Name
PPSM_ERR_PAN_IN
PPSM_ERR_CURSOR
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_OK

20.14 CursorSetStatus

Syntax

STATUS **CursorSetStatus**(U16 *status*)

Description

This will set the hardware cursor status. The status can be set to hardware video mode, or temporary mode. The status is returned in the PPSM_CURSOR_R register.

Parameter

Name
<i>status</i>

**Return Value**

Name
PPSM_ERR_PAN_INIT
PPSM_ERR_CURSOR_INIT
PPSM_OK

Hint

CursorInit() is called to set the cursor position from 0 to 31 in pixels. CursorInit() sets the top left corner of the hardware cursor. To turn the hardware cursor on, CursorSetPos() is called. If the cursor is on, CursorSetPos() sets the hardware cursor position. If the cursor is off, CursorSetStatus() is called again.

20.15 DisplayMove**Syntax**

STATUS **DisplayMove**(U16

Description

This function is to replace the cursor position. When the cursor is set to the top left corner of the screen with top left corner of the screen, DisplayMove(xPos, yPos) should be called.

Parameter

Name
xPos
yPos

Return Value

Name
PPSM_OK
PPSM_ERR_PAN_INIT
PPSM_ERR_COORDINATE

20.16 DrawArc**Syntax**

STATUS **DrawArc**(U16
x1, y1, x2, y2, style)

Description

Draws an arc from (x1, y1) to (x2, y2).

The arc is actually a quarter circle. The arc is drawn from (x1, y1) and (x2, y2).

If dot width is greater than 1, the arc is drawn with a dot.

If both fill pattern mode and fill pattern is set, the arc is not covered by the fill pattern.

If fill pattern is set and fill pattern is not set, the arc is filled.

Parameter

Name
greyLevel
x1
y1
x2
y2
style

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_G
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_S

20.17 DrawCircle**Syntax**



Parameter

Name
<i>greyLevel</i>
<i>xSrc</i>
<i>ySrc</i>
<i>xDest</i>
<i>yDest</i>
<i>dotLine</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_GREY
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_STYLE

20.22 DrawRec

Syntax

STATUS **DrawRec**(U16 *grey*,
yDest, U16 *dotL*

Description

Draws a rectangular outline v
right corner at (*xDest*, *yDest*,

If dot width is greater than 1,

If both fill pattern mode an
rectangle which is not cover

If fill pattern mode is set an
rectangle border will be filled

If dot width is 2, a sq
is (*xPos*, *yPos*). If do
yPos) will be drawn.

Parameter

Name
<i>greyLevel</i>
<i>xPos</i>
<i>yPos</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_G
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_S

20.19 DrawEllipse

Syntax

STATUS **DrawEllips**
xLength

Description

Draws an ellipse cen
in the x-axis, and *yL*

If dot width is greater

If both fill pattern m
which is not covered

If fill pattern mode is
ellipse border will be



Parameter

Name
<i>greyLevel</i>
<i>xCenter</i>
<i>yCenter</i>
<i>xLength</i>
<i>yLength</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_GREY
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_STYLE

20.20 DrawHorz

Syntax

STATUS **DrawHorz**(U16 *gre*
dotLine, U16 *sty*)

Description

Draws a horizontal line from

If dot width is greater than 1,
greater than 1 and the width
indicated by dot width will be

If *dotLine* is non-zero, *dotLin*
grey level; then, the *dotLine*
number of dots will be drawn

Parameter

Name
<i>greyLevel</i>

Name
<i>xSrc</i>
<i>ySrc</i>
<i>width</i>
<i>dotLine</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_G
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_S

20.21 DrawLine

Syntax

STATUS **DrawLine**(
yDest, U

Description

Draws a line from (x

If dot width is greater
than 1 and (*xSrc*, *yS*
by dot width will be c

If *dotLine* is non-zero
grey level; then, the
number of dots will b



Parameter

Name
<i>xSrc</i>
<i>ySrc</i>
<i>width</i>
<i>height</i>
<i>bitmap</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT

20.26 GetDisplayX

Syntax

U16 GetDisplayX(void)

Description

Returns the LCD display scr

Parameter

Name
None

Return Value

Name
N/A

Hint

Parameter

Name
<i>greyLevel</i>
<i>xSrc</i>
<i>ySrc</i>
<i>xDest</i>
<i>yDest</i>
<i>dotLine</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_G
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_S

20.23 DrawVector

Syntax

STATUS DrawVector(
pPoints,

Description

Draws lines to conn
input. No connection
specified by *mode* or

DrawVector() does n



Parameter

Name
<i>greyLevel</i>
<i>numberOfPoints</i>
<i>pPoints</i>
<i>style</i>
<i>mode</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_LCD_GREY
PPSM_ERR_LCD_STYLE
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y

Hint

If the output style is EXOR_
overlapped points.

20.24 DrawVert

Syntax

STATUS **DrawVert**(U16 *grey*
dotLine, U16 *sty*

Description

Draws a vertical line from (x:
If dot width is greater than 1
greater than 1 and the heig
indicated by dot width will be

If *dotLine* is non-zero
grey level; then, the
number of dots will be

Parameter

Name
<i>greyLevel</i>
<i>xSrc</i>
<i>ySrc</i>
<i>height</i>
<i>dotLine</i>
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_G
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_S

20.25 ExchangeRec

Syntax

STATUS **ExchangeRec**(
bitmap

Description

Swaps the image in
specified location of
now be displayed with
stored at *bitmap*.

Note that the image
rectangle in the argu



20.32 LCDContrast

Syntax

STATUS LCDContrast(U8 c

Description

This tool will pass the value
The user needs to set or res

Parameter

Name
contrast

Return Value

Name
PPSM_OK

Application program
applications size ind

20.27 GetDisplayY

Syntax

U16 GetDisplayY(v

Description

Returns the display s

Parameter

Name
None

Return Value

Name
N/A

Hint

Application program
applications size ind

20.28 GetLogicalX

Syntax

U16 GetLogicalX(v

Description

Returns the current p
the size that an app
display screen (i.e. th
screen).

Parameter

Name
None



Return Value

Name
N/A

20.29 GetLogicalY

Syntax

U16 **GetLogicalY**(void)

Description

Returns the current panning gives the size that an applic LCD display screen (i.e. the display screen).

Parameter

Name
None

Return Value

Name
N/A

20.30 GetScreenMem

Syntax

P_VOID **GetScreenMem**(U1

Description

This tool will allocate approp and *height*.

Parameter

Name
<i>width</i>
<i>height</i>

Return Value

Name
N/A

20.31 InvRec

Syntax

STATUS **InvRec**(U1

Description

Inverts the grey level

Parameter

Name
xSrc
ySrc
<i>width</i>
<i>height</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT



Name
<i>reserved</i>

Return Value

Name
PPSM_OK
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT
PPSM_ERR_LCD_STYLE

20.37 SaveRec

Syntax

STATUS **SaveRec**(P_U8 *bitmap*
U16 *reserved*)

Description

Saves a rectangular bitmap screen to memory.

Parameter

Name
<i>bitmap</i>
<i>xSrc</i>
<i>ySrc</i>
<i>width</i>
<i>height</i>
<i>reserved</i>

Return Value

Name
PPSM_OK

20.33 LCDRefreshRate

Syntax

STATUS **LCDRefreshRate**

Description

This tool will set the refresh rate to the second. As the frame rate is set, the Refresh Rate Adjust Register and PLL Clock will be set to the closest possible value. The *refreshRateSet* will be called once more after the calling of **LCDRefreshRate**.

Parameter

Name
<i>refreshRate</i>
<i>refreshRateSet</i>

Return Value

Name
PPSM_OK

20.34 LCDScreenMove

Syntax

STATUS **LCDScreenMove**

Description

This function is used to move the LCD display. Maps the LCD display to the panning screen with the screen.

It is assumed that (x,



Parameter

Name
<i>x</i>
<i>y</i>

Return Value

Name
PPSM_OK

Hint

This must be used with Curs

20.35 PutChar

Syntax

STATUS **PutChar**(U16 greyL
font, U16 width,

Description

This tool will put a 1 bit/pixe
depending on whether ppsm

Parameter

Name
<i>greyLevel</i>
<i>character</i>
<i>xPos</i>
<i>yPos</i>
<i>font</i>
<i>width</i>
<i>height</i>

Name
<i>style</i>

Return Value

Name
PPSM_OK
PPSM_ERR_PAN_IN
PPSM_ERR_GREY
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_LCD_F
PPSM_ERR_LCD_S
PPSM_ERROR

20.36 PutRec

Syntax

STATUS **PutRec**(P_
U16 *styl*

Description

Puts a rectangular b
panning screen.

Parameter

Name
<i>bitmap</i>
<i>xSrc</i>
<i>ySrc</i>
<i>width</i>
<i>height</i>
<i>style</i>



Parameter

Name
<i>dbld</i>
<i>recl</i>
<i>numFmt</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_DBID
PPSM_ERR_NUM_FMT

Hint

For DBAddRecord() to work, a record must be created by calling DBAdd() p

21.3 DBAddRecToTop

Syntax

STATUS DBAddRecToTop(

Description

Adds a blank record at the top of the database. User has the option to specify the number of records. The valid range of *numFmt* is 1 to 255.

This tool is meant to complement the DBAdd() p

Parameter

Name
<i>dbld</i>
<i>numFmt</i>
<i>outRecl</i>

Name
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_WIDTH
PPSM_ERR_HEIGHT

20.38 SetDotWidth

Syntax

STATUS SetDotWidth(

Description

This tool sets the width of the dot drawn by DrawDot(), a the

This dot width is applied to DrawEllipse(), DrawArc(),

If oldWidth is non-zero, the

Parameter

Name
<i>newWidth</i>
<i>oldWidth</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DOT_W

20.39 SetPatternFill

Syntax

STATUS SetPatternFill(

Description



This tool sets the pattern fill
DrawEllipse() and DrawArc()



1



5

The pattern fill mode 0 will tu

Parameter

Name
<i>mode</i>
<i>backGrey</i>
<i>borderMode</i>
<i>fillSpace</i>

Return Value

Name
PPSM_OK
PPSM_ERR_FILL_PATTERN
PPSM_ERR_LCD_GREY
PPSM_ERR_FILL_SPACE

Chapter 21 Database Ma

21.1 DBAdd

Syntax

STATUS DBAdd(P_

Description

Adds a new databas
called whenever a
database.

Parameter

Name
<i>dbId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_AD

Hint

The returned *dbId* m
the database.

21.2 DBAddRecord

Syntax

STATUS DBAddRec

Description

Appends a blank rec
User has the option
The valid range of *n*



Name
PPSM_ERR_DB_TYPE

Hint

The record and database r
environment.

Observes the unformatted d

21.7 DBDelete

Syntax

STATUS **DBDelete**(U32 *dbl*

Description

Removes a database from P

Parameter

Name
<i>dbld</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_DBID

Hint

The database referred to mu

21.8 DBDeleteRecord

Syntax

STATUS **DBDeleteRecord**(l

Description

Removes a particular recor
associated memory.

Return value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DB
PPSM_ERR_NUM_F

Hint

This tool is meant to
ordered record list.

For DBAddRecToTo
created by calling DB
recID passed must b

21.4 DBAppendRecord

Syntax

STATUS **DBAppend**
outRecld

Description

Appends a blank rec
the record identifier,
option to specify ad
range of *numFmt* is

Parameter

Name
<i>dbld</i>
<i>recld</i>
<i>numFmt</i>
<i>outRecld</i>

Return value

Name
PPSM_OK



Name
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RECID
PPSM_ERR_NUM_FMT

Hint

This tool is meant to facilitate
ordered record list.

For DBAppendRecord() to w
created by calling DBAdd() p
recID passed must be a valid

21.5 DBChangeStdData

Syntax

STATUS DBChangeStdData

Description

Changes the data in a pred
database.

Parameter

Name
<i>dbId</i>
<i>recId</i>
<i>fieldId</i>
<i>data</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RE
PPSM_ERR_DB_FD

Hint

Adheres to the size l

The record and dat
environment.

21.6 DBChangeUnfDa

Syntax

STATUS DBChange
S32 size

Description

Changes the *data* in

Parameter

Name
<i>dbId</i>
<i>recId</i>
<i>type</i>
<i>data</i>
<i>size</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RE



Parameter

Name
<i>dbId</i>
<i>recId</i>
<i>fieldId</i>
<i>data</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RECID
PPSM_ERR_DB_FDID

Hint

The database and record r
environment. If a user define
to check the return status for
does exist before using the r

21.13 DBReadTotalNumber

Syntax

STATUS DBReadTotalNum

Description

Reads the total number of d

Parameter

Name
<i>numDB</i>

Return Value

Name
PPSM_OK

Parameter

Name
<i>dbId</i>
<i>recId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RECID

Hint

The database and
environment.

21.9 DBGetFirstRecID

Syntax

STATUS DBGetFirs

Description

Gets the record ID o

Parameter

Name
<i>dbId</i>
<i>recId</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID

Hint



This tool is useful for implem
The database referred to mu

STATUS DBGetPrev
topListF

Description

Gets the identifier
specified record is t
recId, and the topLis

Parameter

Name
dbId
recId
prevID
topListFlag

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_REC

Hint

This tool is useful for
The database and
environment.

21.10 DBGetNextRecID

Syntax

STATUS DBGetNextRecID(
botListFlag)

Description

Gets the identifier of the rec
record is the last record, ne
botListFlag will be set.

Parameter

Name
dbId
recId
nextID
botListFlag

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_REC

Hint

This tool is for implementing
The database and record r
environment

21.11 DBGetPrevRecID

Syntax

21.12 DBReadData

Syntax

STATUS DBReadDa

Description

Reads the formatted



Name
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RECID
PPSM_ERR_DB_FDID
PPSM_NO_MATCH

Hint

Current implementation of to
There is no provision for the

For good programming practi
a valid search is found before

21.18 DBSecretFlag

Syntax

STATUS **DBSecretFlag**(U32

Description

Checks if the secret flag of a

Parameter

Name
<i>dbId</i>
<i>sFlag</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID

Hint

The database referred to mu

Name
PPSM_ERR_DB_RE

21.14 DBReadTotalNum

Syntax

STATUS **DBReadTo**

Description

Reads the total num

Parameter

Name
<i>dbId</i>
<i>numRec</i>

Return Value

Name
PPSM_OK
PPSM_ERR_DB_DB

Hint

The database referre

21.15 DBReadUnfData

Syntax

STATUS **DBReadUn**
P_S32 s

Description

Reads the *data* in the
pointer to the unform
also pass back the t



Parameter

Name
<i>dbId</i>
<i>recId</i>
<i>type</i>
<i>data</i>
<i>size</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RECID

Hint

The database and record r
environment.

It is good practice for user to
using the *data*.

21.16 DBRecordSecret

Syntax

STATUS **DBRecordSecret**(l

Description

Checks if the secret flag of a

Parameter

Name
<i>dbId</i>
<i>recId</i>

Name
<i>sFlag</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_RE

Hint

The database and
environment.

21.17 DBSearchData

Syntax

STATUS **DBSearch**

Description

Searches though the
that matches the s
operation. If PPSM_
identifier of the recor

Parameter

Name
<i>dbId</i>
<i>fieldId</i>
<i>data</i>
<i>recId</i>

Return Value

Name
PPSM_OK



Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID

22.3 TextMap

Syntax

STATUS **TextMap**(U32 temp

Description

Displays the given text onto t
text template identified by te

The text will be displayed sta
font type, output style and
template. Text that extends l
by the text template will be tr
automatically updated by the

Parameter

Name
<i>templateId</i>
<i>buffer</i>
<i>numChar</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_CUR

22.4 TextReadCursor

Syntax

STATUS **TextReadCursor**(L

Description

21.19 DBSetRecordSe

Syntax

STATUS **DBSetRec**

Description

Sets the secret flag o

Parameter

Name
<i>dbId</i>
<i>recId</i>
<i>sFlag</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DB
PPSM_ERR_DB_RE
PPSM_ERR_DB_SF

Hint

The database and m
environment.

Note that when a ne
the secret flag of the
in the database to be
after DBAdd() is call

21.20 DBSetSecretFlag

Syntax

STATUS **DBSetSec**

Description



Sets the secret flag of a
subsequently in the specifie

Parameter

Name
<i>dbId</i>
<i>sFlag</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_DB_DBID
PPSM_ERR_DB_SFLAG

Hint

The database referred to m
User can use this flag to impl

Note that the secret flag is :
wants all records in the
DBSetSecretFlag() immediat

Chapter 22 Text Tools

22.1 TextCreate

Syntax

STATUS TextCreate

Description

Creates and initialize
for the created text t

This is the first text
displayed on the pa
further references to

Parameter

Name
<i>templateId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_

22.2 TextDelete

Syntax

STATUS TextDelete

Description

Deletes a text templa
text template is not r

Parameter

Name
<i>templateId</i>

Name
<i>pFontAttr</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_FONT
PPSM_ERR_NO_MEMORY

22.8 TextSetOutlook

Syntax

STATUS **TextSetOutlook**(U:

Description

Sets up the output style and values. Subsequent text map these new settings.

The output style is defined character bitmap and the im bitmap will be displayed. Five replace, OR with, AND with, existing image.

Up to four grey levels are cur grey levels supported are w grey levels supported are wh

Reads the current c
templateId. The char
text display area.

Parameter

Name
<i>templateId</i>
<i>cursor</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_

22.5 TextSetCursor

Syntax

STATUS **TextSetCu**

Description

Sets the current cha
templateId to the nev
positions to set to
characters - 1).

Parameter

Name
<i>templateId</i>
<i>cursor</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_
PPSM_ERR_TEXT_



22.6 TextSetDisplay

Syntax

STATUS **TextSetDisplay**(U3
U16 *height*, U16

Description

Sets up the text display layout given values. The text displa text template. Subsequent displayed with the new layout

The text display layout spe panning screen. The size of tl the size of the font type sp character cursor positions to number of characters - 1).

Parameter

Name
<i>templateId</i>
<i>xPos</i>
<i>yPos</i>
<i>width</i>
<i>height</i>
<i>cursor</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_X
PPSM_ERR_TEXT_Y
PPSM_ERR_TEXT_WIDTH

Name
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_X

22.7 TextSetFont

Syntax

STATUS **TextSetFont**

Description

Sets up the font attri using this text templ

Eight font types are c 8 pixels English fonts fonts. GB Normal is is the same as GB N 16 Chinese font in B BIG5 code format.

Note: Asian fonts a

The specified font wi type is specified. The font libraries being p

The attribute field is

Parameter

Name
<i>templateId</i>



Parameter

Name
<i>templateId</i>
<i>outputStyle</i>
<i>greyLevel</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_
PPSM_ERR_TEXT_
PPSM_ERR_TEXT_

22.9 TextSetup

Syntax

STATUS **TextSetup**
greyLev

Description

Sets up the font type
template with the g
template will be disp



This tool does not support t
type and is provided for bac
used, default font size of 16 :

Please refer to TextSetDispla
(Section 22.7 - TextSetF
TextSetOutlook) for detailed

Parameter

Name
<i>templateId</i>
<i>fontType</i>
<i>outputStyle</i>
<i>greyLevel</i>
<i>xPos</i>
<i>yPos</i>
<i>width</i>
<i>height</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID

Name
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_ID

22.10 TextUnmap

Syntax

STATUS TextUnmap

Description

Clears the entire tex

Parameter

Name
<i>templateId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TEXT_ID



Return Value

Name
PPSM_OK
PPSM_ERR_YEAR
PPSM_ERR_MONTH
PPSM_ERR_DAY
PPSM_ERR_HOUR
PPSM_ERR_MINUTE
PPSM_ERR_SECOND

23.6 AlarmSetId

Syntax

STATUS **AlarmSetId**(P_U32
hour, U16 minut

Description

Set alarm at specific time an
alarm time, a message with t
task is swapped out or the :
swapped in and the system
tasks happen, the earlier the
in. If alarmId is 0, no alarm i
several alarms are set at the
task which set the alarm first
alarm will stop in the task w
messages are sent to other t

Parameter

Name
<i>alarmId</i>
<i>year</i>
<i>month</i>
<i>date</i>
<i>hour</i>

Chapter 23 Timer Tools

23.1 AlarmClear

Syntax

void **AlarmClear**(voi

Description

Clear all alarms set
other tasks.

Parameter

Name
None

Return Value

Name
None

23.2 AlarmClearId

Syntax

void **AlarmClearId**(U

Description

This function will cle
alarm set can be of a

Parameter

Name
<i>alarmId</i>

Return Value

Name
None



23.3 AlarmRead

Syntax

STATUS **AlarmRead**(P_U16
P_U16 *minute*, F

Description

Reads the up coming alarm :

Parameter

Name
<i>year</i>
<i>month</i>
<i>day</i>
<i>hour</i>
<i>minute</i>
<i>second</i>

Return Value

Name
PPSM_OK
PPSM_ERR_NO_ALARM

23.4 AlarmReadId

Syntax

STATUS **AlarmReadId**(U32
P_U16 *hour*, P_U

Description

This function will read the al

Parameter

Name
<i>alarmId</i>
<i>year</i>
<i>month</i>

Name
<i>day</i>
<i>hour</i>
<i>minute</i>
<i>second</i>

Return Value

Name
PPSM_OK
PPSM_ERROR
PPSM_ERR_NO_AL

23.5 AlarmSet

Syntax

STATUS **AlarmSet**(U
second)

Description

Sets the *year*, *month*
set, the application v
when the specified ti

Parameter

Name
<i>year</i>
<i>month</i>
<i>day</i>
<i>hour</i>
<i>minute</i>
<i>second</i>

For DragonBall not DragonE
pen input sampling rate. A h
accurate result.

Parameter

Name
<i>millisecond</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TMOUT_VALUE

23.11 RefFineTimeAlarm

Syntax

STATUS RefFineTimeAlarm

Description

Sets up an alarm time with re
microseconds. Maximum p
0x7FFFFFFF/10 millisecond.

Parameter

Name
<i>alarmTime</i>

Return Value

Name
PPSM_OK

23.12 RefFineTimeAlarmId

Syntax

Name
<i>minute</i>
<i>second</i>

Return Value

Name
PPSM_OK
PPSM_ERR_YEAR
PPSM_ERR_MONTH
PPSM_ERR_DAY
PPSM_ERR_HOUR
PPSM_ERR_MINUT
PPSM_ERR_SECON

23.7 DateTimeRead

Syntax

STATUS DateTimeR
P_U16 /

Description

Gets the system dat

Parameter

Name
<i>year</i>
<i>month</i>
<i>day</i>
<i>hour</i>
<i>minute</i>
<i>second</i>

Return Value

Name
PPSM_OK



Name
PPSM_ERR_YEAR
PPSM_ERR_MONTH
PPSM_ERR_DAY
PPSM_ERR_HOUR
PPSM_ERR_MINUTE
PPSM_ERR_SECOND

23.8 DateTimeSet

Syntax

STATUS **DateTimeSet**(U16 ,
U16 *second*)

Description

Sets the system date and tim

Parameter

Name
<i>year</i>
<i>month</i>
<i>day</i>
<i>hour</i>
<i>minute</i>
<i>second</i>

Return Value

Name
PPSM_OK
PPSM_ERR_YEAR
PPSM_ERR_MONTH
PPSM_ERR_DAY
PPSM_ERR_HOUR
PPSM_ERR_MINUTE
PPSM_ERR_SECOND

23.9 DeleteTimer

Syntax

STATUS **DeleteTimer**

Description

Delete the timer in ti
task as far as the tim

Parameter

Name
<i>timerId</i>

Return Value

Name
PPSM_OK
PPSM_ERROR

23.10 InputTimeout

Syntax

STATUS **InputTimeo**

Description

Sets the repetitive ti
time-out routine is a
device.

Once this time-out r
argument list is set a
is detected. If the t
occurred, PPSM wi
otherwise, the time-c
This is a repetitive ti
each pen input strok

To disable the time-c
value allowed is 100

In IrptGetData(), the
timeout from normal



This routine takes in two refe
between the two. This routin
32-bit continuous reference v
in unit of milliseconds.

Parameter

Name
<i>beginTime</i>
<i>endTime</i>

Return Value

Name
N/A

23.18 RefTimeRead

Syntax

U32 RefTimeRead(void)

Description

Returns the current 32-bit
milliseconds. The calling of
RefFineTimeRead().

Parameter

Name
void

Return Value

Name
N/A

23.19 SetPeriod

Syntax

STATUS RefFineTim

Description

Sets up an alarm tim
microseconds. Maxi
0x7FFFFFFF/10 mill

Parameter

Name
<i>alarmId</i>
<i>alarmTime</i>

Return Value

Name
PPSM_OK

23.13 RefFineTimeDiff

Syntax

U32 RefFineTimeD

Description

This routine takes in
between the two time
the 32-bit continuous
are in unit of 100 mic

Parameter

Name
<i>beginTime</i>
<i>endTime</i>



Return Value

Name
N/A

23.14 RefFineTimeRead

Syntax

U32 RefFineTimeRead(void)

Description

Returns the current 32-bit r
microseconds. This is recom
it doesn't involve much calcul
will need more CPU time
millisecond.

Parameter

Name
void

Return Value

Name
N/A

23.15 RefTimeAlarm

Syntax

STATUS RefTimeAlarm(U32

Description

Sets up an alarm time with
milliseconds. Maximum per
0x7FFFFFFF/10 millisecond:

Parameter

Name
<i>alarmTime</i>

Return Value

Name
PPSM_OK

23.16 RefTimeAlarmId

Syntax

STATUS RefTimeAl

Description

Sets up an alarm tim
milliseconds. Maxim
0x7FFFFFFF/10 mill

Parameter

Name
<i>alarmId</i>
<i>alarmTime</i>

Return Value

Name
PPSM_OK

23.17 RefTimeDiff

Syntax

U32 RefTimeDiff(U32

Description



STATUS SetPeriod()

Description

Sets the periodic int
send a periodic in
messages, to the ca

Parameter

Name
<i>period</i>

Return Value

Name
PPSM_OK
PPSM_ERR_PERIOD

23.20 SetPeriodId

Syntax

STATUS SetPeriodId

Description

This function will se
interrupt is available
going to be killed w
The returned value c

Parameter

Name
<i>alarmId</i>



Name
<i>period</i>

Return Value

Name
PPSM_OK
PPSM_ERR_PERIOD
PPSM_ERR_NO_MEMORY

23.21 Timeout

Syntax

STATUS **Timeout**(U32 *millis*)

Description

General timer time-out routine.

The application that calls the **Timeout** function is given the PPSM. A time interrupt is generated when the timer expires.

Maximum allowed value for *millis* is 0xFFFF.

Parameter

Name
<i>millisecond</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TMOUT

23.22 TimeoutId

Syntax

STATUS **TimeoutId**(U32 *millis*)

Description

General timer time-out routine.

The application that calls the **TimeoutId** function is given the PPSM. A time interrupt is generated when the timer expires with the timerId.

Maximum allowed value for *millis* is 0xFFFF.

Parameter

Name
<i>timerId</i>
<i>millisecond</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TMOUT



Return Value

Name
PPSM_OK
PPSM_ERROR

24.6 TaskMemUsed

Syntax

STATUS TaskMemUsed(U3

Description

Inquire memory usage of a t
of bytes of memory allocate
Lrealloc().

Parameter

Name
<i>taskId</i>
<i>pSizeUsed</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_ID

24.7 TaskStackAvail

Syntax

S32 TaskStackAvail(void)

Description

PPSM returns to the caller the to
current task when calling TaskSta
has not been used up, negative \

Chapter 24 Memory Man

24.1 Lcalloc

Syntax

void *Lcalloc(U32 s

Description

Dynamic allocation o
caller a pointer to a
the Linker Specifica
memory, in number
memory available in

The memory pointed

Parameter

Name
<i>size</i>

Return Value

Name
N/A

24.2 Lfree

Syntax

void Lfree(void *ptr)

Description

Returns the memory
supplied must be a
allocation tools.



Parameter

Name
<i>ptr</i>

Return Value

Name
None

24.3 Lmalloc

Syntax

void ***Lmalloc**(U32 *size*)

Description

Dynamic allocation of run-time caller a pointer to a region of the Linker Specification File memory, in number of bytes memory available in the system.

The memory pointed to by the

PPSM returns the size of the when calling Lmalloc(LARG

Parameter

Name
<i>size</i>

Return Value

Name
N/A

24.4 Lrealloc

Syntax

void ***Lrealloc**(void **ptr*, U32 *size*)

Description

Moving of memory. from one location to at the original location the heap. The purpose

Parameter

Name
<i>ptr</i>
<i>size</i>

Return Value

Name
N/A

24.5 MoveBlock

Syntax

STATUS **MoveBlock**(U32 *srcAddr*, U32 *destAddr*, U32 *size*)

Description

Copies a block of memory destination location. Overlapping of memory

Parameter

Name
<i>srcAddr</i>
<i>destAddr</i>
<i>size</i>



Parameter

Name
milliSecond

Return Value

Name
PPSM_OK
PPSM_ERR_DOZE_TIME

25.3 SetDutyCycle

Syntax

U16 SetDutyCycle(U16 per

Description

This tool allows the applicat
within a system can ha
automatically changes the F
become active.

Parameter

Name
percentage

Parameter

Name
None

Return Value

Name
N/A

24.8 TotalMemSize

Syntax

U32 TotalMemSize(

Description

This routine returns
allocated through L
returned by this func
specified in the Link

Parameter

Name
None

Return Value

Name
N/A

24.9 TotalMemUsed

Syntax

U32 TotalMemUsed

Description



Inquire run-time memory usage
the total number of bytes of memory
through Lmalloc(), Lcalloc() (

Parameter

Name
None

Return Value

Name
N/A

Note: Value returned by Tc
size of all memory re
variables and strings
function. For SDS us
by the symbol lister,
directory.

Chapter 25 Power Management

25.1 SetDozeMode

Syntax

void SetDozeMode(

Description

Sets system to go in

Parameter

Name
None

Return Value

Name
None

25.2 SetDozePeriod

Syntax

STATUS SetDozePe

Description

Sets the countdown
mode. A value of zero
is no message to be
equals PPSM_NO_D
so no automatically

Return Value



Return Value

Name
PPSM_OK
PPSM_ERR_SLEEP_TIME

Chapter 26 UART Comm

26.1 UARTConfigure

Syntax

STATUS UARTConf
charLen

Description

Configures the UART
of *stopBits*, and *char*

The UART hardware
course of this config
aborted.

Both the normal NR2
and maximum baud
per second correspo

Parameter

Name
<i>mode</i>



26.5 UARTReadData

Syntax

STATUS UARTReadData(P

Description

Reads data received from th

An application can initiate a UART by calling UARTRecei receives data from the UAR calling application. The calli UARTReadData().

The calling application needs the received data. PPSM wi number of bytes of data reac

An error condition will be retu permission to use the UART, UARTReadData() is called.

If RTS/CTS is enabled, RTS Data() and asserted after dai

Parameter

Name
<i>pData</i>
<i>bufSize</i>
<i>sizeRead</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID_ACCE
PPSM_ERR_NO_REQUEST

26.6 UARTReceive

Syntax

STATUS UARTReceive(U8

Name
PPSM_ERR_INVALID
PPSM_ERR_MODE
PPSM_ERR_BAUD
PPSM_ERR_PARITY
PPSM_ERR_STOPB
PPSM_ERR_CHARL

26.2 UARTFlowCtrl

Syntax

STATUS UARTFlow

Description

Enable or disable ha
can handle data con
hardware flow contr
UARTFlowCtrl() with

Parameter

Name
<i>controlType</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID
PPSM_ERROR

26.3 UARTInquire

Syntax



```
void UARTInquire(P_U8 mc  
stopBits, P_U8 c
```

Description

Returns the current operating
charLen settings of the UAR

The returned values, excep
UARTConfigure() (*Section*
returned is in unit of bits per

Parameter

Name
<i>mode</i>
<i>baudRate</i>
<i>parity</i>
<i>stopBits</i>
<i>charLen</i>

Return Value

Name
None

Parameter

Name
<i>controlType</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID
PPSM_ERR_RCTS_

26.4 UARTRcvCtrl

Syntax

STATUS **UARTRcvCtrl**(U8

Description

Pause or continue receiving
application can pause or
hardware control is enabled.
flow control is not enabled.



Return Value

Name
PPSM_OK
PPSM_ERR_INVALID_ACCE:
PPSM_ERR_RCTS_IDLE

26.10 UARTSetDelay

Syntax

STATUS **UARTSetDelay**(L

Description

In order to communicate with app
transmitting data in a burst of pul
racy of transmission. This func
between each transmission of all
interrupts).

The range of delay values suppo

Parameter

Name
<i>type</i>
<i>delay</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID_ACCE:
PPSM_ERR_INVALID_TXDEI

Description

Initiates or aborts a U

If *receiveFlag* is UA
initiated, and PPSM

If *receiveFlag* is UA
be aborted.

When PPSM receiv
application notifying
read the received
UARTReadData).

Application task swa
and re-enabled after

Parameter

Name
<i>receiveFlag</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID
PPSM_ERR_BUSY

26.7 UARTSend

Syntax

STATUS **UARTSend**

Description

Initiates or aborts a U

If *sendFlag* is UART
PPSM will start send

If *sendFlag* is UA
aborted.



The calling application need PPSM for sending out.

When PPSM finishes sendin calling application notifying it

Application task swapping is and re-enabled after the sen

Parameter

Name
<i>sendFlag</i>
<i>pData</i>
<i>dataLen</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID_ACCE
PPSM_ERR_BUSY

26.8 UARTSendAbort

Syntax

STATUS **UARTSendAbort**(*sendSize*)

Description

Terminate the current UART the same as calling UART: aborting the ongoing transmi current position of internal tra have been sent. Caller ca transmission by calling UAR

Parameter

Name
<i>abortFlag</i>
<i>pSendData</i>
<i>sendSize</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID

26.9 UARTSendCtrl

Syntax

STATUS **UARTSen**

Description

Pause or continue application can pau hardware control is e flow control is not en

Parameter

Name
<i>controlType</i>



Name
<i>newScreen</i>
<i>screenWidth</i>
<i>screenHeight</i>
<i>bitmap</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_ID
PPSM_ERR_TASK_FLAG
PPSM_ERR_TASK_WIDTH
PPSM_ERR_TASK_HEIGHT
PPSM_ERR_COORDINATE
PPSM_ERR_NO_MEMORY

27.2 AppSwap

Syntax

void **AppSwap**(U16 *flag*)

Description

If *flag* is FALSE, no task swa
on application icon nor us
AdvSendMessage() are cal
message will still be sent to t

26.11 UARTTimeout

Syntax

STATUS **UARTTime**

Description

Sets the maximum
interrupts.

This time-out funcio
data stream terminat

System do not initia
starts timeout with
UARTReceive(), UA

The valid range of tim
of milliseconds). A
function related to U

Parameter

Name
<i>tmout</i>

Return Value

Name
PPSM_OK
PPSM_ERR_INVALID
PPSM_ERR_INVALID



Chapter 27 Task Handling

27.1 AdvTaskCreate

Syntax

STATUS AdvTaskC
ySrc, S1
screenV

Description

Creation of a new PP
same manner as the
It allows the caller to

- The launch icon
off screen. For e
to be created.
- The stack memo
- The panning scr
associated scree

The default screen
LCDVIRTWIDTH and

Parameter

Name
<i>taskId</i>
<i>procAddr</i>
<i>xSrc</i>
<i>ySrc</i>
<i>xDest</i>
<i>yDest</i>
<i>stackSize</i>



Description

To set the specific task to be swapped in, it will start from a task generally called once the task is swapped in.

Parameter

Name
<i>taskId</i>
<i>flag</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_ID

27.7 TaskStart

Syntax

STATUS **TaskStart**(U32 *taskId*)

Description

Begin execution of the first task. The first PPSM application icon launches the first PPSM application icon activating the application icon system.

Parameter

Name
<i>taskId</i>

Return Value

Name
PPSM_ERROR
PPSM_OK

ignored. Moreover, if the value of AppSwap(TRUE)

Parameter

Name
<i>flag</i>

Return Value

Name
None

27.3 SubTaskCreate

Syntax

STATUS **SubTaskCreate**(U16 *numArg*)

Description

Creating a sub-task. The sub-task is itself a sub-task and the new sub-task and the new sub-task has been created at the head of the sub-task a parent task can change in run-time.

This routine accepts the sub-task passed into the sub-task can accept input arguments.

Parameter

Name
<i>taskId</i>
<i>procAddr</i>
<i>stackSize</i>
<i>numArg</i>



Name
...

Return Value

Name
PPSM_OK
PPSM_ERR_NO_MEMORY

27.4 TaskCreate

Syntax

STATUS **TaskCreate**(P_U32
S16 *xDest*, S16

Description

PPSM needs to know the e
stage. The main body of a P
application. PPSM will create
required to run the applicatio

Parameter

Name
<i>taskId</i>
<i>procAddr</i>
<i>xSrc</i>
<i>ySrc</i>
<i>xDest</i>
<i>yDest</i>
<i>bitmap</i>

Return Value

Name
PPSM_OK

Name
PPSM_ERR_TASK_I
PPSM_ERR_COORR
PPSM_ERR_NO_ME

27.5 TaskHook

Syntax

STATUS **TaskHook**(

Description

Set the entry and exit
to be swapped in, en
is going to be swapp
and exitCallback sho
function should not
newApp) where oldA
and newApp will be t

Parameter

Name
taskId
entryCallback
exitCallback

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_I

27.6 TaskReInit

Syntax

STATUS **TaskReInit**



All data that the sender wants structure. No protocol or data and receiver must have a m the message being sent.

The data structure for the str

```
typedef struct _MESSAGE
{
    U16    messageType;
    U16    message;
    U32    misc;
    P_VOID data;
    U16    size;
    U16    reserved;
} PPSM_MESSAGE, *P_MESS/
```

If AppSwap(FALSE) is calle be sent but any form of task

If the system is in doze mode

Parameter

Name
<i>taskId</i>
<i>msg</i>
<i>flag</i>

27.8 TaskTerminate

Syntax

STATUS TaskTermi

Description

Termination of a tas system memory, suc the task and its sub

A task cannot term TaskTerminate() will the task with Lmallo

Parameter

Name
<i>taskId</i>

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_I



Chapter 28 Inter-Task M

28.1 AdvMessageDel

Syntax

STATUS AdvMessa

Description

This function will de
specific task, type a
0xFFFFFFFF in task
that field. SO if task
messages in all task

Parameter

Name
task
type
shortData

Return Value

Name
PPSM_ERR_TASK_I
PPSM_OK

28.2 AdvSendMessage

Syntax

STATUS AdvSendM

Description

This tool is used wh
task. If the receiver t

If msg is 0, no me
executed.



Return Value

Name
PPSM_OK
PPSM_ERR_TASK_
PPSM_ERR_NO_ME
PPSM_ERROR

28.3 MessageDelete

Syntax

STATUS MessageD

Description

This function will dele
specific type matche
"don't care" in that fi

Parameter

Name
type

Return Value

Name
PPSM_ERR_TASK_
PPSM_OK

28.4 SendMessage

Syntax

STATUS SendMess

Description

This tool is used wh
task. If the receiver t



All data that the sender want
structure. No protocol or dat
and receiver must have a m
the message being sent. O
message received.

The data structure for the str

```
typedef struct _MESSAGE
{
    U16    messageType
    U16    message;
    U32    misc;
    P_VOID data;
    U16    size;
    U16    reserved;
} PPSM_MESSAGE, *P_MESSA
```

If AppSwap(FALSE) is calle
be sent but any form of task

If the system is in doze mode

Parameter

Name
taskId
msg

Corresponding values between

SendMessage
STATUS SendMessage(U:
STATUS IrptGetData(P_U:
msg.messageType
msg.message
msg.misc

SendMes

msg.data
msg.size
msg.reserved

Return Value

Name
PPSM_OK
PPSM_ERR_TASK_I
PPSM_ERR_NO_ME
PPSM_ERROR

Parameter

Name
handlerFlag

Return Value

Name
PPSM_OK
PPSM_ERR_RELEASE

29.3 IrptRequest

Syntax

U32 IrptRequest(U32 handl

Description

This tool is used by the appli
handlers. Once requested a
handlers are directed to
identifiers.

When calling this tool, the us
request. The interrupt flags c
handler with a single call. If th
PPSM system will hook the
nothing.

The return value from this
handlers that have been gra
handler flag parameter. For e
set of handlers, and if all are
the same as the input hanc
handlers cannot be granted, i
parameter. If none is granted

Chapter 29 Interrupt Han

29.1 IrptGetData

Syntax

STATUS IrptGetDat

Description

This tool reads the
message. The intern
interrupt handler is
buffer.

The data returned fro
Different messages f
data. The pre-defin
listed below. The siz
in the last argument

PPSM does not imp
from User Defined h
integrator.

Parameter

Return Value	
IRPT_AUDIO	NA
IRPT_HWR	NA
IRPT_ICON	U3
IRPT_INPUT_ STATUS	U3
IRPT_KEY	NA



Return Value	*sData
IRPT_PEN	U32 - Areal
IRPT_RTC	U32 - Time
IRPT_TIMER	U32 - Time
IRPT_UART	N/A
IRPT_USER	User define

Return Value

Name
IRPT_AUDIO
IRPT_ERROR
IRPT_HWR
IRPT_ICON
IRPT_INPUT_STATUS
IRPT_INT
IRPT_IRQ1
IRPT_IRQ2
IRPT_IRQ3
IRPT_IRQ6
IRPT_KEY
IRPT_NONE
IRPT_PEN
IRPT_PWM
IRPT_RTC

Name
IRPT_SPIM
IRPT_SPIS
IRPT_TIMER
IRPT_UART
IRPT_USER
IRPT_WDG

29.2 IrptRelease

Syntax

STATUS IrptRelease

Description

This tool is used by the application to release an interrupt that has successfully requested. The interrupt must be a valid interrupt. The IrptRequest() tool must be called before the IrptRelease() tool is called. Once the IrptRelease() tool is called, any data on the interrupt is out and removed.

Once an interrupt has been released, other applications that use the interrupt can use it.

The application should call the IrptRelease() tool to release the interrupt.



A request is success
granted to another ta

Parameter

Name
<i>handlerFlag</i>

Return Value

Name
N/A

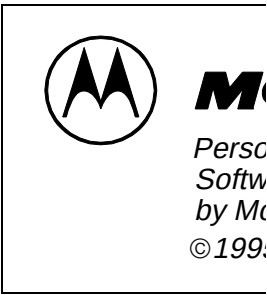


Figure 29-

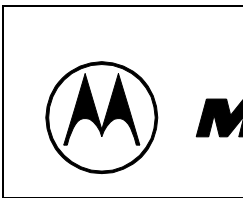


Figure 2

Parameter

Name
<i>calibration</i>

Return Value

Name
PPSM_OK
PPSM_ERR_NO_MEMORY
PPSM_ERROR



29.4 IrptSendData

Syntax

STATUS IrptSendData(U16

Description

Passes the user defined in application level. This routine handler only. After this me application that has requeste via the IrptGetData() tool.

Parameter

Name
<i>irptType</i>
<i>sData</i>
<i>data</i>
<i>size</i>

Return Value

Name
PPSM_OK
PPSM_ERR_IRPT_HANDLEF
PPSM_NO_MEMORY

Chapter 30 System Tool

30.1 PPSMInit

Syntax

STATUS PPSMInit(U

Description

PPSM initialization re system file before an

The input argument required at this time.

With the default calib screen, one near the The user must press the pen input calibra

The default calculati pixels (physical size of 100 (in A/D output edge of the touch p changing CalibrateP

If logo displaying is screen during the p dimensions, a differ screen, one for a sm or the LCD height is

Width (pixe
width => 28
150 <= width <
width < 15



31.2 **AudioInUse**

Syntax

U8 **AudioInUse**(void)

Description

It checks if PPSM audio tool:

Parameter

Name
<i>None</i>

Return Value

Name
AUDIO_OFF
WAVE_IN_USE
TONE_IN_USE

31.3 **AudioPlayTone**

Syntax

STATUS **AudioPlayTone**(P_
U8 autoRepeat)

Description

PPSM plays a sequence of d
having a fixed duration.

Parameter

Name
<i>toneData</i>
<i>toneSize</i>

30.2 **ReadSMVersion**

Syntax

STATUS **ReadSMVe**

Description

Returns PPSM major
major number will be

Parameter

Name
<i>major</i>
<i>minor</i>

Return Value

Name
PPSM_OK
PPSM_ERR_NO_ME



Chapter 31 Audio Tools

31.1 AdvAudioPlayW

Syntax

STATUS AdvAudioP
U8 repe

Description

This tool is valid for
wave signal. This is
configuration details.
• The value of pre
• The repeat rate
• The clkssel in the
This tool assumes th
module. For most ca

Parameter

Name
waveData
waveSize
prescaler
repeat
clkssel

Return Value

Name
PPSM_OK
PPSM_ERR_AUDIO,
PPSM_ERR_AUDIO,

Name
<i>toneDuration</i>
<i>autoRepeat</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AUDIO_
PPSM_ERR_AUDIO_

31.4 AudioPlayWave

Syntax

STATUS AudioPlay
sampling

Description

This tool is for Drag
signal with requested

Parameter

Name
<i>waveData</i>



Name
<i>waveSize</i>
<i>samplingRate</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AUDIO_INUSE

Description

Terminates the wave

Parameter

Name
<i>None</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AUDIO

31.5 AudioStopTone

Syntax

STATUS **AudioStopTone**(vc

Description

Terminates the tone playing.

Parameter

Name
<i>None</i>

Return Value

Name
PPSM_OK
PPSM_ERR_AUDIO

31.6 AudioStopWave (Drag

Syntax

STATUS **AudioStopWave**(v

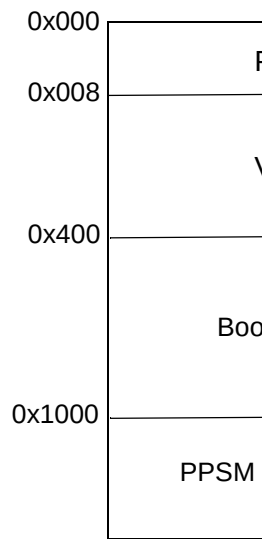


Figure 30-1 Me

Part IV System Integrat Guide

32.1.1.1 ROM_RESET

This is used to map the 68K first
as:

SECTION	rom_reset
DC.L	MON_STACKTOP
DC.L	rom_start-ROMADDR
DCB.L	254,0

The labels MON_STACKTOP an
with their absolute address only
values for these locations dynam
the absolute location and size of

ROMADDR is declared in the Lir

32.1.1.2 ROM_CODE

This regions is declared to store
part of PPSM library, they are de
memory map to avoid memory c

The first line of this region MUST
the region rom_reset to work out

The last line of this region shoul
start PPSM start-up code. The la
the startup code.



Chapter 32 How to make

To make PPSM applicati
different from running PP
items are:

- Boot Strap code
- Linker Specificat

This chapter gives some
PPSM applications.

32.1 Boot Strap Code

The boot strap code perf

- Starts the 68K c
- Map the chip-se
- platform
- Initialization of p
- Jump into PPSM

Depending on the size a
boot.s need to be chang

32.1.1 68K Start-up

In 68K architecture, the f
0x400, are reserved for s
random values. The first
defined for the start prog
reset.

In order to make this ass
than hard-coding the add
and rom_code, are defin
mapping.



32.1.2 Chip Selects

For the M68328ADS dev
and Chip-Select group B
Integrated Processor Us
programming.

32.1.3 Peripheral Devices

Initialization of the periph
controller. Please refer to
MC68328UM/AD, for det

32.2 Linker Supplicat

The Linker Supplications
main difference being tha
address, and some regio
are Read-Only, such as
Read/Write regions, such

The listing below shows

Example 30-1 Linker

```
partition { overlay {
    region {} rom_r
    region {} rom_c
    region {} code[
    region {} const
    region {} strin
    DATA = $;

    LCDPHYSWIDTH =
    LCDPHYSHEIGHT =
    LCDVIRTWIDTH =
    LCDVIRTHEIGHT =
    UARTRCVBUF = 25
} area2;
} ROM[addr=0x400000, s
partition { overlay {
    region {} data[
    region {} ram[r
    region {} mallo
    region {} stack
    STKTOP = $;
} area1; } RAM[addr=0x
```

In this example, a system
location 0x400000 and 1
0x0 has the following cha

- The ROM area s
- The region rom_
address, which i
- The region rom_
address, which i



- As much executable code as possible up to the next byte boundary starting from address 0
- As much constant data as possible up to the next byte boundary
- As much constant string as possible up to the next byte boundary
- DATA symbol to point to constants to pre-initialize
- A LCD physical display size
- A panning screen of 640
- A 256 byte internal UART
- The RAM area starts at 0x00000000
- As much initialized data as possible up to the next 0x400, round to 4-byte boundary
- As much zeroed uninitialized data as possible up to the next byte boundary
- 512 KByte of heap space
- 128 KByte of stack space
- A STKTOP symbol to point to the top of the stack

32.3 Generating S-Record

After the PPSM application has been built, it generates an output file in a proprietary format called S-Record.

SDS provides a tool, the loader, to convert the S-Record file into S-Record format.

32.3.1 Loader Options

To convert .OUT file into S-Record format, use the following options:

Options		
	-d mot	Generate S-Record for Motorola
	-o <path>\<filename>.dwn	Output file name
	-m data, DATA	Code memory address
	-w <address>	Generate S-Record for

32.3.2 Loader Commands

Convert .OUT file format

down -d mot <filename>.c

Example 30-2 Loader Command

down -d mot sample.out

This will convert the sample.out file into S-Record format and be burned into ROM address 0x00000000.

Example 30-3 Loader Command

down -d mot sample.out

This will convert the sample.out file into S-Record format and be burned into ROM address 0x00000000.



Chapter 33 Device Drive

ADS version	Q3
M68328ADS	PJ3
M68EZ328ADS	PD3

33.2.1 Pen Initialization

Syntax

```
void PenDevInit(void)
```

Description

This function initializes SPI sampling.

M68328ADS implementation:

Port J is used to control the
The default initialization value

Table

Port J	address
Direction Register	0xFFFF428
Select Register	0xFFFF42B

For SPI Master, the control r

Table

SPI Control Register, 0xF
Data Rate
SPI Enable
Exchange Bit
SPI Interrupt Enable
Phase Shift
Polarity
Clock Count

M68EZ328ADS implementation

PPSM supports device o
vendor dependent. These

- System configur
- Pen input driver
- LCD driver
- Handwriting reco
- Font driver
- UART driver

In compilation, PIXEL_1
corresponding device dri

33.1 System Configur

There are 2 system conf

- Boot Strap Drive
- Interrupt handler

33.1.1 Boot Strap Driver (I

Description

The boot strap code
devices and to map c
at boot time. Differ
different boot strap
device driver library
selects for the M68
Specification File an
hardware configurati

For hardware chara
MC68328 Integrated

33.1.2 User Interrupt Hanc

Description

This interrupt handle
handlers for certain l

Users can replace th
driver to perform exc
these user-defined h



refer to *Chapter 15 - Interrupt Tools* for details on interrupt

Please refer to the *MC68328UM/AD*, for details

A single argument is passed supplied by PPSM system before calling the user-defined locations of the registers related

Table 3.

Argument is the address

The following functions
void _SPIMIrptHandler(P_U32)
void _SPISIrptHandler(P_U32)
void _IRQ6IrptHandler(P_U32)
void _UARTIrptHandler(P_U32)
void _WatchdogIrptHandler(P_U32)
void _KeyboardIrptHandler(P_U32)
void _PWMIrptHandler(P_U32)
void _INTIrptHandler(P_U32)
void _IRQ3IrptHandler(P_U32)
void _IRQ2IrptHandler(P_U32)
void _IRQ1IrptHandler(P_U32)

M68328ADS implementation:

These interrupt handlers pass the address to the application immediately.

In general, _UARTIrptHandler is used by the user, a "-DNO_UART_HANDLER" option to indicate that the internal _UARTIrptHandler() is used

33.2 Pen Input Device

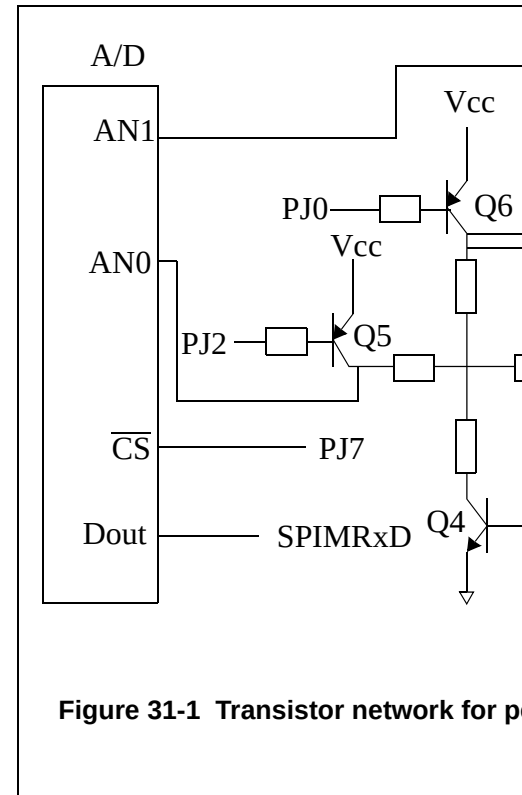


Figure 31-1 Transistor network for pen input device

Figure 31-1 shows the transistor network for the pen input device:

- 4 I/O pins on port D are connected to the network.
- I/O pin 7 on port D is connected to the D convertor.
- The SPI Master is connected to the output for the same

Please refer to the *M68328ADS* hardware configuration.

There are 4 functions in the pen input device:

- Pen Initialization
- Pen Interrupt Enable
- Pen Interrupt Disable
- Pen Read Device

For M68EZ328ADS, the port D and E instead of port D



For X sampling, the transistor
and Q5 are OFF, see *Figure*
the transistors are in this set
convertor for the sampling. T
stored in the SPI Data regist

For Y sampling, the proced
transistors Q3 and Q5 needs
see *Figure 31-1*, i.e. set Port

The X and Y samples thus
arguments passed in by the

Port D and E are use
panel. The default in
O pins.

Port D	ac
Direction Register	0xH
Select Register	0xH
Pullup Register	0xH
Select Register	0xH
Polarity	0xH
INT Enable	0xH
INT Edge	0xH

33.3 Pen Calibration(PenIn

User normally needs to do calibr
a correct mapping between touch
coordination. The system needs
corner of the touch panel coordir
do this coordinate mapping.

Syntax

STATUS CalibratePen(U16

Description

When pen calibration is necessa
default pen calibration algorithm
routine, the origin and maximum
screen coordinate) should be fec
and PenSetInputOrg(x, y).

By default, the Motorola logo is c
and the bottom left corners, are t

Port E3 is initialized
initialized to SPM fun

For SPI Master, the

SPIM Control Regi
Data Rate
SPIM Enable
Exchange Bit
SPIM Interrupt Enabl
Phase Shift
Polarity
Clock Count

33.4 LCD Device Drivers (I

Two functions are needed in this
LCD panel being used in the sys
functions will be called according

33.2.2 Pen Interrupt Enab

Syntax

void PenIrptEnabled

Description

This function enable

33.4.1 1 bit/pixel Initialization

Syntax

void _LCDDev1(void)

Description

This function initializes the
Application programmer ma



M68328ADS implementation:

Port M pin 6 is assigned as the following sequence is required:

- Enable Port M pin 6 pull-up
- Discharge the transistor network to 0, i.e. set Port J Data register, 0xFFFF43
- Charge up the transistor network to 1, i.e. set Port J Data register, 0xFFFF43
- Switch Port M pin 6 to input, i.e. set Port M Data register, 0xFFFF448, bit 6 to 0
- Enable Interrupt Mask Register

Please refer to the *M68328ADS* switching.

M68EZ328ADS implementation:

IRQ5(port F1) is assigned as the following sequence is required:

- Enable Port F pin 1 pull-up
- Discharge the transistor network to 0, i.e. set Port D Data register, 0x0D
- Charge up the transistor network to 1, i.e. set Port D Data register, 0x0D
- Switch Port F pin 1 to input, i.e. set Port F Data register, bit 1 to 0
- Enable Interrupt Mask Register

Please refer to the *M68EZ328ADS* switching.

33.2.3 Pen Interrupt Disable

Syntax

void **PenIrptDisable**(void)

Description

This function disables the Pen

M68328ADS implementation:

Port M pin 6 is assigned as the following sequence is required:

- Disable Interrupt Mask Register
- Switch Port M pin 6 to I/O, i.e. set Port M Data register, 0xFFFF448, bit 6 to 1
- Disable Port M pin 6 pull-up to interfere with A/D sampling

- Discharge the transistor network to 0, i.e. set Port J Data register, 0xFFFF439, to 0
- Switch transistor network to 1, i.e. set Port J Data register, 0xFFFF439, to 0

Please refer to *M68328ADS* switching.

M68EZ328ADS implementation:

IRQ5 is assigned as the following sequence is required:

- Disable Interrupt Mask Register
- Switch Port F pin 1 to I/O, i.e. set Port F Data register, bit 1 to 1
- Disable Port F pin 1 pull-up to interfere with A/D sampling
- Discharge the transistor network to 0, i.e. set Port D Data register, 0x0D
- Switch transistor network to 1, i.e. set Port D Data register, 0x0D

Please refer to *M68EZ328ADS* switching.

33.2.4 Pen Read Device

Syntax

void **PenReadDevice**(void)

Description

This function returns the Pen transistor network address

M68328ADS implementation:

For X sampling, the transistors Q3 and Q5 are OFF, set Port J Data register, 0xF9. While the transistor network is being sampled, the A/D convertor for the X channel is stored in the A/D convertor

For Y sampling, the transistors Q3 and Q5 are ON, see *Figure 31-1*, i.e. set Port J Data register, 0xF9

The X and Y sample values are returned in the arguments passed in

M68EZ328ADS implementation:



33.6.1 Font Library Information

A data structure type FONTLIB is used in the following libraries being used.

The FONTLIB type is defined as

```
typedef struct
{
    P_U8  baseAddr;
    U16   fontType;
    U16   fontWidth;
    U16   fontHeight;
    U16   bitmapSize;
} FONTLIB, *P_FONTLIB;
```

where:

- 1) baseAddr is the base address
- 2) fontType is the font type
- 3) fontWidth is the width of the font in pixels
- 4) fontHeight is the height of the font in pixels
- 5) bitmapSize is the amount of memory required for the font bitmap in unit of bytes

Assuming there is font bitmap or font type, the default font library information is as follows:

```
FONTLIB fontLib[] =
{
    {(P_U8)SMALL_ENG_FONT_ADDR, (P_U8)SMALL_ENG_FONT_WIDTH, (P_U8)SMALL_ENG_FONT_HEIGHT, (P_U8)SMALL_ENG_BITMAP_SIZE},
    {(P_U8)SMALL_ENG_FONT_ADDR, (P_U8)SMALL_ENG_FONT_WIDTH, (P_U8)SMALL_ENG_FONT_HEIGHT, (P_U8)SMALL_ENG_BITMAP_SIZE},
    {(P_U8)LARGE_ENG_FONT_ADDR, (P_U8)LARGE_ENG_FONT_WIDTH, (P_U8)LARGE_ENG_FONT_HEIGHT, (P_U8)LARGE_ENG_BITMAP_SIZE},
    {(P_U8)LARGE_ENG_FONT_ADDR, (P_U8)LARGE_ENG_FONT_WIDTH, (P_U8)LARGE_ENG_FONT_HEIGHT, (P_U8)LARGE_ENG_BITMAP_SIZE},
    {(P_U8)GB_FONT_ADDR, (P_U8)GB_FONT_WIDTH, (P_U8)GB_FONT_HEIGHT, (P_U8)GB_BITMAP_SIZE},
    {(P_U8)BITMAP_BIG5_FONT_ADDR, (P_U8)BITMAP_BIG5_FONT_WIDTH, (P_U8)BITMAP_BIG5_FONT_HEIGHT, (P_U8)BITMAP_BIG5_BITMAP_SIZE},
    {(P_U8)SCALABLE_BIG5_FONT_ADDR, (P_U8)SCALABLE_BIG5_FONT_WIDTH, (P_U8)SCALABLE_BIG5_FONT_HEIGHT, (P_U8)SCALABLE_BIG5_BITMAP_SIZE},
};
```

The fontLib data structure above is for the following types.

33.6.2 Font Library or Font Generation

Syntax

```
void FontInit(void)
```

Description

This function initializes the font library. This function will be called by the application.

Note: Font bitmaps library is applicable, whereas font generation library is not applicable, this driver will not work.

module. Generally, the following code is used:
"move.b #\$00,\$21(a0)"

33.4.2 2 bits/pixel Initialization

Syntax

```
void _LCDDDev2(void)
```

Description

This function initializes the LCD panel. Application program must call this function before using the module. Generally, the following code is used:
"move.b #\$00,\$21(a0)"

Please refer to the MC68000 AD, for details on the LCD panel.

M68328ADS implementation

_LCDDDev1 initializes the LCD panel.

- Panel Interface Configuration: bus size and no. of pins
- Pixel Clock Division: directly
- Polarity Configuration: the LCD panel uses

_LCDDDev2 initializes the LCD panel.

- Panel Interface Configuration: bus size with gray scale
- Pixel Clock Division: directly
- Gray Palette Mapping: 0x3075
- Polarity Configuration: the LCD panel uses

33.5 Handwriting Recognition

This driver is required for handwriting input while using the engines. The driver function is used for handwriting recognition.

This driver consists of the following functions:

33.5.1 Handwriting Recognition

Syntax



void **ResetRecEngine**(void)

Description

This function resets the hanc

This function should call a re
recognition engine. In some
functions as InitRecEngine()
Initialization).

This function is called once v
call of OpenInputPad().

33.5.2 Handwriting Recognition

Syntax

void **InitRecEngine**(void)

Description

This function initializes or ins

This function should call a
handwriting recognition eng
engine for the recognition pr

This function is called once a

33.5.3 Process One Stroke of H

Syntax

void **ProcessStroke**(U16 nu

Description

This function processes one
system.

Based on the input paramet
data for one stroke of input (
the corresponding handwritin
should then be sent to the ha
provided in the handwritir
optimization before the actu

This function is called for eve

Parameter

Name
<i>numPoints</i>
<i>strokeData</i>
<i>inputAreaId</i>

33.5.4 Initiate Character R

Syntax

void **RecognizeInpu**

Description

This function perform

This function should
handwriting recogni
processed stroke da
expected to return to
being recognized, an

This function is calle
an input time-out.

Return Value

Name
<i>numCandidates</i>
<i>candidates</i>

Note: Since PPSM
recognition e
default to pe

33.6 Font Driver (font

This driver is required for
supporting multiple font t
vendors.

The font driver consists o



Return Value

Name
None

Note: The driver function n
operation.

33.8.4 Disabling I/O ports when

Syntax

void PortSleepDisable(void,

Description

Just before PPSM goes into
user defined I/O ports that ar
in the code to disable the I/O

Return Value

Name
None

Note: The driver function n
operation.

routine prov

Since PPSM does n
function is default to

33.6.3 Font Accessing

Syntax

P_U8 FontGetChar.

Description

This function returns
attributes and charac

Please refer to Secti
FONTATTR data stru

Font lookup or gene
supplier. This drive
corresponding font t
the font attributes.

Since PPSM include
method for mapping
font types that use th

- SMALL_NORMA
- SMALL_ITALIC_
- LARGE_NORMA
- LARGE_ITALIC_

Parameter

Name
pFont
code

Return Value

Name
N/A



33.7 UART Device Driver (U

This UART device driver is a sup
Tools as described in *Chapter 26*
driver contains the UARTDevSer
send the BREAK character. This
MC68328 UART hardware regist
restoring of appropriate system i
device driver.

33.7.1 Sending the BREAK Char

Syntax

```
void UARTDevSendBreak(L
```

Description

This function starts or stops t
character depending on the (

If *sendBreak* flag is UART_
sending the BREAK charact

If *sendBreak* flag is UART_
sending the BREAK charact

It is assumed that *sendBrea*
value will be treated as UAR

Parameter

Name
<i>sendBreak</i>

Return Value

Name
None

33.8 Power Management D

4 functions are located in iodev.c
doze or sleep mode or leaving d

33.8.1 Enabling I/O ports v

Syntax

```
void PortDozeEnab
```

Description

When PPSM wakes
user defined I/O port
in their own I/O initia

Return Value

Name
None

Note: The driver fu
operation.

33.8.2 Disabling I/O ports

Syntax

```
void PortDozeDisab
```

Description

Just before PPSM g
user defined I/O port
in the code to disabl

Return Value

Name
None

Note: The driver fu
operation.

33.8.3 Enabling I/O ports v

Syntax

```
void PortSleepEnab
```

Description

When PPSM wakes
user defined I/O port
in their own I/O initia



Chapter 34 Linker Speci

PPSM makes use of the development environment defines the locations and symbols. It is written in a files, please refer to the

PPSM required a few us
Table 32-1.

Table 32-1 Syn

Symbol Name
LCDPHYSWIDTH
LCDPHYSHEIGHT
LCDVIRTWIDTH
LCDVIRTHEIGHT
UARTRCVBUF

System integrators inform hardware system using t

PPSM maintains a stack The system integrator m and heap. In general, the memory for application u For details on memory m

PPSM also maintains an storage for data received is the optimal buffer size

34.1 .SPC File for a R

Following is an example (for SDS use only) with 2 system has the following

- The RAM system
- 4 KByte of reser vectors and SDS
- As much execut boundary
- As much constan boundary



- As much constant string boundary
- As much initialized data byte boundary
- As much zeroed memory boundary
- 704 KByte of heap space
- 128 KByte of stack space
- A STKTOP symbol to point to
- a DATA symbol to point to
- A LCD physical display size
- A panning screen of 640
- A 256 byte internal UART
- 2 MByte of RAM

Example 32-1 Linker Specification

```
partition { overlay {
    region {} reset[addr=0, size=0x1000];
    region {} code[roundsize=0x1000];
    region {} const[roundsize=0x1000];
    region {} string[roundsize=0x1000];
    region {} data[roundsize=0x1000];
    region {} ram[roundsize=0x1000];
    region {} malloc[size=0x1000];
    region {} stack[size=0x1000];
    STKTOP = $; /* SP reset value */
    DATA = $; /* "data" down to 0 */
    LCDPHYSWIDTH = 320; /* LCD physical width */
    LCDPHYSHEIGHT = 240; /* LCD physical height */
    LCDVIRTWIDTH = 640; /* LCD virtual width */
    LCDVIRTHEIGHT = 480; /* LCD virtual height */
    UARTRCVBUF = 256; /* UART receive buffer size in
#bytes) */
} example; } RAM[addr=0x0, size=0x200000];
```

34.2 .SPC File for a ROM-RAM System

The .SPC file for a ROM-RAM system defines the ROM layout and one partition for the RAM. See *Chapter 32 - How to make RC a system*.

34.3 For SingleStep Debugging

One of the methods to find out the .SPC file will be shown below. The following is for a single-step debugging system.

- 1) First of all, we set the RAM size. For example,

```
partition { overlay {
    region {} reset[addr=0x0, size=0x1000];
    ....
```

```
    region {} malloc[size=0x1000];
    ....
} example; } RAM[addr=0x0, size=0x200000];
```

- 2) Following error message is shown:

```
LINKER: error: actual size of region 'data' exceeds
LINKER: error: overlay region 'data' overlaps with region 'ram'
NMAKE : fatal error U107: *** linker.exe failed ***
Stop.
```

- 3) Then, we can change the size of the region 'data' to not exceed the bytes of the region 'ram'.

```
0x1000];
```

- 4) Finally, we can verify the result by running the linker.

```
partition { overlay {
    region {} reset[addr=0x0, size=0x1000];
    ....
    region {} malloc[size=0x1000];
    ....
} example; } RAM[addr=0x0, size=0x200000];
```

- 5) This optimum memory layout is found after debugging the system.



Chapter 35 Trap Usage i

PPSM tools access the P
When an application ma
is called with the correct
calling the actual function

On the 68K, there are 16
instruction mapping for th

Tab

TRAP Number	T
1	
2	
3	
4	
5	
6	
7	

35.1 PPSM Tools Call

For the protection of the
is introduced in the PPSM

The first level is a stub li
application developers. T
function body consists of

The second level is the T
in by the stub library and

With this implementation
PPSM system code can
portability of the PPSM s

35.2 TRAP Implemen

Figure 34-1 shows a blo
application makes a syst
sections are implemente



overhead induces during a syste

the caller's argument list
the PPSM tools function

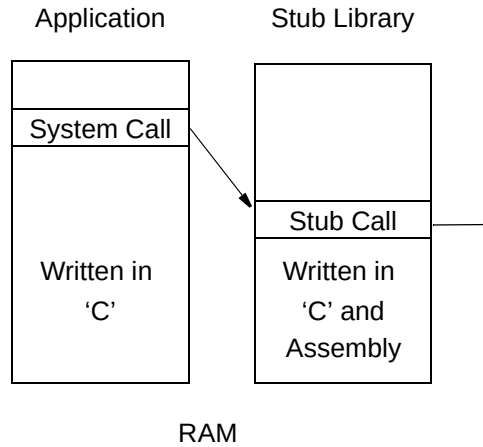


Figure 34-1 P

35.2.1 Application

Applications are written in ANSI C calling convention. Because Single C source code, it is also allowed

35.2.2 Stub Library

The Stub Library provides an interface routines. Its main function is for p routines with the correct arguments. It is v embedded format. Each function shown below:

```
int simplification( int a, int b)
#define NO_OF_ARGUMENT2
#define FUNC_NUMBER5
#define TRAP_NUMBER3

int rv; /* return value */
asm(
    "    LEA    8(A6),%0\n"
    "    MOVE.W #NO_OF_ARGUMENT2,%1\n"
    "    MOVE.W #FUNC_NUMBER5,%2\n"
    "    TRAP   #TRAP_NUMBER3\n"
    "    MOVE.L D0,%0\n"
);
return (rv);
}
```

The first instruction that SingleStep procedure is a "LINK" instruction points to the stack that is used by argument, an offset of 8 is added

Figure 34-2

35.2.3 TRAP Service Handler

The TRAP Service Handler
There are 7 jump tables,
The jump table consists of
are used as the PPSM system
handler when it receives a
general code layout for a

```
.FREF _Func_1,2
.FREF _Func_2,8

JMPTABLE:
DC.L _Func_1,
DC.L _Func_2,

Trap_1:
LSL.W #2,D1 ;
ADD.L D1,A0 ;
LSR.W #2,D1 ;
loop_1:
TST.W D1 ;
BEQ loop_2 ;
MOVE.L -(A0),-(A0) ;
SUBQ.W #1,D1 ;
BRA loop_1 ;
loop_2:
LEA JMPTABLE,%0 ;
LSL #2,D0 ;
ADD.L D0,A0 ;
MOVEA.L(A0),A1 ;
JSR (A1) ;
RTE
```



Table A-

Error Code
PPSM_ERR_DB_ADD
PPSM_ERR_DB_DBID
PPSM_ERR_DB_FDID
PPSM_ERR_DB_READNO
PPSM_ERR_DB_RECID
PPSM_ERR_DB_SFLAG
PPSM_ERR_DB_TYPE
PPSM_ERR_DOT_WIDTH
PPSM_ERR_DOZE_TIME
PPSM_ERR_DRAW_INIT
PPSM_ERR_FILL_PATTERN
PPSM_ERR_FILL_SPACE
PPSM_ERR_GREY
PPSM_ERR_HEIGHT
PPSM_ERR_HOUR
PPSM_ERR_ICON_TYPE
PPSM_ERR_INPUT_PAD_CLOSE
PPSM_ERR_INPUT_PAD_HEIGH
PPSM_ERR_INPUT_PAD_NOSCF
PPSM_ERR_INPUT_PAD_OPENE
PPSM_ERR_INPUT_PAD_WIDTH
PPSM_ERR_INPUT_PAD_X_POS
PPSM_ERR_INPUT_PAD_Y_POS
PPSM_ERR_INVALID_ACCESS
PPSM_ERR_INVALID_TMOUT
PPSM_ERR_IRPT_HDLER
PPSM_ERR_LCD_FONT
PPSM_ERR_LCD_GREY

Append



Appendix A Error Code D

The following are the det

1

Error Cod
PPSM_OK
PPSM_ERROR
PPSM_ERR_ACTIVE_PO
PPSM_ERR_ACTIVE_PU
PPSM_ERR_AREA_COD
PPSM_ERR_AREA_ID
PPSM_ERR_AUDIO_INU
PPSM_ERR_AUDIO_RE
PPSM_ERR_AUDIO_SAF
PPSM_ERR_AUDIO_TO
PPSM_ERR_BAUD
PPSM_ERR_BUSY
PPSM_ERR_CHARLEN
PPSM_ERR_COLOUR
PPSM_ERR_COORDINA
PPSM_ERR_CURSOR_I
PPSM_ERR_DAY



Error Code
PPSM_ERR_LCD_RADIUS
PPSM_ERR_LCD_STYLE
PPSM_ERR_LCD_X
PPSM_ERR_LCD_Y
PPSM_ERR_MINUTE
PPSM_ERR_MODE
PPSM_ERR_MONTH
PPSM_ERR_NO_ALARM
PPSM_ERR_NO_MEMORY
PPSM_ERR_NO_REQUEST
PPSM_ERR_NUM_FMT
PPSM_ERR_PAN_ADDR
PPSM_ERR_PAN_HEIGHT
PPSM_ERR_PAN_INIT
PPSM_ERR_PAN_WIDTH
PPSM_ERR_PARITY
PPSM_ERR_PEN_GET
PPSM_ERR_PEN_INIT
PPSM_ERR_PEN_RATE
PPSM_ERR_PERIOD
PPSM_ERR_RCTS_IDLE
PPSM_ERR_REF_MAX
PPSM_ERR_RELEASE
PPSM_ERR_SECOND
PPSM_ERR_SKBD_USE
PPSM_ERR_SKBD_XSIZE
PPSM_ERR_SKBD_XPOS
PPSM_ERR_SKBD_YSIZE

Table A-

Error Code
PPSM_ERR_SKBD_Y_POS
PPSM_ERR_SLEEP_TIME
PPSM_ERR_STOPBIT
PPSM_ERR_TASK_FLAG
PPSM_ERR_TASK_HEIGHT
PPSM_ERR_TASK_ID
PPSM_ERR_TASK_WIDTH
PPSM_ERR_TEXT_CR
PPSM_ERR_TEXT_CUR
PPSM_ERR_TEXT_FONT
PPSM_ERR_TEXT_GREY
PPSM_ERR_TEXT_HEIGHT
PPSM_ERR_TEXT_ID
PPSM_ERR_TEXT_STYLE
PPSM_ERR_TEXT_WIDTH
PPSM_ERR_TEXT_X
PPSM_ERR_TEXT_Y
PPSM_ERR_TMOUT_VALUE
PPSM_ERR_WIDTH
PPSM_ERR_X_POS
PPSM_ERR_YEAR
PPSM_ERR_Y_POS
PPSM_NO_MATCH

Appendix B List of Refer

- 1) *Addendum and*
Microprocessor
- 2) *Computer Graph*
Feiner and Huger
- 3) *CrossCode® C*
Development Sys
- 4) *MC68328ADS A*
- 5) *MC68328 Integr*
AD.Motorola, Inc
- 6) *SingleStep™ De*
Software Develo
- 7) *M68EZ328ADS*
Motorola, Inc.
- 8) *MC68EZ328 Inte*

RefTimeAlarm
RefTimeAlarmId
RefTimeDiff
RefTimeRead

S

SaveRec
ScanningOff
ScanningOn
SendMessage
SetDotWidth
SetDozeMode
SetDozePeriod
SetDutyCycle
SetPatternFill
SetPeriod
SetPeriodId
SetSleepMode
SetSleepPeriod
SubTaskCreate

T

TaskCreate
TaskHook
TaskMemUsed
TaskRelnit
TaskStackAvail
TaskStart
TaskTerminate
TextCreate
TextDelete
TextMap
TextReadCursor
TextSetCursor
TextSetDisplay
TextSetFont
TextSetOutlook
TextSetup
TextUnmap
Timeout
TimeoutId
TotalMemSize
TotalMemUsed

U

UARTConfigure
UARTFlowCtrl
UARTInquire
UARTRcvCtrl

Appendix C Index of PPS

A

ActiveAreaDisable
ActiveAreaEnable
ActiveAreaPosition
ActiveAreaRead
ActiveAreaSuspend
ActiveAreaToFront
ActiveListPop
ActiveListPush
AdvAudioPlayWave
AdvMessageDelete
AdvOpenInputPad
AdvOpenSoftKey
AdvSendMessage
AdvTaskCreate
AlarmClear
AlarmClearId
AlarmRead
AlarmReadId
AlarmSet
AlarmSetId
AppSwap
AreaEchoDisable
AreaEchoEnable
AudioInUse
AudioPlayTone
AudioPlayWave
AudioStopWave

C

ChangePanning
ChangeWindow
ClearRec
ClearScreen
CloseInputPad
CloseSoftKey
CtrlIconDisable
CtrlIconEnable
CursorGetOrigin
CursorGetPos
CursorGetStatus
CursorInit
CursorOff
CursorSet
CursorSetBlink



CursorSetOrigin
CursorSetPos
CursorSetStatus

D

DateTimeRead
DateTimeSet
DBAdd
DBAddRecord
DBAddRecToTop
DBAppendRecord
DBChangeStdData
DBChangeUnfData
DBDelete
DBDeleteRecord
DBGetFirstRecID
DBGetNextRecID
DBGetPrevRecID
DBReadData
DBReadTotalNumber
DBReadTotalNumberRecords
DBReadUnfData
DBRecordSecret
DBSearchData
DBSecretFlag
DBSetRecordSecretFlag
DBSetSecretFlag
DeleteTimer
DisplayMove
DrawArc
DrawCircle
DrawDot
DrawEllipse
DrawHorz
DrawLine
DrawRec
DrawVector
DrawVert

E

ExchangeRec

G

GetDisplayX
GetDisplayY
GetLogicalX
GetLogicalY
GetScreenMem

I

IconScanOff
IconScanOn
InputTimeout
InvRec
IrptGetData
IrptRelease
IrptRequest
IrptSendData

L

Lcalloc
LCDContrast
LCDRefreshRate
LCDScreenMove
Lfree
Lmalloc
Lrealloc

M

MessageDelete
MoveBlock

O

OpenInputPad
OpenSoftKey

P

PenCalibration
PenEchoParam
PenGetInput
PenSetInputMax
PenSetInputOrg
PenSetRate
PPSMInit
PutChar
PutRec

R

ReadSMVersion
RefFineTimeAlarm ...
RefFineTimeAlarmId ..
RefFineTimeDiff
RefFineTimeRead



UARTReadData
UARTReceive
UARTSend
UARTSendAbort
UARTSendCtrl
UARTSetDelay
UARTTimeout