



Software Implementation of Asynchronous Serial I/O

INTRODUCTION

The PIC16CXX microcontrollers from Microchip Technology, Inc., are mid-range, high performance EPROM based 8-bit microcontrollers. Some of the members of this series (like PIC16C71 and PIC16C84) do not have an on-chip hardware asynchronous serial port. This application note describes the Interrupt driven Software implementation of Asynchronous Serial I/O (Half Duplex RS-232 Communications) using PIC16CXX microcontrollers. These microcontrollers can operate at very high speeds with a minimum of 250 ns cycle time (with input clock frequency of 16 MHz). To test the RS-232 routines, a simple Digital Volt Meter (DVM)/Analog Data Acquisition Systems has been implemented using PIC16C71 in which upon reception of a command from host (IBM® PC), an 8-bit value of the selected A/D channel is transmitted back to host.

IMPLEMENTATION

A half duplex Interrupt driven software implementation of RS-232 communications using PIC16C71 is described in detail below. The transmit pin used in the example code is RB7 and receive pin is connected to RTCC/RA4 pin (see Figure 2). Of course these pins are connected with appropriate voltage translation to/from RS-232/CMOS levels. The voltage translation is given described with schematics in the hardware section of this application note.

Transmit Mode

The transmit mode in software is quite straight forward to implement using interrupts. Once the input clock frequency and baud rate is known, the number of clock cycles per bit can be computed. The on-chip Real Time Clock Counter (RTCC) along with the prescaler can be used to generate interrupt on RTCC overflow. This RTCC overflow interrupt can be used as timing to send each bit. The Input clock frequency ("ClkIn") and the Baud Rate ("BaudRate") are programmable by the user and the RTCC time-out value (the period for each bit) is computed at assembly time. Whether the prescaler must be assigned to RTCC or not is also determined at assembly time. This computation is done in the header file "rs232.h". Note that very high speed transmissions can be obtained if transmission is done with software delays instead of every interrupt driven, however, the processor will be totally dedicated to this job.

Transmission of a byte is performed by calling "PutChar" function and the data byte in the "TxReg" is transmitted out. Before calling this function ("PutChar"), the data must be loaded into TxReg and also made sure that serial port is free. The serial port is free when both _txmtProgress and _rcvOver bits are cleared (see description of these bits in the Serial Status/Control Reg table given later).

Summary of "PutChar" function :

- 1) Make sure _txmtProgress & _rcvOver bits are cleared
- 2) Load TxReg with data to be transmitted
- 3) CALL PutChar function

Receive Mode

The reception mode implementation is slightly different from the transmit mode. Unlike the transmit Pin (TX pin in the example code is RB7, but could be any I/O pin), the receive pin (RX Pin) must be connected to RTCC/RA4 Pin. This is because in reception, the Start Bit which is asynchronous in nature, must be detected. To detect the start bit, when put in Reception mode, the RTCC module is configured to counter mode. The OPTION register is configured so that RTCC module is put in counter mode (increment on external clock on RTCC/RA4 Pin) and set to increment on falling edge on RTCC/RA4 pin with no prescaler assigned. After this configuration setup, RTCC (File Reg 1) is loaded with 0xFF. A falling edge on RTCC Pin will make RTCC roll over from 0xFF to 0x00, thus generating an interrupt indicating a Start Bit. The RTCC/RA4 pin is sampled again to make sure the transition on RTCC is not a glitch. Once the start bit has been detected, the RTCC module is reconfigured to increment on internal clock and the prescaler is assigned to it depending on input master clock frequency and the baud rate (configured same way as the transmission mode).

The software serial port is put in reception mode when a call is made to function "GetChar". Before calling this function make sure serial port is free (i.e. _txmtProgress and _rcvOver status bits must be 0). On completion of reception of a byte, the data is stored in RxReg and _rcvOver bit is set to 0.

Summary of "GetChar" function:

- 1) Make sure _txmtProgress & _rcvOver bits are cleared
- 2) CALL GetChar function
- 3) The received Byte is in TxReg after _rcvOver bit is cleared

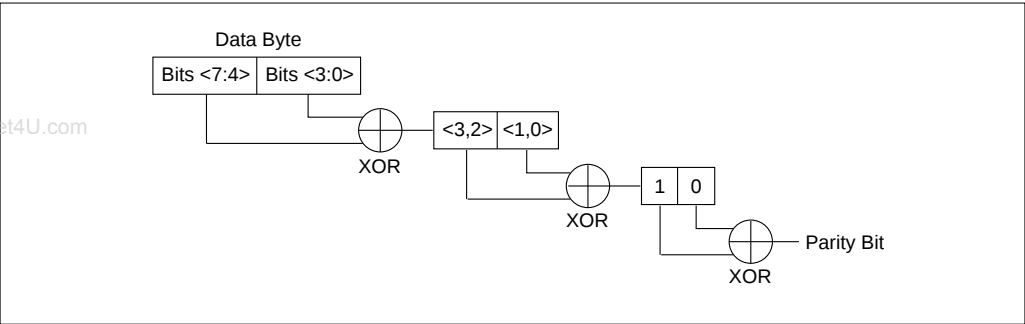
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Parity Generation

Parity can be enabled at assembly time by setting “_PARITY_ENABLE” flag to TRUE. If enabled, the parity can be set to either EVEN or ODD parity. In transmission mode, if parity is enabled, the parity bit is computed and transmitted as the ninth bit. On reception, the parity is computed on the received byte and compared to the ninth bit received. If a match does not occur the parity error bit is set in the RS-232 Status/Control

Register (_ParityErr bit of SerialStatus reg). The parity bit is computed using the algorithm shown in Figure 1. This algorithm is highly efficient using PIC16CXX’s SWAPF and XORWF instructions (with ability to have the destination as either file register itself or W register) and the sub-routine (called “GenParity”) is in file “txmtr.asm”.

FIGURE 1 - AN EFFICIENT PARITY GENERATION SCHEME IN SOFTWARE



Assembly Time Options

The firmware is written as a general purpose routines and the user must specify the following parameters before assembling the program. The Status/Control register is also described below:

TABLE 1 - LIST OF ASSEMBLY TIME OPTIONS

_CkIn	Input clock frequency of the processor.
_BaudRate	Desired Baud Rate. Any valid value can be used. The highest Baud Rate achievable depends on Input Clock Freq. 600 to 4800 Baud was tested using 4 MHz Input Clock. 600 to 19200 Baud was tested using 10 MHz Input Clock. Higher rates can be obtained using higher Input Clock Frequencies. Once the _BaudRate & _CkIn are specified, the program automatically selects all the appropriate timings.
_DataBits	Can specify 1 to 8 data bits.
_StopBits	Limited to 1 Stop Bit. Must be set to 1.
_PARITY_ENABLE	Parity Enable Flag. Set it to TRUE or FALSE. If PARITY is used, then set it to TRUE, else FALSE. See “_ODD_PARITY” flag description below.
_ODD_PARITY	Set it to TRUE or FALSE. If TRUE, then ODD PARITY is used, else mEVEN Parity Scheme is used. This Flag is ignored if _PARITY_ENABLE is set to FALSE.
_USE_RTSC	RTS & CTS Hardware handshaking signals. If set to FALSE, no hardware handshaking is used. If set to TRUE, RTS & CTS use up 2 I/O Pins of PortB.

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TABLE 2 - BIT ASSIGNMENTS OF SERIAL STATUS/CONTROL REGISTER ("SERIALSTATUS" REG)

Bit #	Name	Description
0	_txmtProgress	1 = Transmission in progress. 0 = Transmission line free.
1	_txmtEnable	Set this bit to 1 on initialization to enable transmission. This bit may be used to abort a transmission. The transmission is aborted if in the middle of a transmission (i.e. when _txmtProgress bit is 1) _txmtEnable bit is set to 0. This bit gets automatically set when PutChar function is called.
2	_rcvProgress	1 = Middle of a byte reception. 0 = Reception of a byte (in RxReg) is complete and is set to 1 when a valid start bit is detected in reception mode.
3	_rcvOver	0 = Completion of reception of a byte. The user's code can poll this bit after calling "GetChar" function and check to see if it is set. When set, the received byte is in RxReg. Other status bits should also be checked for any reception errors.
4	_ParityErr	1 = Parity error on reception (irrespective of Even Or Odd parity chosen). Not applicable if No Parity is used.
5	_FrameErr	1 = Framing error on reception.
6		Unused
7	_parityBit	The 9th bit of transmission or reception. In transmission mode, the parity bit of the byte to be transmitted is set in this bit. In receive mode, the 9th bit (or parity bit) received is stored in this bit. Not Applicable if no parity is used.

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Hardware

The hardware is primarily concerned with voltage translation from RS-232 to CMOS levels and vice versa. Three circuits are given below and the user may choose which ever best suits his application. The primary difference between each solution is cost versus number of components. Circuits in Figure 3 and 4 are very low cost but have more components than the circuit in Figure 2. The circuit in Figure 2 interfaces to RS-232 line using a single chip (MAX-232) and single +5V supply. The circuit in Figure 3 is a low cost RS-232 Interface but requires two chips and a single +5V supply source.

Figure 4 shows a very low cost RS-232 Interface to an IBM PC® with no external power requirements. The circuit draws power from RS-232 line (DTR) and meets the spec of drawing power less than 5mA. This requires that the host to communicate must assert DTR high and RTS low. The power is drawn from DTR line and this requires that DTR to be asserted high and must be at least 7V. The negative -5 to -10 V required by LM339 is drawn from RTS line and thus the host must assert RTS low. This circuit is possible because of the low current consumption of PIC16C71 (typical 2 mA).

FIGURE 2 - SINGLE CHIP FOR RS-232 INTERFACE (SINGLE +5V SUPPLY)

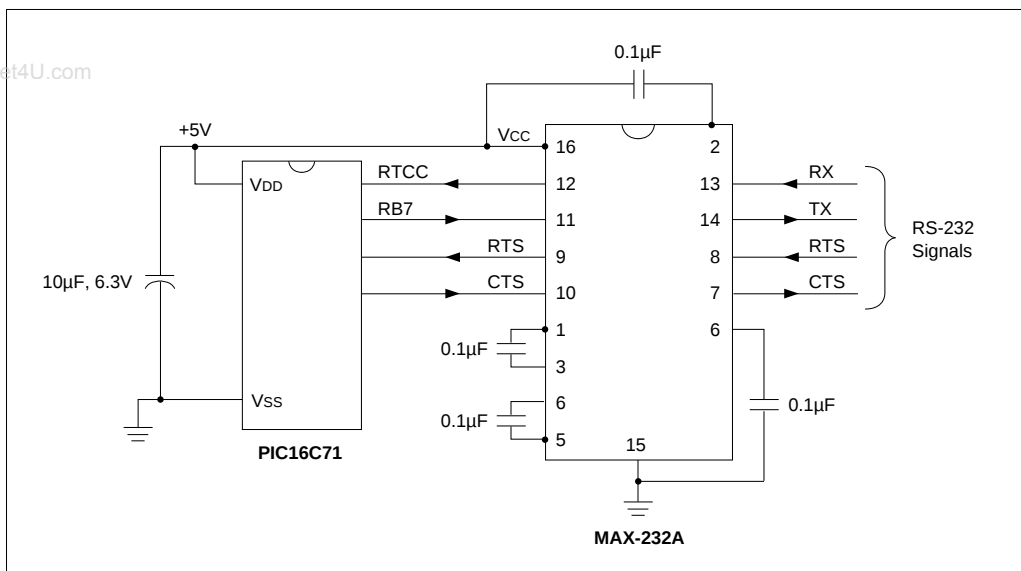
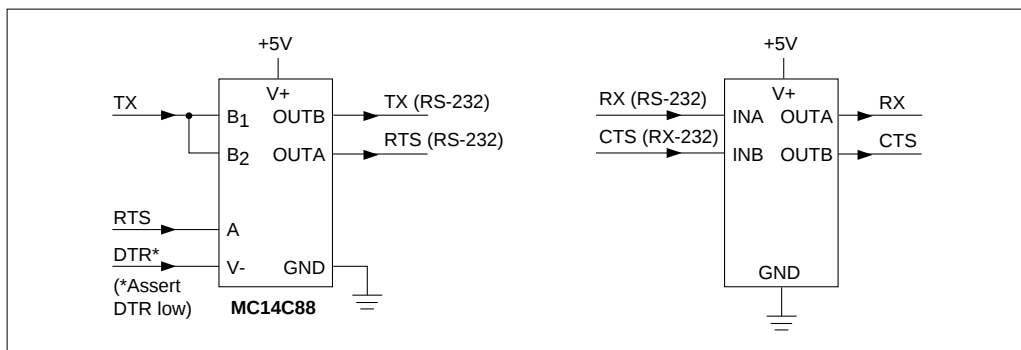


FIGURE 3 - LOW COST RS-232 INTERFACE (TWO CHIPS, SINGLE +5V SUPPLY)

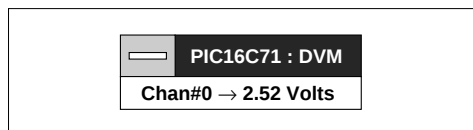


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**FIGURE 5 - MS WINDOWS PROGRAM
FETCHING A/D DATA FROM
PIC16C71 VIA RS-232**



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Source Code

The PIC16CXX source code along with the Microsoft® Windows™ DVM Program (executable running on an IBM PC/AT under MS Windows 3.1 or higher) is available on Microchip's BBS. The assembly code for PIC16CXX must be assembled using Microchip's Universal Assembler, MPASM. The code cannot be assembled using the older assemblers without significant modifications. It is suggested that user's who do not have the new assembler MPASM, must change to the new version.

The MS Windows Program (DVM.EXE) runs under MS Windows 3.1 or higher. The program does not have any menus and shows up as a small window displaying A/D Data and runs as a background job. There are a few command line options and are described below :

- Px : x is the comm port number (e.g. - P2 selects COM2). Default is COM1
- Cy : y is the number of A/D channels to display. Default is one channel (channel #1)
- Sz : z is a floating point number that represents the scaling factor (For example - S5.5 would display the data as $5.5 \times \text{8bit A/D} / 256$). The default value is 5.0 volts. -S0 will display the data in raw format without any scaling.

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Appendix A - RS232.H

NOLIST

```

*****
;
; RS-232 Header File
; PIC16C6X/7X/8X
; *****
_clkOut      equ    (_ClkIn >> 2)      ; Instruction Cycle Freq = CLKIN/4
;
_cyclesPerBit set    (_ClkOut/_BaudRate)
_tempCompute set    (_CyclesPerBit >> 8)
;
; *****
; Auto Generation Of Prescaler & Rtcc Values
; Computed during Assembly Time
; *****
; At first set Default values for RtccPrescale & RtccPreload
;
RtccPrescale set    0
RtccPreload set    _CyclesPerBit
UsePrescale set    FALSE

if (_tempCompute >= 1)
    RtccPrescale set    0
    RtccPreload set    (_CyclesPerBit >> 1)

    UsePrescale set    TRUE
endif

if (_tempCompute >= 2)
    RtccPrescale set    1
    RtccPreload set    (_CyclesPerBit >> 2)
endif

if (_tempCompute >= 4)
    RtccPrescale set    2
    RtccPreload set    (_CyclesPerBit >> 3)
endif

if (_tempCompute >= 8)
    RtccPrescale set    3
    RtccPreload set    (_CyclesPerBit >> 4)
endif

```

```

if (_tempCompute >= 16)
    RtccPrescale set 4
    RtccPreload set (_CyclesPerBit >> 5)
endif

if (_tempCompute >= 32)
    RtccPrescale set 5
    RtccPreload set (_CyclesPerBit >> 6)
endif

if (_tempCompute >= 64)
    RtccPrescale set 6
    RtccPreload set (_CyclesPerBit >> 7)
endif

if (_tempCompute >= 128)
    RtccPrescale set 7
    RtccPreload set (_CyclesPerBit >> 8)
endif

;
; if( (RtccPrescale == 0) && (RtccPreload < 60))
;     messg "Warning : Baud Rate May Be Too High For This Input Clock"
;     endif
;
; Compute RTCC & Prescaler Values For 1.5 Times the Baud Rate for Start Bit Detection
;

_SBitCycles set (_ClkOut/_BaudRate) + ((_ClkOut/4)/_BaudRate)
_tempCompute set (_SBitCycles >> 8)

_BIT1_INIT set 08
_SBitPrescale set 0
_SBitRtccLoad set _SBitCycles
_SBitRtccLoad set _SBitCycles

if (_tempCompute >= 1)
    _SBitPrescale set 0
    _SBitRtccLoad set (_SBitCycles >> 1)
    _BIT1_INIT set 0
endif

if (_tempCompute >= 2)

```



```
_OPTION_SBIT set 0x38 ; Increment on Ext Clock (falling edge), for START Bit Detect
if UsePrescale
_OPTION_INIT set 0x00 ; Prescaler is used depending on Input Clock & Baud Rate
else
_OPTION_INIT set 0x0F
endif

CBLOCK 0x0C
TxReg
RxReg
RxTemp
SerialStatus
BitCount
ExtraBitCount
SaveWReg
SaveStatus
temp1, temp2
ENDC

; Transmit Data Holding/Shift Reg
; Rcv Data Holding Reg
; Txmt & Rev Status/Control Reg
; Parity & Stop Bit Count
; temp hold reg of WREG on INT
; temp hold reg of STATUS Reg on INT

temp1, temp2
ENDC

;*****
LIST
;*****
```

Appendix B - RS232.ASM

```

*****
TITLE      "RS232 Communications : Half Duplex : PIC16C6X/7X/8X"
SUBTITLE   "Software Implementation : Interrupt Driven"
*****
;
; Software Implementation Of RS232 Communications Using PIC16CXX
; Half-Duplex
;
; These routines are intended to be used with PIC16C6X/7X family. These routines can be
; used with processors in the 16C6X/7X family which do not have on board Hardware Async
; Serial Port.
; MX..
;
; Description :
; Half Duplex RS-232 Mode Is implemented in Software.
; Both Reception & Transmission are Interrupt driven
; Only 1 peripheral (RTCC) used for both transmission & reception
; RTCC is used for both timing generation (for bit transmission & bit polling)
; and Start Bit Detection in reception mode.
; This is explained in more detail in the Interrupt Subroutine.
; Programmable Baud Rate (speed depending on Input Clock Freq.), programmable
; #of bits, Parity enable/disable, odd/even parity is implemented.
; Parity & Framing errors are detected on Reception
;
; RS-232 Parameters
;
; The RS-232 Parameters are defined as shown below:
;
; _ClkIn      : Input Clock Frequency of the processor
;               (NOTE : RC Clock Mode Is Not Suggested due to wide variations)
;               Desired Baud Rate. Any valid value can be used.
;               The highest Baud Rate achievable depends on Input Clock Freq.
;               300 to 4800 Baud was tested using 4 Mhz Input Clock
;               300 to 19200 Baud was tested using 10 Mhz Input Clock
;               Higher rates can be obtained using higher Input Clock Frequencies.
;               Once the _BaudRate & _ClkIn are specified the program
;               automatically selects all the appropriate timings
;               Can specify 1 to 8 Bits.
;               Limited to 1 Stop Bit. Must set it to 1.
;               Parity Enable Flag. Set it to TRUE or FALSE. If PARITY
;               is used, then set it to TRUE, else FALSE. See "_ODD_PARITY" flag
;               description below
;
; _DataBits    : Can specify 1 to 8 Bits.
; _StopBits    : Limited to 1 Stop Bit. Must set it to 1.
; _PARITY_ENABLE : Parity Enable Flag. Set it to TRUE or FALSE. If PARITY
;                   is used, then set it to TRUE, else FALSE. See "_ODD_PARITY" flag
;                   description below
;
; _ODD_PARITY   : Set it to TRUE or FALSE. If TRUE, then ODD PARITY is used, else
;                 EVEN Parity Scheme is used.
;                 This Flag is ignored if _PARITY_ENABLE is set to FALSE.
;
*****

```

Processor 16C71

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```

if( (GetADCon0 & 0xff) >= (GetADCon0_End & 0xff))
MESSG: "Warning : Crossing Page Boundary in Computed Jump, Make Sure PCLATH is Loaded Correctly"
endif
;*****
;***** Initialize A/D Converter *****
;***** <RA0:RA3> Configure as Analog Inputs, VDD as Vref *****
;***** A/D Clock Is Internal RC Clock *****
;***** Select Channel 0 *****
;***** Program Memory : 6 locations *****
;***** Cycles : 7 *****
;*****
InitAt0D:
bsf _rp0
clrf _adcon1
bcf _rp0
movlw 0xC1
movwf _adcon0
return
;*****
;***** Main Program Loop *****
;*****
; After appropriate initialization, The main program wait for a command from RS-232
; The command is 0, 1, 2 or 3. This command/data represents the A/D Channel Number.
; After a command is received, the appropriate A/D Channel is selected and when conversion is
; completed the A/D data is transmitted back to the Host. The controller now waits for a new
; command.
;*****
Start:
call InitSerialPort
;
WaitForNextSel:
if _USE_RTSC
bcf _rp0
bcf _RTS
endif
call GetChar
btfsc _rcvOver
goto $-1
; A Byte is received, Select The Desired Channel & TMXT the desired A/D Channel Data
;
bcf _rp0 ; make sure to select Page 0

```

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```

movf    RxReg,w
call    GetADCON0
movwf   _adcon0
nop
;
; WREG = Commanded Channel # (0 thru 3)
; Get ADCON0 Reg Constant from Table Lookup
; Load ADCON0 reg, selecting the desired channel
;
    bsf    _go
    btfsc  _done
    goto   $-1
; start conversion
; Loop Until A/D Conversion Done
;
    movf   _adres,w
    movwf  TxReg
    if _USE_RTSC
    bsf    _RTS
    btfsc  _CTS
    goto   $-1
    endif
    call   PutChar
    btfsc  _txmtProgress
    goto   $-1
; Loop Until Transmission Over, User Can Perform Other Jobs
;
;
; goto    WaitForNextSel      ; wait for next selection (command from Serial Port)
;
; *****
; RS-232 Routines
; *****
; Interrupt Service Routine
;
; Only RTCC Interrupt Is used. RTCC Interrupt is used as timing for Serial Port Receive & Transmit
; Since RS-232 is implemented only as a Half Duplex System, The RTCC is shared by both Receive &
; Transmit Modules.
;
; Transmission :
;
; Reception :
;
; RTCC is setup for Internal Clock increments and interrupt is generated when
; RTCC overflows. Prescaler is assigned, depending on The INPUT CLOCK & the
; desired BAUD RATE.
;
; When put in receive mode, RTCC is setup for external clock mode (FALLING EDGE)
; and preloaded with 0xFF. When a Falling Edge is detected on RTCC Pin, RTCC
; rolls over and an interrupt is generated (thus Start Bit Detect). Once the start
; bit is detected, RTCC is changed to INTERNAL CLOCK mode and RTCC is preloaded
; with a certain value for regular timing interrupts to Poll RTCC Pin (i.e RX pin).
;
; *****
; Interrupt:
; btfss   _rtif
; retfie
;
; other interrupt, simply return & enable GIE

```

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```

; Save Status On INT : WREG & STATUS Regs
;
movwf SaveWReg
swapf _status,w
movwf SaveStatus
; affects no STATUS bits : Only way OUT to save STATUS Reg ?????

; Txmt Next Bit
btfsc _txmtProgress
goto _TxmtNextBit
btfsc _rcvProgress
goto _RcvNextBit
goto _SBitDetected
; Must be start Bit

; RestoreIntStatus:
swapf SaveStatus,w
movwf _status
; restore STATUS Reg
swapf SaveWReg
swapf SaveWReg,w
bcf _rtif
retfie
; *****

; Configure TX Pin as output, make sure TX Pin Comes up in high state on Reset
; Configure, RX_Pin (RTCC pin) as Input, which is used to poll data on Reception
; Program Memory : 9 locations
; Cycles : 10
; *****

InitSerialPort:
clrf SerialStatus
;
bcf _rp0
bsf TX
bsf _rp0
bcf TX
if _USE_RTSCTS
bcf _RTS
bsf _CTS
endif
bsf RX_Pin
return
; *****

```

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Appendix C - RCVR.ASM

```

*****
;
; GetChar Function
; Receives a Byte Of Data
; When reception is complete, _rcvOver Bit is cleared
; The received data is in RxReg
;
; Program Memory : 15 locations (17 locations if PARITY is used)
; Cycles : 16 (18 if PARITY is USED)
;
*****
;
; GetChar:
; bcf _rp0 ; Enable Reception, this bit gets reset on Byte Rcv Complete
; bsf _rcvOver
; LOAD_BITCOUNT
; clrf RxReg
; bcf _ParityErr ; Init Parity & Framing Errors
; clrf _rtcc
; clrwdt
; bsf _rp0
; movlw 07h
; movwf _option
; bcf _rp0
; clrf _rtcc
; bsf _rp0
; movlw 0Fh
; movwf _option
; clrwdt
; movlw _OPTION_SBIT
; movwf _option
; bcf _rp0
; movlw 0xFF
; movwf _rtcc
; bcf _rtif
; bsf _rtie
; retfie
;
; *****
; Internal Subroutine
; entered from Interrupt Service Routine when Start Bit Is detected.
;
; Program Memory : 14 locations
; Cycles : 12 (worst case)
;
; *****
; _SBitDetected:

```

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```

bcf _rp0
btfsc RX_Pin
goto _FalseStartBit
bsf _rcvpProgress
clr _rtcc
clrwdt
bsf _rp0
movlw 07h
movwf _option
bcf _rp0
clr _rtcc
bsf _rp0
movlw 0Fh
movwf _option
clrwdt
movlw (_BIT1_INIT | SBitPrescale) ; Switch Back to INT Clock
movwf _option ; Set Option Reg Located In Page 1
bcf _rp0 ; make sure to select Page 0
LOAD_RTCC 1,(SBitRtccLoad), SBitPrescale
goto RestoreIntStatus
;
;_FalseStartBit:
;movlw 0xFF
;movwf _rtcc
;goto RestoreIntStatus
;*****
;Internal Subroutine
;entered from Interrupt Service Routine when Start Bit Is detected.
;
;Program Memory : 28 locations ( 43 locations with PARITY enabled)
;Cycles : 24 Worst Case
;*****
;_RcvNextBit:
;clrwdt
;bsf _rp0
;movlw 07h
;movwf _option
;bcf _rp0
;clr _rtcc
;clrwdt
;bsf _rp0
;movlw 07h
;movwf _option
;bcf _rp0
;clr _rtcc
;bsf _rp0

```

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Appendix D - TXMTR.ASM

```

;*****
; PutChar Function
;*****
; Function to transmit A Byte Of Data
; Before calling this routine, load the Byte to be transmitted into TxReg
; Make sure _txmtProgress & _rcvOver bits (in Status Reg) are cleared before
; calling this routine
;
; Program Memory : 6 locations (10 locations if PARITY is Used)
; Cycles : 8 (13 if PARITY is Used)
;*****
PutChar:
    bsf _txmtEnable ; enable transmission
    bsf _txmtProgress ; Macro to load bit count
    LOAD_BITCOUNT
    decf BitCount,1
    if _DataBits == 7
        bsf TxReg,7
    endif
;
    if _PARITY_ENABLE
        movf TxReg,w
        call GenParity
    endif
;
    call _TxmtStartBit
    bsf _rtie
    retfie
;*****
; Internal Subroutine
; entered from Interrupt Service Routine when Start Bit Is detected.
;
; Program Memory : 30 locations (38 locations if PARITY is used)
; Cycles : 15 worst Case
;*****
;_TxmtNextBit:
;    bcf _rp0
;    LOAD_RTCC 0,RtccPreLoad, RtccPrescale ; Macro to reload RTCC
;
;    movf BitCount
;    btfsc _Z
;    goto _ParityOrStop
;done with data xmission?
;yes, do parity or stop bit
;*****

```

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```

;
decf BitCount
goto _NextTxmtBit
;
_ParityOrStop:
if _PARITY_ENABLE
btfsc ExtraBitCount,1
goto _SendParity
endif
movf ExtraBitCount,1
btfsc _Z
goto DoneTxmt
decf ExtraBitCount,1
;
_StopBit:
bsf TX
goto RestoreIntStatus
goto DoneTxmt
;
_NextTxmtBit:
bsf _carry
rrf TxReg
btfss _carry TX
btfsc _carry
bsf TX
;
btfss _txmtEnable
bsf _rtie
;
goto RestoreIntStatus
;
if _PARITY_ENABLE
_SendParity:
decf ExtraBitCount,1
btfss _parityBit
bcf TX
btfsc _parityBit
bsf TX
goto RestoreIntStatus
endif
DoneTxmt
bsf TX
bcf _rtie
bcf _txmtProgress
goto RestoreIntStatus
;
;no, send another

;ready for parity bit?

;check if sending stop bit

; STOP Bit is High

; disable further interrupts, Transmission Aborted

;subtract parity from count

;STOP Bit is High
;disable further interrupts
;indicates end of xmission

```

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```

;*****
; Internal Subroutine
; entered from Interrupt Service Routine when Start Bit Is detected.
;
; Program Memory : 9 locations
; Cycles : 10
;*****
; _TxmStartBit:
; bcf _rp0
; clrf _rtcc
; clrwdt
; bsf _rp0
; movlw 07h
; movwf _option
; bcf _rp0
; clrf _rtcc
; bsf _rp0
; movlw 0Fh
; movwf _option
; clrwdt
; movlw (_OPTION_INIT | RtccPrescale)
; movwf _option
; bcf _rp0
; bcf TX
; movlw -RtccPreload
; movwf _rtcc
; bcf _rtif
; return
;*****
;***** Generate Parity for the Value in WREG *****
;
; The parity bit is set in _parityBit (SerialStatus,7)
; Common Routine For Both Transmission & Reception
;
; Program Memory : 16 locations
; Cycles : 72
;*****
; if _PARITY_ENABLE
;
; GenParity:
; movwf temp2
; movf BitCount,w
; movwf temp1
; ParityLoop rrf temp2
; save data
; save bitcount
;*****

```

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Appendix E - RS232.LST

MPASM 01.00.02 Alpha \PICMASTR\VCU 5-20-1994 9:13:56 PAGE 1
 RS232 Communications : Half Duplex : PIC16C6X/7X/8X
 Software Implementation : Interrupt Driven
 LOC OBJECT CODE LINE SOURCE TEXT

```

0001      TITLE      "RS232 Communications : Half Duplex : PIC16C6X/7X/8X"
0002      SUBTITLE    "Software Implementation : Interrupt Driven"
0003      ;*****
0004      ;***** Software Implementation Of RS232 Communications Using PIC16CXX
0005      ;*****
0006      ;***** Half-Duplex
0007      ;*****
0008      ; These routines are intended to be used with PIC16C6X/7X family. These routines can be
0009      ; used with processors in the 16C6X/7X family which do not have on board Hardware Async
0010      ; Serial Port.
0011      ; MX..
0012      ;
0013      ; Description :
0014      ; Half Duplex RS-232 Mode Is implemented in Software.
0015      ; Both Reception & Transmission are Interrupt driven
0016      ; Only 1 peripheral (RTCC) used for both transmission & reception
0017      ; RTCC is used for both timing generation (for bit transmission & bit polling)
0018      ; and Start Bit Detection in reception mode.
0019      ; This is explained in more detail in the Interrupt Subroutine.
0020      ; Programmable Baud Rate (speed depending on Input Clock Freq.), programmable
0021      ; #of bits, Parity enable/disable, odd/even parity is implemented.
0022      ; Parity & Framing errors are detected on Reception
0023      ;
0024      ;
0025      ; RS-232 Parameters
0026      ; The RS-232 Parameters are defined as shown below:
0027      ;
0028      ; _CLKIn      : Input Clock Frequency of the processor
0029      ;              (NOTE : RC Clock Mode Is Not Suggested due to wide variations)
0030      ; _BaudRate   : Desired Baud Rate. Any valid value can be used.
0031      ;              The highest Baud Rate achievable depends on Input Clock Freq.
0032      ;              300 to 4800 Baud was tested using 4 Mhz Input Clock
0033      ;              300 to 19200 Baud was tested using 10 Mhz Input Clock
0034      ;              Higher rates can be obtained using higher Input Clock Frequencies.
0035      ;              Once the _BaudRate & _CLKin are specified the program
0036      ;              automatically selects all the appropriate timings
0037      ;              Can specify 1 to 8 Bits.
0038      ; _DataBits   : Limited to 1 Stop Bit. Must set it to 1.
0039      ; _StopBits   : Parity Enable Flag. Set it to TRUE or FALSE. If PARITY

```

Software Implementation of Asynchronous Serial I/O

is used, then set it to TRUE, else FALSE. See “_ODD_PARITY” flag description below
 _ODD_PARITY : Set it to TRUE or FALSE. If TRUE, then ODD PARITY is used, else EVEN Parity Scheme is used.
 This Flag is ignored if _PARITY_ENABLE is set to FALSE.

Usage :

An example is given in the main program on how to Receive & Transmit Data
 In the example, the processor waits until a command is received. The command is interpreted as the A/D Channel Number of PIC16C71. Upon reception of a command, the desired A/D channel is selected and after A/D conversion, the 8 Bit A/D data is transmitted back to the Host.

The RS-232 Control/Status Reg's bits are explained below :

“SerialStatus” : RS-232 Status/Control Register

Bit 0 : _txmtProgress (1 if transmission in progress, 0 if transmission is complete)
 After a byte is transmitted by calling “PutChar” function, the user's code can poll this bit to check if transmission is complete. This bit is reset after the STOP bit has been transmitted.
 Bit 1 : _txmtEnable Set this bit to 1 on initialization to enable transmission. This bit can be used to Abort a transmission while the transmitter is in progress (i.e when _txmtProgress = 1)
 Bit 2 : _rcvProgress Indicates that the receiver is in middle of reception. It is reset when a byte is received.
 Bit 3 : _rcvOver This bit indicates the completion of Reception of a Byte. The user's code can poll this bit after calling “GetChar” function. Once “GetChar” function is called, this bit is 1 and is set to 0 after reception of a complete byte (parity bit if enabled & stop bit)
 Bit 4 : _ParityErr A 1 indicates Parity Error on Reception (for both even & odd parity)
 Bit 5 : _FrameErr A 1 indicates Framing Error On Reception
 Bit 6 : _unused Unimplemented Bit
 Bit 7 : _parityBit The 9 th bit of transmission or reception (status of PARITY bit if parity is enabled)

To Transmit A Byte Of Data :

- 1) Make sure _txmtProgress & _rcvOver bits are cleared
- 2) Load TxReg with data to be transmitted
- 3) CALL PutChar function

To Receive A Byte Of Data :

- 1) Make sure _txmtProgress & _rcvOver bits are cleared
- 2) CALL GetChar function
- 3) The received Byte is in TxReg after _rcvOver bit is cleared

```

0088 ;
0089 ; Rev 2, May 17, 1994 Scott Fink
0090 ; Corrected 7 bit and parity operation, corrected stop bit generation, corrected
0091 ; receive prescaler settings. Protected against inadvertant WDT reset.
0092 ; *****
0093
0094 Processor 16C71
0095 Radix DEC
0096 EXPAND
0097
0098 include "16Cxx.h"
0099
0100
0101 ; *****
0102 ; Setup RS-232 Parameters
0103 ; *****
0104 _ClkIn equ 4000000 ; Input Clock Frequency is 4 Mhz
0105 _BaudRate set 1200 ; Baud Rate (bits per second) is 1200
0106 _DataBits set 8 ; 8 bit data, can be 1 to 8
0107 _StopBits set 1 ; 1 Stop Bit, 2 Stop Bits is not implemented
0108
0109 #define _PARITY_ENABLE FALSE ; NO Parity
0110 #define _ODD_PARITY FALSE ; EVEN Parity, if Parity enabled
0111 #define _USE_RTSCTS FALSE ; NO Hardware Handshaking is Used
0112
0113 include "rs232.h"
0114
0115 ; *****
0116 ;
0117
0118 ORG _ResetVector
0119 goto Start
0120 ;
0121
0122 ORG _IntVector
0123 goto Interrupt
0124 ; *****
0125 ;
0126 ; Table Of ADCON0 Reg
0127 ; Inputs : WREG (valid values are 0 thru 3)
0128 ; Returns In WREG, ADCON0 Value, selecting the desired Channel
0129 ;

```

Software Implementation of Asynchronous Serial I/O

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```
0130 ; Program Memory : 6 locations
0131 ; Cycles : 5
0132 ; *****
0133 ; *****
0134 ; *****
0135 GetADCon0:
0136 andlw 0x03
0137 addwf _pcl
0138 retlw (0xC1 | (0 << 3)) ; channel 0
0139 retlw (0xC1 | (1 << 3)) ; channel 1
0140 retlw (0xC1 | (2 << 3)) ; channel 2
0141 GetADCon0_End:
0142 retlw (0xC1 | (3 << 3)) ; channel 3
0143
0144 if( (GetADCon0 & 0xFF) >= (GetADCon0_End & 0xFF))
0145 MESSG "Warning : Crossing Page Boundary in Computed Jump, Make Sure PCLATH is Loaded Correctly"
0146 endif
0147 ; *****
0148 ; *****
0149 ; ***** Initialize A/D Converter
0150 ; <RA0:RA3> Configure as Analog Inputs, VDD as Vref
0151 ; A/D Clock Is Internal RC Clock
0152 ; Select Channel 0
0153 ;
0154 ; Program Memory : 6 locations
0155 ; Cycles : 7
0156 ; *****
0157 ; *****
0158 InitAt0D:
0159 bsf _rp0
0160 clrf _adcon1
0161 bcf _rp0
0162 movlw 0xC1
0163 movwf _adcon0
0164 return
0165 ; *****
0166 ; ***** Main Program Loop
0167 ; *****
0168 ; *****
0169 ; After appropriate initialization, The main program wait for a command from RS-232
0170 ; The command is 0, 1, 2 or 3. This command/data represents the A/D Channel Number.
0171 ; After a command is received, the appropriate A/D Channel is selected and when conversion is
0172 ; completed the A/D data is transmitted back to the Host. The controller now waits for a new
0173 ; command.
0174 ; *****
0175 ; *****
0176 Start: call InitSerialPort
0177 ; *****

0005 3903
0006 0782
0007 34C1
0008 34C9
0009 34D1
000A 34D9

000B 1683
000C 0188
000D 1283
000E 30C1
000F 0088
0010 0008

0011 2033
```

```

0178 ;
0179 WaitForNextSel:
0180   if _USE_RTSCSTS
0181     bcf   _rp0
0182     bcf   _RTS
0183   endif
0184   call   GetChar
0185   btfsc  _rcvOver
0186   goto  $-1
0187 ;
0188 ; A Byte is received, Select The Desired Channel & TMXT the desired A/D Channel Data
0189 ;
0190   bcf   _rp0
0191   movf  RxReg,w
0192   call  GetADCon0
0193   movwf _adcon0
0194   nop
0195 ;
0196   bsf   _go
0197   btfsc _done
0198   goto $-1
0199
0200   movf  _adres,w
0201   movwf TxReg
0202
0203   if _USE_RTSCSTS
0204     bsf   _RTS
0205     btfsc _CTS
0206     goto $-1
0207   endif
0208   call  PutChar
0209   btfsc _txmtProgress
0210   goto $-1
0211
0212 ;
0213   goto WaitForNextSel
0214 ;
0215 ; *****
0216 ; RS-232 Routines
0217 ; *****
0218 ; Interrupt Service Routine
0219 ;
0220 ; Only RTCC Interrupt Is used. RTCC Interrupt is used as timing for Serial Port Receive & Transmit
0221 ; Since RS-232 is implemented only as a Half Duplex System, The RTCC is shared by both Receive &
0222 ; Transmit Modules.
0223 ; Transmission :
0224 ; RTCC is setup for Internal Clock increments and interrupt is generated when

```

Software Implementation of Asynchronous Serial I/O

```

0025 ; RTCC overflows. Prescaler is assigned, depending on The INPUT CLOCK & the
0026 ; desired BAUD RATE.
0027 ;
0028 ; Reception :
0029 ; When put in receive mode, RTCC is setup for external clock mode (FALLING EDGE)
0030 ; and preloaded with 0xFF. When a Falling Edge is detected on RTCC Pin, RTCC
0031 ; rolls over and an Interrupt is generated (thus Start Bit Detect). Once the start
0032 ; bit is detected, RTCC is changed to INTERNAL CLOCK mode and RTCC is preloaded
0033 ; with a certain value for regular timing interrupts to Poll RTCC Pin (i.e RX pin).
0034 ; *****
0035 ;
0036 Interrupt:
0037     btfss _rtif
0038     retfie
0039 ;
0040 ; Save Status On INT : WREG & STATUS Regs
0041 ;
0042     movwf SaveWReg
0043     swapf _status,w
0044     movwf SaveStatus
0045 ;
0046     btfsc _TxmtNextBit
0047     goto _TxmtNextBit
0048     btfsc _rcvProgress
0049     goto _RcvNextBit
0050     goto _SBitDetected
0051 ;
0052 RestoreIntStatus:
0053     swapf SaveStatus,w
0054     movwf _status
0055     swapf SaveWReg
0056     swapf SaveWReg,w
0057     bcf _rtif
0058     retfie
0059 ;
0060 ; *****
0061 ;
0062 ;
0063 ;
0064 ; Configure TX pin as output, make sure TX Pin Comes up in high state on Reset
0065 ; Configure, RX_Pin (RTCC pin) as Input, which is used to poll data on reception
0066 ;
0067 ; Program Memory : 9 locations
0068 ; Cycles : 10
0069 ; *****
0070 ;
0071 InitSerialPort:

```

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```

0041 2060      call _TxmtStartBit
0042 188B      bsf _rtie      ; Enable RTCC Overflow INT
0043 0009      retfie      ; return with _GIE Bit Set
*****
0031 0031      ;*****
0032 0032      ; Internal Subroutine
0033 0033      ; entered from Interrupt Service Routine when Start Bit Is detected.
0034 0034      ;
0035 0035      ; Program Memory : 30 locations (38 locations if PARITY is used)
0036 0036      ; Cycles : 15 Worst Case
0037 0037      ;*****
0038 0038      ;*****
0039 0039      ;*****
0040 1283      _TxmtNextBit:
0041      bcf _rp0
0042      LOAD_RTCC 0,RtccPreLoad, RtccPrescale ; Macro to reload RTCC
M      if(UsePrescale == 0 && 0 == 0)
M      movlw -RtccPreLoad + _Cycle_Offset1
M      else
M      movlw -RtccPreLoad + (_Cycle_Offset1 >> (RtccPrescale+1)) ; Re Load RTCC init value + INT La
M      endif
M      movwf _rtcc
0043 ;
0044      movf BitCount
0045      btfsc _z
0046      goto _ParityOrStop
0047 ;
0048      decf BitCount
0049      goto _NextTxmtBit
0050 ;
0051 _ParityOrStop:
0052      if _PARITY_ENABLE
0053      ExtraBitCount,1
0054      goto _SendParity
0055      endif
0056      movf ExtraBitCount,1
0057      btfsc _z
0058      goto DoneTxmt
0059      decf ExtraBitCount,1
0060 ;
0061 _StopBit:
0062      bsf TX
0063      RestoreIntStatus
0064      goto DoneTxmt
0065 ;

```

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```

0053 1403      _carry
0054 0C8C      TxReg
0055 1C03      _carry
0056 1386      TX
0057 1803      _carry
0058 1786      TX
0059 1C8F      _txmtEnable
005A 168B      _rtie
005B 282D      RestoreIntStatus

; disable further interrupts, Transmission Aborted

0066 _NextTxmtBit:
0067     bsf     _carry
0068     rrf     TxReg
0069     btfss   _carry
0070     bcf     TX
0071     btfsc   _carry
0072     bsf     TX
0073 ;
0074     btfss   _txmtEnable
0075     bsf     _rtie
0076 ;
0077     goto    RestoreIntStatus
0078 ;
0079     if _PARITY_ENABLE
0080 _SendParity:
0081     decf     ExtraBitCount,1
0082     btfss   _parityBit
0083     bcf     TX
0084     btfsc   _parityBit
0085     bsf     TX
0086     goto    RestoreIntStatus
0087     endif
0088
0089 DoneTxmt
0090     bsf     TX
0091     bcf     _rtie
0092     bcf     _txmtProgress
0093     goto    RestoreIntStatus
0094 ;
0095 ;*****
0096 ; Internal Subroutine
0097 ; entered from Interrupt Service Routine when Start Bit Is detected.
0098 ;
0099 ; Program Memory : 9 locations
0100 ; Cycles : 10
0101 ;
0102 ;*****
0103 _TxmtStartBit:
0104     bcf     _rp0
0105     clrf    _rtcc
0106     clrwdt
0107     bsf     _rp0
0108     movlw   07h
0109     movwf   _option
0110     bcf     _rp0
0111     clrf    _rtcc
0112     bsf     _rp0
0113     movlw   0Fh

0060 1283      _rp0
0061 0181      clrf _rtcc
0062 0064      clrwdt
0063 1683      bsf _rp0
0064 3007      movlw 07h
0065 0081      movwf _option
0066 1283      bcf _rp0
0067 0181      clrf _rtcc
0068 1683      bsf _rp0
0069 300F      movlw 0Fh

;STOP Bit is High
;disable further interrupts
;indicates end of xmission
;*****

```

Software Implementation of Asynchronous Serial I/O

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```

006A 0081      _option
006B 0064      clrwdt
006C 3001      movlw      (_OPTION_INIT | RtcCPrescale)
006D 0081      movwf      _option
006E 1283      bcf         _rp0
006F 1386      bcf         TX
0070 3030      movlw      -RtcCPreload
0071 0081      movwf      _rtcc
0072 1108      bcf         _rtif
0073 0008      return

0114      _option
0115      clrwdt
0116      movlw      (_OPTION_INIT | RtcCPrescale)
0117      movwf      _option
0118      bcf         _rp0
0119      bcf         TX
0120      movlw      -RtcCPreload
0121      movwf      _rtcc
0122      bcf         _rtif
0123      return
0124

0125      ;*****
0126      ;          Generate Parity for the Value in WREG
0127      ;
0128      ; The parity bit is set in _parityBit (SerialStatus,7)
0129      ; Common Routine For Both Transmission & Reception
0130      ;
0131      ; Program Memory :      16 locations
0132      ; Cycles      :      72
0133      ;
0134      ;*****
0135      ; if _PARITY_ENABLE
0136
0137      GenParity:
0138          movwf      temp2
0139          movf        BitCount,w
0140          movwf      temp1
0141      ParityLoop
0142          rrf
0143          btfss      _carry
0144          goto       NotOne
0145          xorlw      00h
0146          goto       OneDone
0147      NotOne
0148          xorlw      01h
0149      OneDone
0150          decfsz     temp1
0151          goto       ParityLoop
0152          movwf      temp1
0153      ; Parity bit is in Bit 0 of temp1
0154      ;
0155      ; if _ODD_PARITY
0156          bsf         _parityBit
0157          btfsc      temp1,0
0158          bcf         _parityBit
0159      else
0160          bcf         _parityBit
0161          temp1,0

```

```

0162      bsf      _parityBit
0163      endif
0164
0165      return
0166      endif
0167 ;*****
0287 ;*****
0288      include "rcvr.asm" ; The Receiver Routines are in File "rcvr.asm"
0300 ;*****
0301 ;*****
0302      GetChar Function
0303 ; Receives a Byte Of Data
0304 ; When reception is complete, _rcvOver Bit is cleared
0305 ; The received data is in RxReg
0306 ;
0307 ; Program Memory : 15 locations (17 locations if PARITY is used)
0308 ; Cycles : 16 (18 if PARITY is USED)
0309 ;*****
0310 ;*****
0311 GetChar:
0312      bcf      _rp0
0313      bsf      _rcvOver
0314      LOAD_BITCOUNT
0315      movlw   _DataBits+1
0316      movwf   BitCount
0317      movlw   1
0318      movwf   ExtraBitCount
0319      if _PARITY_ENABLE
0320      movlw   2
0321      movwf   ExtraBitCount
0322      endif
0323      clrf    RxReg
0324      bcf     _FrameErr
0325      bcf     _ParityErr
0326      clrf    _rtcc
0327      bsf     _rp0
0328      movlw   07h
0329      movwf   _option
0330      bcf     _rp0
0331      clrf    _rtcc
0332      bsf     _rp0
0333      movlw   0Fh
0334      movwf   _option
0335      clrwdt
0336      movlw   OPTION_SBIT
0337      movwf   _option
0338      bcf     _rp0
0339      movlw   0xFF
0340
0341 ; Inc On Ext Clk Falling Edge
0342 ; Set Option Reg Located In Page 1
0343 ; make sure to select Page 0

```

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```

008C 0081      movwf _rtcc      ; A Start Bit will roll over RTCC & Gen INT
008D 110B      bcf _rtif      ; Enable RTCC Interrupt
008E 168B      bsf _rtie      ; Enable Global Interrupt
008F 0009      retfie
0033 ;
0034 ;
0035 ;
0036 ;
0037 ;
0038 ;
0039 ;
0040 ;
0041 ;
0042 ;
0043 ;
0044 ;
0045 ;
0046 ;
0047 ;
0048 ;
0049 ;
0050 ;
0051 ;
0052 ;
0053 ;
0054 ;
0055 ;
0056 ;
0057 ;
0058 ;
0059 ;
0060 ;
0061 ;
0062 ;
0063 ;
0064 ;
0065 ;
0066 ;
0067 ;
0068 ;
0069 ;
0070 ;
0071 ;
0072 ;
0073 ;
0074 ;

; Make sure Start Bit Interrupt is not a Glitch
; False Start Bit

; Switch Back to INT Clock
; Set Option Reg Located In Page 1
; make sure to select Page 0

LOAD_RTCC 1, (SBitRtccLoad), SBitPrescale
if (UsePrescale == 0 && 1 == 0)
    movlw -(SBitRtccLoad) + _Cycle_Offset1
else
    movlw -(SBitRtccLoad) + (_Cycle_Offset1 >> (SBitPrescale+1)) ; Re Load RTCC init value + INT La
endif
    movwf _rtcc      ; Note that Prescaler is cleared when RTCC is written
    goto RestoreIntStatus

; reload RTCC with 0xFF for start bit detection

Internal Subroutine

```

```

0075 ; entered from Interrupt Service Routine when Start Bit Is detected.
0076 ;
0077 ; Program Memory : 28 locations ( 43 locations with PARITY enabled)
0078 ; Cycles : 24 Worst Case
0079 ;
0080 ;*****
0081 _RcvNextBit:
0082     clrwdt
0083     bsf _rp0
0084     movlw 07h
0085     movwf _option
0086     bcf _rp0
0087     clrf _rtcc
0088     clrwdt
0089     bsf _rp0
0090     movlw 07h
0091     movwf _option
0092     bcf _rp0
0093     clrf _rtcc
0094     bsf _rp0
0095     movlw 0Fh
0096     movwf _option
0097     clrwdt
0098     movlw (_OPTION_INIT | RtccPrescale) ; Switch Back to INT Clock
0099     movwf _option ; Set Option Reg Located In Page 1
0100 ;
0101     bcf _rp0
0102     movf _porta,w
0103     movwf RXTemp ; read RX pin immediately into WREG
0104     LOAD_RTCC 0,RtccPreLoad, RtccPrescale ; Macro to reload RTCC
M     if(UsePrescale == 0 && 0 == 0)
M         movlw -RtccPreLoad + _Cycle_Offset1
M     else
M         movlw -RtccPreLoad + (_Cycle_Offset1 >> (RtccPrescale+1)) ; Re Load RTCC init value + INT La
M     endif
M     movwf _rtcc ; Note that Prescaler is cleared when RTCC is written
0105     movf _porta,w
0106     xorwf RXTemp,w
0107     andlw RX_MASK ; mask for only RX PIN (RA4)
0108     btfsc _Z
0109     goto _PinSampled ; both samples are same state
0110 _SampleAgain:
0111     movf _porta,w
0112     movwf RXTemp ; 2 out of 3 majority sampling done
0113 _PinSampled:
0114     movf BitCount,1
0115     btfsc _Z

```

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```

00C8 28C8      0116      goto    _RcvP_Or_S
00C9 0890      0117      ;
00CA 28D1      0118      decfsz  BitCount
00CB 1E0E      0119      goto    _NextRcvBit
00CC 168F      0120      ;
00CD 128B      0121      _RcvP_Or_S:
00CE 110F      0122      if _PARITY_ENABLE
00CF 118F      0123      decfsz  ExtraBitCount
0100          0124      goto    _RcvParity
0101          0125      endif
0102          0126      ;
0103          0127      _RcvStopBit:
0104          0128      RX      btfss
0105          0129      _FrameErr bsf
0106          0130      _rtie   bcf
0107          0131      _rcvProgress bcf
0108          0132      bcf     _rcvOver
0109          0133      if _PARITY_ENABLE
0110          0134      movf   RxReg,w
0111          0135      call   GenParity
0112          0136      movlw  0
0113          0137      btfsc  _parityBit
0114          0138      movlw  0x10
0115          0139      xorwf  SerialStatus
0116          0140      endif
0117          0141      if _DataBits == 7
0118          0142      rrf     RxReg,1
0119          0143      bcf     RxReg,7
0120          0144      endif
0121          0145      goto    RestoreIntStatus
0122          0146      ;
0123          0147      _NextRcvBit:
0124          0148      bcf     _carry
0125          0149      btfsc  RX
0126          0150      bsf     _carry
0127          0151      rrf     RxReg
0128          0152      goto    RestoreIntStatus
0129          0153      ;
0130          0154      if _PARITY_ENABLE
0131          0155      _RcvParity:
0132          0156      bcf     _ParityErr
0133          0157      btfsc  RX
0134          0158      bsf     _ParityErr
0135          0159      goto    RestoreIntStatus
0136          0160      endif
0137          0161      ;
0138          0162      ;*****
0288          0288      ;*****

```

; may be framing Error or Glitch
 ; disable further interrupts
 ; Byte Received, Can RCV/TXMT an other Byte
 ; Generate Parity, for Parity check
 ; to mask off Received Parity Bit in _ParityErr
 ; _ParityErr bit is set accordingly
 ; prepare bit for shift
 ; shift in received data
 ; Temporarily store PARITY Bit in _ParityErr
 ; Sample again to avoid any glitches

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