

Sensorless Motor Control IC for Appliances

Features

- **MCE™ (Motion Control Engine) - Hardware based computation engine for high efficiency sinusoidal sensorless control of permanent magnet AC motor**
- **Integrated Power Factor Correction control**
- **Supports both interior and surface permanent magnet motors**
- **Built-in hardware peripheral for single shunt current feedback reconstruction**
- **No external current or voltage sensing operational amplifier required**
- **Three/two-phase Space Vector PWM**
- **Three-channel analog output (PWM)**
- **Embedded 8-bit high speed microcontroller (8051) for flexible I/O and man-machine control**
- **JTAG programming port for emulation/debugger**
- **Serial communication interface (UART)**
- **I²C/SPI serial interface**
- **Watchdog timer with independent analog clock**
- **Three general purpose timers/counters**
- **Two special timers: periodic timer, capture timer**
- **Internal 'One-Time Programmable' (OTP) memory and internal RAM for final production usage**
- **Pin compatible with IRMCK343, RAM version**
- **1.8V/3.3V CMOS**

Product Summary

| | |
|---|-----------------|
| Maximum crystal frequency | 60 MHz |
| Maximum internal clock (SYSCLK) frequency | 128 MHz |
| Maximum 8051 clock frequency | 33 MHz |
| Sensorless control computation time | 11 µsec typ |
| MCE™ computation data range | 16 bit signed |
| 8051 OTP Program memory | 56K bytes |
| MCE program and Data RAM | 8K bytes |
| GateKill latency (digital filtered) | 2 µsec |
| PWM carrier frequency counter | 16 bits/ SYSCLK |
| A/D input channels | 5 |
| A/D converter resolution | 12 bits |
| A/D converter conversion speed | 2 µsec |
| 8051 instruction execution speed | 2 SYSCLK |
| Analog output (PWM) resolution | 8 bits |
| UART baud rate (typ) | 57.6K bps |
| Number of I/O (max) | 23 |
| Package (lead-free) | QFP64 |
| Operating temperature | -40°C ~ 85°C |

Description

IRMCK343 is a high performance OTP based motion control IC designed primarily for appliance applications. IRMCK343 is designed to achieve low cost and high performance control solutions for advanced inverterized appliance motor control. IRMCK343 contains two computation engines. One is Motion Control Engine (MCE™) for sensorless control of permanent magnet motors; the other is an 8-bit high-speed microcontroller (8051). Both computation engines are integrated into one monolithic chip. The MCE™ contains a collection of control elements such as Proportional plus Integral, Vector rotator, Angle estimator, Multiply/Divide, Low loss SVPWM, Single Shunt IFB. The user can program a motion control algorithm by connecting these control elements using a graphic compiler. Key components of the sensorless control algorithms, such as the Angle Estimator, are provided as complete pre-defined control blocks implemented in hardware. A unique analog/digital circuit and algorithm to fully support single shunt current reconstruction is also provided. The 8051 microcontroller performs 2-cycle instruction execution (60MIPS at 120MHz). The MCE and 8051 microcontroller are connected via dual port RAM to process signal monitoring and command input. An advanced graphic compiler for the MCE™ is seamlessly integrated into the MATLAB/Simulink environment, while third party JTAG based emulator tools are supported for 8051 developments. IRMCK343 comes with a small QFP64 pin lead-free package.

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1 Overview

IRMCK343 is a new International Rectifier integrated circuit device primarily designed as a one-chip solution for complete inverter controlled appliance motor control applications. Unlike a traditional microcontroller or DSP, the IRMCK343 provides a built-in closed loop sensorless control algorithm using the unique Motion Control Engine (MCE™) for permanent magnet motor. The MCE™ consists of a collection of control elements, motion peripherals, a dedicated motion control sequencer and dual port RAM to map internal signal nodes. IRMCK343 also employs a unique single shunt current reconstruction circuit to eliminate additional analog/digital circuitry and enables a direct shunt resistor interface to the IC. Motion control programming is achieved using a dedicated graphical compiler integrated into the MATLAB/Simulink™ development environment. Sequencing, user interface, host communication, and upper layer control tasks can be implemented in the 8051 high-speed 8-bit microcontroller. The 8051 microcontroller is equipped with a JTAG port to facilitate emulation and debugging tools. Figure 1 shows a typical application schematic using the IRMCK343.

IRMCK343 is intended for volume production purpose and contains 64K bytes of OTP (One Time Programming) ROM, which can be programmed through a JTAG port. For a development purpose use, IRMCF343 contains a 48k byte of RAM in place of program OTP to facilitate an application development work. Both IRMCF343 and IRMCK343 come in the same 64-pin QFP package with identical pin configuration to facilitate PC board layout and transition to mass production

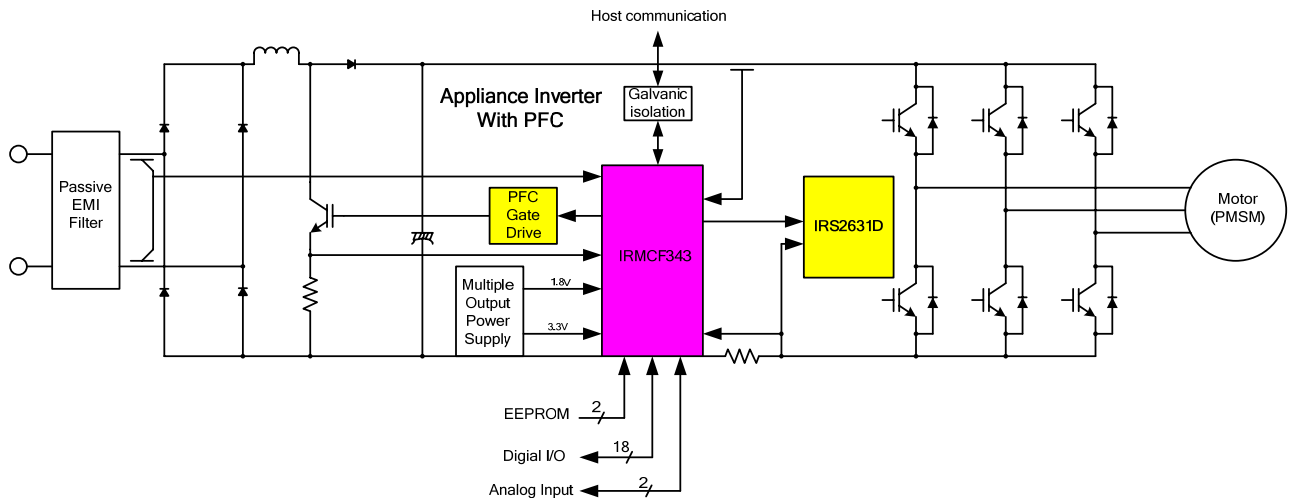


Figure 1 Typical Application Block Diagram Using IRMCK343

2 IRMCK343 Block Diagram and Main Functions

IRMCK343 block diagram is shown in Figure 2.

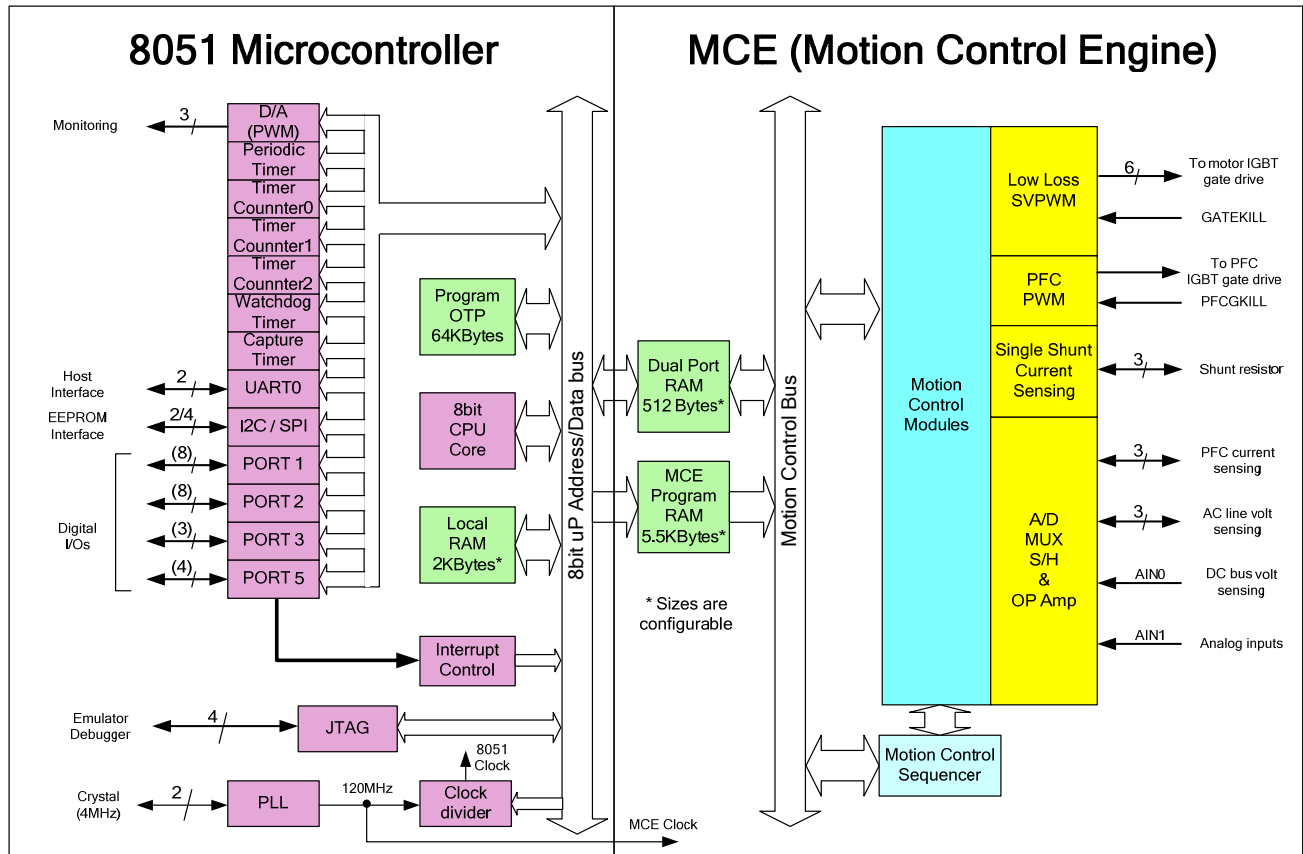


Figure 2. IRMCK343 Internal Block Diagram

IRMCK343 contains the following functions for sensorless AC motor control applications:

- Motion Control Engine (MCE™)
 - Proportional plus Integral block
 - Low pass filter
 - Differentiator and lag (high pass filter)
 - Ramp
 - Limit
 - Angle estimate (sensorless control)
 - Inverse Clark transformation
 - Vector rotator
 - Bit latch
 - Peak detect

- Transition
- Multiply-divide (signed and unsigned)
- Divide (signed and unsigned)
- Adder
- Subtractor
- Comparator
- Counter
- Accumulator
- Switch
- Shift
- ATAN (arc tangent)
- Function block (any curve fitting, nonlinear function)
- 16-bit wide Logic operations (AND, OR, XOR, NOT, NEGATE)
- MCE™ program and data memory (6K byte). ^{Note 1}
- MCE™ control sequencer

- 8051 microcontroller
 - Three 16-bit timer/counters
 - 16-bit periodic timer
 - 16-bit analog watchdog timer
 - 16-bit capture timer
 - Up to 23 discrete I/Os
 - Five-channel 12-bit A/D
 - Three buffered channels (0 – 1.2V input)
 - Two unbuffered channels (0 – 1.2V input)
 - JTAG port (4 pins)
 - Up to three channels of analog output (8-bit PWM)
 - UART
 - I²C/SPI port
 - 64K byte program OTP
 - 2K byte data RAM. ^{Note 1}

Note 1: Total size of RAM is 8K byte including MCE program, MCE data, and 8051 data. Different sizes can be allocated depending on applications.

3 Pinout

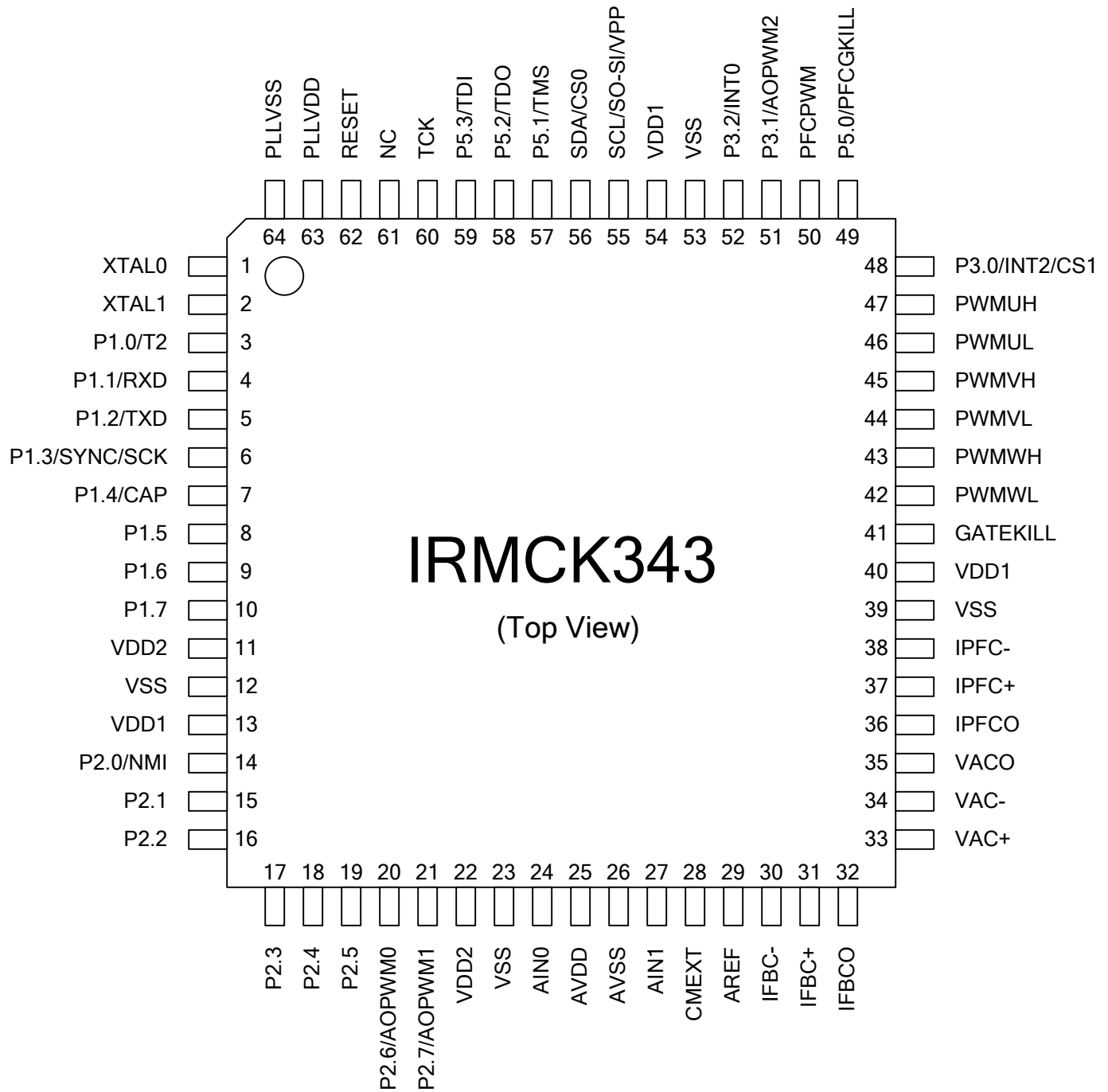


Figure 3. IRMCK343 Pin Configuration

4 Input/Output of IRMCK343

All I/O signals of IRMCK343 are shown in Figure 4. All I/O pins are 3.3V logic interface except A/D interface pins.

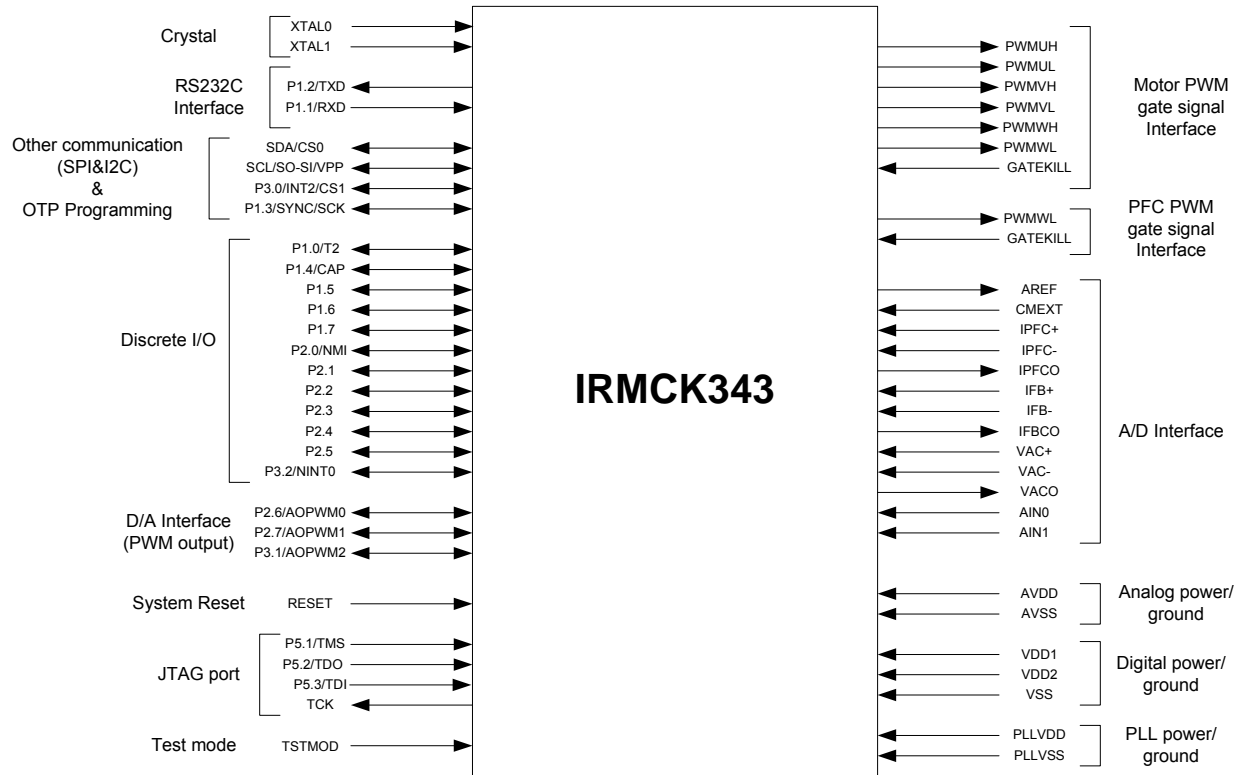


Figure 4. Input/Output of IRMCK343

4.1 8051 Peripheral Interface Group

UART Interface

| | |
|----------|-------------------------------------|
| P1.2/TXD | Output, Transmit data from IRMCK343 |
| P1.1/RXD | Input, Receive data to IRMCK343 |

Discrete I/O Interface

| | |
|---------------|--|
| P1.0/T2 | Input/output port 1.0, can be configured as Timer/Counter 2 input |
| P1.3/SYNC/SCK | Input/output port 1.3, can be configured as SYNC output or SPI clock |
| P1.4/CAP | Input/output port 1.4, can be configured as Capture Timer input |
| P1.5 | Input/output port 1.5 |
| P1.6 | Input/output port 1.6 |
| P1.7 | Input/output port 1.7 |
| P2.0/NMI | Input/output port 2.0, can be configured as Non-maskable interrupt input |
| P2.1 | Input/output port 2.1 |

| | |
|---------------|---|
| P2.2 | Input/output port 2.2 |
| P2.3 | Input/output port 2.3 |
| P2.4 | Input/output port 2.4 |
| P2.5 | Input/output port 2.5 |
| P3.0/INT2/CS1 | Input/output port 3.0, can be configured as INT2 input or SPI chip select 1 |
| P3.2/INT0 | Input/output port 3.2, can be configured as INT0 input |

Analog Output Interface

| | |
|-------------|---|
| P2.6/AOPWM0 | Input/output, can be configured as 8-bit PWM output 0 with programmable carrier frequency |
| P2.7/AOPWM1 | Input/output, can be configured as 8-bit PWM output 1 with programmable carrier frequency |
| P3.1/AOPWM2 | Input/output, can be configured as 8-bit PWM output 2 with programmable carrier frequency |

Crystal Interface

| | |
|-------|------------------------------|
| XTAL0 | Input, connected to crystal |
| XTAL1 | Output, connected to crystal |

Reset Interface

| | |
|-------|---|
| RESET | Input/output, system reset, needs to be pulled up to VDD1 but doesn't require external RC time constant |
|-------|---|

I²C/SPI Interface/OTP Programming

| | |
|---------------|---|
| SCL/SO-SI/VPP | Output or Power, I ² C clock output or SPI data or OTP Programming |
| SDA/CS0 | Input/output, I ² C data line or SPI chip select 0 |
| P3.0/INT2/CS1 | Input/output, INT2 or SPI chip select 1 |
| P1.3/SYNC/SCK | Input/output, SYNC output or SPI clock, needs to be pulled up to VDD1 in order to boot from I ² C EEPROM |

4.2 Motion Peripheral Interface Group

PWM

| | |
|--------|---|
| PWMUH | Output, PWM phase U high side gate signal |
| PWMUL | Output, PWM phase U low side gate signal |
| PWMVH | Output, PWM phase V high side gate signal |
| PWMVL | Output, PWM phase V low side gate signal |
| PWMWH | Output, PWM phase W high side gate signal |
| PWMWL | Output, PWM phase W low side gate signal |
| PFCPWM | Output, PFC PWM gate signal |

Fault

| | |
|---------------|---|
| GATEKILL | Input, upon assertion, this negates all six PWM signals, programmable logic sense |
| P5.0/PFCGKILL | Input, upon assertion, this negates PFCPWM signal, programmable logic sense, can be configured as discrete I/O in which case CGATEKILL negates PFCPWM |

4.3 Analog Interface Group

| | |
|-------|---|
| AVDD | Analog power (1.8V) |
| AVSS | Analog power return |
| CMEXT | Unbuffered 0.6V, input to the AREF buffer, capacitor needs to be connected. |
| AREF | 0.6V buffered output |
| IFB+ | Input, Operational amplifier positive input for shunt resistor current sensing |
| IFB- | Input, Operational amplifier negative input for shunt resistor current sensing |
| IFBO | Output, Operational amplifier output for shunt resistor current sensing |
| IPFC+ | Input, Operational amplifier positive input for PFC current sensing |
| IPFC- | Input, Operational amplifier negative input for PFC current sensing |
| IPFO | Output, Operational amplifier output for PFC current sensing |
| VAC+ | Input, Operational amplifier positive input for PFC AC voltage sensing |
| VAC- | Input, Operational amplifier negative input for PFC AC voltage sensing |
| VACO | Output, Operational amplifier output for PFC AC voltage sensing |
| AIN0 | Input, Analog input channel 0 (0 – 1.2V), typically configured for DC bus voltage input |
| AIN1 | Input, analog input channel 1 (0 – 1.2V), needs to be pulled down to AVSS if unused |

4.4 Power Interface Group

| | |
|--------|-------------------------------------|
| VDD1 | Digital power for I/O (3.3V) |
| VDD2 | Digital power for core logic (1.8V) |
| VSS | Digital common |
| PLLVD | PLL power (1.8V) |
| PLLVSS | PLL ground return |

4.5 Test Interface Group

| | |
|----------|---|
| TSTMOD | Must be tied to VSS, used only for factory testing. |
| P5.3/TDI | Input, JTAG test data input |
| P5.1/TMS | Input, JTAG test mode select |
| TCK | Input, JTAG test clock |
| P5.2/TDO | Output, JTAG test data output |

5 Application Connections

Typical application connection is shown in Figure 5. All components necessary to implement a complete sensorless drive control algorithm are shown connected to IRMCK343.

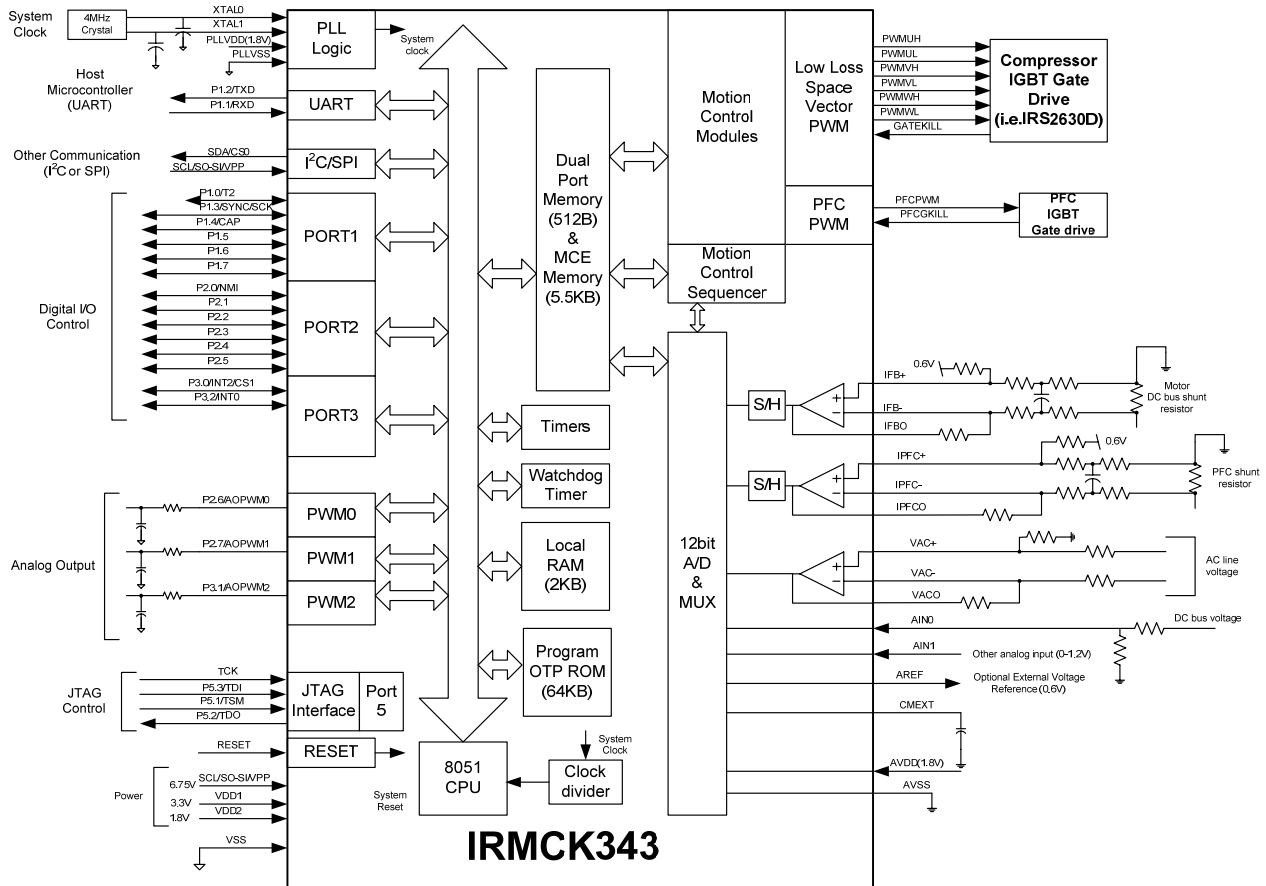


Figure 5. Application Connection of IRMCK343

6 DC Characteristics

6.1 Absolute Maximum Ratings

| Symbol | Parameter | Min | Typ | Max | Condition |
|------------------|-----------------------|--------|-----|--------|-----------------|
| V _{DD1} | Supply Voltage | -0.3 V | - | 3.6 V | Respect to VSS |
| V _{DD2} | Supply Voltage | -0.3 V | - | 1.98 V | Respect to VSS |
| V _{IA} | Analog Input Voltage | -0.3 V | - | 1.98 V | Respect to AVSS |
| V _{ID} | Digital Input Voltage | -0.3 V | - | 3.65 V | Respect to VSS |
| T _A | Ambient Temperature | -40 °C | - | 85 °C | |
| T _S | Storage Temperature | -65 °C | - | 150 °C | |

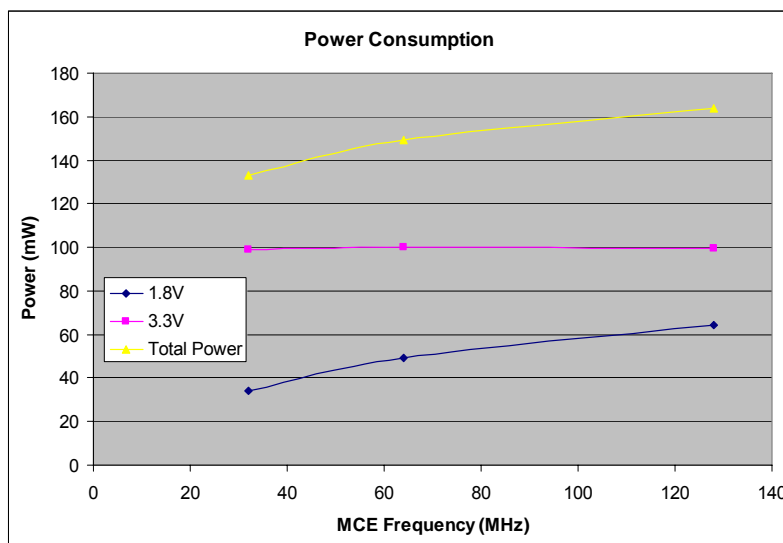
Table 1. Absolute Maximum Ratings

Caution: Stresses beyond those listed in “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only and function of the device at these or any other conditions beyond those indicated in the operational sections of the specifications are not implied.

6.2 System Clock Frequency and Power Consumption

| Symbol | Parameter | Min | Typ | Max | Unit |
|----------|--------------|-----|-----|-----|------|
| SYSCLOCK | System Clock | 32 | - | 128 | MHz |
| 8051CLK | 8051 Clock | - | - | 32 | MHz |

Table 2. System Clock Frequency



6.3 Digital I/O DC Characteristics

| Symbol | Parameter | Min | Typ | Max | Condition |
|---------------------------------|---------------------------|---------|---------|---------|--------------------------------|
| V _{DD1} | Supply Voltage | 3.0 V | 3.3 V | 3.6 V | Recommended |
| V _{DD2} | Supply Voltage | 1.62 V | 1.8 V | 1.98 V | Recommended |
| V _{IL} | Input Low Voltage | -0.3 V | - | 0.8 V | Recommended |
| V _{IH} | Input High Voltage | 2.0 V | | 3.6 V | Recommended |
| C _{IN} | Input capacitance | - | 3.6 pF | - | (1) |
| I _L | Input leakage current | | ±10 nA | ±1 µA | V _O = 3.3 V or 0 V |
| I _{OL1} ⁽²⁾ | Low level output current | 8.9 mA | 13.2 mA | 15.2 mA | V _{OL} = 0.4 V (1) |
| I _{OH1} ⁽²⁾ | High level output current | 12.4 mA | 24.8 mA | 38 mA | V _{OH} = 2.4 V (1) |
| I _{OL2} ⁽³⁾ | Low level output current | 17.9 mA | 26.3 mA | 33.4 mA | V _{OL} = 0.4 V (1) |
| I _{OH2} ⁽³⁾ | High level output current | 24.6 mA | 49.5 mA | 81 mA | V _{OH} = 2.4 V (1) |

Table 3. Digital I/O DC Characteristics

Note:

- (1) Data guaranteed by design.
- (2) Applied to SCL/SO-SI, SDA/CS0 pins.
- (3) Applied to P1.0/T2, P1.1/RXD, P1.2/TXD, P1.3/SYNC/SCK, P1.4/CAP, P1.5, P1.6, P1.7, P2.0/NMI, P2.1, P2.2, P2.3, P2.4, P2.5, P2.6/AOPWM0, P2.7/AOPWM1, P3.0/INT2/CS1, P3.1/AOPWM2, P3.2/INT0, P5.0/PFCGKILL, P5.1/TMS, P5.2/TDO, P5.3/TDI, GATEKILL, PWMUL, PWMUH, PWMVL, PWMVH, PWMWL, PWMWH, and PFCPWM pins.

6.4 PLL and Oscillator DC Characteristics

| Symbol | Parameter | Min | Typ | Max | Condition |
|---------------------|-------------------------------|----------------------------|-------|----------------------------|-----------------------------------|
| V _{PLLVD} | Supply Voltage | 1.62 V | 1.8 V | 1.92 V | Recommended |
| V _{IL OSC} | Oscillator Input Low Voltage | V _{PLLSS} | - | 0.2* V _{PLLVD} | V _{PLLVD} = 1.8 V (1) |
| V _{IH OSC} | Oscillator Input High Voltage | 0.8* V _{PLLVD} | | V _{PLLVD} | V _{PLLVD} = 1.8 V (1) |

Table 4. PLL DC Characteristics

Note:

- (1) Data guaranteed by design.

6.5 Analog I/O DC Characteristics

- OP amps for current sensing (IFB+, IFB-, IFBO, IPFC+, IPFC-, IPFCO)

$C_{AREF} = 1nF$, $C_{MEXT} = 100nF$. Unless specified, $T_a = 25^{\circ}C$.

| Symbol | Parameter | Min | Typ | Max | Condition |
|---------------|-------------------------------|----------------------|-------------|---------------|--|
| V_{AVDD} | Supply Voltage | 1.71 V | 1.8 V | 1.89 V | Recommended |
| V_{OFFSET} | Input Offset Voltage | - | - | 26 mV | $V_{AVDD} = 1.8 V$ |
| V_I | Input Voltage Range | 0 V | - | 1.2 V | Recommended |
| V_{OUTSW} | OP amp output operating range | 50 mV ⁽¹⁾ | - | 1.2 V | $V_{AVDD} = 1.8 V$ |
| C_{IN} | Input capacitance | - | 3.6 pF | - | (1) |
| R_{FDBK} | OP amp feedback resistor | 5 k Ω | - | 20 k Ω | Requested between op amp output and negative input |
| OP_{GAINCL} | Operating Close loop Gain | 80 db | - | - | (1) |
| CMRR | Common Mode Rejection Ratio | - | 80 db | - | (1) |
| I_{SRC} | Op amp output source current | - | 1 mA | - | $V_{OUT} = 0.6 V$ (1) |
| I_{SNK} | Op amp output sink current | - | 100 μA | - | $V_{OUT} = 0.6 V$ (1) |

Table 5. Analog I/O DC Characteristics

Note:

(1) Data guaranteed by design.

6.6 Under Voltage Lockout DC Characteristics

- Based on AVDD (1.8V)

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Condition |
|------------|--|--------|--------|--------|--------------------------|
| UV_{CC+} | UVcc positive going Threshold ⁽¹⁾ | 1.53 V | 1.66 V | 1.71 V | $V_{DD1} = 3.3\text{ V}$ |
| UV_{CC-} | UVcc negative going Threshold | 1.52 V | 1.62 V | 1.71 V | $V_{DD1} = 3.3\text{ V}$ |
| UV_{CCH} | UVcc Hysteresys | - | 40 mV | - | |

Table 6. UVcc DC Characteristics

Note:

(1) Data guaranteed by design.

6.7 AREF Characteristics

$C_{AREF} = 1\text{nF}$, $C_{MEXT} = 100\text{nF}$. Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Condition |
|--------------|----------------------------------|--------|--------|--------|---------------------------|
| V_{AREF} | AREF Output Voltage | 495 mV | 600 mV | 700 mV | $V_{AVDD} = 1.8\text{ V}$ |
| ΔV_o | Load regulation ($V_{DC}-0.6$) | - | 1 mV | - | (1) |
| PSRR | Power Supply Rejection Ratio | - | 75 db | - | (1) |

Table 7. AREF DC Characteristics

Note:

(1) Data guaranteed by design.

7 AC Characteristics

7.1 PLL AC Characteristics

| Symbol | Parameter | Min | Typ | Max | Condition |
|-------------|-----------------------------|----------------------|----------|---------------|--------------------------------------|
| F_{CLKIN} | Crystal input frequency | 3.2 MHz | 4 MHz | 60 MHz | ⁽¹⁾ (see figure below) |
| F_{PLL} | Internal clock frequency | 32 MHz | 50 MHz | 128 MHz | ⁽¹⁾ |
| F_{LWPW} | Sleep mode output frequency | $F_{CLKIN} \div 256$ | - | - | ⁽¹⁾ |
| J_S | Short time jitter | - | 200 psec | - | ⁽¹⁾ |
| D | Duty cycle | - | 50 % | - | ⁽¹⁾ |
| T_{LOCK} | PLL lock time | - | - | 500 μ sec | ⁽¹⁾ |

Table 8. PLL AC Characteristics

Note:

(1) Data guaranteed by design.

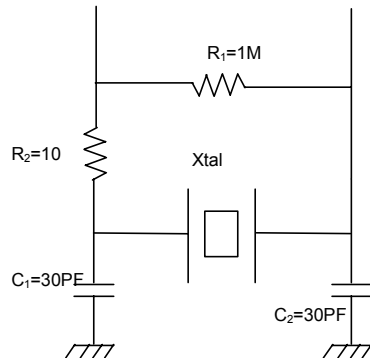


Figure 7 Crystal oscillator circuit

7.2 Analog to Digital Converter AC Characteristics

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Condition |
|-------------------|-------------------------------|-----|-----|----------------------|---|
| T_{CONV} | Conversion time | - | - | 2.05 μsec | ⁽¹⁾ |
| T_{HOLD} | Sample/Hold maximum hold time | - | - | 10 μsec | Voltage droop \leq 15 LSB (see figure below) |

Table 9. A/D Converter AC Characteristics

Note:

(1) Data guaranteed by design.

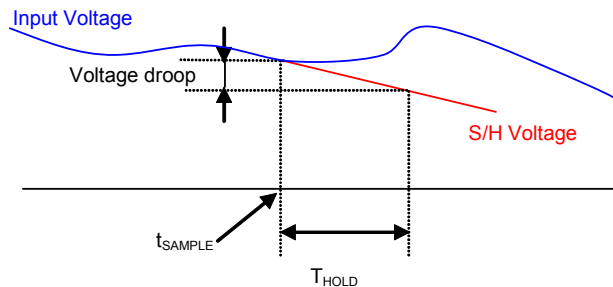


Figure 8 Voltage droop of sample and hold

7.3 Op Amp AC Characteristics

- OP amps for current sensing (IFB+, IFB-, IFBO, IPFC+, IPFC-, IPFCO)

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Condition |
|-------------------|--------------------|-----|-----------------------|-----|---|
| OP_{SR} | OP amp slew rate | - | 10 V/ μsec | - | $V_{\text{AVDD}} = 1.8 \text{ V}$, $CL = 33 \text{ pF}$ ⁽¹⁾ |
| OP_{IMP} | OP input impedance | - | $10^8 \Omega$ | - | ⁽¹⁾ |
| T_{SET} | Settling time | - | 400 ns | - | $V_{\text{AVDD}} = 1.8 \text{ V}$, $CL = 33 \text{ pF}$ ⁽¹⁾ |

Table 10. Current Sensing OP amp AC Characteristics

Note:

(1) Data guaranteed by design.

7.4 SYNC to SVPWM and A/D Conversion AC Timing

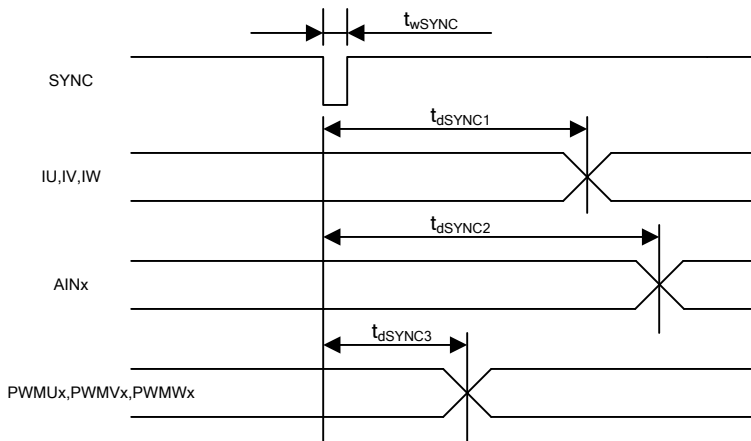


Figure 9 SYNC to SVPWM and A/D Conversion AC Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------|---|-----|-----|-----|-----------------------|
| t_{wSYNC} | SYNC pulse width | - | 32 | - | SYSClk |
| t_{dSYNC1} | SYNC to current feedback conversion time | - | - | 100 | SYSClk |
| t_{dSYNC2} | SYNC to AIN0-6 analog input conversion time | - | - | 200 | SYSClk ⁽¹⁾ |
| t_{dSYNC3} | SYNC to PWM output delay time | - | - | 2 | SYSClk |

Table 11. SYNC AC Characteristics

Note:

(1) AIN1 through AIN6 channels are converted once every 6 SYNC events

7.5 GATEKILL to SVPWM AC Timing

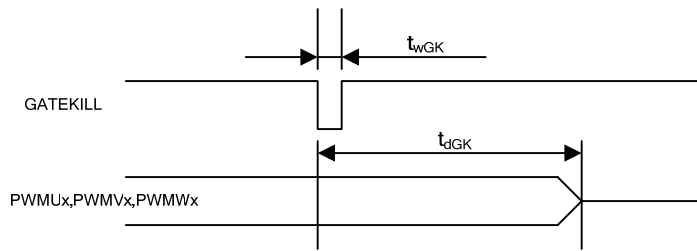


Figure 10 GATEKILL to SVPWM AC Timing

Unless specified, Ta = 25°C.

| Symbol | Parameter | Min | Typ | Max | Unit |
|------------------|------------------------------|-----|-----|-----|--------|
| t _{wGK} | GATEKILL pulse width | 32 | - | - | SYSClk |
| t _{dGK} | GATEKILL to PWM output delay | - | - | 100 | SYSClk |

Table 12. GATEKILL to SVPWM AC Timing

7.6 Interrupt AC Timing

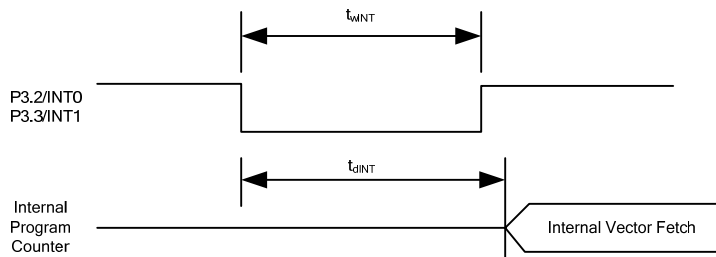


Figure 11 Interrupt AC Timing

Unless specified, Ta = 25°C.

| Symbol | Parameter | Min | Typ | Max | Unit |
|-------------------|-------------------------------------|-----|-----|-----|--------|
| t _{wINT} | INT0, INT1 Interrupt Assertion Time | 4 | - | - | SYSClk |
| t _{dINT} | INT0, INT1 latency | - | - | 4 | SYSClk |

Table 13. Interrupt AC Timing

7.7 I²C AC Timing

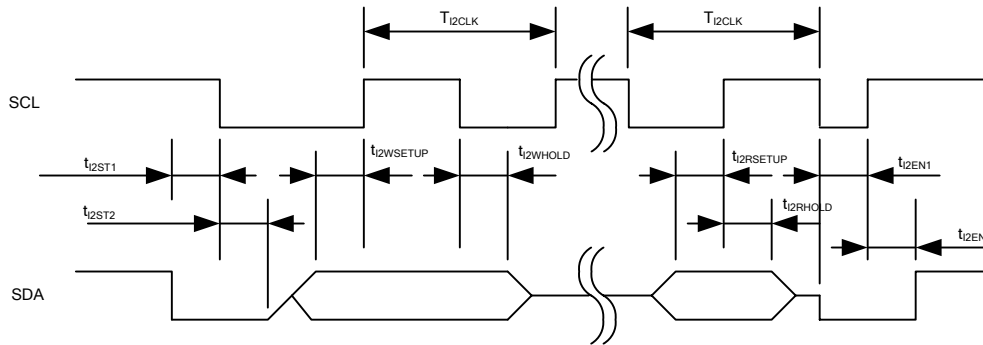


Figure 12 I²C AC Timing

Unless specified, Ta = 25°C.

| Symbol | Parameter | Min | Typ | Max | Unit |
|-----------------------|-----------------------------------|---|-----|------|--------------------|
| T _{I2CLK} | I ² C clock period | 10 | - | 8192 | SYCLK |
| t _{I2ST1} | I ² C SDA start time | 0.25 | - | - | T _{I2CLK} |
| t _{I2ST2} | I ² C SCL start time | 0.25 | - | - | T _{I2CLK} |
| t _{I2WSETUP} | I ² C write setup time | 0.25 | - | - | T _{I2CLK} |
| t _{I2WHOLD} | I ² C write hold time | 0.25 | - | - | T _{I2CLK} |
| t _{I2RSETUP} | I ² C read setup time | I ² C filter time ⁽¹⁾ | - | - | SYCLK |
| t _{I2RHOLD} | I ² C read hold time | 1 | - | - | SYCLK |

Table 14. I²C AC Timing

Note:

- (1) I²C read setup time is determined by the programmable filter time applied to I²C communication.

7.8 SPI AC Timing

7.8.1 SPI Write AC timing

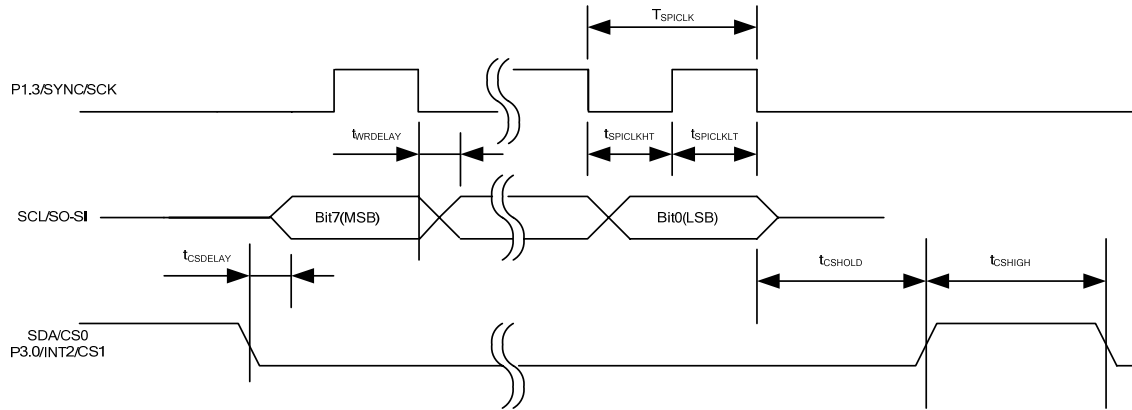


Figure 13 SPI write AC Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|-----------------------|--|-----|-----|-----|---------------------|
| T_{SPICLK} | SPI clock period | 4 | - | - | SYSCLK |
| t_{SPICLKHT} | SPI clock high time | - | 1/2 | - | T_{SPICLK} |
| t_{SPICLKLT} | SPI clock low time | - | 1/2 | - | T_{SPICLK} |
| t_{CSDELAY} | CS to data delay time | - | - | 10 | nsec |
| t_{WRDELAY} | CLK falling edge to data delay time | - | - | 10 | nsec |
| t_{CSHIGH} | CS high time between two consecutive byte transfer | 1 | - | - | T_{SPICLK} |
| t_{CSHOLD} | CS hold time | - | 1 | - | T_{SPICLK} |

Table 15. SPI Write AC Timing

7.8.2 SPI Read AC Timing

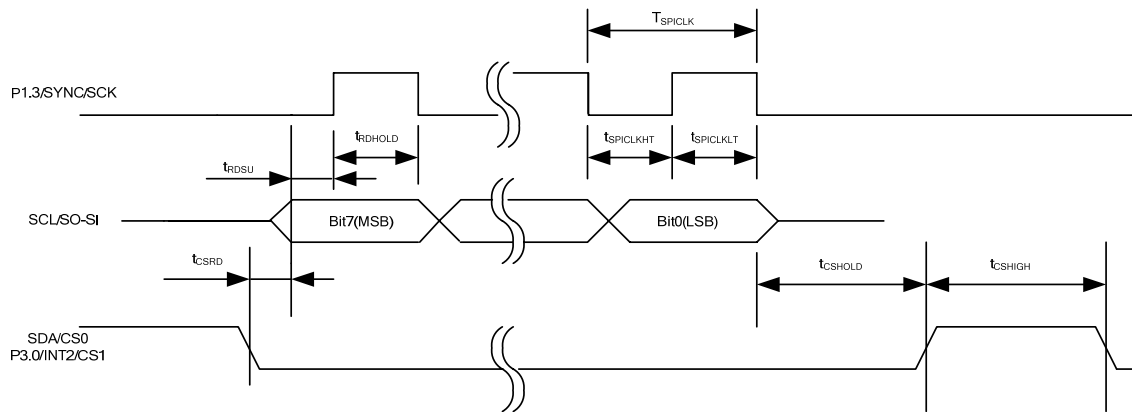


Figure 14 SPI read AC Timing

Unless specified, Ta = 25°C.

| Symbol | Parameter | Min | Typ | Max | Unit |
|-----------------------|--|-----|-----|-----|---------------------|
| T _{SPICLK} | SPI clock period | 4 | - | - | SYSCLK |
| t _{SPICLKHT} | SPI clock high time | - | 1/2 | - | T _{SPICLK} |
| t _{SPICLKLT} | SPI clock low time | - | 1/2 | - | T _{SPICLK} |
| t _{CSRDL} | CS to data delay time | - | - | 10 | nsec |
| t _{RDSU} | SPI read data setup time | 10 | - | - | nsec |
| t _{RDHOLD} | SPI read data hold time | 10 | - | - | nsec |
| t _{CSHIGH} | CS high time between two consecutive byte transfer | 1 | - | - | T _{SPICLK} |
| t _{CSHOLD} | CS hold time | - | 1 | - | T _{SPICLK} |

Table 16. SPI Read AC Timing

7.9 UART AC Timing

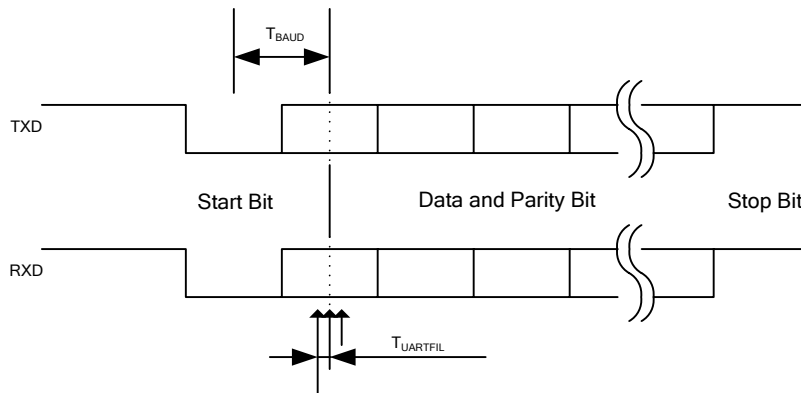


Figure 15 UART AC Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|---------------|--|-----|-------|-----|------------|
| T_{BAUD} | Baud Rate Period | - | 57600 | - | bit/sec |
| $T_{UARTFIL}$ | UART sampling filter period ⁽¹⁾ | - | 1/16 | - | T_{BAUD} |

Table 17. UART AC Timing

Note:

- (1) Each bit including start and stop bit is sampled three times at center of a bit at an interval of $1/16 T_{BAUD}$. If three sampled values do not agree, then UART noise error is generated.

7.10 CAPTURE Input AC Timing

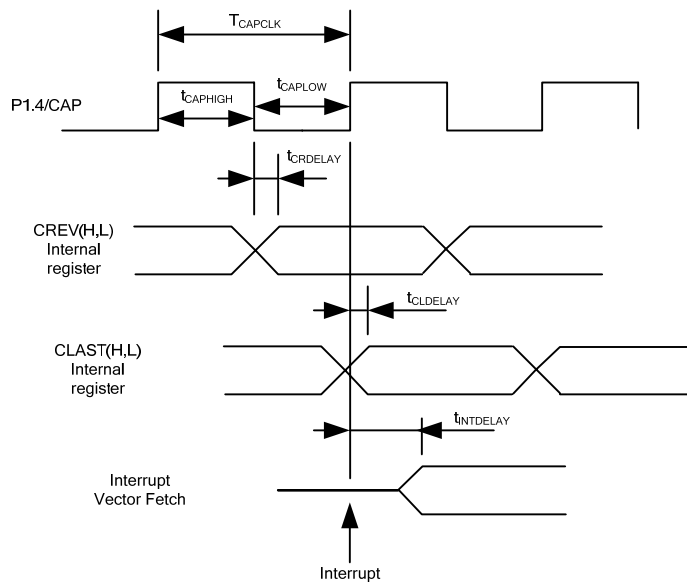


Figure 16 CAPTURE Input AC Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|----------------|---|-----|-----|-----|--------|
| T_{CAPCLK} | CAPTURE input period | 8 | - | - | SYSCLK |
| $t_{CAPHIGH}$ | CAPTURE input high time | 4 | - | - | SYSCLK |
| t_{CAPLOW} | CAPTURE input low time | 4 | - | - | SYSCLK |
| $t_{CRDELAY}$ | CAPTURE falling edge to capture register latch time | - | - | 4 | SYSCLK |
| $t_{CLDELAY}$ | CAPTURE rising edge to capture register latch time | - | - | 4 | SYSCLK |
| $t_{INTDELAY}$ | CAPTURE input interrupt latency time | - | - | 4 | SYSCLK |

Table 18. CAPTURE AC Timing

7.11 JTAG AC Timing

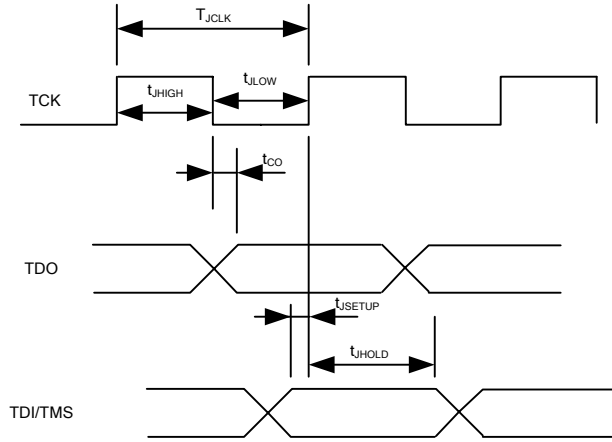


Figure 17 JTAG AC Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------|-----------------------------------|-----|-----|-----|------|
| T_{JCLK} | TCK Period | - | - | 50 | MHz |
| t_{JHIGH} | TCK High Period | 10 | - | - | nsec |
| t_{JLOW} | TCK Low Period | 10 | - | - | nsec |
| t_{CO} | TCK to TDO propagation delay time | 0 | - | 5 | nsec |
| t_{JSETUP} | TDI/TMS setup time | 4 | - | - | nsec |
| t_{JHOLD} | TDI/TMS hold time | 0 | - | - | nsec |

Table 19. JTAG AC Timing

7.12 OTP Programming Timing

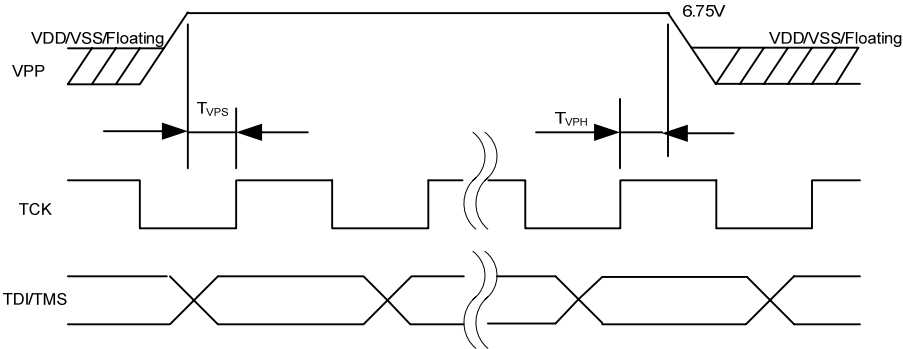


Figure 18 OTP Programming Timing

Unless specified, $T_a = 25^\circ\text{C}$.

| Symbol | Parameter | Min | Typ | Max | Unit |
|-----------|----------------|-----|-----|-----|------|
| T_{VPS} | VPP Setup Time | 10 | - | - | nsec |
| T_{VPH} | VPP Hold Time | 15 | - | - | nsec |

Table 20. OTP Programming Timing

8 I/O Structure

The following figure shows the motor PWM and digital I/O structure

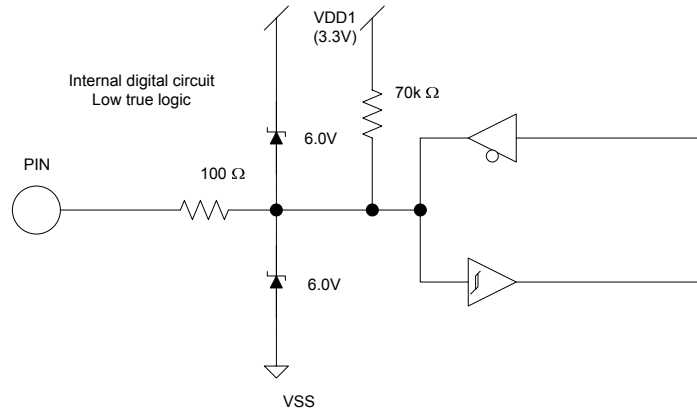


Figure 19 All digital I/O and motor PWM output

The following figure shows RESET and GATEKILL I/O structure.

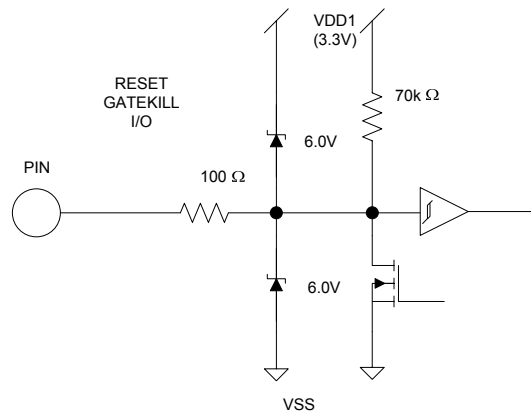


Figure 20 RESET, GATEKILL I/O

The following figure shows the analog input structure.

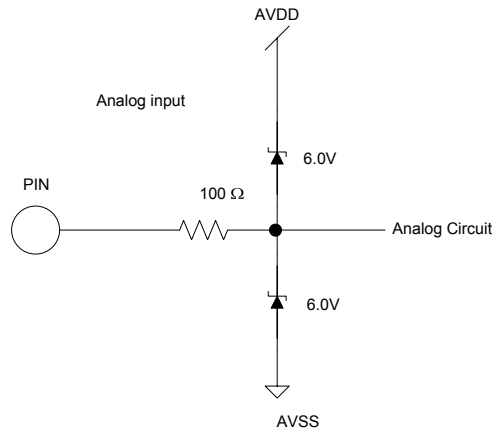


Figure 21 Analog input

The following figure shows all analog operational amplifier output pins and AREF pin I/O structure.

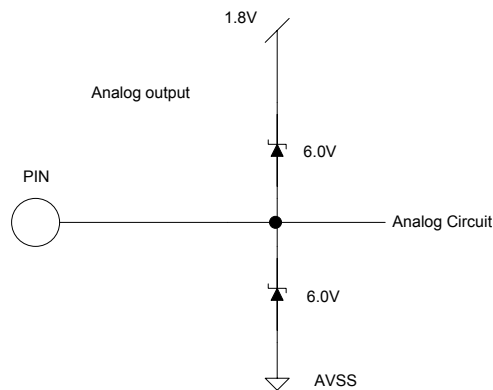


Figure 22 Analog operational amplifier output and AREF I/O structure

The following figure shows the VPP pin I/O structure

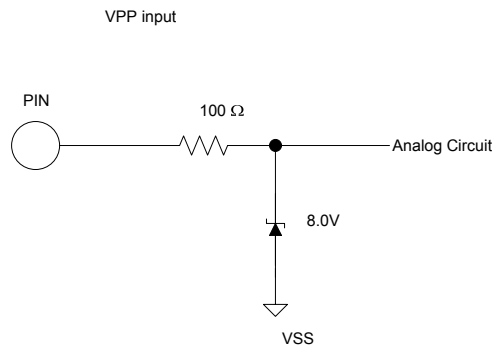


Figure 23 VPP programming pin

The following figure shows the VSS, AVSS and PLLVSS pin structure

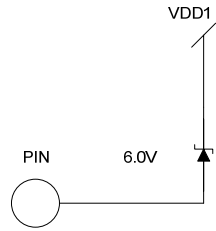


Figure 24 VSS, AVSS and PLLVSS pin structure

The following figure shows the VDD1, VDD2, AVDD and PLLVDD pin structure

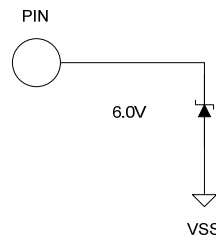


Figure 25 VDD1, VDD2, AVDD and PLLVDD pin structure

The following figure shows the XTAL0 and XTAL1 pins structure

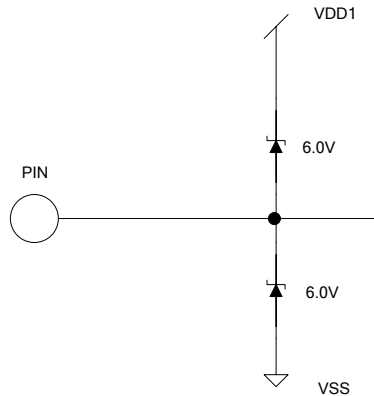


Figure 26 XTAL0/XTAL1 pins structure

9 Pin List

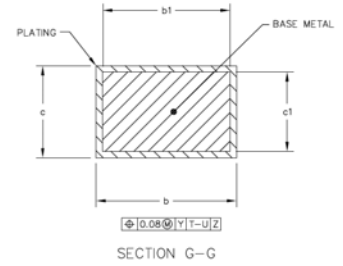
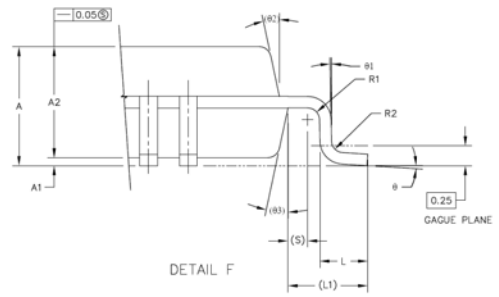
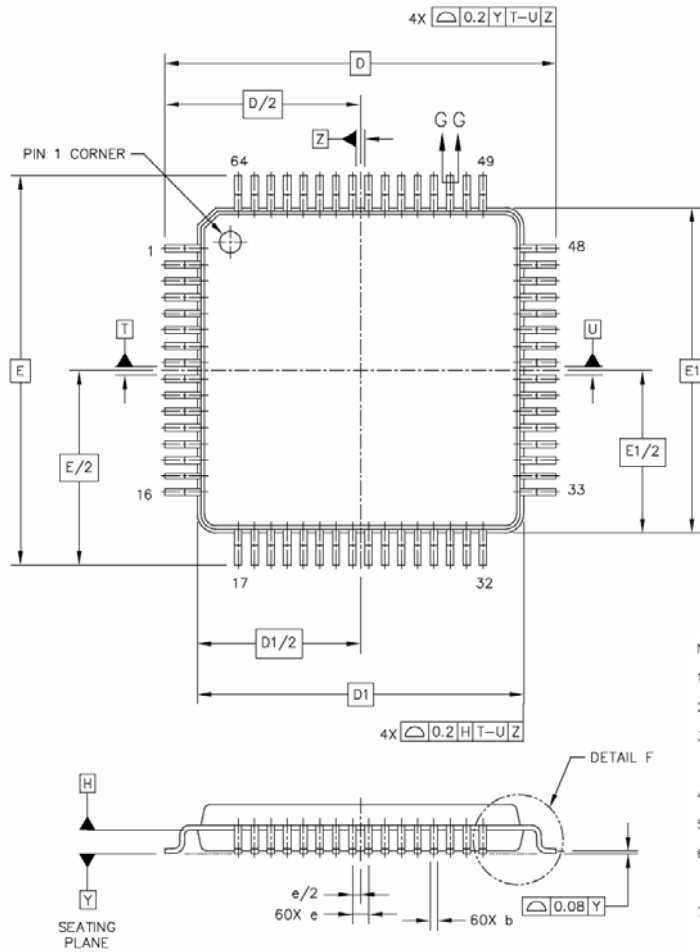
| Pin Number | Pin Name | Internal IC Pull-up /Pull-down | Pin Type | Description |
|------------|-------------------|--------------------------------|----------|---|
| 1 | XTAL0 | | I | Crystal input |
| 2 | XTAL1 | | O | Crystal output |
| 3 | P1.0/T2 | | I/O | Discrete programmable I/O or Timer/Counter 2 input |
| 4 | P1.1/RXD | | I/O | Discrete programmable I/O or UART receive input |
| 5 | P1.2/TXD | | I/O | Discrete programmable I/O or UART transmit output |
| 6 | P1.3/SYNC/ SCK | | I/O | Discrete programmable I/O or SYNC output or SPI clock |
| 7 | P1.4/CAP | | I/O | Discrete programmable I/O or Capture Timer input |
| 8 | P1.5 | | I/O | Discrete programmable I/O |
| 9 | P1.6 | | I/O | Discrete programmable I/O |
| 10 | P1.7 | | I/O | Discrete programmable I/O |
| 11 | VDD2 | | P | 1.8V digital power |
| 12 | VSS | | P | Digital common |
| 13 | VDD1 | | P | 3.3V digital power |
| 14 | P2.0/NMI | | I/O | Discrete programmable I/O or Non-maskable Interrupt input |
| 15 | P2.1 | | I/O | Discrete programmable I/O |
| 16 | P2.2 | | I/O | Discrete programmable I/O |
| 17 | P2.3 | | I/O | Discrete programmable I/O |
| 18 | P2.4 | | I/O | Discrete programmable I/O |
| 19 | P2.5 | | I/O | Discrete programmable I/O |
| 20 | P2.6/ AOPWM0 | | I/O | Discrete programmable I/O or PWM 0 output |
| 21 | P2.7/ AOPWM1 | | I/O | Discrete programmable I/O or PWM 1 output |
| 22 | VDD2 | | P | 1.8V digital power |
| 23 | VSS | | P | Digital common |
| 24 | AIN0 | | I | Analog input channel 0, 0-1.2V range, needs to be pulled down to AVSS if unused |
| 25 | AVDD | | P | 1.8V analog power |
| 26 | AVSS | | P | Analog common |
| 27 | AIN1 | | I | Analog input channel 1, 0-1.2V range, needs to be pulled down to AVSS if unused |
| 28 | CMEXT | | O | Unbuffered 0.6V output. Capacitor needs to be connected. |
| 29 | AREF | | O | Analog reference voltage output (0.6V) |
| 30 | IFB- | | I | Single shunt current sensing OP amp input (-) |
| 31 | IFB+ | | I | Single shunt current sensing OP amp input (+) |

| Pin Number | Pin Name | Internal IC Pull-up /Pull-down | Pin Type | Description |
|------------|-------------------|--------------------------------|----------|---|
| 32 | IFBO | | O | Single shunt current sensing OP amp output |
| 33 | VAC+ | | I | AC input voltage sensing OP amp input (+) |
| 34 | VAC- | | I | AC input voltage sensing OP amp input (-) |
| 35 | VACO | | O | AC input voltage sensing OP amp output |
| 36 | IFPCO | | O | PFC shunt current sensing OP amp output |
| 37 | IFPC+ | | I | PFC shunt current sensing OP amp input (+) |
| 38 | IFPC- | | I | PFC shunt current sensing OP amp input (-) |
| 39 | VSS | | P | Digital common |
| 40 | VDD1 | | P | 3.3V digital power |
| 41 | GATEKILL | | I | PWM shutdown input, 2- μ sec digital filter, configurable either high or low true. |
| 42 | PWMWL | 70 k Ω Pull up | O | PWM gate drive for phase W low side, configurable either high or low true |
| 43 | PWMWH | 70 k Ω Pull up | O | PWM gate drive for phase W high side, configurable either high or low true |
| 44 | PWMVL | 70 k Ω Pull up | O | PWM gate drive for phase V low side, configurable either high or low true |
| 45 | PWMVH | 70 k Ω Pull up | O | PWM gate drive for phase V high side, configurable either high or low true |
| 46 | PWMUL | 70 k Ω Pull up | O | PWM gate drive for phase U low side, configurable either high or low true |
| 47 | PWMUH | 70 k Ω Pull up | O | PWM gate drive for phase U high side, configurable either high or low true |
| 48 | P3.0/INT2/ CS1 | | I/O | Discrete programmable I/O or external interrupt 2 input or SPI chip select 1 |
| 49 | P5.0/ PFCGKILL | | I/O | Discrete programmable I/O or PFC PWM shutdown input, 2- μ sec digital filter, configurable either high or low true. |
| 50 | PFCPWM | | O | PFC PWM output |
| 51 | P3.1/ AOPWM2 | | I/O | Discrete programmable I/O or PWM analog output 2 |
| 52 | P3.2/INT0 | | I/O | Discrete programmable I/O or Interrupt 0 input |
| 53 | VSS | | P | Digital common |
| 54 | VDD1 | | P | 3.3V digital power |
| 55 | SCL/ SO-SI/VPP | | I/O P | I ² C clock output (open drain, need pull up) or SPI data or OTP Programming |
| 56 | SDA/CS0 | | I/O | I ² C data (open drain, need pull up) or SPI chip select 0 |
| 57 | P5.1/TMS | | I/O | Discrete programmable I/O or JTAG test mode select |
| 58 | P5.2/TDO | | I/O | Discrete programmable I/O or JTAG test data output |
| 59 | P5.3/TDI | | I/O | Discrete programmable I/O or JTAG test data input |
| 60 | TCK | | I | JTAG test clock |

| Pin Number | Pin Name | Internal IC Pull-up /Pull-down | Pin Type | Description |
|------------|----------|--------------------------------|----------|--|
| 61 | TSTMOD | 58 k Ω pull down | I | Test mode. Must be tied to VSS. Factory use only |
| 62 | RESET | | I/O | Reset, low true, Schmitt trigger input |
| 63 | PLLVDD | | P | 1.8V PLL power |
| 64 | PLLVSS | | P | PLL ground |

Table 21. Pin List

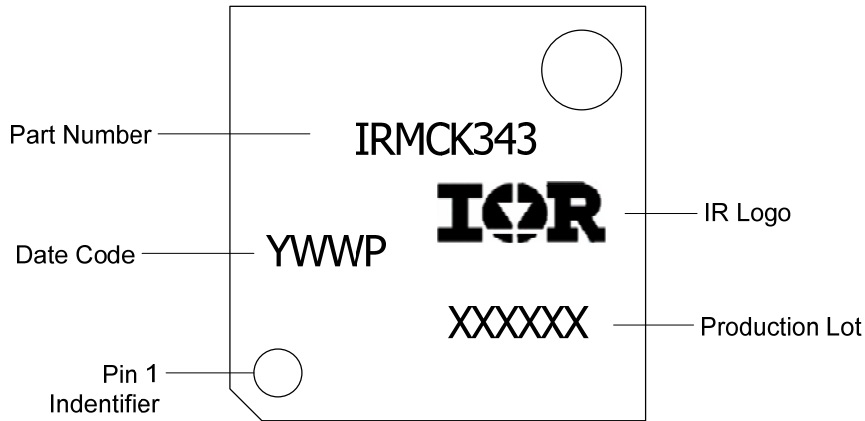
10 Package Dimensions



- NOTES:
1. DIMENSIONS ARE IN MILLIMETERS.
 2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M-1994.
 3. DATUM PLANE DATUM H IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.
 4. DATUM T, U, AND Z TO BE DETERMINED AT DATUM PLANE H.
 5. DIMENSIONS D AND E TO BE DETERMINED AT SEATING PLANE DATUM Y.
 6. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 PER SIDE. DIMENSIONS D1 AND E1 DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE DATUM H.
 7. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE b DIMENSION TO EXCEED 0.35. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD OR PROTRUSION 0.07.

| DIM | MIN | MAX | DIM | MIN | MAX | DIM | MIN | MAX |
|-----|------|---------|-----|---------|-----|-----|-----|-----|
| A | --- | 1.6 | L1 | 1 REF | | | | |
| A1 | 0.05 | 0.15 | R1 | 0.1 | 0.2 | | | |
| A2 | 1.35 | 1.45 | R2 | 0.1 | 0.2 | | | |
| b | 0.17 | 0.27 | S | 0.2 REF | | | | |
| b1 | 0.17 | 0.23 | θ | 0° | 7° | | | |
| c | 0.09 | 0.2 | θ1 | 0° | --- | | | |
| c1 | 0.09 | 0.16 | θ2 | 12° REF | | | | |
| D | | 12 BSC | θ3 | 12° REF | | | | |
| D1 | | 10 BSC | | | | | | |
| e | | 0.5 BSC | | | | | | |
| E | | 12 BSC | | | | | | |
| E1 | | 10 BSC | | | | | | |
| L | 0.45 | 0.75 | | | | | | |

11 Part Marking Information



12 Order Information

Lead-Free Part in 64-lead QFP
Moisture Sensitivity Rating – MSL3

| Part number | Order quantities |
|-------------|--|
| IRMCK343TR | 1500 parts on tape and reel in dry pack |
| IRMCK343TY | 1600 parts on trays (160 parts per tray) in dry pack |

International
IR Rectifier

The LQFP-64 is MSL3 qualified
 This product has been designed and qualified for the industrial level
 Qualification standards can be found at www.irf.com <<http://www.irf.com>>
IR WORLD HEADQUARTERS: 233 Kansas St., El Segundo, California 90245, Tel: (310) 252-7105
 Data and specifications subject to change without notice. 12/25/2007