## FEATURES

Charge pump with automatic gain selection of $1 \times, 1.5 \times$, and
$2 \times$ for maximum efficiency
7 independent, programmable LED drivers
7 drivers capable of $\mathbf{3 0 ~ m A ~ ( t y p i c a l ) ~}$
1 driver also capable of 60 mA (typical)
Programmable maximum current limit ( 128 levels)
Standby mode for <1 $\mu \mathrm{A}$ current consumption
16 programmable fade in and fade out times
0.1 sec to 5.5 sec

Choose from linear, square, or cubic rates
Fading override
$I^{2} \mathrm{C}$-compatible interface for all programming
Dedicated reset pin and built-in power-on reset (POR)
Short-circuit, overvoltage, and overtemperature protection
Internal soft start to limit inrush currents
Input-to-output isolation during faults or shutdown
Operation down to $\mathrm{V}_{\mathrm{IN}}=2.5 \mathrm{~V}$ with undervoltage lockout
(UVLO) at $\mathrm{V}_{\mathrm{IN}}=2.0 \mathrm{~V}$
Small lead frame chip scale package (LFCSP)

## APPLICATIONS

Mobile display backlighting
Mobile phone keypad backlighting
Dual RGB backlighting
LED indication
General backlighting of small format displays

## GENERAL DESCRIPTION

The ADP8861 provides a powerful charge pump driver with independent control of up to seven LEDs. These seven LEDs can be independently driven up to 30 mA (typical). The seventh LED can also be driven to 60 mA (typical). All LEDs are programmable for maximum current and fade in/out times via the $\mathrm{I}^{2} \mathrm{C}$ interface. These LEDs can also be combined into groups to reduce the processor instructions during fade in/out.
This entire configuration is driven by a two-capacitor charge pump with gains of $1 \times, 1.5 \times$, and $2 \times$. The charge pump is

capable of driving a maximum Iout of 240 mA from a supply of 2.5 V to 5.5 V . A full suite of safety features, including shortcircuit, overvoltage, and overtemperature protection, allows easy implementation of a safe and robust design. Additionally, input inrush currents are limited via an integrated soft start combined with controlled input-to-output isolation.
The ADP8861 is available in a compact lead frame chip scale package (LFCSP).

Rev. 0

## ADP8861

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## REVISION HISTORY

4/10—Revision 0: Initial Version

## SPECIFICATIONS

$\mathrm{VIN}=3.6 \mathrm{~V}, \mathrm{SCL}=2.7 \mathrm{~V}, \mathrm{SDA}=2.7 \mathrm{~V}, \mathrm{nINT}=$ open, $\mathrm{nRST}=2.7 \mathrm{~V}, \mathrm{~V} 1: \mathrm{D7} 7 \mathrm{C}, 4 \mathrm{~V}$, Capacitor $\mathrm{C} 1=1 \mu \mathrm{~F}$, Capacitor $\mathrm{C} 2=1 \mu \mathrm{~F}, \mathrm{Cout}=1 \mu \mathrm{~F}$, typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ and are not guaranteed, minimum and maximum limits are guaranteed from $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted.

Table 1.

\begin{tabular}{|c|c|c|c|c|c|c|}
\hline Parameter \& Symbol \& Test Conditions/Comments \& Min \& Typ \& Max \& Unit \\
\hline \begin{tabular}{l}
SUPPLY \\
Input Voltage \\
Operating Range \\
Start-Up Level \\
Low Level \\
\(\mathrm{V}_{\text {IN(START) }}\) Hysteresis \\
UVLO Noise Filter \\
Quiescent Current \\
Prior to \(\mathrm{VIn}_{\text {Intart }}\) \\
During Standby \\
After Startup and Switching
\end{tabular} \& \begin{tabular}{l}
\(V_{\text {IN }}\) \\
VIn(Start) \\
Vin(stop) \\
Vin(HYs) \\
tuvio \\
lo \\
lelstart) \\
\(\mathrm{l}_{\mathrm{Q}(\mathrm{STBY})}\) \\
le(active)
\end{tabular} \& \begin{tabular}{l}
\(\mathrm{V}_{\text {IN }}\) increasing \\
Vin decreasing \\
After startup
\[
\begin{aligned}
\& \mathrm{V}_{\mathbb{I N}}=\mathrm{V}_{\text {IN(START })}-100 \mathrm{mV} \\
\& \mathrm{~V}_{\mathbb{N}}=3.6 \mathrm{~V}, \text { Bit } \mathrm{nSTBY}=0, \mathrm{SCL}=\mathrm{SDA}=0 \mathrm{~V} \\
\& \mathrm{~V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \text { Bit } \mathrm{nSTBY}=1, \text { lout }=0 \mathrm{~mA}, \text { gain }=2 \times
\end{aligned}
\]
\end{tabular} \& 2.5
1.75 \& \[
\begin{aligned}
\& 2.05 \\
\& 1.97 \\
\& 80 \\
\& 10 \\
\& 10 \\
\& 10 \\
\& 0.3 \\
\& 4.5
\end{aligned}
\] \& 5.5
2.30

1.0

7.2 \& | V |
| :--- |
| V |
| V |
| mV |
| $\mu \mathrm{s}$ |
| $\mu \mathrm{A}$ |
| $\mu \mathrm{A}$ |
| mA | <br>

\hline | OSCILLATOR |
| :--- |
| Switching Frequency Duty Cycle | \& \[

$$
\begin{aligned}
& \text { fsw } \\
& \text { D }
\end{aligned}
$$

\] \& Charge pump gain $=2 \times$ \& 0.8 \& \[

$$
\begin{aligned}
& 1 \\
& 50
\end{aligned}
$$

\] \& 1.32 \& \[

$$
\begin{aligned}
& \mathrm{MHz} \\
& \%
\end{aligned}
$$
\] <br>

\hline | OUTPUT CURRENT CONTROL |
| :--- |
| Maximum Drive Current |
| Diode1 to Diode 7 $\begin{aligned} & \mathrm{T}_{\mu}=25^{\circ} \mathrm{C} \\ & \mathrm{~T}_{\mathrm{J}}=-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C} \end{aligned}$ |
| Diode 7 Only ( 60 mA Setting) $\begin{aligned} & \mathrm{T}_{\mu}=25^{\circ} \mathrm{C} \\ & \mathrm{~T}_{\mathrm{J}}=-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C} \end{aligned}$ |
| LED Current Source Matching ${ }^{1}$ |
| All Current Sinks |
| Diode 2 to Diode 7 Current Sinks |
| Leakage Current on LED Pins Equivalent Output Resistance $\begin{aligned} & \text { Gain }=1 \times \\ & \text { Gain }=1.5 \times \\ & \text { Gain }=2 \times \end{aligned}$ |
| Regulated Output Voltage | \& | ID1:D7(MAX) |
| :--- |
| ID7(60 mA) |
| $\mathrm{I}_{\text {мatch }}$ |
| Іматсн7 |
| IMATCH6 |
| $\mathrm{I}_{\mathrm{D} 1: \mathrm{D7}(\text { LKG })}$ |
| Rout |
| Voutreg) | \& | $\mathrm{V}_{\mathrm{DI}: D 7}=0.4 \mathrm{~V}$ |
| :--- |
| Bit SCR $=0$ in the ISC7 register |
| $V_{D 7}=0.4 \mathrm{~V}$, Bit $\mathrm{SCR}=1$ in the $\mathrm{ISC7}$ register |
| $V_{D 1: D 7}=0.4 \mathrm{~V}$ |
| $\mathrm{V}_{\mathrm{D} 2: \mathrm{D7}}=0.4 \mathrm{~V}$ |
| $\mathrm{V}_{\mathrm{IN}}=5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DI}: \mathrm{D7}}=2.5 \mathrm{~V}, \mathrm{Bit} \mathrm{nSTBY}=1$ $\begin{aligned} & \mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \text { lout }=100 \mathrm{~mA} \\ & \mathrm{~V}_{\mathbb{I}}=3.1 \mathrm{~V} \text {, lout }=100 \mathrm{~mA} \\ & \mathrm{~V}_{\mathbb{I}}=2.5 \mathrm{~V} \text {, lout }=100 \mathrm{~mA} \\ & \mathrm{~V}_{\mathbb{I}}=3 \mathrm{~V} \text {, gain }=2 \times, \text { lout }=10 \mathrm{~mA} \end{aligned}$ | \& \[

$$
\begin{gathered}
26.2 \\
24.4 \\
\\
52.5 \\
48.8
\end{gathered}
$$
\]

\[
4.3

\] \& | 30 |
| :--- |
| 60 |
| 2.0 |
| 1.5 |
| 0.5 |
| 3.0 |
| 3.8 |
| 4.9 | \& 34.1

34.1
67
67

0.5

5.5 \& $m A$
$m A$
$m A$
$m A$
$\%$
$\%$
$\mu A$
$\Omega$
$\Omega$
$\Omega$
$V$ <br>

\hline | AUTOMATIC GAIN SELECTION |
| :--- |
| Minimum Voltage |
| Gain Increases |
| Minimum Current Sink Headroom Voltage |
| Gain Delay | \& | Vhrup) |
| :--- |
| $\mathrm{V}_{\text {HR(MII) }}$ |
| tgain | \& | Decrease $\mathrm{V}_{\mathrm{D} 1: \mathrm{D7}}$ until the gain switches up $I_{D X}=I_{D X(\operatorname{MAX})} \times 95 \%$ |
| :--- |
| The delay after gain has changed and before gain is allowed to change again | \& 162 \& \[

$$
\begin{aligned}
& 200 \\
& 180 \\
& 100
\end{aligned}
$$
\] \& 276 \& mV mV $\mu \mathrm{s}$ <br>

\hline | FAULT PROTECTION |
| :--- |
| Start-Up Charging Current Source Output Voltage Threshold Exit Soft Start Short-Circuit Protection | \& | Iss |
| :--- |
| Vout |
| Vout(start) |
| Vout(SC) | \& | $\mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=0.8 \times \mathrm{V}_{\mathbb{I N}}$ |
| :--- |
| Vout rising |
| Vout falling | \& 2.5 \& \[

$$
\begin{aligned}
& 3.75 \\
& 0.92 \times \mathrm{V}_{\text {IN }} \\
& 0.55 \times \mathrm{V}_{\text {IN }}
\end{aligned}
$$

\] \& 5.5 \& | mA |
| :--- |
| V |
| V | <br>

\hline
\end{tabular}

## ADP8861


${ }^{1}$ Current source matching is calculated by dividing the difference between the maximum and minimum currents from the sum of the maximum and minimum.
${ }^{2} V_{\text {IL }}$ is a function of the input voltage. See Figure 15 in the Typical Performance Characteristics section for typical values over operating ranges.
${ }^{3} \mathrm{~V}_{I H}$ is a function of the input voltage. See Figure 15 in the Typical Performance Characteristics section for typical values over operating ranges.

## $I^{2}$ C TIMING DIAGRAM



S = START CONDITION
$\mathrm{Sr}=$ REPEATED START CONDITION
P = STOP CONDITION

Figure 2. ${ }^{1}$ C Interface Timing Diagram

## ABSOLUTE MAXIMUM RATINGS

Table 2.

| Parameter | Rating |
| :--- | :--- |
| VIN, VOUT | -0.3 V to +6 V |
| D1, D2, D3, D4, D5, D6, and D7 | -0.3 V to +6 V |
| nINT, nRST, SCL, and SDA | -0.3 V to +6 V |
| Output Short-Circuit Duration | Indefinite |
| Operating Temperature Range |  |
| $\quad$ Ambient ( $\mathrm{T}_{\mathrm{A}}$ ) | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}^{1}$ |
| $\quad$ Junction (TJ) | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Soldering Conditions | $\mathrm{JEDEC} \mathrm{J}-$ STD -020 |
| ESD (Electrostatic Discharge) |  |
| $\quad$ Human Body Model (HBM) | $\pm 3 \mathrm{kV}$ |
| $\quad$ Charged Device Model (CDM) | $\pm 1.5 \mathrm{kV}$ |

${ }^{1}$ The maximum operating junction temperature ( $\mathrm{T}_{\mathrm{J} \text { (MAX) }}$ ) takes precedence over the maximum operating ambient temperature $\left(\mathrm{T}_{\text {A(MAX) }}\right)$. See the Maximum Temperature Ranges section for more information.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
Absolute maximum ratings apply individually only, not in combination. Unless otherwise specified, all voltages are referenced to ground.

## MAXIMUM TEMPERATURE RANGES

The maximum operating junction temperature ( $\mathrm{T}_{\mathrm{J}(\mathrm{MAX})}$ ) takes precedence over the maximum operating ambient temperature ( $\mathrm{T}_{\mathrm{A}(\mathrm{MAX})}$ ). Therefore, in situations where the ADP8861 is exposed to poor thermal resistance and high power dissipation $\left(\mathrm{P}_{\mathrm{D}}\right)$, the maximum ambient temperature may need to be derated. In these cases, the maximum ambient temperature can be calculated with the following equation:

$$
T_{A(M A X)}=T_{J(M A X)}-\left(\theta_{I A} \times P_{D(M A X)}\right)
$$

## THERMAL RESISTANCE

$\theta_{J A}$ (junction to air) is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages. The $\theta_{J A}$ and $\theta_{\mathrm{JC}}$ (junction to case) are determined according to JESD51-9 on a 4-layer printed circuit board (PCB) with natural convection cooling. For the LFCSP package, the exposed pad must be soldered to the GND1 and/or GND2 terminal on the board.

Table 3. Thermal Resistance

| Package Type | $\boldsymbol{\theta}_{\text {JA }}$ | $\boldsymbol{\theta}_{\text {Jc }}$ | Unit |
| :--- | :--- | :--- | :--- |
| 20-Lead LFCSP_WQ | 49.5 | 5.3 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## ADP8861

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

|  | ADP8861 <br> TOP VIEW （Not to Scale） |  |
| :---: | :---: | :---: |
|  | 号㶡 ペーำํ |  |
|  | いいいいい |  |
| D3 1 | － | 15 GND1 |
| D2 2 | 二 ！ | 14 VIN |
| D1 3 | －＝ | 13 vout |
| SCL 4 | －： | $12 \mathrm{C2+}$ |
| nRST 5 | －1－－－－－－－ | 11 C1＋ |
|  |  |  |
|  | －へのo？ |  |
|  | $\sum_{\varepsilon}^{\underline{k}}$ |  |
| NOTES |  |  |
| $\begin{aligned} & \text { 1. CON } \\ & \text { TO GI } \end{aligned}$ | NECT THE EXPOSED GND1 AND／OR GND2． | PADDLE |
|  | 3．3．Pin Config |  |

Table 4．Pin Function Descriptions

| Pin No． | Mnemonic | Description |
| :--- | :--- | :--- |
| 14 | VIN | Input Voltage，2．5 V to 5．5 V． |
| 3 | D1 | LED Sink 1． |
| 2 | D2 | LED Sink 2． |
| 1 | D3 | LED Sink 3． |
| 20 | D4 | LED Sink 4． |
| 19 | D5 | LED Sink 5． |
| 17 | D6 | LED Sink 6． |
| 16 | D7 | LED Sink 7． |
| 18 | NA | This pin is not used and must be connected to ground． |
| 13 | VOUT | Charge Pump Output． |
| 11 | C1＋ | Charge Pump C1＋． |
| 9 | C1－ | Charge Pump C1－． |
| 12 | C2＋ | Charge Pump C2＋． |
| 10 | C2－ | Charge Pump C2－． |
| 15 | GND1 | Ground．Connect the exposed pad to GND1 and／or GND2． |
| 8 | GND2 | Ground．Connect the exposed pad to GND1 and／or GND2． |
| 6 | nINT | Processor Interrupt（Active Low）．Requires an external pull－up resistor．If this pin is not used，it can be left floating． |
| 5 | nRST | Hardware Reset（Active Low）．This pin resets the device to the default conditions．If not used，this pin must be tied |
| 7 |  | above VIH（MIN）． |
| 4 | SDA | I2C Serial Data．Requires an external pull－up resistor． |
| 21 | SCL | IC Clock．Requires an external pull－up resistor． |

## TYPICAL PERFORMANCE CHARACTERISTICS

$\mathrm{VIN}=3.6 \mathrm{~V}, \mathrm{SCL}=2.7 \mathrm{~V}, \mathrm{SDA}=2.7 \mathrm{~V}, \mathrm{nRST}=2.7 \mathrm{~V}, \mathrm{~V}_{\mathrm{D} 1: \mathrm{D7}}=0.4 \mathrm{~V}, \mathrm{C}_{\mathrm{IN}}=1 \mu \mathrm{~F}$, Capacitor $\mathrm{C} 1=1 \mu \mathrm{~F}$, Capacitor $\mathrm{C} 2=1 \mu \mathrm{~F}, \mathrm{C}_{\text {out }}=1 \mu \mathrm{~F}$, $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted.


Figure 4. Typical Quiescent Current, $G=1 \times$


Figure 5. Typical Quiescent Current, $G=2 \times$, $I_{\text {Q(ACtive) }}$


Figure 6. Typical Standby IQ vs. $V_{I N}$


Figure 7. Typical Diode Current vs. Current Sink Headroom Voltage ( $V_{H R}$ )


Figure 8. Typical Diode Current vs. VIN


Figure 9. Typical Diode Matching vs. Current Sink Headroom Voltage ( $V_{H R}$ )

## ADP8861



Figure 10. Typical Diode Current vs. Current Sink Headroom Voltage (VHR)


Figure 11. Typical Change In Diode Current vs. Temperature


Figure 12. Rout vs. Temperature


Figure 13. Typical Rout $(G=1 \times)$ vs. $V_{I N}$


Figure 14. Typical Output Soft Start Current, Iss


Figure 15. Typical I ${ }^{2}$ C Thresholds, $V_{I H}$ and $V_{I L}$


Figure 16. Typical Regulated Output Voltage (Vout(REG))


Figure 17. Typical Overvoltage Protection (OVP) Threshold


Figure 18. Typical Efficiency (Low Vf Diode)


Figure 19. Typical Efficiency (High Vf Diode)


Figure 20. Typical Operating Waveforms, G = 1×


Figure 21. Typical Operating Waveforms, $G=1.5 \times$

## ADP8861



Figure 22. Typical Operating Waveforms, G = 2×


Figure 23. Typical Start-Up Waveform

## THEORY OF OPERATION

The ADP8861 provides a powerful charge pump driver with programmable LED control. Up to seven LEDs can be independently driven up to 30 mA (typical) each. The seventh LED can also be driven to 60 mA (typical). All LEDs can be individually programmed or combined into a group to operate backlight

LEDs. A full suite of safety features, including short-circuit, overvoltage, and overtemperature protection with input-tooutput isolation, allows for a robust and safe design. The integrated soft start limits inrush currents at startup, restart attempts, and gain transitions.


## ADP8861

## POWER STAGE

Because typical white LEDs require up to 4 V to drive them, some form of boosting is required over the typical variation in battery voltage. The ADP8861 accomplishes this with a high efficiency charge pump capable of producing a maximum Iout of 240 mA over the entire input voltage range ( 2.5 V to 5.5 V ). Charge pumps use the basic principle that a capacitor stores charge based on the voltage applied to it, as shown in the following equation:

$$
\begin{equation*}
Q=C \times V \tag{1}
\end{equation*}
$$

By charging the capacitors in different configurations, the charge, and therefore the gain, can be optimized to deliver the voltage required to power the LEDs. Because a fixed charging and discharging combination must be used, only certain multiples of gain are available. The ADP8861 is capable of automatically optimizing the gain (G) from $1 \times, 1.5 \times$, and $2 \times$. These gains are accomplished with two capacitors (labeled C1 and C2 in Figure 24) and an internal switching network.
In $G=1 \times$ mode, the switches are configured to pass VIN directly to VOUT. In this mode, several switches are connected in parallel to minimize the resistive drop from input to output. In $G=1.5 \times$ and $2 \times$ modes, the switches alternatively charge from the battery and discharge into the output. For $\mathrm{G}=1.5 \times$, the capacitors are charged from $\mathrm{V}_{\text {IN }}$ in series and are discharged to $V_{\text {out }}$ in parallel. For $G=2 \times$, the capacitors are charged from $V_{\text {IN }}$
in parallel and are discharged to Vout in parallel. In certain fault modes, the switches are opened and the output is physically isolated from the input.

## Automatic Gain Selection

Each LED that is driven requires a current source. The voltage on this current source must be greater than a minimum headroom voltage ( 180 mV typical) to maintain accurate current regulation. The gain is automatically selected based on the minimum voltage $\left(\mathrm{V}_{\mathrm{DX}}\right)$ at all of the current sources. At startup, the device is placed into $\mathrm{G}=1 \times$ mode and the output charges to $\mathrm{V}_{\mathrm{IN}}$. If any $\mathrm{V}_{\mathrm{DI}: \mathrm{D7}}$ level is less than the required headroom $(180 \mathrm{mV})$, the gain is increased to the next step ( $\mathrm{G}=1.5 \times$ ). A $100 \mu$ delay is allowed for the output to stabilize prior to the next gain switching decision. If there remains insufficient current sink headroom, then the gain is increased again to $2 \times$. Conversely, to optimize efficiency, it is not desirable for the output voltage to be too high. Therefore, the gain reduces when the headroom voltage is great enough. This point (labeled $\mathrm{V}_{\mathrm{DMAX}}$ in Figure 25) is internally calculated to ensure that the lower gain still results in ample headroom for all the current sinks. The entire cycle is illustrated in Figure 25.
Note that the gain selection criteria apply only to active current sources. If current sources have been deactivated through an $I^{2} \mathrm{C}$ command (for example only five LEDs are used), then the voltages on the deactivated current sources are ignored.


Figure 25. State Diagram for Automatic Gain Selection
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## Soft Start Feature

At startup (either from UVLO activation or fault/standby recovery), the output is first charged by $\mathrm{I}_{\mathrm{SS}}$ ( 3.75 mA typical) until it reaches about $92 \%$ of $V_{\text {IN. }}$. This soft start feature reduces the inrush current that is otherwise present when the output capacitance is initially charged to $\mathrm{V}_{\text {IN }}$. When this point is reached, the controller enters $G=1 \times$ mode. If the output voltage is not sufficient, then the automatic gain selection determines the optimal point as defined in the Automatic Gain Selection section.

## OPERATING MODES

There are four different operating modes: active, standby, shutdown, and reset.

## Active Mode

In active mode, all circuits are powered up and in a fully operational state. This mode is entered when Bit nSTBY (in Register MDCR) is set to 1 .

## Standby Mode

Standby mode disables all circuitry except for the $\mathrm{I}^{2} \mathrm{C}$ receivers. Current consumption is reduced to less than $1 \mu \mathrm{~A}$. This mode is entered when the nSTBY bit is set to 0 or when the nRST pin is held low for more than $100 \mu \mathrm{~s}$ (maximum). When standby is exited, a soft start sequence is performed.

## Shutdown Mode

Shutdown mode disables all circuitry, including the $\mathrm{I}^{2} \mathrm{C}$ receivers. Shutdown occurs when $V_{\text {IN }}$ is below the undervoltage thresholds. When $\mathrm{V}_{\text {IN }}$ rises above $\mathrm{V}_{\text {In(START) }}(2.05 \mathrm{~V}$ typical), all registers are reset and the part is placed into standby mode.

## Reset Mode

In reset mode, all registers are set to their default values and the part is placed into standby. There are two ways to reset the part: by power-on reset (POR) or using the nRST pin. POR is activated any time that the part exits shutdown mode. After a POR sequence is complete, the part automatically enters standby mode.
After startup, the part can be reset by pulling the nRST pin low. As long as the nRST pin is low, the part is held in a standby state but no $\mathrm{I}^{2} \mathrm{C}$ commands are acknowledged (all registers are kept at their default values). After releasing the nRST pin, all registers remain at their default values, and the part remains in standby; however, the part does accept $\mathrm{I}^{2} \mathrm{C}$ commands.

The nRST pin has a $50 \mu$ s (typical) noise filter to prevent inadvertent activation of the reset function. The nRST pin must be held low for this entire time to activate reset.

The operating modes function according to the timing diagram in Figure 26.


Figure 26. Typical Timing Diagram

## ADP8861

## BACKLIGHT OPERATING LEVELS

The backlight can be operated at either the maximum level (Register 0x09) or the dim level (Register 0x0A). The backlight maximum and dim current settings are determined by a 7 -bit code programmed by the user into these registers. The 7-bit resolution allows the user to set the backlight to one of 128 different levels between 0 mA and 30 mA .


Figure 27. Backlight Operating Levels
The maximum and dim settings can be set between 0 mA and 30 mA ; therefore, it is possible to program a dim setting that is greater than a maximum setting. For normal expected operation, ensure that the dim setting is programmed to be less than the maximum setting.

## BACKLIGHT MAXIMUM AND DIM SETTINGS

The ADP8861 can implement two distinct algorithms to achieve a linear and a nonlinear relationship between input code and backlight current. The law bits in Register 0x04 are used to change between these algorithms.

By default, the ADP8861 uses a linear algorithm (law = 00), where the backlight current increases linearly for a corresponding increase in input code. Backlight current (in milliamperes) is determined by the following equation:

Backlight Current (mA) $=$ Code $\times($ Full-Scale Current/127) (2)

## where:

Code is the input code programmed by the user.
Full-Scale Current is the maximum sink current allowed per LED (typically 30 mA ).
The ADP8861 can also implement a nonlinear (square approximation) relationship between input code and backlight current level. In this case (law $=01$ ), the backlight current (in milliamperes) is determined by the following equation:

$$
\begin{equation*}
\text { Backlight Current }(\mathrm{mA})=\left(\operatorname{Code} \times \frac{\sqrt{\text { Full-Scale Current }}}{127}\right)^{2} \tag{3}
\end{equation*}
$$

Figure 28 shows the backlight current level vs. input code for both the linear and square law algorithms.


Figure 28. Backlight Current vs. Input Code

## AUTOMATED FADE IN AND FADE OUT

The LED drivers are easily configured for automated fade in and fade out. Sixteen fade in and fade out rates can be selected via the $\mathrm{I}^{2} \mathrm{C}$ interface. Fade in and fade out rates range from 0.1 sec to 5.5 sec (per full-scale current, either 30 mA or 60 mA ).

Table 5. Available Fade In and Fade Out Rates

| Code | Fade Rate (in sec per Full-Scale Current) |
| :--- | :--- |
| 0000 | 0.1 (disabled) |
| 0001 | 0.3 |
| 0010 | 0.6 |
| 0011 | 0.9 |
| 0100 | 1.2 |
| 0101 | 1.5 |
| 0110 | 1.8 |
| 0111 | 2.1 |
| 1000 | 2.4 |
| 1001 | 2.7 |
| 1010 | 3.0 |
| 1011 | 3.5 |
| 1100 | 4.0 |
| 1101 | 4.5 |
| 1110 | 5.0 |
| 1111 | 5.5 |

The fade profile is based on the transfer law selected (linear, square, Cubic 10, or Cubic 11) and the delta between the actual current and the target current. Smaller changes in current reduce the fade time. For linear and square law fades, the fade time is given by

$$
\begin{equation*}
\text { Fade Time }=\text { Fade Rate } \times(\text { Code } / 127) \tag{4}
\end{equation*}
$$

where the Fade Rate is shown in Table 5.
The Cubic 10 and Cubic 11 laws also use the square law backlight currents derived from Equation 3; however, the time between each step is varied to produce a steeper slope at higher currents and a shallower slope at lower currents (see Figure 29).


Figure 29. Comparison of the Dimming Transfers Laws

## BACKLIGHT TURN ON/TURN OFF/DIM

With the device in active mode ( $\mathrm{nSTBY}=1$ ), the backlight can be turned on using the BL_EN bit in Register 0x01. Before turning on the backlight, the user should ensure that the maximum and dim settings are programmed. The backlight turns on when BL_EN $=1$. The backlight turns off when BL_EN $=0$.


Figure 30. Backlight Turn On/Turn Off
While the backlight is on (BL_EN = 1 ), the user can change to the dim setting by programming DIM_EN $=1$ in Register $0 \times 01$. If DIM_EN $=0$, the backlight reverts to its maximum setting.


Figure 31. Backlight Turn On/Dim/Turn Off

## AUTOMATIC DIM AND TURN OFF TIMERS

The user can program the backlight to dim automatically by using the DIMT bits in Register 0x07. The dim timer has 127 settings ranging from 1 sec to 127 sec . Program the dim timer (DIMT) before turning on the backlight. If BL_EN $=1$, the backlight turns on to its maximum setting and the dim timer starts counting. When the dim timer expires, the internal state machine sets DIM_EN = 1, and the backlight enters its dim setting.


If the user clears the DIM_EN bit, the backlight reverts to its maximum setting and the dim timer begins counting again. When the dim timer expires, the internal state machine again sets DIM_EN = 1, and the backlight enters its dim setting. The backlight can be turned off at any point during the dim timer countdown by clearing BL_EN.
The user can also program the backlight to turn off automatically by using the OFFT bits in Register 0x06. The off timer has 127 settings ranging from 1 sec to 127 sec . Program the off timer (OFFT) before turning on the backlight. If BL_EN $=1$, the backlight turns on to its maximum setting and the off timer starts counting. When the off timer expires, the internal state machine clears the BL_EN bit, and the backlight turns off.


Figure 33. Off Timer
The backlight can be turned off at any point during the off timer countdown by clearing BL_EN.

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The dim timer and off timer can be used together for sequential maximum-to-dim-to-off functionality. With both the dim and off timers programmed, and BL_EN asserted, the backlight turns on to its maximum setting, and when the dim timer expires, the backlight changes to its dim setting. When the off timer expires, the backlight turns off.


Figure 34. Dim and Off Timers Used Together

## FADE OVERRIDE

A fade override feature (FOVR in Register CFGR (0x04)) enables the host to override the preprogrammed fade in or fade out settings. If FOVR is set and the backlight is enabled in the middle of a fade out process, the backlight instantly (within approximately 100 ms ) returns to its prefade brightness level. Alternatively, if the backlight is fading in, reasserting BL_EN overrides the programmed fade in time, and the backlight instantly goes to its final fade value. This is useful for situations where a key is pressed during a fade sequence. However, if FOVR is cleared and the backlight is enabled in the middle of a fade process, the backlight gradually brightens from where it was interrupted (it does not go down to 0 and then comes back on).


Figure 35. Fade Override Function (FOVR Is High)

## INDEPENDENT SINK CONTROL

Each of the seven LEDs can be configured (in Register 0x05) to operate as either part of the backlight or to operate as an independent sink current (ISC). Each ISC can be enabled independently and has its own current level. All ISCs share the same fade in rates, fade out rates, and fade law.

The ISCs have additional timers to facilitate blinking functions. A shared on timer (SCON) used in conjunction with the off timers of each ISC (SC1_OFF, SC2_OFF, SC3_OFF, and SC4_OFF in Register 0x12, and SC5_OFF, SC6_OFF, and SC7_OFF in Register 0x11) allows the LED current sinks to be configured in various blinking modes. The on timer can be set to one of four different settings: $0.2 \mathrm{sec}, 0.6 \mathrm{sec}, 0.8 \mathrm{sec}$, or 1.2 sec . The off timers have four different settings: disabled, $0.6 \mathrm{sec}, 1.2 \mathrm{sec}$, and 1.8 sec . Blink mode is activated by setting the off timers to any setting other than disabled.

Program all fade, on, and off timers before enabling any of the LED current sinks. If ISCx is on during a blink cycle and SCx_EN is cleared, the LED turns off (or fades to off if fade out is enabled). If ISCx is off during a blink cycle and SCx_EN is cleared, it stays off.


Figure 36. Independent Sink Blink Mode with Fading

## SHORT-CIRCUIT PROTECTION MODE

The ADP8861 can protect against short circuits on the output (VOUT). Short-circuit protection (SCP) is activated at the point when VOUT $<55 \%$ of $\mathrm{V}_{\text {IN }}$. Note that SCP sensing is disabled during both startup and restart attempts (fault recovery). SCP sensing is reenabled 4 ms (typical) after activation. During a short-circuit fault, the device enters a low current consumption state and an interrupt flag is set. The device can be restarted at any time after receiving a short-circuit fault by simply rewriting nSTBY $=1$. It then repeats another complete soft start sequence. Note that the value of the output capacitance (Cout) should be small enough to allow VOUT to reach approximately $55 \%$ (typical) of $\mathrm{V}_{\text {IN }}$ within the 4 ms (typical) time. If Cout is too large, the device inadvertently enters short-circuit protection.

## OVERVOLTAGE PROTECTION

Overvoltage protection (OVP) is implemented on the output. There are two types of overvoltage events: normal (no fault) and abnormal (from a fault or sudden load change).

## Normal Overvoltage

In a normal (no fault) overvoltage, the output voltage approaches $V_{\text {Out(REG) }}(4.9 \mathrm{~V}$ typical) during normal operation. This is not caused by a fault or load change, but it is simply a consequence of the input voltage times the gain reaching the same level as the clamped output voltage (Vout(REG)). To prevent this type of overvoltage, the ADP8861 detects when the output voltage rises to Vout(REG). It then increases the effective Rout of the gain stage to reduce the voltage that is delivered. This effectively regulates Vout to $V_{\text {out(Reg); }}$; however, there is a limit to the effect that this system can have on regulating Vout. It is designed only for normal operation and it is not intended to protect against faults or sudden load changes. When the output voltage is regulated to Vout(REG), no interrupt is set and the operation is transparent to the LEDs and the overall application.

## Abnormal Overvoltage

Because of the open-loop behavior of the charge pump as well as how the gain transitions are computed, a sudden load change or fault can abnormally force Vout beyond 6 V . This causes an abnormal overvoltage situation. If the event happens slowly enough, the system first tries to regulate the output to 4.9 V as in a normal overvoltage scenario. However, if this is not sufficient, or if the event happens too quickly, then the ADP8861 enters OVP mode when Vout exceeds the OVP threshold (typically 5.8 V ). In OVP mode, only the charge pump is disabled to prevent $V_{\text {out }}$ from rising too high. The current sources and all other device functionality remain intact. When the output voltage falls by about 500 mV (to 5.3 V typical), the charge
pump resumes operation. If the fault or load event recurs, the process may repeat. An interrupt flag is set at each OVP instance.

## THERMAL SHUTDOWN/OVERTEMPERATURE PROTECTION

If the die temperature of the ADP8861 rises above a safe limit $\left(150^{\circ} \mathrm{C}\right.$ typical), the controllers enter thermal shutdown (TSD) protection mode. In this mode, most of the internal functions shut down, the part enters standby, and the TSD_INT interrupt (Register $0 \times 02$ ) is set. When the die temperature decreases below $\sim 130^{\circ} \mathrm{C}$, the part can be restarted. To restart the part, simply remove it from standby. No interrupt is generated when the die temperature falls below $130^{\circ} \mathrm{C}$. However, if the software clears the pending TSD_INT interrupt and the temperature remains above $130^{\circ} \mathrm{C}$, another interrupt is generated.

The complete state machine for these faults (SCP, OVP, and TSD) is shown in Figure 37.

## INTERRUPTS

There are three interrupt sources available on the ADP8861 in Register 0x02.

- Overvoltage protection: The OVP_INT interrupt is generated when the output voltage exceeds 5.8 V (typical).
- Thermal shutdown circuit: An interrupt (TSD_INT) is generated when entering overtemperature protection.
- Short-circuit detection: SHORT_INT is generated when the device enters short-circuit protection mode.

The interrupt (if any) that appears on the nINT pin is determined by the bits mapped in Register INTR_EN (0x03). To clear an interrupt, write a 1 to the interrupt in the MDCR2 register ( $0 \times 02$ ) or reset the part. Reading the interrupt, or writing a 0 , has no effect.

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[^0]
## APPLICATIONS INFORMATION

The ADP8861 allows the charge pump to operate efficiently with a minimum of external components. Specifically, the user must select an input capacitor ( $\mathrm{C}_{\mathrm{IN}}$ ), output capacitor (Cout), and two charge pump fly capacitors ( C 1 and C 2 ). $\mathrm{C}_{\mathrm{IN}}$ should be $1 \mu \mathrm{~F}$ or greater. The value must be high enough to produce a stable input voltage signal at the minimum input voltage and maximum output load. A $1 \mu \mathrm{~F}$ capacitor for Cout is recommended. Larger values are permissible, but care must be exercised to ensure that VOUT charges above $55 \%$ (typical) of V ${ }_{\text {IN }}$ within 4 ms (typical). See the Short-Circuit Protection Mode section for more details.

For best practice, it is recommended that the two charge pump fly capacitors be $1 \mu \mathrm{~F}$; larger values are not recommended, and smaller values may reduce the ability of the charge pump to deliver maximum current. For optimal efficiency, the charge pump fly capacitors should have low equivalent series resistance (ESR). Low ESR X5R or X7R capacitors are recommended for all four components. The use of fly capacitors sized 0402 and smaller is allowed, but the GDWN_DIS bit in Register 0x01 must be set. Minimum voltage ratings should adhere to the guidelines in Table 6.

Table 6. Capacitor Stress in Each Charge Pump Gain State

| Capacitor | Gain $=\mathbf{1} \times$ | Gain $=\mathbf{1 . 5} \times$ | Gain $=\mathbf{2 \times}$ |
| :--- | :--- | :--- | :--- |
| $\mathrm{C}_{\mathbb{N}}$ | $\mathrm{V}_{\mathbb{N}}$ | $\mathrm{V}_{\mathbb{N}}$ | $\mathrm{V}_{\mathbb{N}}$ |
| $\mathrm{C}_{\text {Out }}$ | $\mathrm{V}_{\mathbb{N}}$ | $\mathrm{V}_{\mathbb{N}} \times 1.5(\max$ of 5.5 V$)$ | $\mathrm{V}_{\mathbb{N}} \times 2.0(\max$ of 5.5 V$)$ |
| $\mathrm{C}_{1}$ | None | $\mathrm{V}_{\mathbb{N}} / 2$ | $\mathrm{~V}_{\mathbb{N}}$ |
| $\mathrm{C}_{2}$ | None | $\mathrm{V}_{\mathbb{N}} / 2$ | $\mathrm{~V}_{\mathbb{N}}$ |

Any color LED can be used if the Vf (forward voltage) is less than 4.1 V. However, using lower Vf LEDs reduces the input power consumption by allowing the charge pump to operate at lower gain states.
The equivalent circuit model for a charge pump is shown in Figure 38.


Figure 38. Charge Pump Equivalent Circuit Model
The input voltage is multiplied by the gain (G) and delivered to the output through an effective resistance (Rout). The output current flows through Rout and produces an IR drop to yield:

$$
\begin{equation*}
V_{\text {OUT }}=G \times V_{\text {IN }}-I_{\text {OUT }} \times R_{\text {OUT }}(G) \tag{5}
\end{equation*}
$$

The Rout term is a combination of the $\mathrm{R}_{\text {DSON }}$ resistance for the switches used in the charge pump and a small resistance, which accounts for the effective dynamic charge pump resistance. The Rour level changes based upon the gain (the configuration of the switches). Typical Rout values are given in Table 1, Figure 12, and Figure 13.

Vout is also equal to the largest Vf of the LEDs used plus the voltage drop across the regulating current source. This gives

$$
\begin{equation*}
V_{O U T}=V f_{(M A X)}+V_{D X} \tag{6}
\end{equation*}
$$

Combining Equation 5 and Equation 6 gives

$$
\begin{equation*}
V_{I N}=\left(V f_{(M A X)}+V_{D X}+I_{O U T} \times R_{\text {OUT }}(G)\right) / G \tag{7}
\end{equation*}
$$

Equation 7 is useful for calculating approximate bounds for the charge pump design.

## DETERMINING THE TRANSITION POINT OF THE CHARGE PUMP

Consider the following design example where:
$\mathrm{Vf}_{(\mathrm{MAX})}=3.7 \mathrm{~V}$
Iout $=140 \mathrm{~mA}(7 \mathrm{LEDs}$ at 20 mA each $)$
Rout $(G=1.5 \times)=3 \Omega$ (obtained from Figure 12)
At the point of a gain transition, $V_{D x}=V_{H R(U P)}$. Table 1 gives the typical value of $\mathrm{V}_{\mathrm{HR}(\mathrm{UP})}$ as 0.2 V . Therefore, the input voltage level when the gain transitions from $1.5 \times$ to $2 \times$ is

$$
V_{I N}=(3.7 \mathrm{~V}+0.2 \mathrm{~V}+140 \mathrm{~mA} \times 3 \Omega) / 1.5=2.88 \mathrm{~V}
$$

## LAYOUT GUIDELINES

Note the following layout guidelines:

- For optimal noise immunity, place the $\mathrm{C}_{\mathrm{IN}}$ and Cout capacitors as close to their respective pins as possible. These capacitors should share a short ground trace. If the LEDs are a significant distance from the VOUT pin, another capacitor on VOUT, placed closer to the LEDs, is advisable.
- For optimal efficiency, place the charge pump fly capacitors ( C 1 and C 2 ) as close to the part as possible.
- The ADP8861 does not distinguish between power ground and analog ground. Therefore, both ground pins can be connected directly together. It is recommended that these ground pins be connected at the ground for the input and output capacitors.
- Unused diode pins (Pin D1 to Pin D7) can be connected to ground or to VOUT, or remain floating. However, the unused diode current sinks must be disabled by setting them as independent sinks in Register 0x05 and then disabling them in Register 0x10. If they are not disabled, the charge pump efficiency may suffer.
- If the interrupt pin (nINT) is not used, connect it to ground or leave it floating. Never connect it to a voltage supply, except through a $\geq 1 \mathrm{k} \Omega$ series resistor.
- The ADP8861 has an integrated noise filter on the nRST pin. Under normal conditions, it is not necessary to filter the reset line. However, if the part is exposed to an unusually noisy signal, it is beneficial to add a small RC filter or bypass capacitor on this pin. If the nRST pin is not used, it must be pulled well above the $\mathrm{V}_{\mathrm{IH}(\mathrm{Min})}$ level (see Table 1). Do not allow the nRST pin to float.


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## EXAMPLE CIRCUITS



## I²C PROGRAMMING AND DIGITAL CONTROL

The ADP8861 provides full software programmability to facilitate its adoption in various product architectures. The default $I^{2} \mathrm{C}$ address is 0101010 x ( $\mathrm{x}=0$ during write, $\mathrm{x}=1$ during read). Therefore, the default write address is $0 \times 54$ and the read address is $0 \times 55$.

Table 7 through Table 55 provide register and bit descriptions. The reset value for all bits in the bit map tables is all 0 s, except in Table 9 (see Table 9 for its unique reset value). Wherever the acronym N/A appears in the tables, it means not applicable.

Note the following general behavior of registers:

- All registers are set to their default values during reset or after a UVLO event.
- All registers are read/write unless otherwise specified.
- Unused bits are read as zero.


Figure 41. $I^{2} C$ Read Command Sequence


Figure $42 . I^{2} C$ Write Command Sequence

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Table 7. Register Set Definitions

| Address (Hex) | Register Name | Description |
| :--- | :--- | :--- |
| $0 \times 00$ | MFDVID | Manufacturer and device ID |
| $0 \times 01$ | MDCR | Device mode and status |
| $0 \times 02$ | MDCR2 | Device mode and Status Register 2 |
| $0 \times 03$ | INTR_EN | Interrupts enable |
| $0 \times 04$ | CFGR | Configuration register |
| $0 \times 05$ | BLSEN | Sink enable, backlight or independent |
| $0 \times 06$ | BLOFF | Backlight off timeout |
| $0 \times 07$ | BLDIM | Backlight dim timeout |
| $0 \times 08$ | BLFR | Backlight fade in and fade out rates |
| $0 \times 09$ | BLMX | Backlight maximum current |
| $0 \times 0$ A | BLDM | Backlight dim current |
| $0 \times 0$ B to $0 \times 0 E$ | Reserved |  |
| $0 \times 0 F$ | ISCFR | Independent sink current fade control register |
| $0 \times 10$ | ISCC | Independent sink current control register |
| $0 \times 11$ | ISCT1 | Independent Sink Current Timer Register, LED[7:5] |
| $0 \times 12$ | ISCT2 | Independent Sink Current Timer Register, LED[4:1] |
| $0 \times 13$ | ISCF | Independent sink current fade register |
| $0 \times 14$ | ISC7 | Independent Sink Current, LED7 |
| $0 \times 15$ | ISC6 | Independent Sink Current, LED6 |
| $0 \times 16$ | ISC5 | Independent Sink Current, LED5 |
| $0 \times 17$ | ISC4 | Independent Sink Current, LED4 |
| $0 \times 18$ | ISC3 | Independent Sink Current, LED3 |
| $0 \times 19$ | ISC2 | Independent Sink Current, LED2 |
| $0 \times 1$ A | ISC1 | Independent Sink Current, LED1 |

Table 8. Register Map


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## Manufacturer and Device ID (MFDVID)—Register 0x00

Multiple device revisions are tracked by the device ID field. This is a read-only register.
Table 9. MFDVID Bit Map

| Bit 7 Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: |
| Manufacturer ID |  |  |  |  |  |  |  |  |  | Device ID |
|  | 0 | 1 | 0 | 0 | 0 | 0 | 0 |  |  |  |

## Mode Control Register (MDCR)—Register 0x01

Table 10. MDCR Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | INT_CFG | nSTBY | DIM_EN | GDWN_DIS | SIS_EN | Reserved | BL_EN |

Table 11. Bit Descriptions for the MDCR Register

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | 7 | Reserved. |
| INT_CFG | 6 | Interrupt configuration. <br> $1=$ processor interrupt deasserts for 50 s and reasserts with pending events. <br> $0=$ processor interrupt remains asserted if the host tries to clear the interrupt while there is a pending event. |
| nSTBY | 5 | $1=$ device is in active mode. <br> $0=$ device is in standby mode; only the I 2 C interface is enabled. |
| DIM_EN | 4 | DIM_EN is set by the hardware after a dim timeout. The user can also force the backlight into dim mode by <br> asserting this bit. Dim mode can only be entered if BL_EN is also enabled. <br> $1=$ backlight is operating at the dim current level (BL_EN must also be asserted). <br> $0=$ backlight is not in dim mode. |
| GDWN_DIS | 3 | $1=$ the charge pump does not switch down in gain until all LEDs are off. The charge pump switches up in gain as <br> needed. This feature is useful if the ADP8861 charge pump is used to drive an external load. This feature must be <br> used when utilizing small fly capacitors (0402 or smaller). <br> $0=$ the charge pump automatically switches up and down in gain. This provides optimal efficiency, but is not <br> suitable for driving loads that are not connected through the ADP8861 diode drivers. Additionally, the charge <br> pump fly capacitors should be low ESR and sized 0603 or greater. |
| SIS_EN | 2 | Synchronous independent sinks enable. <br> $1=$ enables all LED current sinks designated as independent sinks. This bit has no effect if any of the SCx_EN bits <br> in Register $0 \times 10$ are set. <br> $0=$ disables all LED current sinks designated as independent sinks. This bit has no effect if any of the SCx_EN bits <br> in Register 0x10 are set. |
| N/A | 1 | Reserved. |
| BL_EN | 0 | $1=$ backlight is enabled (nSTBY must also be asserted). <br> $0=$ backlight is disabled. |

## Mode Control Register 2 (MDCR2)—Register 0x02

Table 12. MDCR2 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved |  | SHORT_INT | TSD_INT | OVP_INT | Reserved |  |

Table 13. Bit Descriptions for the MDCR2 Register

| Bit Name | Bit No. | Description ${ }^{1}$ |
| :--- | :--- | :--- |
| N/A | $[7: 5]$ | Reserved |
| SHORT_INT | 4 | Short-circuit error interrupt. <br> $1=$ a short-circuit or overload condition on VOUT has been detected. <br> $0=$ no short-circuit or overload condition has been detected. |
|  |  | 3 |
| TSD_INT | Thermal shutdown interrupt. <br> $1=$ the device temperature has exceeded $150^{\circ} \mathrm{C}$ (typical). <br> $0=$ no overtemperature condition has been detected. |  |
| OVP_INT | 2 | Overvoltage interrupt. <br> $1=$ VOUT has exceeded Vovp. <br>  |
|  |  | $0=$ VOUT has not exceeded Vovp. |

${ }^{1}$ Interrupt bits are cleared by writing a 1 to the flag; writing a 0 or reading the flag has no effect.

## Interrupt Enable (INTR_EN)—Register 0x03

Table 14. INTR_EN Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved |  | SHORT_IEN | TSD_IEN | OVP_IEN |  | Reserved |

Table 15. Bit Descriptions for the INTR_EN Register

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | $[7: 5]$ | Reserved. |
| SHORT_IEN | 4 | Short-circuit interrupt is enabled. When the SHORT_INT status bit is set after an error condition, an interrupt is <br> raised to the host if the SHORT_IEN flag is enabled. <br> $1=$ the short-circuit interrupt is enabled. <br> $0=$ the short-circuit interrupt is disabled (the SHORT_INT flag continues to assert). |
| TSD_IEN | 3 | Thermal shutdown interrupt is enabled. When the TSD_INT status bit is set after an error condition, an interrupt is <br> raised to the host if the TSD_IEN flag is enabled. <br> $1=$ the thermal shutdown interrupt is enabled. <br> $0=$ the thermal shutdown interrupt is disabled (the TSD_INT flag continues to assert). |
| OVP_IEN | 2 | Overvoltage interrupt enabled. When the OVP_INT status bit is set after an error condition, an interrupt is raised to <br> the host if the OVP_IEN flag is enabled. <br> $1=$ the overvoltage interrupt is enabled. <br> 0= the overvoltage interrupt is disabled (the OVP_INT flag continues to assert). |
| N/A | $[1: 0]$ | Reserved. |

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## BACKLIGHT REGISTER DESCRIPTIONS

## Configuration Register (CFGR)—Register 0x04

Table 16. CFGR Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved |  |  |  |  | Law |  | FOVR |

Table 17. Bit Descriptions for the CFGR Register

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | $[7: 3]$ | Reserved |
| Law | $[2: 1]$ | Backlight transfer law |
|  |  | $00=$ linear law DAC, linear time steps |
|  |  | $01=$ square law DAC, linear time steps |
|  | $10=$ square law DAC, nonlinear time steps (Cubic 10) |  |
|  | $11=$ square law DAC, nonlinear time steps (Cubic 11) |  |
|  |  | Backlight fade override <br> $1=$ the backlight fade override is enabled <br>  <br> FOVR |
|  |  | $0=$ the backlight fade override is disabled |

Backlight Sink Enable (BLSEN)—Register 0x05
Table 18. BLSEN Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | D7EN | D6EN | D5EN | D4EN | D3EN | D2EN | D1EN |

Table 19. Bit Descriptions for the BLSEN Register

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | 7 | Reserved |
| D7EN | 6 | Diode 7 backlight sink enable <br> $1=$ selects LED7 as an independent sink <br> $0=$ connects LED7 sink to backlight enable (BL_EN) |
| D6EN | 5 | Diode 6 backlight sink enable <br> $1=$ selects LED6 as an independent sink <br> $0=$ connects LED6 sink to backlight enable (BL_EN) |
| D5EN | 4 | Diode 5 backlight sink enable <br> $1=$ selects LED5 as an independent sink <br> $0=$ connects LED5 sink to backlight enable (BL_EN) |
| D4EN | 3 | Diode 4 backlight sink enable <br> $1=$ selects LED4 as an independent sink <br> $0=$ connects LED4 sink to backlight enable (BL_EN) |
| D3EN | 2 | Diode 3 backlight sink enable <br> $1=$ selects LED3 as an independent sink <br> $0=$ connects LED3 sink to backlight enable (BL_EN) |
| D2EN | 1 | Diode 2 backlight sink enable <br> $1=$ selects LED2 as an independent sink <br> $0=$ connects LED2 sink to backlight enable (BL_EN) |
| D1EN | 0 | Diode 1 backlight sink enable <br> $1=$ selects LED1 as an independent sink <br> $0=$ connects LED1 sink to backlight enable (BL_EN) |

## Backlight Off Timeout (BLOFF)—Register 0x06

Table 20. BLOFF Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | OFFT |  |  |  |  |  |  |

Table 21. Bit Descriptions for the BLOFF Register

| Bit Name | Bit No. | Description |
| :---: | :---: | :---: |
| N/A | 7 | Reserved. |
| OFFT | [6:0] | Backlight off timeout. After the off timeout (OFFT) period, the backlight turns off. If the dim timeout (DIMT) is enabled, the off timeout starts after the dim timeout. $\begin{aligned} & 0000000=\text { timeout disabled } \\ & 0000001=1 \mathrm{sec} \\ & 0000010=2 \mathrm{sec} \\ & 0000011=3 \mathrm{sec} \\ & \ldots \\ & 1111111=127 \mathrm{sec} \end{aligned}$ |

## Backlight Dim Timeout (BLDIM)—Register 0x07

Table 22. BLDIM Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | DIMT |  |  |  |  |  |  |

Table 23. Bit Descriptions for the BLDIM Register

| Bit Name | Bit No. | Description |
| :---: | :---: | :---: |
| N/A | 7 | Reserved. |
| DIMT | [6:0] | Backlight dim timeout. After the dim timeout (DIMT) period, the backlight is set to the dim current value. The dim timeout starts after backlight reaches the maximum current. $\begin{aligned} & 0000000=\text { timeout disabled } \\ & 0000001=1 \mathrm{sec} \\ & 0000010=2 \mathrm{sec} \\ & 0000011=3 \mathrm{sec} \end{aligned}$ $1111111=127 \mathrm{sec}$ |

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## Backlight Fade (BLFR)—Register 0x08

Table 24. BLFR Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| BL_FO |  |  |  |  |  |  |  |

Table 25. Bit Descriptions for the BLFR Register

| Bit Name | Bit No. | Description |
| :---: | :---: | :---: |
| BL_FO | [7:4] | Backlight fade out rate. If fade out is disabled (BL_FO = 0000), the backlight changes instantly (within 100 ms ). If the fade out rate is set, the backlight fades from its current value to the dim or the off value. The times listed for BL_FO are for a full-scale fade out ( 30 mA to 0 mA ). Fades between closer current values reduce the fade time. See the Automated Fade In and Fade Out section for more information. $\begin{aligned} & 0000=0.1 \mathrm{sec}(\text { fade out disabled })^{1} \\ & 0001=0.3 \mathrm{sec} \\ & 0010=0.6 \mathrm{sec} \\ & 0011=0.9 \mathrm{sec} \\ & 0100=1.2 \mathrm{sec} \\ & 0101=1.5 \mathrm{sec} \\ & 0110=1.8 \mathrm{sec} \\ & 0111=2.1 \mathrm{sec} \\ & 1000=2.4 \mathrm{sec} \\ & 1001=2.7 \mathrm{sec} \\ & 1010=3.0 \mathrm{sec} \\ & 1011=3.5 \mathrm{sec} \\ & 1100=4.0 \mathrm{sec} \\ & 1101=4.5 \mathrm{sec} \\ & 1110=5.0 \mathrm{sec} \\ & 1111=5.5 \mathrm{sec} \\ & \hline \end{aligned}$ |
| BL_FI | [3:0] | Backlight fade in rate. If fade in is disabled (BL_FI = 0000), the backlight changes instantly (within 100 ms ). If the fade in rate is set, the backlight fades from its current value to its maximum value when the backlight is turned on. The times listed for BL_Fl are for a full-scale fade in ( 0 mA to 30 mA ). Fades between closer current values reduce the fade time. See the Automated Fade In and Fade Out section for more information. $\begin{aligned} & 0000=0.1 \mathrm{sec}(\text { fade in disabled })^{1} \\ & 0001=0.3 \mathrm{sec} \\ & 0010=0.6 \mathrm{sec} \\ & 0011=0.9 \mathrm{sec} \\ & \ldots \\ & 1111=5.5 \mathrm{sec} \end{aligned}$ |

[^1]
## Backlight Maximum Current Register (BLMX)—Register 0x09

Table 26. BLMX Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | BL_MC |  |  |  |  |  |  |

Table 27. Bit Descriptions for the BLMX Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| BL_MC | [6:0] | Backlight maximum current. The backlight maximum current can be set according to the linear or square law function (see Table 28 for a complete list of values). |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | $1111111$ | ... 30 | $30$ |

Table 28. Linear and Square Law Currents Per DAC Code (SCR = 0)

| DAC Code | Linear Law (mA) | Square Law (mA) ${ }^{1}$ | DAC Code | Linear Law (mA) | Square Law (mA) ${ }^{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0x00 | 0 | 0.000 | 0x22 | 8.031 | 2.150 |
| $0 \times 01$ | 0.236 | 0.002 | $0 \times 23$ | 8.268 | 2.279 |
| $0 \times 02$ | 0.472 | 0.007 | $0 \times 24$ | 8.504 | 2.411 |
| 0x03 | 0.709 | 0.017 | $0 \times 25$ | 8.740 | 2.546 |
| $0 \times 04$ | 0.945 | 0.030 | $0 \times 26$ | 8.976 | 2.686 |
| $0 \times 05$ | 1.181 | 0.047 | $0 \times 27$ | 9.213 | 2.829 |
| $0 \times 06$ | 1.417 | 0.067 | $0 \times 28$ | 9.449 | 2.976 |
| $0 \times 07$ | 1.654 | 0.091 | $0 \times 29$ | 9.685 | 3.127 |
| $0 \times 08$ | 1.890 | 0.119 | $0 \times 2 \mathrm{~A}$ | 9.921 | 3.281 |
| 0x09 | 2.126 | 0.151 | $0 \times 2 B$ | 10.157 | 3.439 |
| $0 \times 0 \mathrm{~A}$ | 2.362 | 0.186 | $0 \times 2 \mathrm{C}$ | 10.394 | 3.601 |
| $0 \times 0 \mathrm{~B}$ | 2.598 | 0.225 | $0 \times 2 \mathrm{D}$ | 10.630 | 3.767 |
| 0xOC | 2.835 | 0.268 | $0 \times 2 \mathrm{E}$ | 10.866 | 3.936 |
| $0 \times 0 \mathrm{D}$ | 3.071 | 0.314 | $0 \times 2 \mathrm{~F}$ | 11.102 | 4.109 |
| 0x0E | 3.307 | 0.365 | $0 \times 30$ | 11.339 | 4.285 |
| 0x0F | 3.543 | 0.419 | $0 \times 31$ | 11.575 | 4.466 |
| 0x10 | 3.780 | 0.476 | $0 \times 32$ | 11.811 | 4.650 |
| $0 \times 11$ | 4.016 | 0.538 | $0 \times 33$ | 12.047 | 4.838 |
| $0 \times 12$ | 4.252 | 0.603 | $0 \times 34$ | 12.283 | 5.029 |
| $0 \times 13$ | 4.488 | 0.671 | $0 \times 35$ | 12.520 | 5.225 |
| $0 \times 14$ | 4.724 | 0.744 | $0 \times 36$ | 12.756 | 5.424 |
| $0 \times 15$ | 4.961 | 0.820 | $0 \times 37$ | 12.992 | 5.627 |
| $0 \times 16$ | 5.197 | 0.900 | $0 \times 38$ | 13.228 | 5.833 |
| $0 \times 17$ | 5.433 | 0.984 | $0 \times 39$ | 13.465 | 6.043 |
| $0 \times 18$ | 5.669 | 1.071 | $0 \times 3 \mathrm{~A}$ | 13.701 | 6.257 |
| $0 \times 19$ | 5.906 | 1.163 | $0 \times 3 \mathrm{~B}$ | 13.937 | 6.475 |
| $0 \times 1 \mathrm{~A}$ | 6.142 | 1.257 | $0 \times 3 \mathrm{C}$ | 14.173 | 6.696 |
| $0 \times 1 \mathrm{~B}$ | 6.378 | 1.356 | 0x3D | 14.409 | 6.921 |
| $0 \times 1 \mathrm{C}$ | 6.614 | 1.458 | $0 \times 3 \mathrm{E}$ | 14.646 | 7.150 |
| 0x1D | 6.850 | 1.564 | $0 \times 3 \mathrm{~F}$ | 14.882 | 7.382 |
| $0 \times 1 \mathrm{E}$ | 7.087 | 1.674 | 0x40 | 15.118 | 7.619 |
| $0 \times 1 \mathrm{~F}$ | 7.323 | 1.787 | $0 \times 41$ | 15.354 | 7.859 |
| $0 \times 20$ | 7.559 | 1.905 | $0 \times 42$ | 15.591 | 8.102 |
| $0 \times 21$ | 7.795 | 2.026 | $0 \times 43$ | 15.827 | 8.350 |

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| DAC Code | Linear Law $(\mathbf{m A})$ | ${\text { Square Law }(\mathbf{m A})^{\mathbf{1}}}^{\prime 2}$ |
| :--- | :--- | :--- |
| $0 \times 44$ | 16.063 | 8.601 |
| 0x45 | 16.299 | 8.855 |
| 0x46 | 16.535 | 9.114 |
| 0x47 | 16.772 | 9.376 |
| 0x48 | 17.008 | 9.642 |
| 0x49 | 17.244 | 9.912 |
| 0x4A | 17.480 | 10.185 |
| 0x4B | 17.717 | 10.463 |
| 0x4C | 17.953 | 10.743 |
| 0x4D | 18.189 | 11.028 |
| 0x4E | 18.425 | 11.316 |
| 0x4F | 18.661 | 11.608 |
| 0x50 | 18.898 | 11.904 |
| 0x51 | 19.134 | 12.203 |
| 0x52 | 19.370 | 12.507 |
| 0x53 | 19.606 | 12.814 |
| 0x54 | 19.842 | 13.124 |
| 0x55 | 20.079 | 13.439 |
| 0x56 | 20.315 | 13.757 |
| 0x57 | 20.551 | 14.078 |
| 0x58 | 20.787 | 14.404 |
| 0x59 | 21.024 | 14.733 |
| 0x5A | 21.260 | 15.066 |
| 0x5B | 21.496 | 15.403 |
| 0x5C | 21.732 | 15.743 |
| 0x5D | 21.968 | 16.087 |
| 0x5E | 22.205 | 16.435 |
| 0x5F | 22.441 | 16.787 |
| 0x60 | 22.677 | 17.142 |
| 0x61 | 22.913 | 17.501 |
|  |  |  |


| DAC Code | Linear Law (mA) | Square Law (mA) ${ }^{1}$ |
| :--- | :--- | :--- |
| $0 \times 62$ | 23.150 | 17.863 |
| 0x63 | 23.386 | 18.230 |
| 0x64 | 23.622 | 18.600 |
| 0x65 | 23.858 | 18.974 |
| $0 \times 66$ | 24.094 | 19.351 |
| 0x67 | 24.331 | 19.733 |
| 0x68 | 24.567 | 20.118 |
| 0x69 | 24.803 | 20.507 |
| 0x6A | 25.039 | 20.899 |
| 0x6B | 25.276 | 21.295 |
| 0x6C | 25.512 | 21.695 |
| 0x6D | 25.748 | 22.099 |
| 0x6E | 25.984 | 22.506 |
| 0x6F | 26.220 | 22.917 |
| 0x70 | 26.457 | 23.332 |
| 0x71 | 26.693 | 23.750 |
| 0x72 | 26.929 | 24.173 |
| 0x73 | 27.165 | 24.599 |
| 0x74 | 27.402 | 25.028 |
| 0x75 | 27.638 | 25.462 |
| 0x76 | 27.874 | 25.899 |
| 0x77 | 28.110 | 26.340 |
| 0x78 | 28.346 | 26.784 |
| 0x79 | 28.583 | 27.232 |
| 0x7A | 28.819 | 27.684 |
| 0x7B | 29.055 | 28.140 |
| 0x7C | 29.291 | 28.599 |
| 0x7D | 29.528 | 29.063 |
| 0x7E | 29.764 | 29.529 |
| 0x7F | 30.000 | 30.000 |
| C |  |  |

${ }^{1}$ Cubic 10 and Cubic 11 laws use the square law DAC setting but vary the time step per DAC code (see Figure 29).

## Backlight Dim Current Register (BLDM)—Register 0x0A

Table 29. BLDM Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | BL_DC |  |  |  |  |  |  |

Table 30. Bit Descriptions for the BLDM Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| BL_DC | [6:0] | Backlight dim current. The backlight is set to the dim current value after a dim timeout or if the DIM_EN flag is set by the user (see Table 28 for a complete list of values). |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | ... <br> 1111111 | ... 30 | ... 30 |

## INDEPENDENT SINK REGISTER DESCRIPTIONS

Independent Sink Current Fade Control Register (ISCFR)—Register 0x0F
Table 31. ISCFR Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved |  |  |  |  |  |  |  |

Table 32. Bit Descriptions for the ISCFR

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | $[7: 2]$ | Reserved |
| SC_LAW | $[1: 0]$ | Independent sink current fade transfer law |
|  |  | $00=$ linear law DAC, linear time steps |
|  |  | $01=$ square law DAC, linear time steps |
|  | $10=$ square law DAC, nonlinear time steps (Cubic 10) |  |
|  |  | $11=$ square law DAC, nonlinear time steps (Cubic 11) |

## Independent Sink Current Control (ISCC)—Register 0x10

Table 33. ISCC Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SC7_EN | SC6_EN | SC5_EN | SC4_EN | SC3_EN | SC2_EN | SC1_EN |

Table 34. Bit Descriptions for the ISCC Register

| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| N/A | 7 | Reserved |
| SC7_EN | 6 | This enable acts upon LED7 |
|  |  | $1=$ SC7 is turned on |
|  | $0=$ SC7 is turned off |  |
| SC6_EN | 5 | This enable acts upon LED6 <br>  <br>  |
|  | $1=$ SC6 is turned on |  |
| $0=$ SC6 is turned off |  |  |
| SC5_EN | 4 | This enable acts upon LED5 |
|  |  | $1=$ SC5 is turned on |
|  |  | $0=$ SC5 is turned off |

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| Bit Name | Bit No. | Description |
| :--- | :--- | :--- |
| SC4_EN | 3 | This enable acts upon LED4 <br> $1=$ SC4 is turned on <br>  |
|  |  | $0=$ SC4 is turned off |
| SC3_EN | 2 | This enable acts upon LED3 <br> $1=$ SC3 is turned on <br> $0=$ SC3 is turned off |
| SC2_EN | 1 | This enable acts upon LED2 |
|  |  | $1=$ SC2 is turned on |
|  | $0=$ SC2 is turned off |  |
| SC1_EN | 0 | This enable acts upon LED1 |
|  |  | $1=$ SC1 is turned on |
|  |  | $0=$ SC1 is turned off |

## Independent Sink Current Time (ISCT1)—Register 0x11

Table 35. ISCT1 Bit Map

| Bit 7 Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |  |
| :---: | :---: | :---: | :--- | :--- | :--- | :--- | :--- |
| SCON |  |  |  |  |  |  |  |

Table 36. Bit Descriptions for the ISCT1 Register

| Bit Name | Bit No. | Description ${ }^{1}$ |
| :---: | :---: | :---: |
| SCON | [7:6] | SC on time. If the SCx_OFF time is not disabled and the independent current sink is enabled (Register $0 \times 10$ ), the LED(s) remains on for the on time selected (per the following list) and then turns off. $\begin{aligned} & 00=0.2 \mathrm{sec} \\ & 01=0.6 \mathrm{sec} \\ & 10=0.8 \mathrm{sec} \\ & 11=1.2 \mathrm{sec} \end{aligned}$ |
| SC7_OFF | [5:4] | SC7 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |
| SC6_OFF | [3:2] | SC6 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |
| SC5_OFF | [1:0] | SC5 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |

[^2]
## Independent Sink Current Time (ISCT2)—Register 0x12

Table 37. ISCT2 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| SC4_OFF |  | SC3_OFF | SC2_OFF | SC1_OFF |  |  |  |

Table 38. Bit Descriptions for the ISCT2 Register

| Bit Name | Bit No. | Description ${ }^{1}$ |
| :---: | :---: | :---: |
| SC4_OFF | [7:6] | SC4 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |
| SC3_OFF | [5:4] | SC3 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |
| SC2_OFF | [3:2] | SC2 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |
| SC1_OFF | [1:0] | SC1 off time. When the SC off time is disabled, the ISC remains on while enabled. When the SC off time is set to any other value, then the ISC turns off for the off time (per the following listed times) and then turns on according to the SCON setting. $\begin{aligned} & 00=\text { off time disabled } \\ & 01=0.6 \mathrm{sec} \\ & 10=1.2 \mathrm{sec} \\ & 11=1.8 \mathrm{sec} \end{aligned}$ |

[^3]
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## Independent Sink Current Fade (ISCF)—Register 0x13

Table 39. ISCF Bit Map

| Bit 7 Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| SCFO |  |  |  |  | SCFI |  |

Table 40. Bit Descriptions for the ISCF Register

| Bit Name | Bit No. | Description |
| :---: | :---: | :---: |
| SCFO | [7:4] | Sink current fade out rate. The following times listed are for a full-scale fade out ( 30 mA to 0 mA ). Fades between closer current values reduce the fade time. See the Automated Fade In and Fade Out section for more information. $0000=\text { disabled }$ <br> $0001=0.30 \mathrm{sec}$ <br> $0010=0.60 \mathrm{sec}$ <br> $0011=0.90 \mathrm{sec}$ <br> $0100=1.2 \mathrm{sec}$ <br> $0101=1.5 \mathrm{sec}$ <br> $0110=1.8 \mathrm{sec}$ <br> $0111=2.1 \mathrm{sec}$ <br> $1000=2.4 \mathrm{sec}$ <br> $1001=2.7 \mathrm{sec}$ <br> $1010=3.0 \mathrm{sec}$ <br> $1011=3.5 \mathrm{sec}$ <br> $1100=4.0 \mathrm{sec}$ <br> $1101=4.5 \mathrm{sec}$ <br> $1110=5.0 \mathrm{sec}$ <br> $1111=5.5 \mathrm{sec}$ |
| SCFI | [3:0] | Sink current fade in rate. The following times listed are for a full-scale fade in ( 0 mA to 30 mA ). Fades between closer current values reduce the fade time. See the Automated Fade In and Fade Out section for more information. |

## Sink Current Register LED7 (ISC7)—Register 0x 14

Table 41. ISC7 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| SCR | SCD7 |  |  |  |  |  |  |

Table 42. Bit Descriptions for the ISC7 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| SCR | 7 | $\begin{aligned} & 1=\text { Sink Current } 1 . \\ & 0=\text { Sink Current } 0 . \end{aligned}$ |  |  |
| SCD7 | [6:0] | For Sink Current 0, use the following DAC code schedule (see Table 28 for a complete list of values): |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | $\ldots$ | $\ldots$ | ... |
|  |  | 1111111 | 30 | 30 |
|  |  | For Sink C | urrent 1, use the foll | ing DAC code schedule (see Table 43 for a complete list of values): |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0.000 | 0 |
|  |  | 0000001 | 0.472 | 0.004 |
|  |  | 0000010 | 0.945 | 0.014 |
|  |  | 0000011 | 1.417 | 0.034 |
|  |  | $1111111$ | $60$ | $60$ |

Table 43. Linear and Square Law Currents for LED7 (SCR = 1)

| DAC Code | Linear Law (mA) | Square Law (mA) ${ }^{1}$ | DAC Code | Linear Law (mA) | Square Law (mA) ${ }^{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0x00 | 0.000 | 0 | 0x19 | 11.81 | 2.326 |
| $0 \times 01$ | 0.472 | 0.004 | $0 \times 1 \mathrm{~A}$ | 12.28 | 2.514 |
| $0 \times 02$ | 0.945 | 0.014 | $0 \times 1 \mathrm{~B}$ | 12.76 | 2.712 |
| $0 \times 03$ | 1.42 | 0.034 | $0 \times 1 \mathrm{C}$ | 13.23 | 2.916 |
| $0 \times 04$ | 1.89 | 0.06 | 0x1D | 13.70 | 3.128 |
| $0 \times 05$ | 2.36 | 0.094 | $0 \times 1 \mathrm{E}$ | 14.17 | 3.348 |
| $0 \times 06$ | 2.83 | 0.134 | $0 \times 1 \mathrm{~F}$ | 14.65 | 3.574 |
| $0 \times 07$ | 3.31 | 0.182 | $0 \times 20$ | 15.12 | 3.81 |
| $0 \times 08$ | 3.78 | 0.238 | $0 \times 21$ | 15.59 | 4.052 |
| $0 \times 09$ | 4.25 | 0.302 | $0 \times 22$ | 16.06 | 4.3 |
| $0 \times 0 \mathrm{~A}$ | 4.72 | 0.372 | $0 \times 23$ | 16.54 | 4.558 |
| $0 \times 0 \mathrm{~B}$ | 5.20 | 0.45 | $0 \times 24$ | 17.01 | 4.822 |
| $0 \times 0 \mathrm{C}$ | 5.67 | 0.536 | $0 \times 25$ | 17.48 | 5.092 |
| 0x0D | 6.14 | 0.628 | $0 \times 26$ | 17.95 | 5.372 |
| 0x0E | 6.61 | 0.73 | $0 \times 27$ | 18.43 | 5.658 |
| 0x0F | 7.09 | 0.838 | $0 \times 28$ | 18.90 | 5.952 |
| $0 \times 10$ | 7.56 | 0.952 | $0 \times 29$ | 19.37 | 6.254 |
| $0 \times 11$ | 8.03 | 1.076 | $0 \times 2 \mathrm{~A}$ | 19.84 | 6.562 |
| $0 \times 12$ | 8.50 | 1.206 | $0 \times 2 \mathrm{~B}$ | 20.31 | 6.878 |
| $0 \times 13$ | 8.98 | 1.342 | $0 \times 2 \mathrm{C}$ | 20.79 | 7.202 |
| $0 \times 14$ | 9.45 | 1.488 | $0 \times 2 \mathrm{D}$ | 21.26 | 7.534 |
| $0 \times 15$ | 9.92 | 1.64 | $0 \times 2 \mathrm{E}$ | 21.73 | 7.872 |
| $0 \times 16$ | 10.39 | 1.8 | $0 \times 2 \mathrm{~F}$ | 22.20 | 8.218 |
| $0 \times 17$ | 10.87 | 1.968 | $0 \times 30$ | 22.68 | 8.57 |
| 0x18 | 11.34 | 2.142 | $0 \times 31$ | 23.15 | 8.932 |

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| DAC Code | Linear Law (mA) | Square Law $(\mathbf{m A})^{\mathbf{1}}$ |
| :--- | :--- | :--- |
| 0x32 | 23.62 | 9.3 |
| 0x33 | 24.09 | 9.676 |
| 0x34 | 24.57 | 10.058 |
| 0x35 | 25.04 | 10.45 |
| 0x36 | 25.51 | 10.848 |
| 0x37 | 25.98 | 11.254 |
| 0x38 | 26.46 | 11.666 |
| 0x39 | 26.93 | 12.086 |
| 0x3A | 27.40 | 12.514 |
| 0x3B | 27.87 | 12.95 |
| 0x3C | 28.35 | 13.392 |
| 0x3D | 28.82 | 13.842 |
| 0x3E | 29.29 | 14.3 |
| 0x3F | 29.76 | 14.764 |
| 0x40 | 30.24 | 15.238 |
| 0x41 | 30.71 | 15.718 |
| 0x42 | 31.18 | 16.204 |
| 0x43 | 31.65 | 16.7 |
| 0x44 | 32.13 | 17.202 |
| 0x45 | 32.60 | 17.71 |
| 0x46 | 33.07 | 18.228 |
| 0x47 | 33.54 | 18.752 |
| 0x48 | 34.02 | 19.284 |
| 0x49 | 34.49 | 19.824 |
| 0x4A | 34.96 | 20.37 |
| 0x4B | 35.43 | 20.926 |
| 0x4C | 35.91 | 21.486 |
| 0x4D | 36.38 | 22.056 |
| 0x4E | 36.85 | 22.632 |
| 0x4F | 37.32 | 23.216 |
| 0x50 | 37.80 | 23.808 |
| 0x51 | 38.27 | 24.406 |
| 0x52 | 38.74 | 25.014 |
| 0x53 | 39.21 | 25.628 |
| 0x54 | 39.69 | 26.248 |
| 0x55 | 40.16 | 26.878 |
| 0x56 | 40.63 | 27.514 |
| 0x57 | 41.10 | 28.156 |
| $0 \times 58$ | 28.808 |  |
|  |  |  |


| DAC Code | Linear Law (mA) | Square Law $(\mathbf{m A})^{\mathbf{1}}$ |
| :--- | :--- | :--- |
| 0x59 | 42.05 | 29.466 |
| 0x5A | 42.52 | 30.132 |
| 0x5B | 42.99 | 30.806 |
| 0x5C | 43.46 | 31.486 |
| 0x5D | 43.94 | 32.174 |
| 0x5E | 44.41 | 32.87 |
| 0x5F | 44.88 | 33.574 |
| 0x60 | 45.35 | 34.284 |
| 0x61 | 45.83 | 35.002 |
| 0x62 | 46.30 | 35.726 |
| 0x63 | 46.77 | 36.46 |
| 0x64 | 47.24 | 37.2 |
| 0x65 | 47.72 | 37.948 |
| 0x66 | 48.19 | 38.702 |
| 0x67 | 48.66 | 39.466 |
| 0x68 | 49.13 | 40.236 |
| 0x69 | 49.61 | 41.014 |
| 0x6A | 50.08 | 41.798 |
| 0x6B | 50.55 | 42.59 |
| 0x6C | 51.02 | 43.39 |
| 0x6D | 51.50 | 44.198 |
| 0x6E | 51.97 | 45.012 |
| 0x6F | 52.44 | 45.834 |
| 0x70 | 52.91 | 46.664 |
| 0x71 | 53.39 | 47.5 |
| 0x72 | 53.86 | 48.346 |
| 0x73 | 54.33 | 49.198 |
| 0x74 | 54.80 | 50.056 |
| 0x75 | 55.28 | 50.924 |
| 0x76 | 55.75 | 51.798 |
| 0x77 | 56.22 | 52.68 |
| 0x78 | 56.69 | 53.568 |
| 0x79 | 57.17 | 54.464 |
| 0x7A | 57.64 | 55.368 |
| 0x7B | 58.11 | 56.28 |
| 0x7C | 58.58 | 57.198 |
| 0x7D | 59.06 | 58.126 |
| 0x7E | 59.53 | 6058 |
| 0x7F | 60 |  |
|  |  |  |
| step per DAC cubic | 11 laws use the square law | DAC seting but vary the time |
| 29). |  |  |

## Sink Current Register LED6 (ISC6)—Register 0x15

Table 44. ISC6 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SCD6 |  |  |  |  |  |  |

Table 45. Bit Descriptions for the ISC6 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| SCD6 | [6:0] | Sink current. Use the following DAC code schedule (see Table 28 for a complete list of values). |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | $1111111$ | ... 30 | ... 30 |

Sink Current Register LED5 (ISC5)—Register 0x16
Table 46. ISC5 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | Bit 0 |  |  |  |  |  |

Table 47. Bit Descriptions for the ISC5 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| SCD5 | [6:0] | Sink current. Use the following DAC code schedule (see Table 28 for a complete list of values): |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | $1111111$ | $30$ | $30$ |

## Sink Current Register LED4 (ISC4)—Register 0x17

Table 48. ISC4 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SCD4 |  |  |  |  |  |  |

Table 49. Bit Descriptions for the ISC4 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| SCD4 | [6:0] | Sink current. Use the following DAC code schedule (see Table 28 for a complete list of values): |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | ... | $\ldots$ | ... |
|  |  | 1111111 | 30 | 30 |

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## Sink Current Register LED3 (ISC3)—Register 0x18

Table 50. ISC3 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SCD3 |  |  |  |  |  |  |

Table 51. Bit Descriptions for the ISC3 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| SCD3 | [6:0] | Sink current. Use the following DAC code schedule (see Table 28 for a complete list of values): |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | $1111111$ | .. 30 | ... 30 |

Sink Current Register LED2 (ISC2)—Register 0x19
Table 52. ISC2 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SCD2 |  |  |  |  |  |  |

Table 53. Bit Descriptions for the ISC2 Register


## Sink Current Register LED1 (ISC1)—Register 0x1A

Table 54. ISC1 Bit Map

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Reserved | SCD1 |  |  |  |  |  |  |

Table 55. Bit Descriptions for the ISC1 Register

| Bit Name | Bit No. | Description |  |  |
| :---: | :---: | :---: | :---: | :---: |
| N/A | 7 | Reserved. |  |  |
| SCD1 | [6:0] | Sink current. Use the following DAC code schedule (see Table 28 for a complete list of values): |  |  |
|  |  | DAC | Linear Law (mA) | Square Law (mA) |
|  |  | 0000000 | 0 | 0.000 |
|  |  | 0000001 | 0.236 | 0.002 |
|  |  | 0000010 | 0.472 | 0.007 |
|  |  | 0000011 | 0.709 | 0.017 |
|  |  | ... | ... 30 |  |
|  |  | 1111111 | 30 | 30 |

## OUTLINE DIMENSIONS




COMPLIANT TO JEDEC STANDARDS MO-220-WGGD.
Figure 43. 20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]
$4 \mathrm{~mm} \times 4 \mathrm{~mm}$ Body, Very Thin Quad (CP-20-10)
Dimensions shown in millimeters


Figure 44. Tape and Reel Orientation for LFCSP Units

| ORDERING GUIDE |
| :--- |
| Model ${ }^{1}$ |
| ADP8861ACPZ-RL |
| ADP8861DBCB-EVALZ |

[^4]
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## NOTES


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[^1]:    ${ }^{1}$ When fade in and fade out are disabled, the backlight does not instantly fade, but instead, fades rapidly within about 100 ms .

[^2]:    ${ }^{1}$ Each current sink remains on continuously when its enable is set to 1 and its off time is set to 00 (disabled).

[^3]:    ${ }^{1}$ Each current sink remains on continuously when its enable is set to 1 and its off time is set to 00 (disabled).

[^4]:    ${ }^{1} \mathrm{Z}=$ RoHS Compliant Part.

