

# HT82V38 16-Bit CCD/CIS Analog Signal Processor

### Features

- Operating voltage: 3.3V (typ.)
- Low Power CMOS: 300 mW (typ.)
- Power-Down Mode: 10μA (max.)
- 16-Bit 30 MSPS A/D converter
- Guaranteed won't miss codes
- 1~5.85x programmable gain
- Correlated double sampling
- ±250 mV programmable offset
- Input clamp circuitry

- Internal voltage reference
- Multiplexed byte-wide output (8+8 format)
- Programmable 3-wire serial interface
- 3.3V digital I/O compatibility
- 3-Channel operation up to 30 MSPS
- · 2-Channel (even-odd) operation up to 30 MSPS
- 1-Channel operation up to 20 MSPS
- 28-pin SSOP (209mil) package

### Applications

- Flatbed document scanners
- Film scanners

### **General Description**

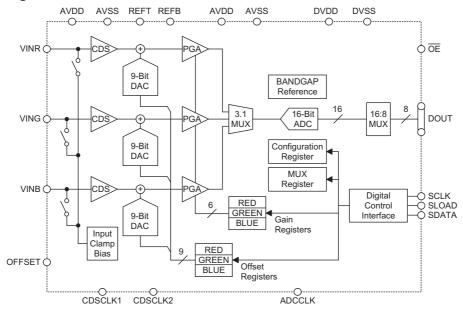
The HT82V38 is a complete analog signal processor for CCD imaging applications. It features a 3 channel architecture designed to sample and condition the outputs of trilinear color CCD arrays. Each channel consists of an input clamp, Correlated Double Sampler (CDS), offset DAC and Programmable Gain Amplifier (PGA), multiplexed to a high performance 16-bit A/D converter.

The CDS amplifiers may be disabled for use with sensors such as Contact Image Sensors (CIS) and CMOS active pixel sensors, which do not require CDS.

- Digital color copiers
- Multifunction peripherals

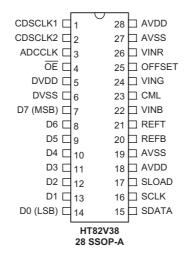
The 16-bit digital output is multiplexed into an 8-bit output word that is accessed using two read cycles. The internal registers are programmed through a 3-wire serial interface, and provide adjustment of the gain, offset, and operating mode.

### **Block Diagram**





### **Pin Assignment**



### **Pin Description**

Pin No.	Pin Name	I/O	Description
1	CDSCLK1	DI	CDS Reference Clock Pulse Input
2	CDSCLK2	DI	CDS Data Clock Pulse Input
3	ADCCLK	DI	A/D Sample Clock Input for 3-channels Mode
4	ŌĒ	DI	Output Enable, Active Low Internal pull-low 50Ω
5	DVDD	Р	Digital Power
6	DVSS	Р	Digital Ground
7~14	D7~D0	DO	Digital Data Output
15	SDATA	DI/DO	Serial Data Input/Output
16	SCLK	DI	Clock Input for Serial Interface
17	SLOAD	DI	Serial Interface Load Pulse
18, 28	AVDD	Р	Analog Supply
19, 27	AVSS	Р	Analog Ground
20	REFB	AO	Reference Decoupling
21	REFT	AO	Reference Decoupling
22	VINB	AI	Analog Input, Blue
23	CML	AO	Internal Reference Output
24	VING	AI	Analog Input, Green
25	OFFSET	AO	Clamp Bias Level Decoupling
26	VINR	AI	Analog Input, Red

Note: Al=Analog Input, AO=Analog Output, DI=Digital Input, DO=Digital Output, P=Power



### **Absolute Maximum Ratings**

Supply VoltageV_SS-0.3V to V_SS+4.3V	Storage Temperature50°C to 125°C
Input VoltageV_SS=0.3V to V_DD+0.3V	Operating Temperature0°C to 70°C

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

### **D.C. Characteristics**

Symbol	Parameter	Tes	t Conditions	Min.	Turn	Max.	Unit
Symbol	Parameter	$V_{DD}$	Conditions	win.	Тур.	wax.	Unit
Logic Inp	outs						
VIH	High Level Input Voltage	—		0.8V <sub>DD</sub>	_		V
VIL	Low Level Input Voltage	_			_	$0.2V_{DD}$	V
I <sub>IH</sub>	High Level Input Current				_	1	μΑ
IIL	Low Level Input Current	_			_	1	μA
C <sub>IN</sub>	Input Capacitance	_		_	5		pF
Logic Ou	tputs						
V <sub>OH</sub>	High Level Output Voltage	_	I <sub>OH</sub> =3mA	DV <sub>DD</sub> -0.5			V
V <sub>OL</sub>	Low Level Output Voltage	_	I <sub>OL</sub> =3mA			0.5	V

### A.C. Characteristics

Complete L	Domonoton	Tes	t Conditions	Min.	<b>T</b>	Max.	Unit
Symbol	Parameter	$V_{\text{DD}}$	Conditions	win.	Тур.	wax.	Onit
Power St	upplies						
AV <sub>DD</sub>	AVDD	_	_	3.15	3.3	3.45	V
DV <sub>DD</sub>	DVDD	—		3.15	3.3	3.45	V
Maximun	n Conversion Rate						
	3-channel Mode with CDS	_	_	30	_		MPS
t <sub>MAX</sub>	2-channel Mode with CDS	—		30			MPS
	1-channel Mode with CDS	_		20			MPS
Accuracy	y (Entire Signal Path)						
	ADC Resolution	_		_	16		Bits
	Integral Nonlinear (INL)	—		_	±32		LSB
	Differential Nonlinear (DNL)		_	-1		+1	mV
	Offset Error	_		-100		+100	mV
	Gain Error	—			5		%FSR



Cumbed.	Donomotor	Tes	t Conditions	Min.	<b>T</b>	Maria	Unit
Symbol	Parameter	$V_{DD}$	Conditions	win.	Тур.	Max.	Unit
Analog li	nputs						
R <sub>FS</sub>	Full-scale Input Range	_	_	_	1.6/2.0		V
Vi	Input Limits	—	_	AV <sub>SS</sub> -0.3		AV <sub>DD</sub> +0.3	V
Ci	Input Capacitance	—	_	_	10		pF
li	Input Current	—	_	_	10		μA
Amplifie	'S						
	PGA Gain at Minimum	—	_	_	1	_	V/V
	PGA Gain at Maximum	_	_	—	5.85		V/V
	PGA Gain Resolution	—	_	_	6		Bits
	Programmable Offset at Minimum	—	_	_	-250		mV
	Programmable Offset at Maximum	—	_	_	250		mV
	Offset Resolution	—	_	_	9		Bits
Clamp D	AC Circuit					·	
t <sub>A</sub>	Clamp DAC resolution	_	_	_	4		Bits
	Clamp DAC output voltage at code 0			_	0.45		V
	Clamp DAC output voltage at code F			_	2.7	_	V
	Clamp DAC Step size			_	0.15		V/Step
	Clamp DAC deviation (AV <sub>DD</sub> =3.300V)			-50	_	50	mV
Tempera	ture Range	1				· ·	
t <sub>A</sub>	Operating	_		0		70	°C
Power Co	onsumption						
P <sub>tot</sub>	Total Power Consumption		_	_	300	_	mW

 $\label{eq:constraint} \textbf{Timing Specification} \qquad \text{AV}_{\text{DD}} = \text{DRV}_{\text{DD}} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = \text{DRV}_{\text{SS}} = 0 \text{V}, \ \text{Ta} = 25^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{unless otherwise stated} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{AV}_{\text{SS}} = 10^{\circ}\text{C}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{ADCCLK} = 30 \text{MHz} \ \text{and} = 3.3 \text{V}, \ \text{ADCCLK} = 3.3 \text$ 

Symbol	Parameter	Min.	Тур.	Max.	Unit
Clock Para	meters	·	÷		
t <sub>PRA</sub>	3-Channel Pixel Rate	100	_		ns
t <sub>PRB</sub>	2-Channel Pixel Rate	66	_		ns
t <sub>PRC</sub>	1-Channel Pixel Rate	50	_		ns
t <sub>ADCLK</sub>	ADCCLK Pulse Width	16			ns
t <sub>C1</sub>	CDSCLK1 Pulse Width	10			ns
t <sub>C2</sub>	CDSCLK2 Pulse Width	10			ns
t <sub>C1C2</sub>	CDSCLK1 Falling to CDSCLK2 Rising	0	_		ns
t <sub>ADC2</sub>	ADCCLK Falling to CDSCLK2 Rising	2			ns
t <sub>C2ADR</sub>	CDSCLK2 Rising to ADCCLK Rising	2			ns
t <sub>C2ADF</sub>	CDSCLK2 Falling to ADCCLK Falling	20			ns
t <sub>ADC1</sub>	ADCCLK Falling to CDSCLK1 Rising	0			ns
t <sub>AD</sub>	Aperture Delay for CDS Clocks	_	3	_	ns

July 23, 2009



Symbol	Parameter	Min.	Тур.	Max.	Unit
Serial Inter	face	·			
f <sub>SCLK</sub>	Maximum SCLK Frequency	10			MHz
t <sub>LS</sub>	SLOAD to SCLK Setup Time	10	_		ns
t <sub>LH</sub>	SCLK to SLOAD Hold Time	10			ns
t <sub>DS</sub>	SDATA to SCLK Rising Setup Time	10			ns
t <sub>DH</sub>	SCLK Rising to SDATA Hold Time	10			ns
t <sub>RDV</sub>	SCLK Falling to SDATA Valid	10			ns
Data Outpu	ıt	·			
t <sub>OD</sub>	Output Delay (output load 10pF)	_	10		ns
	Latency (Pipeline Delay)		9		Cycles

### **Functional Description**

#### Integral Nonlinear (INL)

Integral nonlinearity error refers to the deviation of each individual code from a line drawn from "zero scale" through "positive full scale". The point used as "zero scale" occurs 1/2 LSB before the first code transition. "Positive full scale" is defined as a level 1/2 LSB beyond the last code transition. The deviation is measured from the middle of each particular code to the true straight line.

#### Differential Nonlinear (DNL)

An ideal ADC exhibits code transitions that are exactly 1 LSB apart. DNL is the deviation from this ideal value. Thus every code must have a finite width. No missing codes guaranteed to 16-bit resolution indicates that all 4096 codes, respectively, must be present over all operating ranges.

#### **Offset Error**

The first ADC code transition should occur at a level 1/2 LSB above the nominal zero scale voltage. The offset error is the deviation of the actual first code transition level from the ideal level.

#### Gain Error

The last code transition should occur for an analog value 1/2 LSB below the full-scale voltage ( $2\times(REFT-REFB)$ ). Gain error is the deviation of the actual difference between first and last code transitions and the ideal difference between the first and last code transitions.

#### Aperture Delay

The aperture delay is the time delay that occurs from when a sampling edge is applied to the HT82V38 until the actual sample of the input signal is held. Both CDSCLK1 and CDSCLK2 sample the input signal during the transition from high to low, so the aperture delay is measured from each clock's falling edge to the instant the actual internal sample is taken.



#### Internal Register Descriptions

Register	Α	ddres	s		Data Bits									
Name	A2	A1	A0	D8	D7	D6	D5	D4	D3	D2	D1	D0		
Configuration	0	0	0	0	0	Clamp Int	3 CH	CDS on	0	Pwr Dn	Full scale input range	1byte out		
MUX	0	0	1	0	RGB/ BGR	Red	Green	Blue	ClapC[3]	ClapC[2]	ClapC[1]	ClapC[0]		
Red PGA	0	1	0	0	0	0	MSB					LSB		
Green PGA	0	1	1	0	0	0	MSB					LSB		
Blue PGA	1	0	0	0	0	0	MSB					LSB		
Red Offset	1	0	1	MSB								LSB		
Green Offset	1	1	0	MSB								LSB		
Blue Offset	1	1	1	MSB								LSB		

#### Internal Register Map

#### **Configuration Register**

The Configuration Register controls the HT82V38's operating mode and bias levels. Bits D6 controls reference clamp voltage. Setting this bit low change OFFSET to high-Z, allowing OFFSET to be driven from external power source. Bit D5 will configure the HT82V38 for the 3-Channel (high) mode of operation. Setting Bit D4 high will enable the CDS mode of operation, and setting this bit low will enable the SHA mode of operation. Bit D3 should always be set low. Bit D2 controls the power-down mode. Setting Bit D2 high will place the HT82V38 into a very low power "sleep" mode. All register contents are retained while the HT82V38 is in the powered-down state. Bit D1 controls full-scale input range. D1=1, full scale input range will be 2V, D1=0 full scale input range will be 1.6V. Bit D0 controls the output mode of the HT82V38. Setting bit D0 high will enable a single byte output mode where only 8 MSBs of the 16-bit ADC will be output. If bit D0 is set low, then the 16-bit ADC output is multiplexed into two bytes.

D8	D7	D6	D5	D4	D3	D2	D1	D0
Set	Set Set	3 Channels	CDS operation		Power-down	Full scale input range	1 byte out	
to	to			1=CDS mode*	_	1=On	1=2V	1=On
0	0	0=External	0=Off	0=SHA mode	0*	0=Off (Normal)*	0=1.6V*	0=Off *

Note: \* Power-on default value

**Configuration Register Settings** 



#### **MUX Register**

The MUX Register controls the sampling channel order in the HT82V38. Bits D8 should always be set low. Bit D7 is used when operating in 3-Channel Mode. Setting Bit D7 high will sequence the MUX to sample the red channel first, then the green channel, and then the blue channel. When in this mode, the CDSCLK2 rising edge always resets the MUX to sample the red channel first (see Timing Figure). When Bit D7 is set low, the channel order is reversed to blue first, green second, and red third. The CDSCLK2 rising edge pulse will always reset the MUX to sample the blue channel first. Bits D6, D5, and D4 are used when operating in 1-Channel Mode. Bit D6 is set high to sample the red channel. Bit D5 is set high to sample the green channel. Bit D4 is set high to sample the blue channel. The MUX will remain stationary during 1-Channel Mode. Bit D3 to Bit D0 control 4 bits DAC clamp voltage from 0.45V to 2.7V.

D8	D7	D6	D5	D4	D3	D2	D1	D0
	3-Channel	1-Channel	1-Channel	1-Channel	Clap[3]	Clap[2]	Clap[1]	Clap[0]
Set to 0	1=R-G-B* 0=B-G-R	1=RED* 0=Off	1=GREEN 0=Off*	1=BLUE 0=Off *				

Note: \* Power-on default value

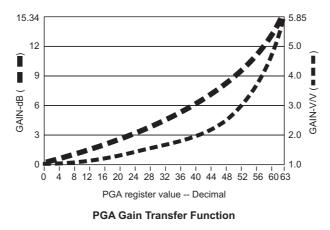
#### MUX Register Settings

#### **PGA Gain Register**

There are three PGA registers for individually programming the gain in the red, green, and blue channels. Bits D8, D7, and D6 in each register must be set low, and bits D5 through D0 control the gain range in 64 increments. See Figure for a graph of the PGA Gain versus PGA register code. The coding for the PGA registers is straight binary, with an all "zeros" word corresponding to the minimum gain setting (1x) and an all "ones" word corresponding to the maximum gain setting (5.85x).

The PGA has a gain range from  $1 \times (0dB)$  to  $5.85 \times (15.3dB)$ , adjustable in 64 steps. The Figure shows the PGA gain as a function of the PGA register code. Although the gain curve is approximately linear in dB, the gain in V/V varies in non-linear proportion with the register code, according to the following the equation:

Where "G" is the decimal value of the gain register contents, and varies from 0 to 63.





D8	D7	D6	D5	D4	D3	D2	D1	D0	Gain (V/V)	Gain (dB)
Set to 0	Set to 0	Set to 0	MSB					LSB		
0 0	0 0	0 0	0 0	0 0	0 0 :	0 0	0 0	0* 1	1.0 1.013 :	0.0 0.11 :
0 0	0 0	0 0	1 1	1 1	1	1 1	1 1	0 1	5.43 5.85	14.7 15.34

Note: \* Power-on default value

#### PGA Gain Register Settings

### Offset Register

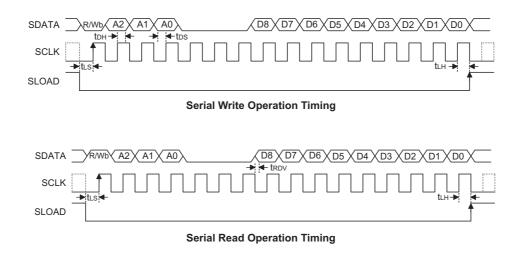
There are three PGA registers for individually programming the offset in the red, green, and blue channels. Bits D8 through D0 control the offset range from -250 mV to +250 mV in 512 increments. The coding for the offset registers is sign magnitude, with D8 as the sign bit. Table shows the offset range as a function of the Bits D8 through D0.

D8	D7	D6	D5	D4	D3	D2	D1	D0	Offset (mV)
MSB								LSB	
0	0	0	0	0	0	0	0	0* 1	0 +0.98
		Ū	Ū	Ū	:	Ū	Ū		:
0	1	1	1	1	1	1	1	1	+250
1	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0 : :	0	0	1	-0.98 : :
1	1	1	1	1	1	1	1	1	-250

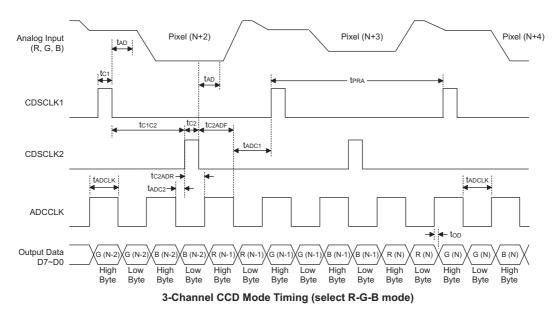
Note: \* Power-on default value

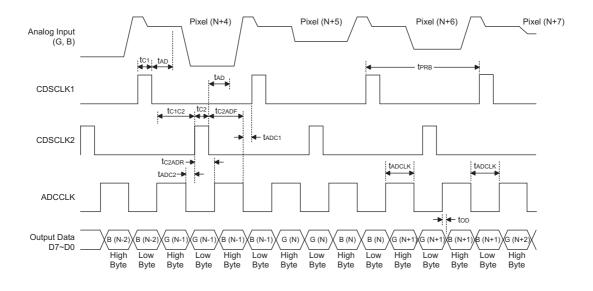
#### **Offset Register Settings**

### **Timing Diagrams**



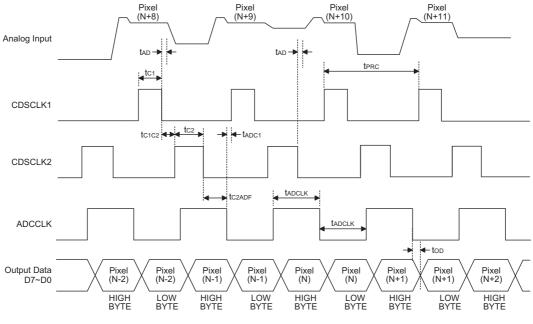




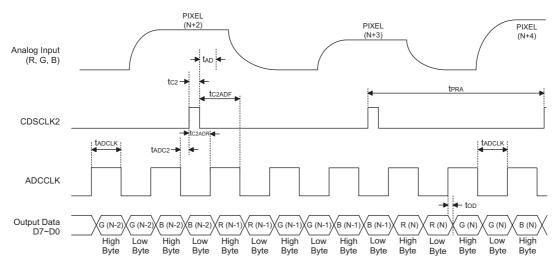


2-Channel CCD Mode Timing (select G-B mode)



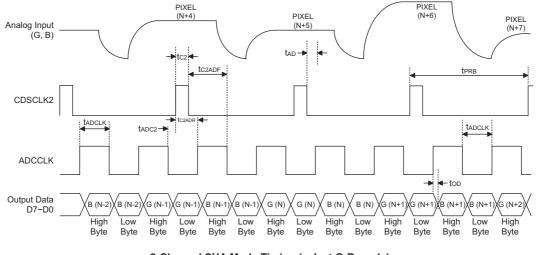




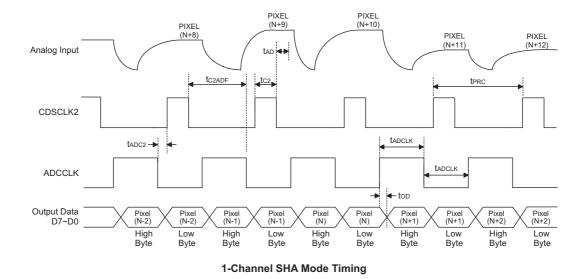


3-Channel SHA Mode Timing (select R-G-B mode)











### **Application Circuits**

#### **Circuit and Layout Recommendations**

The recommended circuit configuration for 3-Channel CDS mode operation is shown in Figure. The recommended input coupling capacitor value is  $0.1\mu$ F (see Circuit Operation section for more details). A single ground plane is recommended for the HT82V38. A separate power supply may be used for DRV<sub>DD</sub>, the digital driver supply, but this supply pin should still be decoupled to the same ground plane as the rest of the HT82V38. The loading of the digital outputs should be minimized, either by using short traces to the digital ASIC, or by using external digital buffers. To minimize the effect of digital transients during major output code transitions, the falling edge of CDSCLK2 should occur coincident with or before the transient edge of ADCCLK. All  $0.1\mu$ F decoupling capacitors should be located as close as possible to the HT82V38 pins. When operating in single channel mode, the unused analog inputs should be grounded.

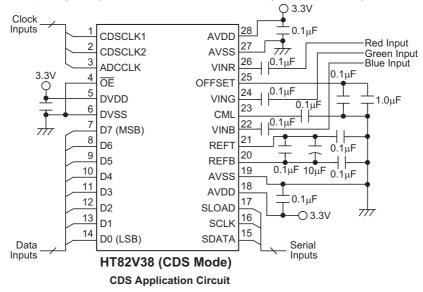
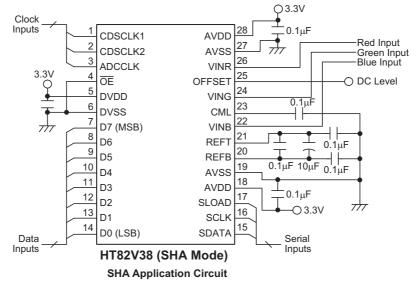


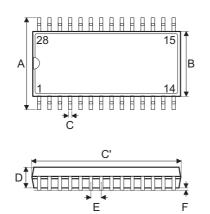
Figure shows the recommended circuit configuration for 3-Channel SHA mode. All of the above considerations also apply for this configuration, except that the analog input signals are directly connected to the HT82V38 without the use of coupling capacitors. The analog input signals must already be dc-biased (relative to OFFSET pin) between 0V and 1.60V/2.0V.





# Package Information

28-pin SSOP (209mil) Outline Dimensions





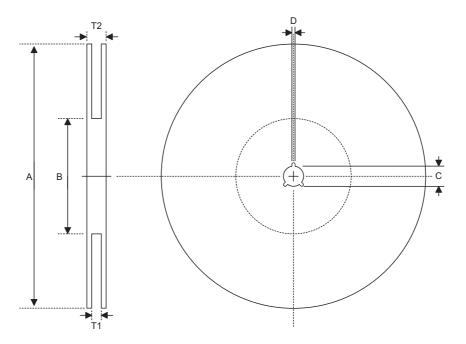
• MO-150

Symbol	Dimensions in mm		
	Min.	Nom.	Max.
A	7.40		8.20
В	5.00	—	5.60
С	0.22	_	0.33
C'	9.90		10.50
D	_		2.00
E	_	0.65	_
F	0.05	—	_
G	0.55		0.95
Н	0.09		0.21
α	0°		8°



# Product Tape and Reel Specifications

### **Reel Dimensions**

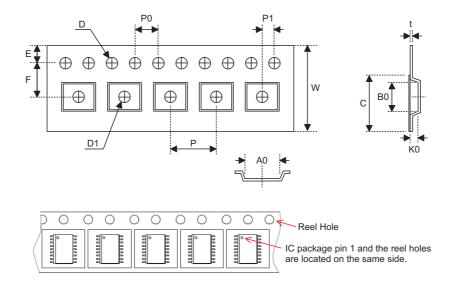


SSOP 28S (209mil)

Symbol	Description	Dimensions in mm
А	Reel Outer Diameter	330.0±1.0
В	Reel Inner Diameter	100.0±1.5
С	Spindle Hole Diameter	13.0 +0.5/-0.2
D	Key Slit Width	2.0±0.5
T1	Space Between Flange	28.4 +0.3/-0.2
T2	Reel Thickness	31.1 (max.)



### **Carrier Tape Dimensions**



### SSOP 28S (209mil)

Symbol	Description	Dimensions in mm
W	Carrier Tape Width	24.0±0.3
Р	Cavity Pitch	12.0±0.1
E	Perforation Position	1.75±0.10
F	Cavity to Perforation (Width Direction)	11.5±0.1
D	Perforation Diameter	1.5 +0.1/-0.0
D1	Cavity Hole Diameter	1.50 +0.25/-0.00
P0	Perforation Pitch	4.0±0.2
P1	Cavity to Perforation (Length Direction)	2.0±0.1
A0	Cavity Length	8.4±0.1
В0	Cavity Width	10.65±0.10
K0	Cavity Depth	2.4±0.1
t	Carrier Tape Thickness	0.30±0.05
С	Cover Tape Width	21.3±0.1

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