

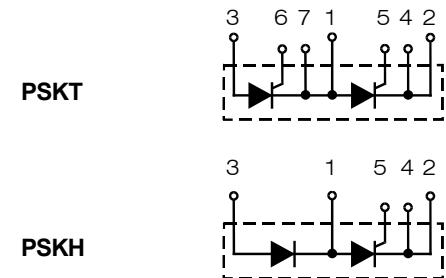
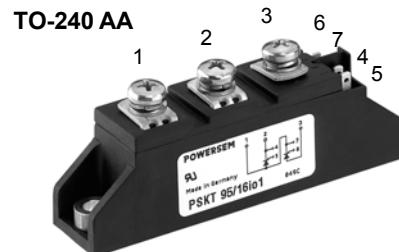
## PSKT94 /PSKH 94

### High Voltage Thyristor Module High Voltage Thyristor/Diode Modules

$I_{TRMS}$  = 2x 180 A  
 $I_{TAVM}$  = 2x 104 A  
 $V_{RRM}$  = 2000-2200 V

#### Preliminary Data Sheet

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
V	V	
2100	2000	PSKT 94/20io1 PSKH 94/20io1
2300	2200	PSKT 94/22io1 PSKH 94/22io1



Symbol	Test Conditions	Maximum Ratings		
$I_{TRMS}$	$T_{VJ} = T_{VJM}$	180	A	
$I_{TAVM}$	$T_c = 85^\circ C$ ; 180° sine	104	A	
$I_{TSM}$	$T_{VJ} = 45^\circ C$ ; $t = 10 \text{ ms}$ (50 Hz) $V_R = 0$ $t = 8.3 \text{ ms}$ (60 Hz)	1700	A	
	$T_{VJ} = T_{VJM}$ $t = 10 \text{ ms}$ (50 Hz) $V_R = 0$ $t = 8.3 \text{ ms}$ (60 Hz)	1800	A	
		1540	A	
		1640	A	
$\int i^2 dt$	$T_{VJ} = 45^\circ C$ $t = 10 \text{ ms}$ (50 Hz) $V_R = 0$ $t = 8.3 \text{ ms}$ (60 Hz)	14450	$A^2 s$	
		13500	$A^2 s$	
	$T_{VJ} = T_{VJM}$ $t = 10 \text{ ms}$ (50 Hz) $V_R = 0$ $t = 8.3 \text{ ms}$ (60 Hz)	11850	$A^2 s$	
		11300	$A^2 s$	
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ repetitive, $I_T = 250 \text{ A}$ $f = 50 \text{ Hz}$ , $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.45 \text{ A}$ , non repetitive, $I_T = I_{TAVM}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$	150	$A/\mu\text{s}$	
		500	$A/\mu\text{s}$	
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ ; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$ ; method 1 (linear voltage rise)	1000	$V/\mu\text{s}$	
$P_{GM}$	$T_{VJ} = T_{VJM}$ $t_p = 30 \mu\text{s}$ $I_T = I_{TAVM}$ $t_p = 300 \mu\text{s}$	10	W	
		5	W	
$P_{GAV}$		0.5	W	
$V_{RGM}$		10	V	
$T_{VJ}$		-40...125	$^\circ C$	
$T_{VJM}$		125	$^\circ C$	
$T_{stg}$		-40...125	$^\circ C$	
$V_{ISOL}$	50/60 Hz, RMS $t = 1 \text{ min}$	3000	V~	
	$I_{ISOL} \leq 1 \text{ mA}$ $t = 1 \text{ s}$	3600	V~	
$M_d$	Mounting torque (M5)	2.5-4.0/22-35	Nm/lb.in.	
	Terminal connection torque (M5)	2.5-4.0/22-35	Nm/lb.in.	
<b>Weight</b>	Typical including screws	90	g	

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.

#### Features

- International standard package, JEDEC TO-240 AA
- Direct Copper Bonded  $Al_2O_3$  -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 148688
- Gate-cathode twin pins for version 1

#### Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

#### Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling capability
- Reduced protection circuits

Symbol	Test Conditions	Characteristic Values	
$I_{RRM}, I_{DRM}$	$T_{VJ} = T_{VJM}; V_R = V_{RRM}$	15	mA
$V_T$	$I_T = 300 \text{ A}; T_{VJ} = 25^\circ\text{C}$	1.74	V
$V_{T0}$ $r_T$	For power-loss calculations only ( $T_{VJ} = T_{VJM}$ )	0.85 3.2	V $\text{m}\Omega$
$V_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	1.5	V
	$T_{VJ} = -40^\circ\text{C}$	1.6	V
$I_{GT}$	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	100	mA
	$T_{VJ} = -40^\circ\text{C}$	200	mA
$V_{GD}$ $I_{GD}$	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	0.25	V
	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	10	mA
$I_L$	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; t_p = 30 \mu\text{s}$ $di/dt = 0.45 \text{ A}/\mu\text{s}; I_G = 0.45 \text{ A}$	200	mA
$I_H$	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	150	mA
$t_{gd}$	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $di/dt = 0.45 \text{ A}/\mu\text{s}; I_G = 0.45 \text{ A}$	2	$\mu\text{s}$
$t_q$	$T_{VJ} = T_{VJM}; V_R = 100 \text{ V}; V_D = 2/3 V_{DRM}; t_p = 200 \mu\text{s}$ $dv/dt = 20 \text{ V}/\mu\text{s}; I_T = 150 \text{ A}; -di/dt = 10 \text{ A}/\mu\text{s}$	typ. 185	$\mu\text{s}$
$Q_s$ $I_{RM}$	$T_{VJ} = T_{VJM}$ $-di/dt = 6 \text{ A}/\mu\text{s}; I_T = 50 \text{ A}$	170 45	$\mu\text{C}$ A
$R_{thJC}$	per thyristor; DC current	0.22	K/W
	per module	0.11	K/W
$R_{thJK}$	per thyristor; DC current	0.42	K/W
	per module	0.21	K/W
$d_s$	Creeping distance on surface	12.7	mm
$d_A$	Creepage distance in air	9.6	mm
$a$	Maximum allowable acceleration	50	$\text{m}/\text{s}^2$

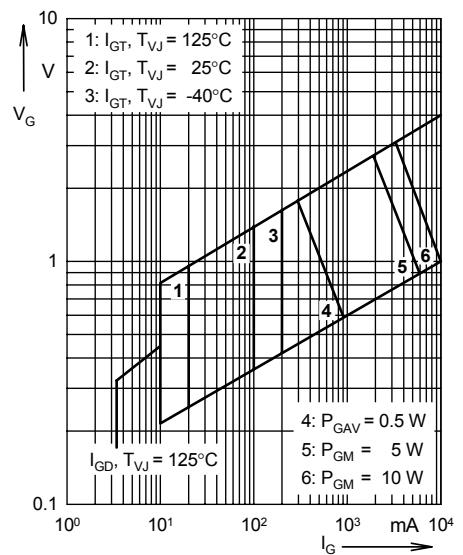


Fig. 1 Gate trigger characteristics

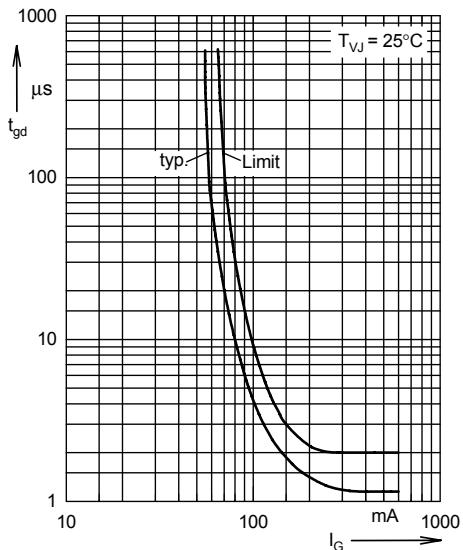
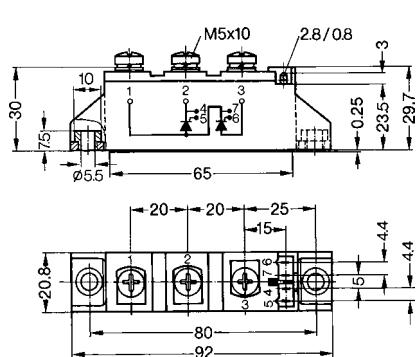


Fig. 2 Gate trigger delay time

### Dimensions in mm (1 mm = 0.0394")



### $R_{thJC}$ for various conduction angles d:

d	$R_{thJC}$ (K/W)
DC	0.22
180°	0.23
120°	0.25
60°	0.27
30°	0.28

### $R_{thJK}$ for various conduction angles d:

d	$R_{thJK}$ (K/W)
DC	0.42
180°	0.43
120°	0.45
60°	0.47
30°	0.48

### Constants for $Z_{thJC}$ calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344

### Constants for $Z_{thJK}$ calculation:

i	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344
4	0.2	1.32