Dual, VARIABLE GAIN AMPLIFIER
with Low-Noise Preamp

FEATURES

● **LOW NOISE PREAMP:**
  Low Input Noise: $1.0nV/\sqrt{Hz}$
  Active Termination Noise Reduction
  Switchable Termination Value
  80MHz Bandwidth
  5dB to 25dB Gain
  Differential In and Out
● **LOW NOISE VARIABLE GAIN AMPLIFIER:**
  Low Noise VCA: $3.3nV/\sqrt{Hz}$, Differential
  Programming Optimizes Noise Figure
  24dB to 45dB Gain
  40MHz Bandwidth
  Differential In and Out
● **LOW CROSSTALK: 52dB at Max Gain, 5MHz**
● **HIGH-SPEED VARIABLE GAIN ADJUST**
● **SWITCHABLE EXTERNAL PROCESSING**

APPLICATIONS

● **ULTRASOUND SYSTEMS**
● **WIRELESS RECEIVERS**
● **TEST EQUIPMENT**

DESCRIPTION

The VCA2613 is a dual, Low-Noise Preamplifier (LNP), plus low-noise Variable Gain Amplifier (VGA). The combination of Active Termination (AT) and Maximum Gain Select (MGS) allow for the best noise performance. The VCA2613 also features low crosstalk and outstanding distortion performance.

The LNP has differential input and output capability and is strappable for gains of 5dB, 17dB, 22dB or 25dB. Low input impedance is achieved by AT, resulting in as much as a 4.6dB improvement in noise figure over conventional shunt termination. The termination value can also be switched to accommodate different sources. The output of the LNP is available for external signal processing.

The variable gain is controlled by an analog voltage whose gain varies from 0dB to the gain set by the MGS. The ability to program the variable gain also allows the user to optimize dynamic range. The VCA input can be switched from the LNP to external circuits for different applications. The output can be used in either a single-ended or differential mode to drive high-performance Analog-to-Digital (A/D) converters, and is cleanly limited for optimum overdrive recovery.

The combination of low noise, gain, and gain range programmability makes the VCA2613 a versatile building block in a number of applications where noise performance is critical. The VCA2613 is available in a TQFP-48 package.
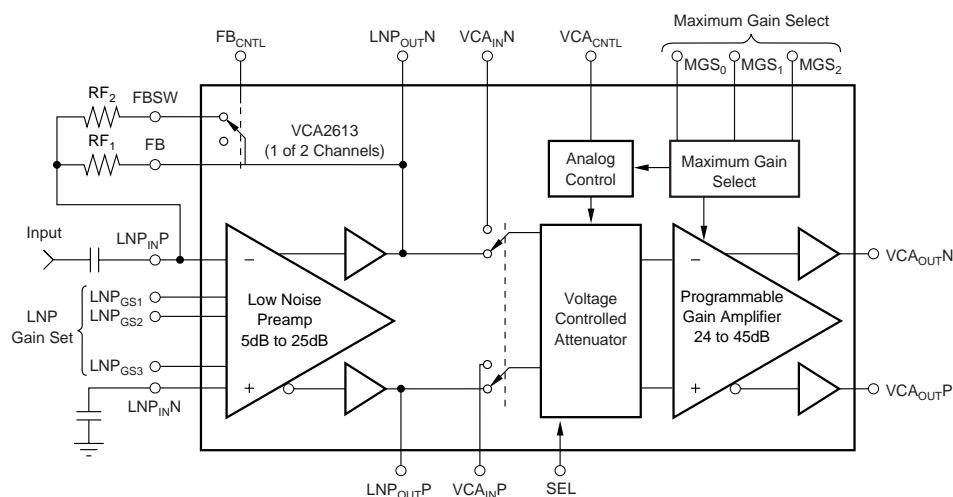
TEXAS INSTRUMENTS
www.ti.com

ABSOLUTE MAXIMUM RATINGS

Power Supply (+V$_S$) .... +6V
Analog Input .... −0.3V to (+V$_S$ + 0.3V)
Logic Input .... −0.3V to (+V$_S$ + 0.3V)
Case Temperature .... +100°C
Junction Temperature .... +150°C
Storage Temperature .... −40°C to +150°C

PACKAGE/ORDERING INFORMATION

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
VCA2613Y	TQFP-48	PFB	VCA2613	VCA2613Y/250	Tape and Reel, 250
"	"	"	"	VCA2613Y/2K	Tape and Reel, 2000

NOTE: (1) Models with a slash (/) are available only in Tape and Reel in the quantities indicated (e.g., /2K indicates per reel). Ordering 2000 pieces of "VCA2613Y/2K" will get a single 2000-piece Tape and Reel.
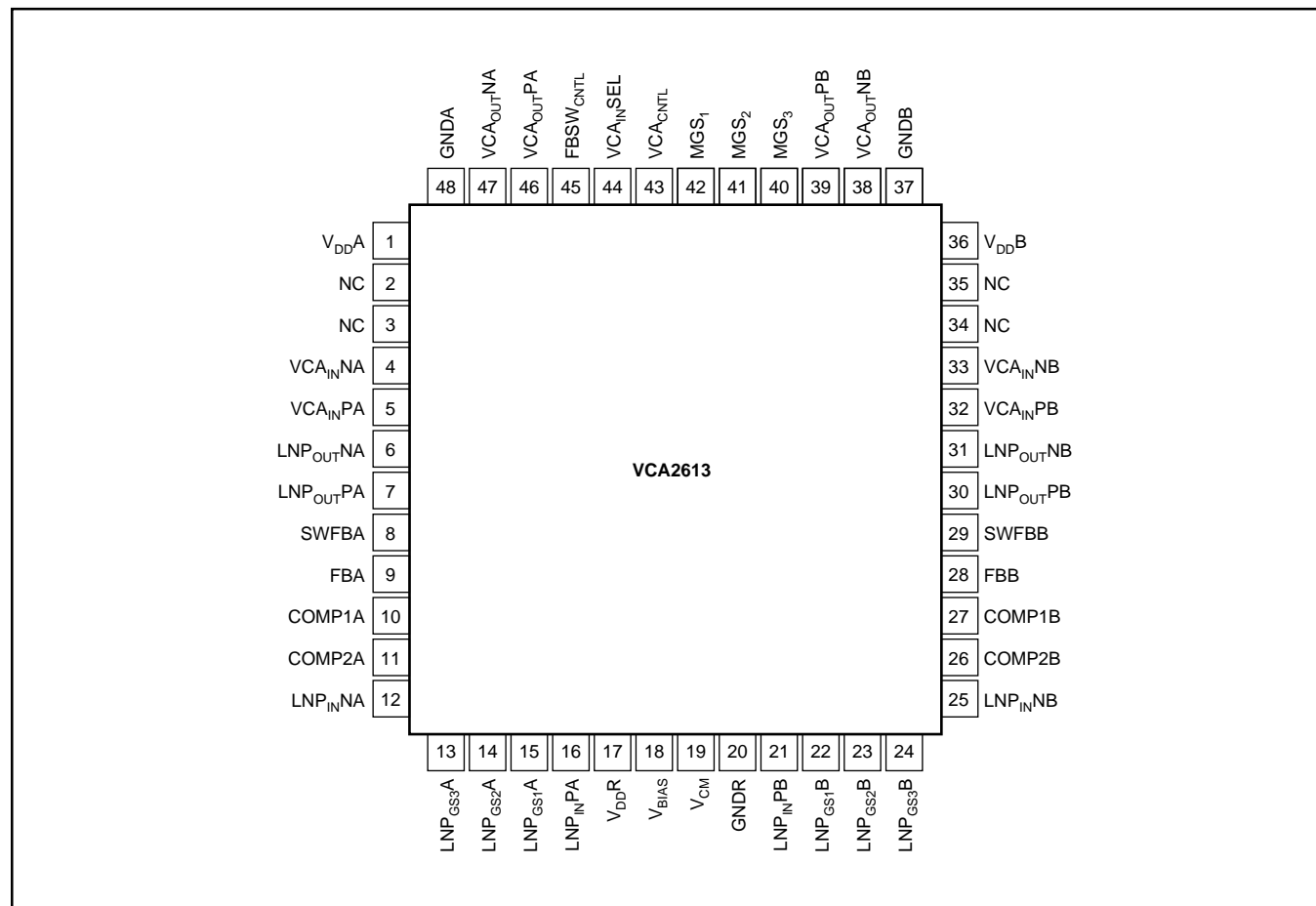
ELECTRICAL CHARACTERISTICS

At T$_A$ = +25°C, V$_{DDA}$ = V$_{DDB}$ = V$_{DDR}$ = +5V, load resistance = 500Ω on each output to ground, MGS = 011, LNP = 22dB and f$_{IN}$ = 5MHz, unless otherwise noted. The input to the preamp (LNP) is single-ended, and the output from the VCA is single-ended unless otherwise noted.

PARAMETER	CONDITIONS	VCA2613Y MIN	VCA2613Y TYP	VCA2613Y MAX	UNITS
PREAMPLIFIER					
Input Resistance			600		kΩ
Input Capacitance			15		pF
Input Bias Current			1		nA
CMRR	f = 1MHz, VCA$_{CNTL}$ = 0.2V		50		dB
Maximum Input Voltage	Preamp Gain = +5dB		1		Vp-p
	Preamp Gain = +25dB		112		mVp-p
Input Voltage Noise[1]	Preamp Gain = +5dB		3.5		nV/√Hz
	Preamp Gain = +25dB		1.0		nV/√Hz
Input Current Noise	Independent of Gain		0.35		pA/√Hz
Noise Figure, R$_S$ = 75Ω, R$_{IN}$ = 75Ω[1]	R$_F$ = 550Ω, Preamp Gain = 22dB, PGA Gain = 39dB		6.2		dB
Bandwidth	Gain = 22dB		80		MHz
PROGRAMMABLE VARIABLE GAIN AMPLIFIER					
Peak Input Voltage	Differential		2		Vp-p
−3dB Bandwidth			40		MHz
Slew Rate			300		V/µs
Output Signal Range	R$_L$ ≥ 500Ω Each Side to Ground		2		Vp-p
Output Impedance	f = 5MHz		1		Ω
Output Short-Circuit Current			±40		mA
Third Harmonic Distortion	f = 5MHz, V$_{OUT}$ = 1Vp-p, VCA$_{CNTL}$ = 3.0V	−45	−71		dBc
Second Harmonic Distortion	f = 5MHz, V$_{OUT}$ = 1Vp-p, VCA$_{CNTL}$ = 3.0V	−45	−63		dBc
IMD, Two-Tone	V$_{OUT}$ = 2Vp-p, f = 1MHz		−80		dBc
	V$_{OUT}$ = 2Vp-p, f = 10MHz		−80		dBc
1dB Compression Point	f = 5MHz, Output Referred, Differential		6		Vp-p
Crosstalk	V$_{OUT}$ = 1Vp-p, f = 1MHz, Max Gain Both Channels		−68		dB
Group Delay Variation	1MHz < f < 10MHz, Full Gain Range		±2		ns
DC Output Level, V$_{IN}$ = 0			2.5		V
ACCURACY					
Gain Slope			10.9		dB/V
Gain Error				±1[2]	dB
Output Offset Voltage			±50		mV
GAIN CONTROL INTERFACE					
Input Voltage (VCA$_{CNTL}$) Range			0.2 to 3.0		V
Input Resistance			1		MΩ
Response Time	45dB Gain Change, MGS = 111		0.2		µs
POWER SUPPLY					
Operating Temperature Range		−40		+85	°C
Specified Operating Range		4.75	5.0	5.25	V
Power Dissipation	Operating, Both Channels		410	495	mW

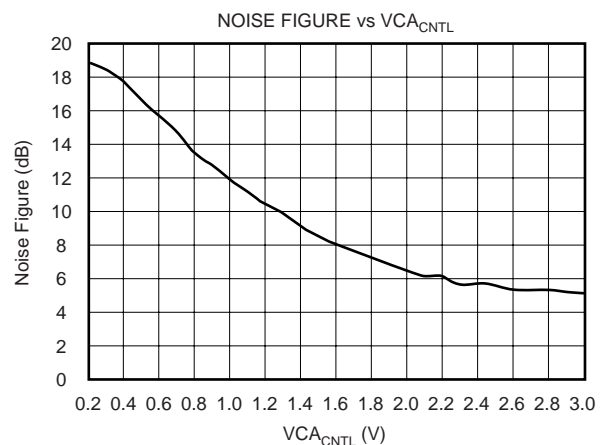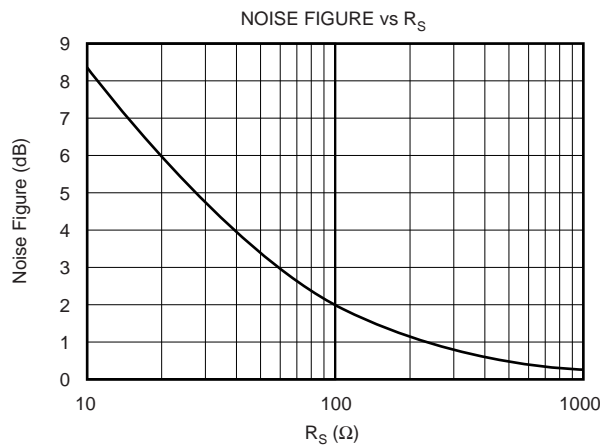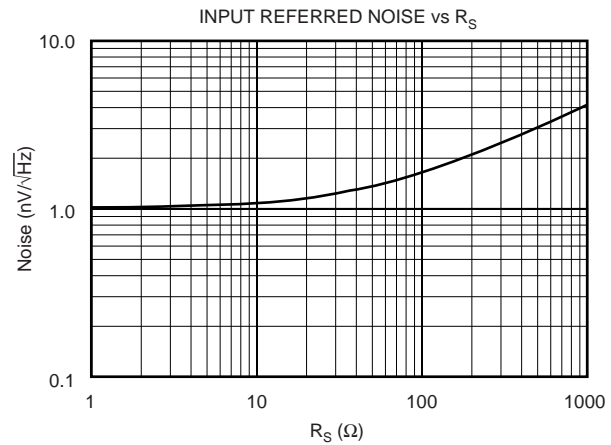NOTE: (1) For preamp driving VGA. (2) Referenced to best fit dB-linear curve.

TEXAS INSTRUMENTS
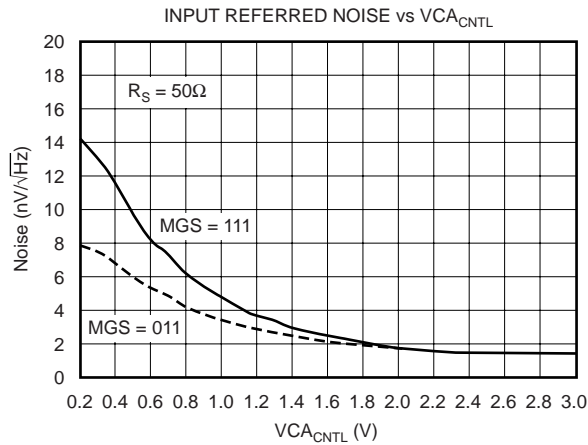www.ti.com

VCA2613
SBOS179B

PIN CONFIGURATION

Top pins (left to right, 48–37): GNDA (48), VCA$_{OUT}$NA (47), VCA$_{OUT}$PA (46), FBSW$_{CNTL}$ (45), VCA$_{IN}$SEL (44), VCA$_{CNTL}$ (43), MGS$_1$ (42), MGS$_2$ (41), MGS$_3$ (40), VCA$_{OUT}$PB (39), VCA$_{OUT}$NB (38), GNDB (37)

Left pins (top to bottom, 1–12): V$_{DD}$A (1), NC (2), NC (3), VCA$_{IN}$NA (4), VCA$_{IN}$PA (5), LNP$_{OUT}$NA (6), LNP$_{OUT}$PA (7), SWFBA (8), FBA (9), COMP1A (10), COMP2A (11), LNP$_{IN}$NA (12)

Right pins (top to bottom, 36–25): V$_{DD}$B (36), NC (35), NC (34), VCA$_{IN}$NB (33), VCA$_{IN}$PB (32), LNP$_{OUT}$NB (31), LNP$_{OUT}$PB (30), SWFBB (29), FBB (28), COMP1B (27), COMP2B (26), LNP$_{IN}$NB (25)

Bottom pins (left to right, 13–24): LNP$_{GS3}$A (13), LNP$_{GS2}$A (14), LNP$_{GS1}$A (15), LNP$_{IN}$PA (16), V$_{DD}$R (17), V$_{BIAS}$ (18), V$_{CM}$ (19), GNDR (20), LNP$_{IN}$PB (21), LNP$_{GS1}$B (22), LNP$_{GS2}$B (23), LNP$_{GS3}$B (24)

Center: **VCA2613**

PIN DESCRIPTIONS

PIN	DESIGNATOR	DESCRIPTION	PIN	DESIGNATOR	DESCRIPTION
1	V$_{DD}$A	Channel A +Supply	25	LNP$_{IN}$NB	Channel B LNP Inverting Input
2	NC	Do Not Connect	26	COMP2B	Channel B Frequency Compensation 2
3	NC	Do Not Connect	27	COMP1B	Channel B Frequency Compensation 1
4	VCA$_{IN}$NA	Channel A VCA Negative Input	28	FBB	Channel B Feedback Output
5	VCA$_{IN}$PA	Channel A VCA Positive Input	29	SWFBB	Channel B Switched Feedback Output
6	LNP$_{OUT}$NA	Channel A LNP Negative Output	30	LNP$_{OUT}$PB	Channel B LNP Positive Output
7	LNP$_{OUT}$PA	Channel A LNP Positive Output	31	LNP$_{OUT}$NB	Channel B LNP Negative Output
8	SWFBA	Channel A Switched Feedback Output	32	VCA$_{IN}$PB	Channel B VCA Positive Input
9	FBA	Channel A Feedback Output	33	VCA$_{IN}$NB	Channel B VCA Negative Input
10	COMP1A	Channel A Frequency Compensation 1	34	NC	Do Not Connect
11	COMP2A	Channel A Frequency Compensation 2	35	NC	Do Not Connect
12	LNP$_{IN}$NA	Channel A LNP Inverting Input	36	V$_{DD}$B	Channel B +Analog Supply
13	LNP$_{GS3}$A	Channel A LNP Gain Strap 3	37	GNDB	Channel B Analog Ground
14	LNP$_{GS2}$A	Channel A LNP Gain Strap 2	38	VCA$_{OUT}$NB	Channel B VCA Negative Output
15	LNP$_{GS1}$A	Channel A LNP Gain Strap 1	39	VCA$_{OUT}$PB	Channel B VCA Positive Output
16	LNP$_{IN}$PA	Channel A LNP Noninverting Input	40	MGS$_3$	Maximum Gain Select 3 (LSB)
17	V$_{DD}$R	+Supply for Internal Reference	41	MGS$_2$	Maximum Gain Select 2
18	V$_{BIAS}$	0.01µF Bypass to Ground	42	MGS$_1$	Maximum Gain Select 1 (MSB)
19	V$_{CM}$	0.01µF Bypass to Ground	43	VCA$_{CNTL}$	VCA Control Voltage
20	GNDR	Ground for Internal Reference	44	VCA$_{IN}$SEL	VCA Input Select, HI = External
21	LNP$_{IN}$PB	Channel B LNP Noninverting Input	45	FBSW$_{CNTL}$	Feedback Switch Control: HI = ON
22	LNP$_{GS1}$B	Channel B LNP Gain Strap 1	46	VCA$_{OUT}$PA	Channel A VCA Positive Output
23	LNP$_{GS2}$B	Channel B LNP Gain Strap 2	47	VCA$_{OUT}$NA	Channel A VCA Negative Output
24	LNP$_{GS3}$B	Channel B LNP Gain Strap 3	48	GNDA	Channel A Analog Ground

VCA2613

SBOS179B

TEXAS INSTRUMENTS
www.ti.com

3

TYPICAL PERFORMANCE CURVES

At T_A = +25°C, V_{DDA} = V_{DDB} = V_{DDR} = +5V, load resistance = 500Ω on each output to ground, MGS = 011, LNP = 22dB and f_{IN} = 5MHz, unless otherwise noted. The input to the preamp (LNP) is single-ended, and the output from the VCA is single-ended unless otherwise noted. This results in a 6dB reduction in signal amplitude compared to differential operation.

GAIN vs VCA_CNTL

MGS = 111
MGS = 110
MGS = 101
MGS = 100
MGS = 011
MGS = 010
MGS = 001
MGS = 000

Gain (dB)
VCA_{CNTL} (V)

OUTPUT REFERRED NOISE vs VCA_CNTL

R_S = 50Ω
MGS = 111
MGS = 011

Noise (nV/√Hz)
VCA_{CNTL} (V)

INPUT REFERRED NOISE vs VCA_CNTL

R_S = 50Ω
MGS = 111
MGS = 011

Noise (nV/√Hz)
VCA_{CNTL} (V)

INPUT REFERRED NOISE vs R_S

Noise (nV/√Hz)
R_S (Ω)

NOISE FIGURE vs R_S

Noise Figure (dB)
R_S (Ω)

NOISE FIGURE vs VCA_CNTL

Noise Figure (dB)
VCA_{CNTL} (V)

TEXAS INSTRUMENTS
www.ti.com

4

VCA2613
SBOS179B

THEORY OF OPERATION

The VCA2613 is a dual-channel system consisting of three primary blocks: a Low Noise Preamplifier (LNP), a Voltage Controlled Attenuator (VCA), and a Programmable Gain Amplifier (PGA). For greater system flexibility, an onboard multiplexer is provided for the VCA inputs, selecting either the LNP outputs or external signal inputs. Figure 1 shows a simplified block diagram of the dual-channel system.
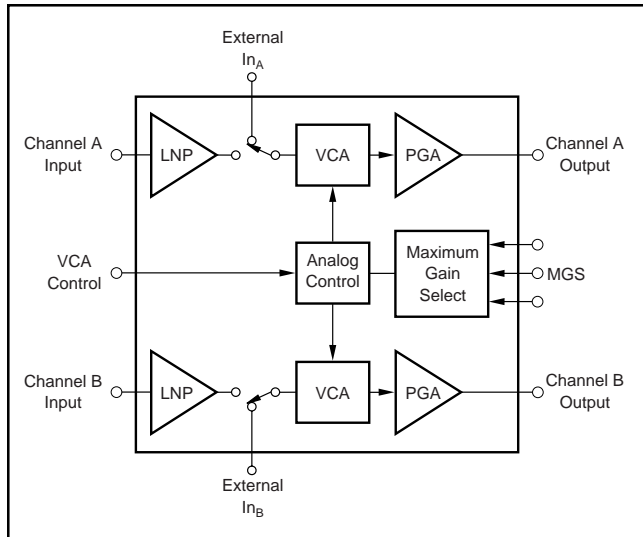

FIGURE 1. Simplified Block Diagram of the VCA2613.

LNP—OVERVIEW

The LNP input may be connected to provide active-feedback signal termination, achieving lower system noise performance than conventional passive shunt termination. Even lower noise performance is obtained if signal termination is not required. The unterminated LNP input impedance is 600kΩ. The LNP can process fully differential or single-ended signals in each channel. Differential signal processing results in significantly reduced 2nd-harmonic distortion and improved rejection of common-mode and power-supply noise. The first gain stage of the LNP is AC coupled into its output buffer with a 44μs time constant (3.6kHz high-pass characteristic). The buffered LNP outputs are designed to drive the succeeding VCA directly or, if desired, external loads as low as 135Ω with minimal impact on signal distortion. The LNP employs very low impedance local feedback to achieve stable gain with the lowest possible noise and distortion. Four pin-programmable gain settings are available: 5dB, 17dB, 22dB, and 25dB. Additional intermediate gains can be programmed by adding trim resistors between the Gain Strap programming pins.

The common-mode DC level at the LNP output is nominally 2.5V, matching the input common-mode requirement of the VCA for simple direct coupling. When external signals are fed to the VCA, they should also be set up with a 2.5VDC common-mode level. Figure 2 shows a circuit that demonstrates the recommended coupling method using an external

op amp. The "V_{CM}" node shown in the drawing is the V_{CM} output (pin 19). Typical R and C values are shown, yielding a high-pass time constant similar to that of the LNP. If a different common-mode referencing method is used, it is important that the common-mode level be within 10mV of the V_{CM} output for proper operation.
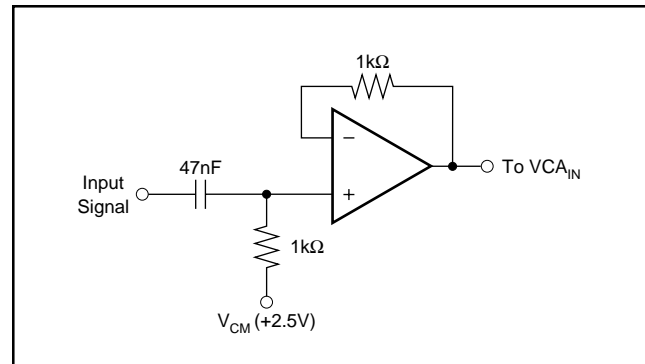

FIGURE 2. Recommended Circuit for Coupling an External Signal into the VCA Inputs.

VCA—OVERVIEW

The magnitude of the differential VCA input signal (from the LNP or an external source) is reduced by a programmable attenuation factor, set by the analog VCA Control Voltage (VCA_{CNTL}) at pin 43. The maximum attenuation factor is further programmable by using the three MGS bits (pins 40-42). Figure 3 illustrates this dual-adjustable characteristic. Internally, the signal is attenuated by having the analog VCA_{CNTL} vary the channel resistance of a set of shunt-connected FET transistors. The MGS bits effectively adjust the overall size of the shunt FET by switching parallel components in or out under logic control. At any given maximum gain setting, the analog variable gain characteristic is linear in dB as a function of the control voltage, and is created as a piecewise approximation of an ideal dB-linear transfer function. The VCA gain control circuitry is common to both channels of the VCA2613.
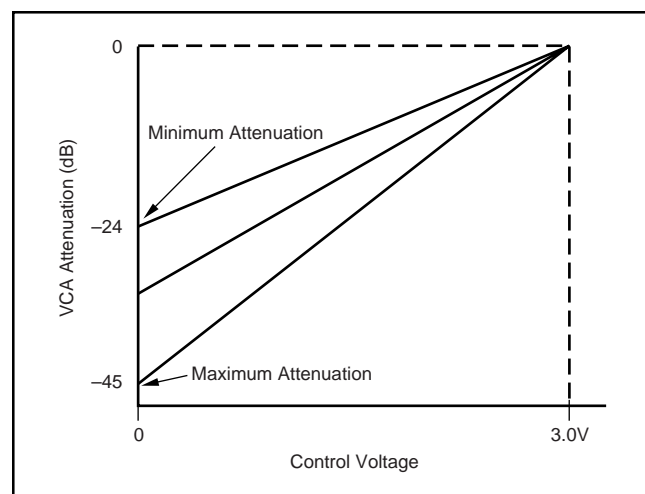

FIGURE 3. Swept Attenuator Characteristic.

PGA OVERVIEW AND OVERALL DEVICE CHARACTERISTICS

The differential output of the VCA attenuator is then amplified by the PGA circuit block. This post-amplifier is programmed by the same MGS bits that control the VCA attenuator, yielding an overall swept-gain amplifier characteristic in which the VCA • PGA gain varies from 0dB (unity) to a programmable peak gain of 24, 27, 30, 33, 36, 39, 42, or 45dB.

The "GAIN vs VCA$_{CNTL}$" curve in the typical characteristics shows the composite gain control characteristic of the entire VCA2613. Setting VCA$_{CNTL}$ to 3.0V causes the digital MGS gain control to step in 3dB increments. Setting VCA$_{CNTL}$ to 0V causes all the MGS-controlled gain curves to converge at one point. The gain at the convergence point is the LNP gain less 6dB, because the measurement setup looks at only one side of the differential PGA output, resulting in 6dB lower signal amplitude.

ADDITIONAL FEATURES—OVERVIEW

Overload protection stages are placed between the attenuator and the PGA, providing a symmetrically clipped output whenever the input becomes large enough to overload the PGA. A comparator senses the overload signal amplitude and substitutes a fixed DC level to prevent undesirable overload recovery effects. As with the previous stages, the VCA is AC coupled into the PGA. In this case, the coupling time constant varies from 5μs at the highest gain (45dB) to 59μs at the lowest gain (25dB).

The VCA2613 includes a built-in reference, common to both channels, to supply a regulated voltage for critical areas of the circuit. This reduces the susceptibility to power supply variation, ripple, and noise. In addition, separate power supply and ground connections are provided for each channel and for the reference circuitry, further reducing interchannel cross-talk.

Further details regarding the design, operation and use of each circuit block are provided in the following sections.

LOW NOISE PREAMPLIFIER (LNP)—DETAIL

The LNP is designed to achieve a low noise figure, especially when employing active termination. Figure 4 is a simplified schematic of the LNP, illustrating the differential input and output capability. The input stage employs low resistance local feedback to achieve stable low noise, low distortion performance with very high input impedance. Normally, low noise circuits exhibit high power consumption due to the large bias currents required in both input and output stages. The LNP uses a patented technique that combines the input and output stages such that they share the same bias current. Transistors Q_4 and Q_5 amplify the signal at the gate-source input of Q_4, the +IN side of the LNP. The signal is further amplified by the Q_1 and Q_2 stage, and then by the final Q_3 and R_L gain stage, which uses the same bias current as the input devices Q_4 and Q_5. Devices Q6 through Q_{10} play the same role for signals on the –IN side.

The differential gain of the LNP is given in Equation (1):

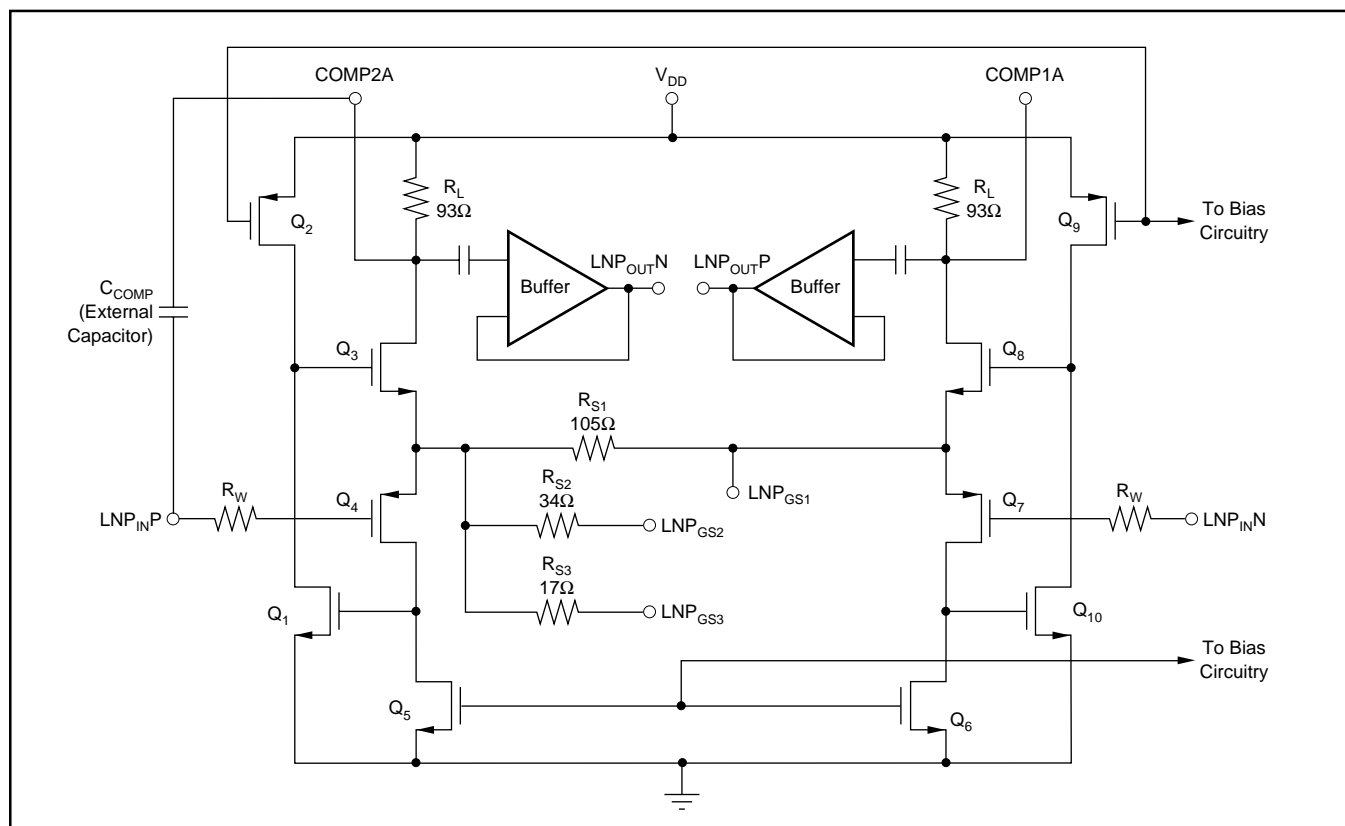$$\text{Gain} = 2 \bullet \left[\frac{R_L}{R_S} \right] \qquad (1)$$

FIGURE 4. Schematic of the Low Noise Preamplifier (LNP).

TEXAS INSTRUMENTS
www.ti.com

VCA2613
SBOS179B

where R_L is the load resistor in the drains of Q_3 and Q_8, and R_S is the resistor connected between the sources of the input transistors Q_4 and Q_7. The connections for various R_S combinations are brought out to device pins LNPG$_{S1}$, LNPG$_{S2}$, and LNPG$_{S3}$ (pins 13-15 for channel A, 22-24 for channel B). These Gain Strap pins allow the user to establish one of four fixed LNP gain options as shown in Table I.

LNP PIN STRAPPING	LNP GAIN (dB)
LNPG$_{S1}$, LNPG$_{S2}$, LNPG$_{S3}$ Connected Together	25
LNPG$_{S1}$ Connected to LNPG$_{S3}$	22
LNPG$_{S1}$ Connected to LNPG$_{S2}$	17
All Pins Open	5

TABLE I. Pin Strappings of the LNP for Various Gains.

It is also possible to create other gain settings by connecting an external resistor between LNPG$_{S1}$ on one side, and LNPG$_{S2}$ and/or LNPG$_{S3}$ on the other. In that case, the internal resistor values shown in Figure 4 should be combined with the external resistor to calculate the effective value of R_S for use in Equation (1). The resulting expression for external resistor value is given in Equation (2).

$$R_{EXT} = \frac{2R_{S1}R_L + 2R_{FIX}R_L - Gain \bullet R_{S1}R_{FIX}}{Gain \bullet R_{S1} - 2R_L} \qquad (2)$$

where R_{EXT} is the externally selected resistor value needed to achieve the desired gain setting, R_{S1} is the fixed parallel resistor in Figure 4, and R_{FIX} is the effective fixed value of the remaining internal resistors: R_{S2}, R_{S3}, or ($R_{S2} \| R_{S3}$) depending on the pin connections.

Note that the best process and temperature stability will be achieved by using the pre-programmed fixed gain options of Table I, since the gain is then set entirely by internal resistor ratios, which are typically accurate to ±0.5%, and track quite well over process and temperature. When combining external resistors with the internal values to create an effective R_S value, note that the internal resistors have a typical temperature coefficient of +700ppm/°C and an absolute value tolerance of approximately ±5%, yielding somewhat less predictable and stable gain settings. With or without external resistors, the board layout should use short Gain Strap connections to minimize parasitic resistance and inductance effects.

The overall noise performance of the VCA2613 will vary as a function of gain. Table II shows the typical input-and output-referred noise densities of the entire VCA2613 for maximum VCA and PGA gain; i.e., VCA$_{CNTL}$ set to 3.0V and all MGS bits set to "1". Note that the input-referred noise values include the contribution of a 50Ω fixed source impedance, and are therefore somewhat larger than the intrinsic input noise. As the LNP gain is reduced, the noise contribution from the VCA/PGA portion becomes more significant, resulting in higher input-referred noise. However, the output-referred noise, which is indicative of the overall SNR at that gain setting, is reduced.

To preserve the low noise performance of the LNP, the user should take care to minimize resistance in the input lead. A parasitic resistance of only 10Ω will contribute 0.4nV/√Hz.

LNP GAIN (dB)	NOISE (nV/√Hz)	
	Input-Referred	Output-Referred
25	1.54	2260
22	1.59	1650
17	1.82	1060
5	4.07	597

TABLE II. Noise Performance for MGS = 111 and VCA$_{CNTL}$ = 3.0V.

The LNP is capable of generating a 2Vp-p differential signal. The maximum signal at the LNP input is therefore 2Vp-p divided by the LNP gain. An input signal greater than this would exceed the linear range of the LNP, an especially important consideration at low LNP gain settings.

ACTIVE FEEDBACK WITH THE LNP

One of the key features of the LNP architecture is the ability to employ active-feedback termination to achieve superior noise performance. Active feedback termination achieves a lower noise figure than conventional shunt termination, essentially because no signal current is wasted in the termination resistor itself. Another way to understand this is as follows: Consider first that the input source, at the far end of the signal cable has a cable-matching source resistance of R_S. Using conventional shunt termination at the LNP input, a second terminating resistor of value R_S is connected to ground. Therefore, the signal loss is 6dB due to the voltage divider action of the series and shunt R_S resistors. The effective source resistance has been reduced by the same factor of 2, but the noise contribution has been reduced by only the $\sqrt{2}$, only a 3dB reduction. Therefore, the net theoretical SNR degradation is 3dB, assuming a noise-free amplifier input. (In practice, the amplifier noise contribution will degrade both the unterminated and the terminated noise figures, somewhat reducing the distinction between them.)

See Figure 5 for an amplifier using active feedback. This diagram appears very similar to a traditional inverting amplifier. However, the analysis is somewhat different because the gain "A" in this case is not a very large open-loop op amp gain; rather it is the relatively low and controlled gain of the LNP itself. Thus, the impedance at the inverting amplifier terminal will be reduced by a finite amount, as given in the familiar relationship of Equation (3):

$$R_{IN} = \frac{R_F}{(1 + A)} \qquad (3)$$

where R_F is the feedback resistor (supplied externally between the LNP$_{IN}$P and FB terminals for each channel), A is the user-selected gain of the LNP, and R_{IN} is the resulting amplifier input impedance with active feedback. In this case, unlike the conventional termination above, both the signal voltage and the R_S noise are attenuated by the same factor of
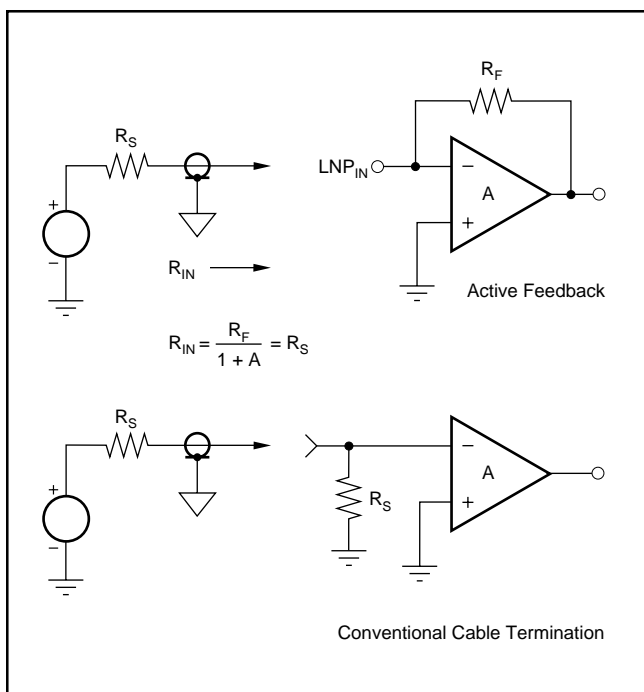

VCA2613
SBOS179B

TEXAS
INSTRUMENTS
www.ti.com

7

FIGURE 5. Configurations for Active Feedback and Conventional Cable Termination.

two (6dB) before being re-amplified by the "A" gain setting. This avoids the extra 3dB degradation due to the square-root effect described above, the key advantage of the active termination technique.

As mentioned above, the previous explanation ignored the input noise contribution of the LNP itself. Also, the noise contribution of the feedback resistor must be included for a completely correct analysis. The curves given in Figures 6 and 7 allow the VCA2613 user to compare the achievable noise figure for active and conventional termination methods. The left-most set of data points in each graph give the results for typical 50Ω cable termination, showing the worst noise figure but also the greatest advantage of the active feedback method.
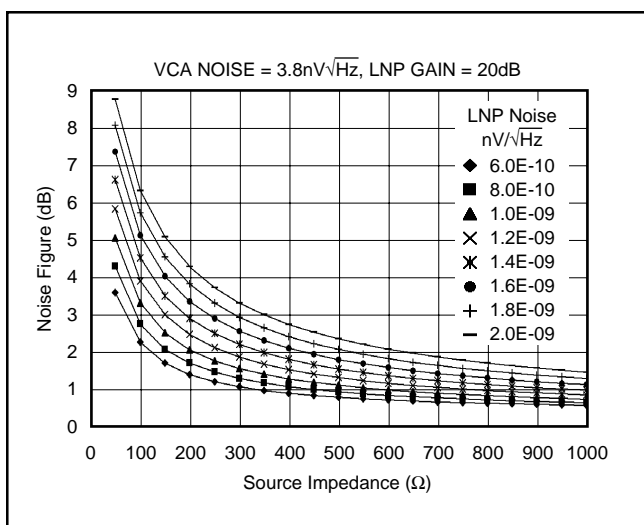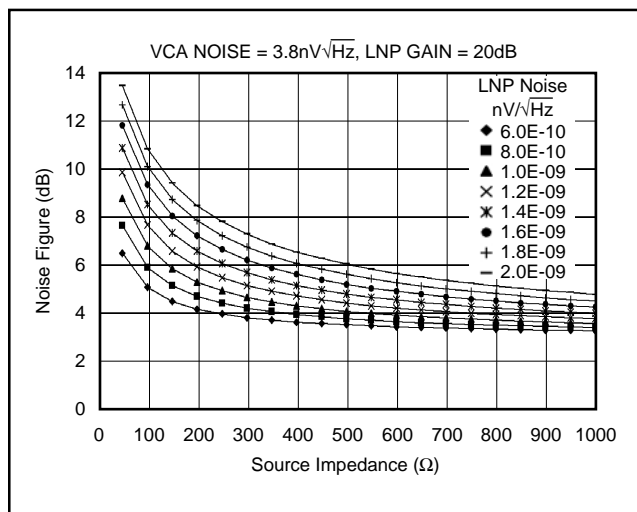

FIGURE 7. Noise Figure for Conventional Termination.

A switch, controlled by the $FBSW_{CNTL}$ signal on pin 45, enables the user to reduce the feedback resistance by adding an additional parallel component, connected between the $LNP_{IN}P$ and SWFB terminals. The two different values of feedback resistance will result in two different values of active-feedback input resistance. Thus, the active-feedback impedance can be optimized at two different LNP gain settings. The switch is connected at the buffered output of the LNP and has an "ON" resistance of approximately 1Ω.

When employing active feedback, the user should be careful to avoid low-frequency instability or overload problems. Figure 8 illustrates the various low-frequency time constants. Referring again to the input resistance calculation of Equation (3), and considering that the gain term "A" falls off below 3.6kHz, it is evident that the effective LNP input impedance will rise below 3.6kHz, with a DC limit of approximately R_F. To avoid interaction with the feedback pole/zero at low frequencies, and to avoid the higher signal levels resulting from the rising impedance characteristic, it is recommended that the external $R_F C_C$ time constant be set to about 5µs.
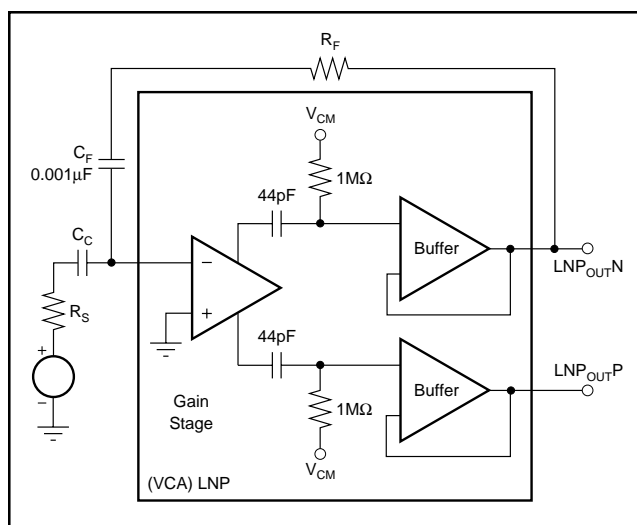

FIGURE 6. Noise Figure for Active Termination.

FIGURE 8. Low Frequency LNP Time Constants.

VCA2613

SBOS179B

Achieving the best active feedback architecture is difficult with conventional op amp circuit structures. The overall gain "A" must be negative in order to close the feedback loop, the input impedance must be high to maintain low current noise and good gain accuracy, but the gain ratio must be set with very low value resistors to maintain good voltage noise. Using a two-amplifier configuration (noninverting for high impedance plus inverting for negative feedback reasons) results in excessive phase lag and stability problems when the loop is closed. The VCA2613 uses a patented architecture that achieves these requirements, with the additional benefits of low power dissipation and differential signal handling at both input and output.

For greatest flexibility and lowest noise, the user may wish to shape the frequency response of the LNP. The COMP1 and COMP2 pins for each channel (pins 10 and 11 for channel A, pins 26 and 27 for channel B) correspond to the drains of Q_3 and Q_8, see Figure 4. A capacitor placed between these pins will create a single-pole low-pass response, in which the effective "R" of the "RC" time constant is approximately 186Ω.

COMPENSATION WHEN USING ACTIVE FEEDBACK

The typical open-loop gain versus frequency characteristic for the LNP is shown in Figure 9. The –3dB bandwidth is approximately 180MHz and the phase response is such that when feedback is applied the LNP will exhibit a peaked response or might even oscillate. One method for compensating for this undesirable behavior is to place a compensation capacitor at the input to the LNP, as shown in Figure 10. This method is effective when the desired –3dB bandwidth is much less than the open-loop bandwidth of the LNP. This compensation technique also allows the total compensation capacitor to include any stray or cable capacitance that is
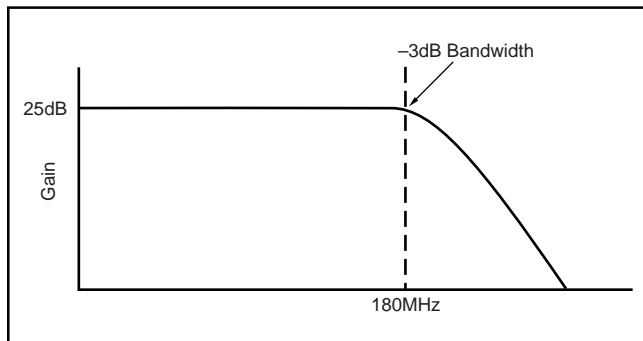

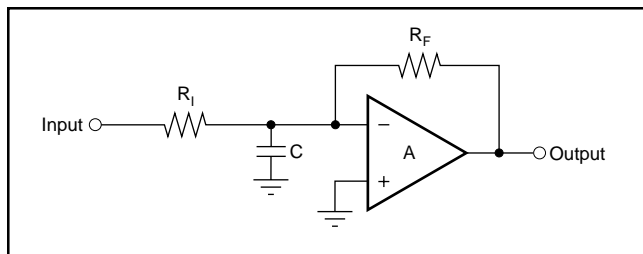FIGURE 9. Open-loop Gain Characteristic of LNP.

FIGURE 10. LNP with Compensation Capacitor.

associated with the input connection. Equation 4 relates the bandwidth to the various impedances that are connected to the LNP.

$$BW = \frac{(A+1)R_I + R_F}{2\pi C(R_I)(R_F)} \qquad (4)$$

AVOIDING UNSTABLE PERFORMANCE

The VCA2612 and the VCA2613 are very similar in performance in all respects, except in the area of noise performance. See Figure 4 for a schematic of the LNP. The improvement in noise performance is because the input wiring resistor (R_W) of the VCA2613, see Figure 4, has been considerably reduced compared to the VCA2612. This brings the input noise of the VCA2613 down to $1.0nV/\sqrt{Hz}$ compared to VCA2612's $1.25nV/\sqrt{Hz}$. The input impedance at the gate of either Q_4 or Q_7 can be approximated by the network shown in Figure 11. The resistive component shown in Figure 11 is negative, which gives rise to unstable behavior when the signal source resistance has both inductive and capacitive elements. It should be noted that this negative resistance is not a physical resistor, but an equivalent resistance that is a function of the devices shown in Figure 4. Normally, when an inductor and capacitor are placed in series or parallel, there is a positive resistance in the loop that prevents unstable behavior.
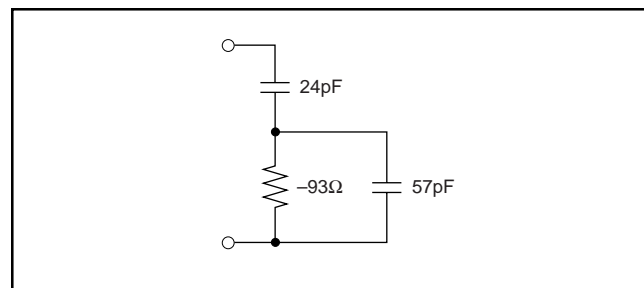

FIGURE 11. VCA2613 Input Impedance.

For the VCA2613, the situation can be remedied by placing an external resistor with a value of approximately 15Ω or higher in series with the input lead. The net series resistance will be positive, and there will be no observed instability. Although this technique will prevent oscillations, it is not recommended, as it will also increase the input noise. The preferred technique is to place an external capacitor between pins COMP2A (pin 11) and $LNP_{IN}PA$ (pin 16), and between pins COMP2B (pin 26) and $LNP_{IN}PB$ (pin 21). This has the effect of making the input impedance always capacitive due to the feedback effect of the compensation capacitor and the gain of the LNP. Using capacitive feedback, the LNP becomes unconditionally stable, as there is no longer a negative component to the input impedance. The compensation capacitor mentioned above will be reflected to the input by the formula:

$$C_{IN} = (A + 1)C_{COMP} \qquad (5)$$

VCA2613
SBOS179B

TEXAS
INSTRUMENTS
www.ti.com

9

The capacitance that is determined in Equation 5 should be added to the capacitance shown in Equation 4 to determine the overall bandwidth of the LNP. The $LNP_{IN}NA$ (pin 12) and the $LNP_{IN}NB$ (pin 25) should be bypassed to ground by the shortest means possible to avoid any inductance in the lead.

LNP OUTPUT BUFFER

The differential LNP output is buffered by wideband class AB voltage followers which are designed to drive low impedance loads. This is necessary to maintain LNP gain accuracy, since the VCA input exhibits gain-dependent input impedance. The buffers are also useful when the LNP output is brought out to drive external filters or other signal processing circuitry. Good distortion performance is maintained with buffer loads as low as 135Ω. As mentioned previously, the buffer inputs are AC coupled to the LNP outputs with a 3.6kHz high-pass characteristic, and the DC common mode level is maintained at the correct V_{CM} for compatibility with the VCA input.

VOLTAGE-CONTROLLED ATTENUATOR (VCA)—DETAIL

The VCA is designed to have a "dB-linear" attenuation characteristic, i.e. the gain loss in dB is constant for each equal increment of the VCA_{CNTL} control voltage. See Figure 1 for a block diagram of the VCA. The attenuator is essentially a variable voltage divider consisting of one series input resistor, R_S, and ten identical shunt FETs, placed in parallel and controlled by sequentially activated clipping amplifiers. Each clipping amplifier can be thought of as a specialized voltage comparator with a "soft" transfer characteristic and well-controlled output limit voltages. The reference voltages V1 through V10 are equally spaced over the 0V to 3.0V control voltage range. As the control voltage rises through the input range of each clipping amplifier, the amplifier output will rise from 0V (FET completely "ON") to $V_{CM} - V_T$ (FET nearly "OFF"), where V_{CM} is the common source voltage and V_T is the threshold voltage of the FET. As each FET approaches its "OFF" state and the control voltage continues to rise, the next clipping amplifier/FET combination takes over for the next portion of the piecewise-linear attenuation characteristic. Thus, low control voltages have most of the FETs turned "ON", while high control voltages have most turned "OFF". Each FET acts to decrease the shunt resistance of the voltage divider formed by R_S and the parallel FET network.

The attenuator is comprised of two sections, with five parallel clipping amplifier/FET combinations in each. Special reference circuitry is provided so that the $(V_{CM} - V_T)$ limit voltage will track temperature and IC process variations, minimizing the effects on the attenuator control characteristic.

In addition to the analog VCA_{CNTL} gain setting input, the attenuator architecture provides digitally programmable adjustment in eight steps, via the three Maximum Gain Setting (MGS) bits. These adjust the maximum achievable gain (corresponding to minimum attenuation in the VCA, with $VCA_{CNTL} = 3.0V$) in 3dB increments. This function is accomplished by providing multiple FET sub-elements for each of the Q_1 to Q_{10} FET shunt elements (see Figure 12). In the simplified diagram of Figure 13, each shunt FET is shown as two sub-elements, Q_{NA} and Q_{NB}. Selector switches, driven by the MGS bits, activate either or both of the sub-element FETs to adjust the maximum R_{ON} and thus achieve the stepped attenuation options.

The VCA can be used to process either differential or single-ended signals. Fully differential operation will reduce 2nd-harmonic distortion by about 10dB for full-scale signals.

Input impedance of the VCA will vary with gain setting, due to the changing resistances of the programmable voltage divider structure. At large attenuation factors (i.e., low gain settings), the impedance will approach the series resistor value of approximately 135Ω.

As with the LNP stage, the VCA output is AC coupled into the PGA. This means that the attenuation-dependent DC common-mode voltage will not propagate into the PGA, and so the PGA's DC output level will remain constant.

Finally, note that the VCA_{CNTL} input consists of FET gate inputs. This provides very high impedance and ensures that multiple VCA2613 devices may be connected in parallel with no significant loading effects. The nominal voltage range for the VCA_{CNTL} input spans from 0V to 3V. Over driving this input ($\leq 5V$) does not affect the performance.

OVERLOAD RECOVERY CIRCUITRY—DETAIL

With a maximum overall gain of 70dB, the VCA2613 is prone to signal overloading. Such a condition may occur in either the LNP or the PGA depending on the various gain and attenuation settings available. The LNP is designed to produce low-distortion outputs as large as 1Vp-p single-ended (2Vp-p differential). Therefore the maximum input signal for linear operation is 2Vp-p divided by the LNP differential gain setting. Clamping circuits in the LNP ensure that larger input amplitudes will exhibit symmetrical clipping and short recovery times. The VCA itself, being basically a voltage divider, is intrinsically free of overload conditions. However, the PGA post-amplifier is vulnerable to sudden overload, particularly at high gain settings. Rapid overload recovery is essential in many signal processing applications such as ultrasound imaging. A special comparator circuit is provided at the PGA input which detects overrange signals (detection level dependent on PGA gain setting). When the signal exceeds the comparator input
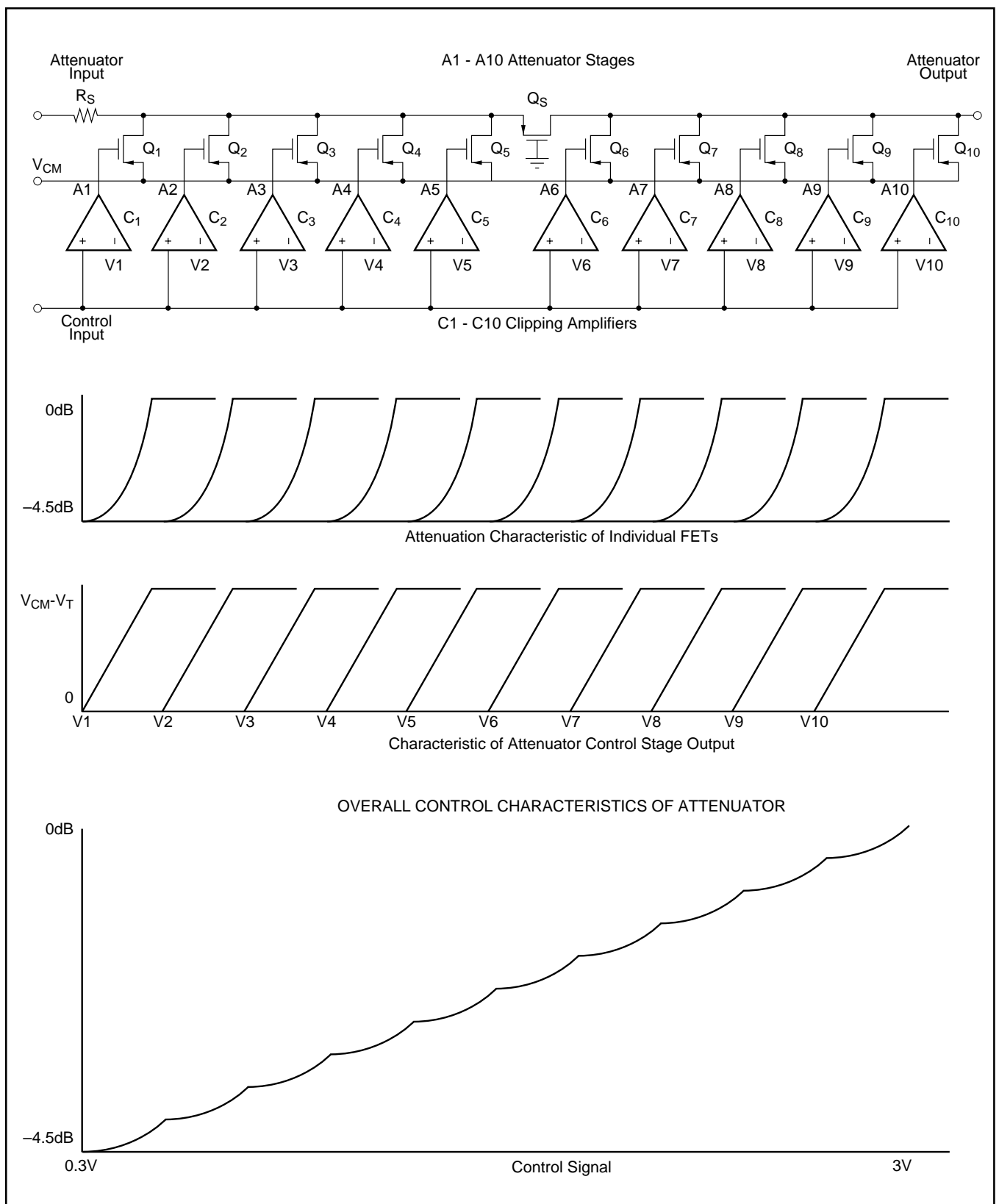
TEXAS INSTRUMENTS
www.ti.com

Attenuator
Input

A1 - A10 Attenuator Stages

Attenuator
Output

R_S

Q_S

Q_1 Q_2 Q_3 Q_4 Q_5 Q_6 Q_7 Q_8 Q_9 Q_{10}

V_{CM}

A1 C_1 A2 C_2 A3 C_3 A4 C_4 A5 C_5 A6 C_6 A7 C_7 A8 C_8 A9 C_9 A10 C_{10}

V1 V2 V3 V4 V5 V6 V7 V8 V9 V10

Control
Input

C1 - C10 Clipping Amplifiers

0dB

−4.5dB

Attenuation Characteristic of Individual FETs

$V_{CM}-V_T$

0

V1 V2 V3 V4 V5 V6 V7 V8 V9 V10

Characteristic of Attenuator Control Stage Output

OVERALL CONTROL CHARACTERISTICS OF ATTENUATOR

0dB

−4.5dB

0.3V Control Signal 3V

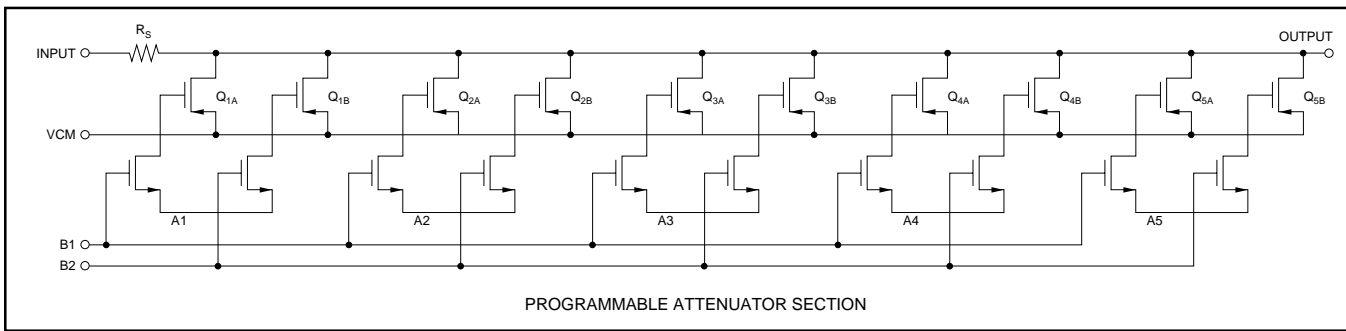FIGURE 12. Piecewise Approximation to Logarithmic Control Characteristics.

FIGURE 13. Programmable Attenuator Section.

threshold, the VCA output is blocked and an appropriate fixed DC level is substituted, providing fast and clean overload recovery. The basic architecture is shown in Figure 14. Both high and low overrange conditions are sensed and corrected by this circuit.
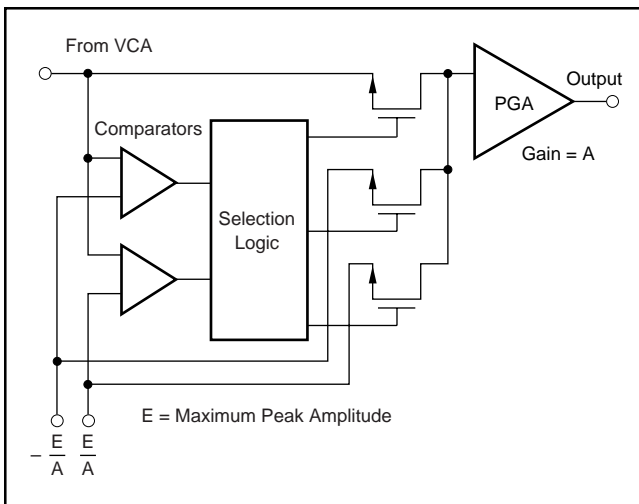

FIGURE 14. Overload Protection Circuitry.

Figures 15 and 16 show typical overload recovery waveforms with MGS = 100, for VCA + PGA minimum gain (0dB) and maximum gain (36dB), respectively. LNP gain is set to 25dB in both cases.
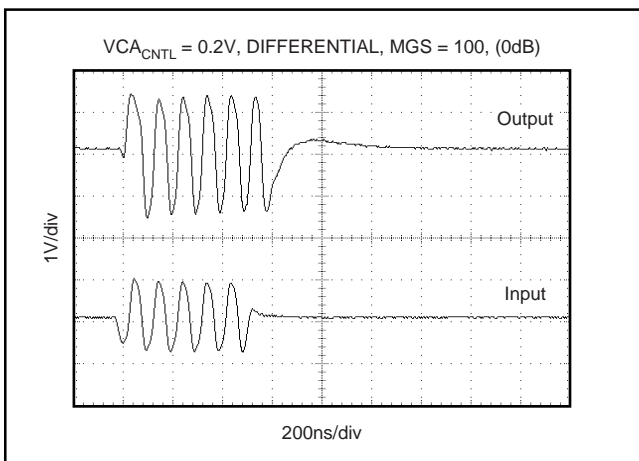

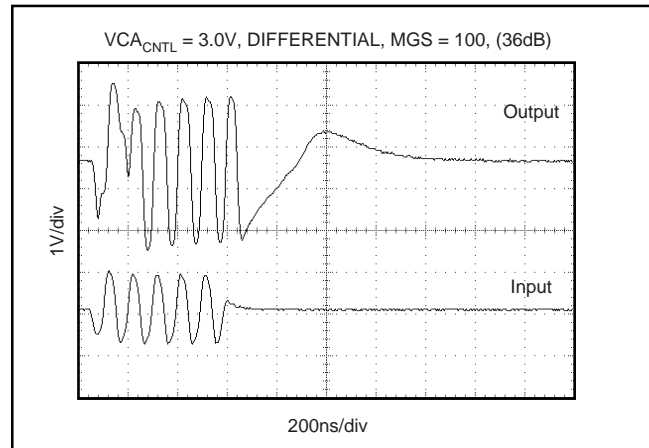FIGURE 15. Overload Recovery Response For Minimum Gain.

FIGURE 16. Overload Recovery Response For Maximum Gain.

INPUT OVERLOAD RECOVERY

One of the most important applications for the VCA2613 is processing signals in an ultrasound system. The ultrasound signal flow begins when a large signal is applied to a transducer, which converts electrical energy to acoustic energy. It is not uncommon for the amplitude of the electrical signal that is applied to the transducer to be ±50V or greater. To prevent damage, it is necessary to place a protection circuit between the transducer and the VCA2613, as shown in Figure 17. Care must be taken to prevent any signal from turning the ESD diodes on. Turning on the ESD diodes inside the VCA2613 could cause the input coupling capacitor (C_C) to charge to the wrong value.
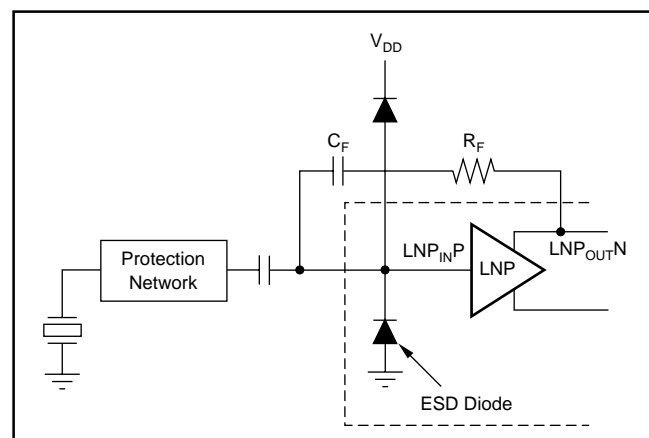

FIGURE 17. VCA2613 Diode Bridge Protection Circuit.

TEXAS
INSTRUMENTS
www.ti.com

VCA2613
SBOS179B

PGA POST-AMPLIFIER—DETAIL

Figure 18 shows a simplified circuit diagram of the PGA block. As described previously, the PGA gain is programmed with the same MGS bits which control the VCA maximum attenuation factor. Specifically, the PGA gain at each MGS setting is the inverse (reciprocal) of the maximum VCA attenuation at that setting. Therefore, the VCA + PGA overall gain will always be 0dB (unity) when the analog VCA_{CNTL} input is set to 0V (= maximum attenuation). For VCA_{CNTL} = 3V (no attenuation), the VCA + PGA gain will be controlled by the programmed PGA gain (24 to 45 dB in 3dB steps). For clarity, the gain and attenuation factors are detailed in Table III.

The PGA architecture consists of a differential, program-mable-gain voltage to current converter stage followed by transimpedance amplifiers to create and buffer each side of the differential output. The circuitry associated with the voltage to current converter is similar to that previously described for the LNP, with the addition of eight selectable PGA gain-setting resistor combinations (controlled by the MGS bits) in place of the fixed resistor network used in the LNP. Low input noise is also a requirement of the PGA design due to the large amount of signal attenuation which can be inserted between the LNP and the PGA. At minimum VCA attenuation (used for small input signals) the LNP noise dominates; at maximum VCA attenuation (large input signals) the PGA noise dominates. Note that if the PGA output is used single-ended, the apparent gain will be 6dB lower.
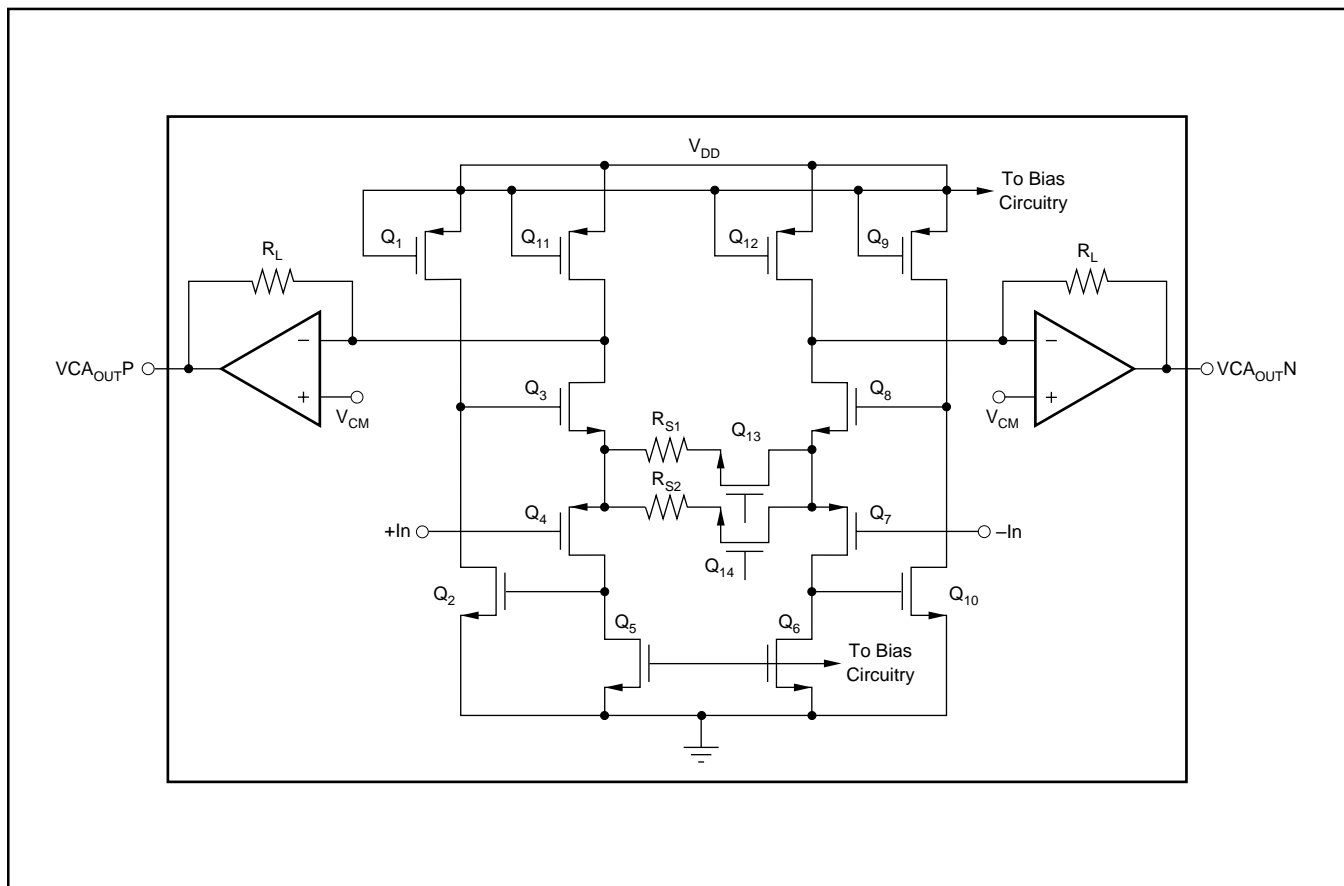
MGS SETTING	ATTENUATOR GAIN VCA_{CNTL} = 0V to 3V	DIFFERENTIAL PGA GAIN	ATTENUATOR + DIFF. PGA GAIN
000	−24dB to 0dB	24dB	0dB to 24dB
001	−27dB to 0dB	27dB	0dB to 27dB
010	−30dB to 0dB	30dB	0dB to 30dB
011	−33dB to 0dB	33dB	0dB to 33dB
100	−36dB to 0dB	36dB	0dB to 36dB
101	−39dB to 0dB	39dB	0dB to 39dB
110	−42dB to 0dB	42dB	0dB to 42dB
111	−45dB to 0dB	45dB	0dB to 45dB

TABLE III. MGS Settings.

FIGURE 18. Simplified Block Diagram of the PGA section within the VCA2613.

PFB (S-PQFP-G48)   **PLASTIC QUAD FLATPACK**

4073176 / B 10/96
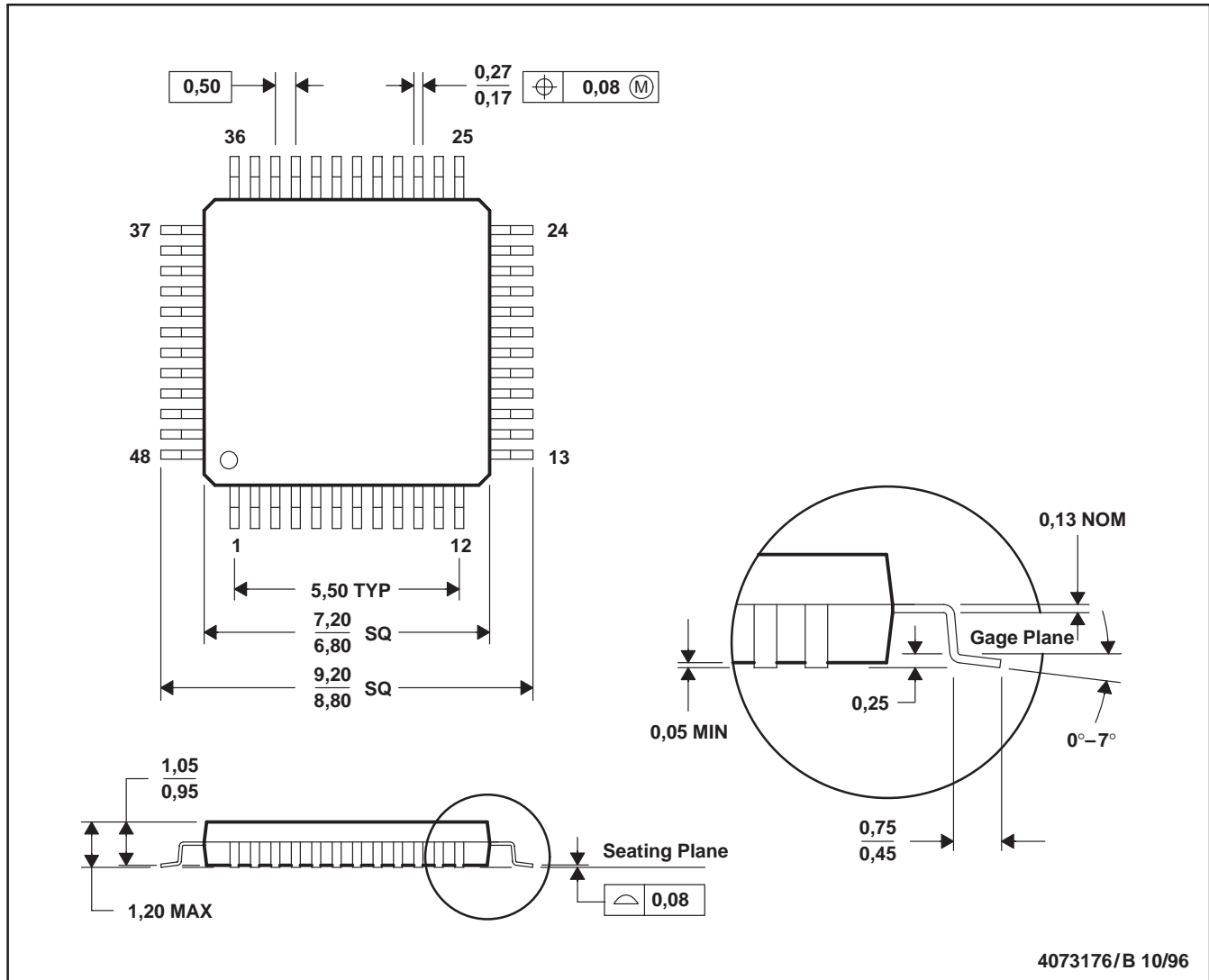
NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Falls within JEDEC MS-026

TEXAS
INSTRUMENTS
www.ti.com

14

VCA2613
SBOS179B

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third–party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Mailing Address:

Texas Instruments
Post Office Box 655303
Dallas, Texas 75265