

# MOS INTEGRATED CIRCUIT $\mu$ PD703031A, 703031AY, 703033A, 703033AY, 70F3033A, 70F3033AY

V850/SB1™

## 32-/16-BIT SINGLE-CHIP MICROCONTROLLERS

### DESCRIPTION

The  $\mu$ PD703031A, 703031AY, 703033A, 703033AY, 70F3033A, and 70F3033AY (V850/SB1) are 32-/16-bit single-chip microcontrollers of the V850 Family™ for AV equipment. 32-bit CPU, ROM, RAM, timer/counters, serial interfaces, A/D converter, DMA controller, and so on are integrated on a single chip.

The  $\mu$ PD70F3033A and 70F3033AY have flash memory in place of the internal mask ROM of the  $\mu$ PD703033A and 703033AY. Because flash memory allows the program to be written and erased electrically with the device mounted on the board, these products are ideal for the evaluation stages of system development, small-scale production, and rapid development of new products.

Detailed function descriptions are provided in the following user's manuals. Be sure to read them before designing.

V850/SB1, V850/SB2™ User's Manual Hardware: U13850E  
V850 Family User's Manual Architecture: U10243E

### FEATURES

- Number of instructions: 74
- Minimum instruction execution time: 50 ns (@ internal 20 MHz operation)
- General-purpose registers: 32 bits × 32 registers
- Instruction set: Signed multiplication, saturation operations, 32-bit shift instructions, bit manipulation instructions, load/store instructions
- Memory space: 16 MB linear address space
- Internal memory ROM: 128 KB ( $\mu$ PD703031A, 703031AY: mask ROM)  
256 KB ( $\mu$ PD703033A, 703033AY: mask ROM)  
256 KB ( $\mu$ PD70F3033A, 70F3033AY: flash memory)
- RAM: 12 KB ( $\mu$ PD703031A, 703031AY)  
16 KB ( $\mu$ PD703033A, 703033AY, 70F3033A, 70F3033AY)
- Interrupt/exception:  $\mu$ PD703031A, 703033A, 70F3033A (external: 8, internal: 30 sources, exception: 1 source)  
 $\mu$ PD703031AY, 703033AY, 70F3033AY (external: 8, internal: 31 sources, exception: 1 source)
- I/O lines Total: 83
- Timer/counters: 16-bit timer (2 channels: TM0, TM1)  
8-bit timer (6 channels: TM2 to TM7)
- Watch timer: 1 channel
- Watchdog timer: 1 channel

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version.  
Not all devices/types available in every country. Please check with local NEC representative for availability and additional information.

- Serial interface
  - Asynchronous serial interface (UART0, UART1)
  - Clocked serial interface (CSI0 to CSI3)
  - 3-wire variable length serial interface (CSI4)
  - I<sup>2</sup>C bus interface (I<sup>2</sup>C0, I<sup>2</sup>C1) (μPD703031AY, 703033AY, 70F3033AY only)
- 10-bit resolution A/D converter: 12 channels
- DMA controller: 6 channels
- Real-time output port: 8 bits × 1 channel or 4 bits × 2 channels
- ROM correction: 4 places can be corrected
- Power-saving function: HALT/IDLE/STOP modes
- Packages: 100-pin plastic LQFP (fine pitch) (14 × 14)  
100-pin plastic QFP (14 × 20)
- μPD70F3033A, 70F3033AY
  - Can be replaced with μPD703033A and 703033AY (internal mask ROM) in mass production

**APPLICATIONS**

- AV equipment (audio, car audio, VCR, TV, etc.)

**ORDERING INFORMATION**

Part Number	Package	Internal ROM
μPD703031AGC-xxx-8EU	100-pin plastic LQFP (fine pitch) (14 × 14)	Mask ROM (128 KB)
μPD703031AYGC-xxx-8EU	100-pin plastic LQFP (fine pitch) (14 × 14)	Mask ROM (128 KB)
μPD703031AGF-xxx-3BA	100-pin plastic QFP (14 × 20)	Mask ROM (128 KB)
μPD703031AYGF-xxx-3BA	100-pin plastic QFP (14 × 20)	Mask ROM (128 KB)
μPD703033AGC-xxx-8EU	100-pin plastic LQFP (fine pitch) (14 × 14)	Mask ROM (256 KB)
μPD703033AYGC-xxx-8EU	100-pin plastic LQFP (fine pitch) (14 × 14)	Mask ROM (256 KB)
μPD703033AGF-xxx-3BA	100-pin plastic QFP (14 × 20)	Mask ROM (256 KB)
μPD703033AYGF-xxx-3BA	100-pin plastic QFP (14 × 20)	Mask ROM (256 KB)
μPD70F3033AGC-8EU <sup>Note</sup>	100-pin plastic LQFP (fine pitch) (14 × 14)	Flash memory (256 KB)
μPD70F3033AYGC-8EU <sup>Note</sup>	100-pin plastic LQFP (fine pitch) (14 × 14)	Flash memory (256 KB)
μPD70F3033AGF-3BA <sup>Note</sup>	100-pin plastic QFP (14 × 20)	Flash memory (256 KB)
μPD70F3033AYGF-3BA <sup>Note</sup>	100-pin plastic QFP (14 × 20)	Flash memory (256 KB)

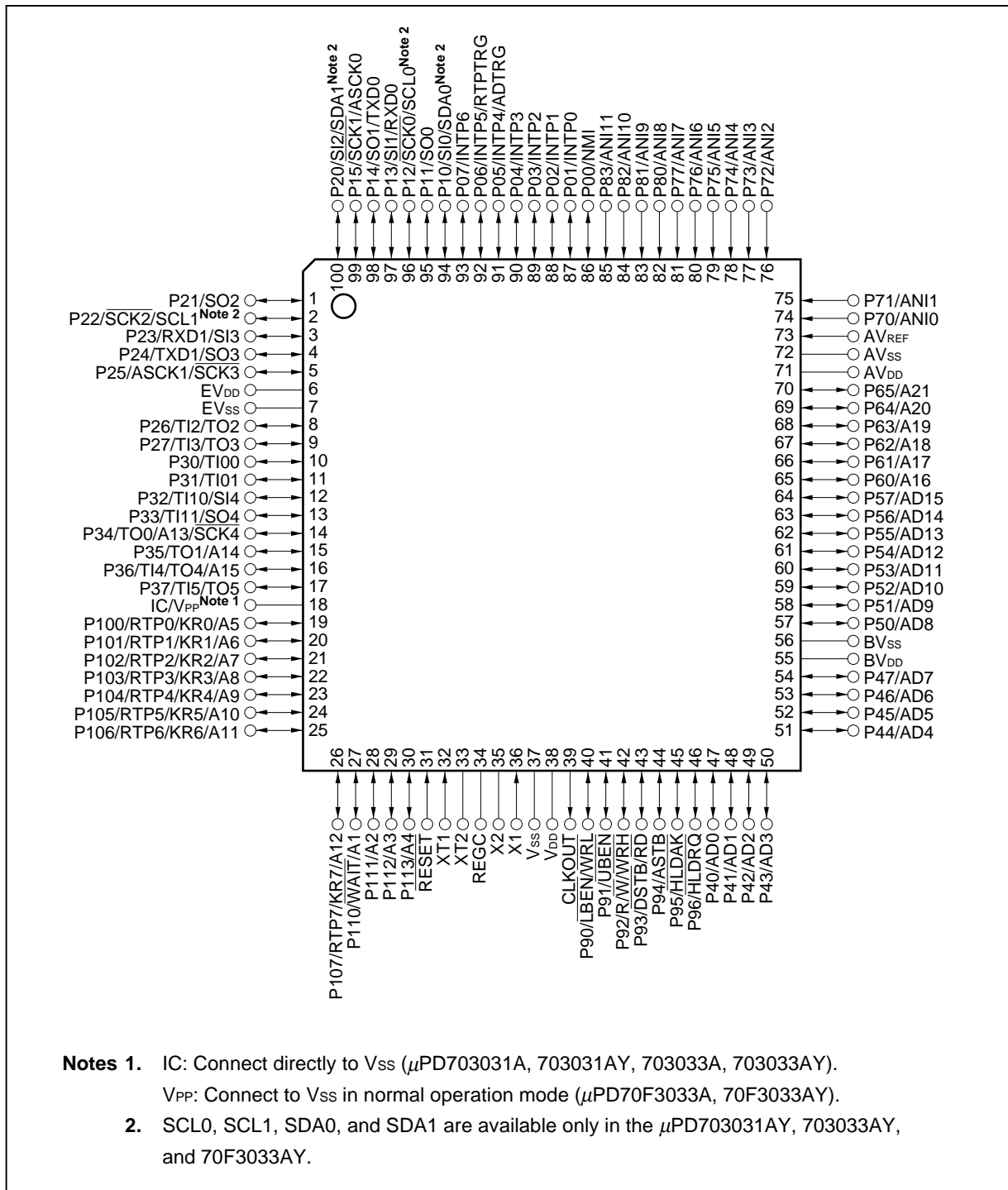
**Note** Under development

- Remarks**
1. xxx indicates ROM code suffix.
  2. ROMless versions are not provided.

PIN CONFIGURATION (Top View)

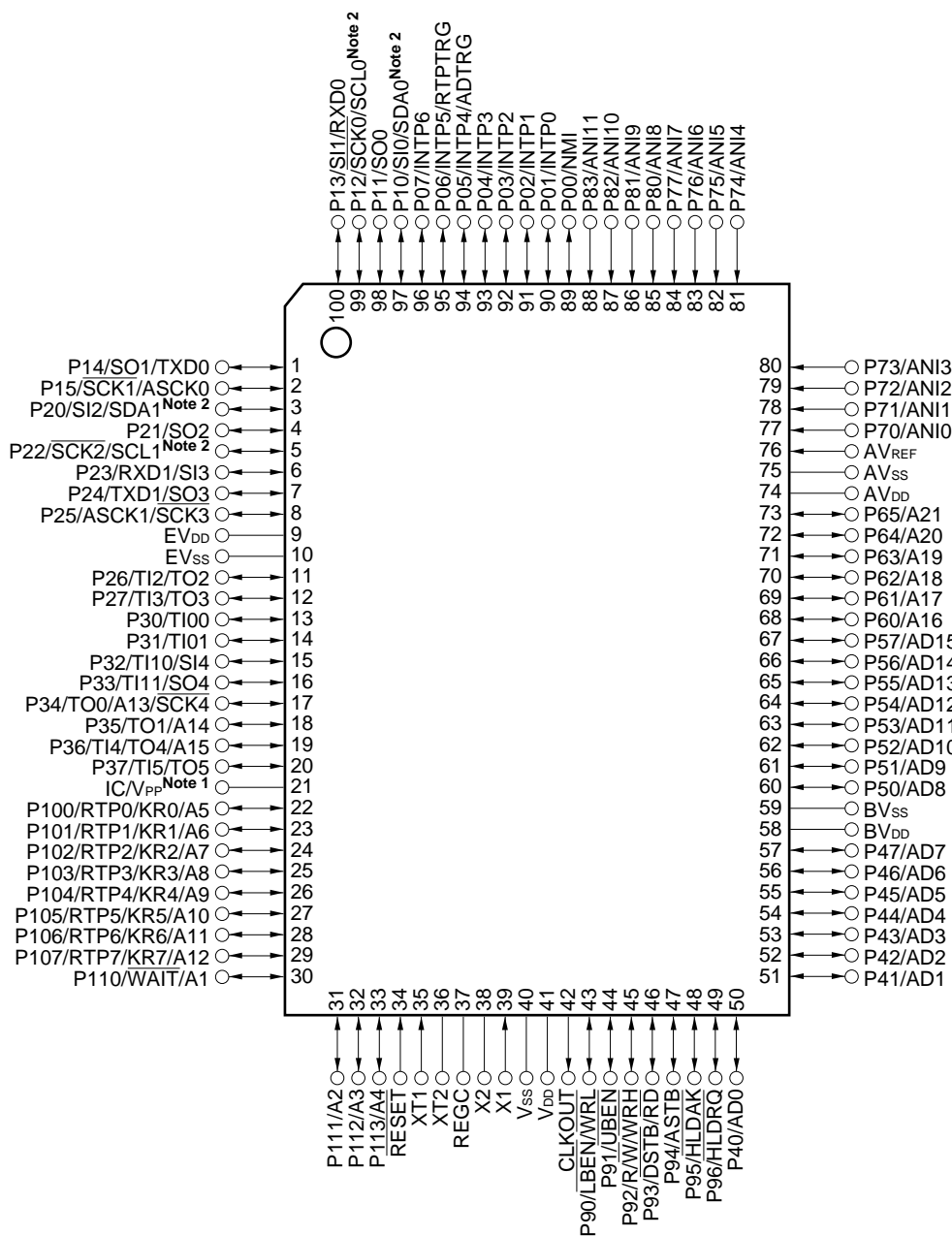
100-pin plastic LQFP (fine pitch) (14 x 14)

- μPD703031AGC-xxx-8EU
- μPD703031AYGC-xxx-8EU
- μPD703033AGC-xxx-8EU
- μPD703033AYGC-xxx-8EU
- μPD70F3033AGC-8EU
- μPD70F3033AYGC-8EU



100-pin plastic QFP (14 × 20)

- μPD703031AGF-xxx-3BA
- μPD703031AYGF-xxx-3BA
- μPD703033AGF-xxx-3BA
- μPD703033AYGF-xxx-3BA
- μPD70F3033AGF-3BA
- μPD70F3033AYGF-3BA

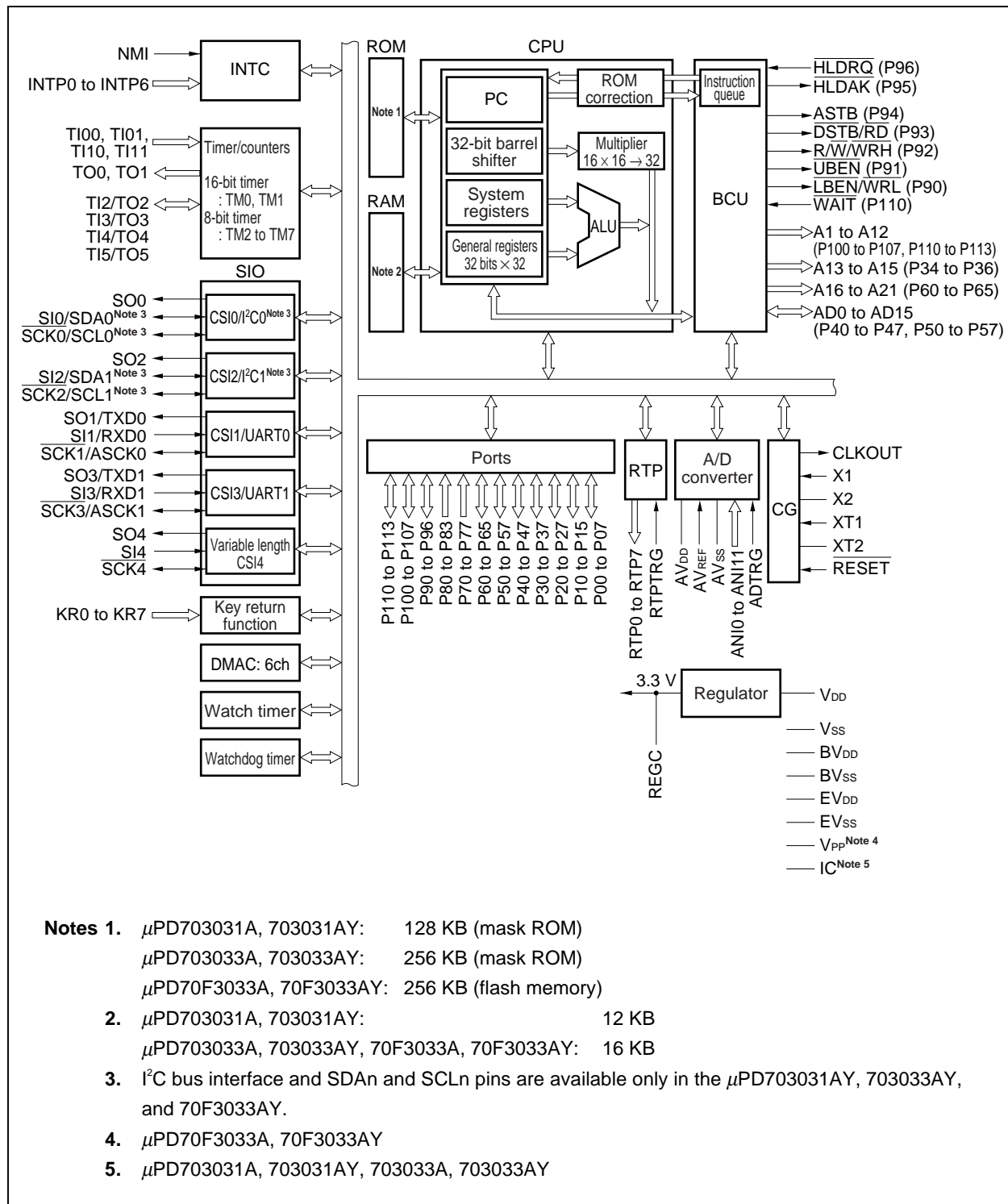


- Notes 1.** IC: Connect directly to V<sub>SS</sub> (μPD703031A, 703031AY, 703033A, 703033AY).  
V<sub>PP</sub>: Connect to V<sub>SS</sub> in normal operation mode (μPD70F3033A, 70F3033AY).
- 2.** SCL0, SCL1, SDA0, and SDA1 are available only in the μPD703031AY, 703033AY, and 70F3033AY.

**PIN IDENTIFICATION**

A1 to A21:	Address Bus	P80 to P83:	Port 8
AD0 to AD15:	Address/Data Bus	P90 to P96:	Port 9
ADTRG:	AD Trigger Input	P100 to P107:	Port 10
ANI0 to ANI11:	Analog Input	P110 to P113:	Port 11
ASCK0, ASCK1:	Asynchronous Serial Clock	$\overline{RD}$ :	Read
ASTB:	Address Strobe	REGC:	Regulator Clock
AV <sub>DD</sub> :	Analog Power Supply	$\overline{RESET}$ :	Reset
AV <sub>REF</sub> :	Analog Reference Voltage	RTP0 to RTP7:	Real-time Output Port
AV <sub>SS</sub> :	Analog Ground	RTPTRG:	RTP Trigger Input
BV <sub>DD</sub> :	Power Supply for Bus Interface	R $\overline{W}$ :	Read/Write Status
BV <sub>SS</sub> :	Ground for Bus Interface	RXD0, RXD1:	Receive Data
CLKOUT:	Clock Output	$\overline{SCK0}$ to $\overline{SCK4}$ :	Serial Clock
$\overline{DSTB}$ :	Data Strobe	SCL0, SCL1:	Serial Clock
EV <sub>DD</sub> :	Power Supply for Port	SDA0, SDA1:	Serial Data
EV <sub>SS</sub> :	Ground for Port	SI0 to SI4:	Serial Input
$\overline{HLDK}$ :	Hold Acknowledge	SO0 to SO4:	Serial Output
$\overline{HLDRQ}$ :	Hold Request	TI00, TI01, TI10, :	Timer Input
IC:	Internally Connected	TI11, TI2 to TI5	
INTP0 to INTP6:	Interrupt Request from Peripherals	TO0 to TO5:	Timer Output
KR0 to KR7:	Key Return	TXD0, TXD1:	Transmit Data
$\overline{LBEN}$ :	Lower Byte Enable	$\overline{UBEN}$ :	Upper Byte Enable
NMI:	Non-Maskable Interrupt Request	V <sub>DD</sub> :	Power Supply
P00 to P07:	Port 0	V <sub>PP</sub> :	Programming Power Supply
P10 to P15:	Port 1	V <sub>SS</sub> :	Ground
P20 to P27:	Port 2	$\overline{WAIT}$ :	Wait
P30 to P37:	Port 3	$\overline{WRH}$ :	Write Strobe High Level Data
P40 to P47:	Port 4	$\overline{WRL}$ :	Write Strobe Low Level Data
P50 to P57:	Port 5	X1, X2:	Crystal for Main Clock
P60 to P65:	Port 6	XT1, XT2:	Crystal for Sub-clock
P70 to P77:	Port 7		

INTERNAL BLOCK DIAGRAM



**CONTENTS**

**1. DIFFERENCES AMONG PRODUCTS ..... 8**

**1.1 Differences of μPD703031A, 703031AY, 703033A, 703033AY, 70F3033A, and 70F3033AY ..... 8**

**2. PIN FUNCTIONS..... 9**

**2.1 Port Pins..... 9**

**2.2 Non-Port Pins..... 11**

**2.3 Pin I/O Circuits and Recommended Connection of Unused Pins ..... 15**

**3. PROGRAMMING FLASH MEMORY (μPD70F3033A, 70F3033AY ONLY) ..... 19**

**3.1 Selecting Communication Mode ..... 19**

**3.2 Function of Flash Memory Programming..... 20**

**3.3 Connecting Dedicated Flash Programmer ..... 20**

**4. ELECTRICAL SPECIFICATIONS..... 22**

**4.1 Flash Memory Programming Mode (μPD70F3033A, 70F3033AY only) ..... 47**

**5. PACKAGE DRAWINGS..... 48**

**6. RECOMMENDED SOLDERING CONDITIONS ..... 50**

**1. DIFFERENCES AMONG PRODUCTS**

**1.1 Differences of μPD703031A, 703031AY, 703033A, 703033AY, 70F3033A, and 70F3033AY**

Part Number / Item	μPD703031A	μPD703031AY	μPD703033A	μPD703033AY	μPD70F3033A	μPD70F3033AY
Internal ROM	128 KB (mask ROM)		256 KB (mask ROM)		256 KB (flash memory)	
Flash memory programming pin	None				Provided ( $V_{PP}$ )	
Flash memory programming mode	None				Provided ( $V_{PP} = 7.8\text{ V}$ )	
I <sup>2</sup> C bus interface pins (SCL0, SCL1, SDA0, SDA1)	None	Provided	None	Provided	None	Provided
Electrical specifications	Current consumption, etc. differs.					
Others	Noise immunity and noise radiation differ because circuit scale and mask layout differ.					

- Cautions 1. There are differences in noise immunity and noise radiation between the flash memory and mask ROM versions. When pre-producing an application set with the flash memory version and then mass-producing it with the mask ROM version, be sure to conduct sufficient evaluations for the commercial samples (not engineering samples) of the mask ROM version.**
- 2. When replacing the flash memory versions with mask ROM versions, write the same code in the empty area of the internal ROM.**



2. PIN FUNCTIONS

2.1 Port Pins

(1/2)

Pin Name	I/O	PULL	Function	Alternate Function
P00	I/O	Yes	Port 0 8-bit I/O port Input/output can be specified in 1-bit units.	NMI
P01				INTP0
P02				INTP1
P03				INTP2
P04				INTP3
P05				INTP4/ADTRG
P06				INTP5/RTPTRG
P07				INTP6
P10	I/O	Yes	Port 1 6-bit I/O port Input/output can be specified in 1-bit units.	SI0/SDA0
P11				SO0
P12				SCK0/SCL0
P13				SI1/RXD0
P14				SO1/TXD0
P15				SCK1/ASCK0
P20	I/O	Yes	Port 2 8-bit I/O port Input/output can be specified in 1-bit units.	SI2/SDA1
P21				SO2
P22				SCK2/SCL1
P23				SI3/RXD1
P24				SO3/TXD1
P25				SCK3/ASCK1
P26				TI2/TO2
P27				TI3/TO3
P30	I/O	Yes	Port 3 8-bit I/O port Input/output can be specified in 1-bit units.	TI00
P31				TI01
P32				TI10/SI4
P33				TI11/SO4
P34				TO0/A13/SCK4
P35				TO1/A14
P36				TI4/TO4/A15
P37				TI5/TO5
P40 to P47	I/O	No	Port 4 8-bit I/O port Input/output can be specified in 1-bit units.	AD0 to AD7
P50 to P57	I/O	No	Port 5 8-bit I/O port Input/output can be specified in 1-bit units.	AD8 to AD15

**Remark** PULL: On-chip pull-up resistor

(2/2)

Pin Name	I/O	PULL	Function	Alternate Function
P60 to P65	I/O	No	Port 6 6-bit I/O port Input/output can be specified in 1-bit units.	A16 to A21
P70 to P77	Input	No	Port 7 8-bit input port	ANI0 to ANI7
P80 to P83	Input	No	Port 8 4-bit input port	ANI8 to ANI11
P90	I/O	No	Port 9 7-bit I/O port Input/output can be specified in 1-bit units.	$\overline{\text{LBEN}}/\overline{\text{WRL}}$
P91				$\overline{\text{UBEN}}$
P92				$\overline{\text{R}}/\overline{\text{WRH}}$
P93				$\overline{\text{DSTB}}/\overline{\text{RD}}$
P94				ASTB
P95				$\overline{\text{HLDAK}}$
P96				$\overline{\text{HLDRQ}}$
P100	I/O	Yes	Port 10 8-bit I/O port Input/output can be specified in 1-bit units.	RTP0/A5/KR0
P101				RTP1/A6/KR1
P102				RTP2/A7/KR2
P103				RTP3/A8/KR3
P104				RTP4/A9/KR4
P105				RTP5/A10/KR5
P106				RTP6/A11/KR6
P107				RTP7/A12/KR7
P110	I/O	Yes	Port 11 4-bit I/O port Input/output can be specified in 1-bit units.	$\overline{\text{A1}}/\overline{\text{WAIT}}$
P111				A2
P112				A3
P113				A4

**Remark** PULL: On-chip pull-up resistor

2.2 Non-Port Pins

(1/4)

Pin Name	I/O	PULL	Function	Alternate Function
A1	Output	Yes	Low-order address bus used for external memory expansion	P110/ $\overline{\text{WAIT}}$
A2				P111
A3				P112
A4				P113
A5				P100/RTP0/KR0
A6				P101/RTP1/KR1
A7				P102/RTP2/KR2
A8				P103/RTP3/KR3
A9				P104/RTP4/KR4
A10				P105/RTP5/KR5
A11				P106/RTP6/KR6
A12				P107/RTP7/KR7
A13				P34/TO0/ $\overline{\text{SCK4}}$
A14				P35/TO1
A15				P36/TO4/TI4
A16 to A21	Output	No	High-order address bus used for external memory expansion	P60 to P65
AD0 to AD7	I/O	No	16-bit multiplexed address/data bus used for external memory expansion	P40 to P47
AD8 to AD15				P50 to P57
ADTRG	Input	Yes	A/D converter external trigger input	P05/ $\overline{\text{INTP4}}$
ANI0 to ANI7	Input	No	Analog input to A/D converter	P70 to P77
ANI8 to ANI11				P80 to P83
ASCK0	Input	Yes	Baud rate clock input for UART0	P15/ $\overline{\text{SCK1}}$
ASCK1			Baud rate clock input for UART1	P25/ $\overline{\text{SCK3}}$
ASTB	Output	No	External address strobe output	P94
AV <sub>DD</sub>	–	–	Positive power supply for A/D converter and alternate port	–
AV <sub>REF</sub>	Input	–	Reference voltage input for A/D converter	–
AV <sub>SS</sub>	–	–	Ground potential for A/D converter and alternate port	–
BV <sub>DD</sub>	–	–	Positive power supply for bus interface and alternate port	–
BV <sub>SS</sub>	–	–	Ground potential for bus interface and alternate port	–
CLKOUT	Output	–	Internal system clock output	–
DSTB	Output	No	External data strobe output	P93/ $\overline{\text{RD}}$
EV <sub>DD</sub>	–	–	Positive power supply for I/O ports and alternate-function pins (except bus interface alternate port)	–
EV <sub>SS</sub>	–	–	Ground potential for I/O ports and alternate-function pins (except bus interface alternate port)	–
$\overline{\text{HLDAK}}$	Output	No	Bus hold acknowledge output	P95
$\overline{\text{HLDRQ}}$	Input	No	Bus hold request input	P96
IC	–	–	Internally connected (μPD703031A, 703031AY, 703033A, 703033AY only)	–

**Remark** PULL: On-chip pull-up resistor

(2/4)

Pin Name	I/O	PULL	Function	Alternate Function
INTP0	Input	Yes	External interrupt request input (analog noise elimination)	P01
INTP1				P02
INTP2				P03
INTP3				P04
INTP4	Input	Yes	External interrupt request input (digital noise elimination)	P05/ADTRG
INTP5				P06/RTPTRG
INTP6	Input	Yes	External interrupt request input (digital noise elimination supporting remote controller)	P07
KR0	Input	Yes	Key return input	P100/RTP0/A5
KR1				P101/RTP1/A6
KR2				P102/RTP2/A7
KR3				P103/RTP3/A8
KR4				P104/RTP4/A9
KR5				P105/RTP5/A10
KR6				P106/RTP6/A11
KR7				P107/RTP7/A12
$\overline{\text{LBEN}}$	Output	No	External data bus's low-order byte enable output	P90/ $\overline{\text{WRL}}$
NMI	Input	Yes	Non-maskable interrupt request input	P00
$\overline{\text{RD}}$	Output	No	Read strobe output	P93/ $\overline{\text{DSTB}}$
REGC	–	–	Regulator output stabilization capacitance connection	–
$\overline{\text{RESET}}$	Input	–	System reset input	–
RTP0	Output	Yes	Real-time output port	P100/KR0/A5
RTP1				P101/KR1/A6
RTP2				P102/KR2/A7
RTP3				P103/KR3/A8
RTP4				P104/KR4/A9
RTP5				P105/KR5/A10
RTP6				P106/KR6/A11
RTP7				P107/KR7/A12
RTPTRG	Input	Yes	Real-time output port external trigger input	P06/INTP5
$\overline{\text{R/W}}$	Output	No	External read/write status output	P92/ $\overline{\text{WRH}}$
RXD0	Input	Yes	Serial receive data input for UART0 and UART1	P13/SI1
RXD1				P23/SI3
$\overline{\text{SCK0}}$	I/O	Yes	Serial clock I/O (3-wire type) for CSI0 to CSI3	P12/SCL0
$\overline{\text{SCK1}}$				P15/ASCK0
$\overline{\text{SCK2}}$				P22/SCL1
$\overline{\text{SCK3}}$				P25/ASCK1
$\overline{\text{SCK4}}$	I/O	Yes	Serial clock I/O (3-wire type) for variable length CSI4	P34/TO0/A13

**Remark** PULL: On-chip pull-up resistor

Pin Name	I/O	PULL	Function	Alternate Function
SCL0	I/O	Yes	Serial clock I/O for I <sup>2</sup> C0 and I <sup>2</sup> C1 (μPD703031AY, 703033AY, 70F3033AY only)	P12/SCK0
SCL1				P22/SCK2
SDA0	I/O	Yes	Serial transmit/receive data I/O for I <sup>2</sup> C0 and I <sup>2</sup> C1 (μPD703031AY, 703033AY, 70F3033AY only)	P10/SI0
SDA1				P20/SI2
SI0	Input	Yes	Serial receive data input (3-wire type) for CSI0 to CSI3	P10/SDA0
SI1				P13/RXD0
SI2				P20/SDA1
SI3				P23/RXD1
SI4	Input	Yes	Serial receive data input (3-wire type) for variable length CSI4	P32/TI10
SO0	Output	Yes	Serial transmit data output (3-wire type) for CSI0 to CSI3	P11
SO1				P14/TXD0
SO2				P21
SO3				P24/TXD1
SO4	Output	Yes	Serial transmit data output (3-wire type) for variable length CSI4	P33/TI11
TI00	Input	Yes	External count clock input for TM0/external capture trigger input for TM0	P30
TI01			External capture trigger input for TM0	P31
TI10			External count clock input for TM1/external capture trigger input for TM1	P32/SI4
TI11			External capture trigger input for TM1	P33/SO4
TI2	Input	Yes	External count clock input for TM2 to TM5	P26/TO2
TI3				P27/TO3
TI4				P36/TO4/A15
TI5				P37/TO5
TO0	Output	Yes	Pulse signal output for TM0 and TM1	P34/A13/SCK4
TO1				P35/A14
TO2	Output	Yes	Pulse signal output for TM2 to TM5	P26/TI2
TO3				P27/TI3
TO4				P36/TI4/A15
TO5				P37/TI5
TXD0	Output	Yes	Serial transmit data output for UART0 and UART1	P14/SO1
TXD1				P24/SO3
UBEN	Output	No	High-order byte enable output for external data bus	P91
V <sub>DD</sub>	–	–	Positive power supply pin	–
V <sub>PP</sub>	–	–	High voltage apply pin for program write/verify (μPD70F3033A, 70F3033AY only)	–
V <sub>SS</sub>	–	–	Ground potential	–
WAIT	Input	Yes	Control signal input for inserting wait in bus cycle	P110/A1
WRH	Output	No	High-order byte write strobe signal output for external data bus	P92/RW

**Remark** PULL: On-chip pull-up resistor

(4/4)

Pin Name	I/O	PULL	Function	Alternate Function
$\overline{\text{WRL}}$	Output	No	Low-order byte write strobe signal output for external data bus	P90/ $\overline{\text{LBEN}}$
X1	Input	No	Resonator connection for main clock	–
X2	–			–
XT1	Input	No	Resonator connection for subsystem clock	–
XT2	–			–

**Remark** PULL: On-chip pull-up resistor

**2.3 Pin I/O Circuits and Recommended Connection of Unused Pins**

The input/output circuit type of each pin and recommended connection of unused pins are show in Table 2-1. For the input/output schematic circuit diagram of each type, refer to Figure 2-1.

**Table 2-1. Types of Pin I/O Circuits (1/2)**

Pin	Alternate Function	I/O Circuit Type	I/O Buffer Power Supply	Recommended Connection of Unused Pins	
P00	NMI	8-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.	
P01	INTP0				
P02	INTP1				
P03	INTP2				
P04	INTP3				
P05	INTP4/ADTRG				
P06	INTP5/RTPTRG				
P07	INTP6				
P10	SI0/SDA0	10-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.	
P11	SO0	26			
P12	SCK0/SCL0	10-A			
P13	SI1/RXD0	8-A			
P14	SO0/TXD0	26			
P15	SCK1/ASCK0	10-A			
P20	SI2/SDA1	10-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.	
P21	SO2	26			
P22	SCK2/SCL1	10-A			
P23	SI3/RXD1				
P24	SO3/TXD1	26			
P25	SCK3/ASCK1	10-A			
P26	TI2/TO2	8-A			
P27	TI3/TO3				
P30	TI00	8-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.	
P31	TI01				
P32	TI10/SI4				
P33	TI11/SO4				
P34	TO0/A13/SCK4				
P35	TO1/A14				5-A
P36	TI4/TO4/A15				8-A
P37	TI5/TO5				
P40 to P47	AD0 to AD7	5	BV <sub>DD</sub>	Input state: Independently connect to BV <sub>DD</sub> or BV <sub>SS</sub> via a resistor. Output state: Leave open.	
P50 to P57	AD8 to AD15	5	BV <sub>DD</sub>		
P60 to P65	A16 to A21	5	BV <sub>DD</sub>		

Table 2-1. Types of Pin I/O Circuits (2/2)

Pin	Alternate Function	I/O Circuit Type	I/O Buffer Power Supply	Recommended Connection of Unused Pins
P70 to P77	ANI0 to ANI7	9	AV <sub>DD</sub>	Independently connect to AV <sub>DD</sub> or AV <sub>SS</sub> via a resistor.
P80 to P83	ANI8 to ANI11	9	AV <sub>DD</sub>	
P90	$\overline{\text{LBEN}}/\overline{\text{WRL}}$	5	BV <sub>DD</sub>	Input state: Independently connect to BV <sub>DD</sub> or BV <sub>SS</sub> via a resistor. Output state: Leave open.
P91	$\overline{\text{UBEN}}$			
P92	R/W/WRH			
P93	$\overline{\text{DSTB}}/\overline{\text{RD}}$			
P94	ASTB			
P95	$\overline{\text{HLDAK}}$	26		
P96	$\overline{\text{HLDRQ}}$			
P100	RTP0/A5/KR0	10-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.
P101	RTP1/A6/KR1			
P102	RTP2/A7/KR2			
P103	RTP3/A8/KR3			
P104	RTP4/A9/KR4			
P105	RTP5/A10/KR5			
P106	RTP6/A11/KR6			
P107	RTP7/A12/KR7			
P110	A1/WAIT	5-A	EV <sub>DD</sub>	Input state: Independently connect to EV <sub>DD</sub> or EV <sub>SS</sub> via a resistor. Output state: Leave open.
P111	A2			
P112	A3			
P113	A4			
CLKOUT	–	4	BV <sub>DD</sub>	Leave open.
RESET	–	2	EV <sub>DD</sub>	–
XT1	–	16	–	Connect to V <sub>SS</sub> via a resistor.
XT2	–	16	–	Leave open.
AV <sub>REF</sub>	–	–	–	Connect to AV <sub>SS</sub> via a resistor.
IC <sup>Note 1</sup>	–	–	–	Connect directly to V <sub>SS</sub> .
V <sub>PP</sub> <sup>Note 2</sup>	–	–	–	Connect to V <sub>SS</sub> .

- Notes 1. μPD703031A, 703031AY, 703033A, 703033AY  
 2. μPD70F3033A, 70F3033AY

**Caution** Three power supply systems are available to supply power to the I/O buffers of the V850/SB1's pins: EV<sub>DD</sub>, BV<sub>DD</sub>, and AV<sub>DD</sub>. The voltage ranges that can be used for these I/O buffer power supplies are shown below.

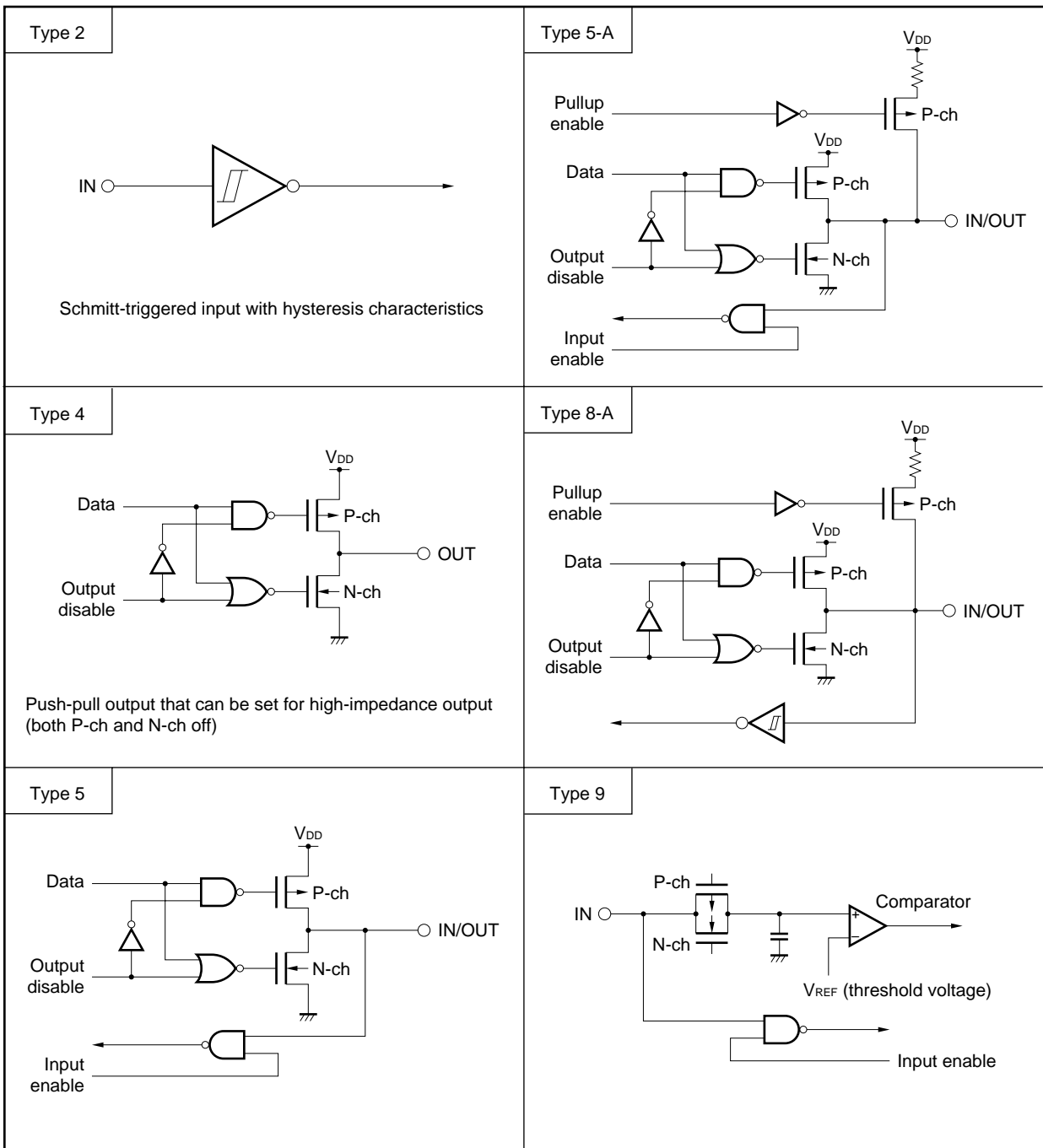
EV<sub>DD</sub>, BV<sub>DD</sub>: 3.0 V to 5.5 V

AV<sub>DD</sub>: 4.5 V to 5.5 V

The electrical specifications differ depending on whether the power supply voltage range is 3.0 V to under 4.0 V, or 4.0 V to 5.5 V.

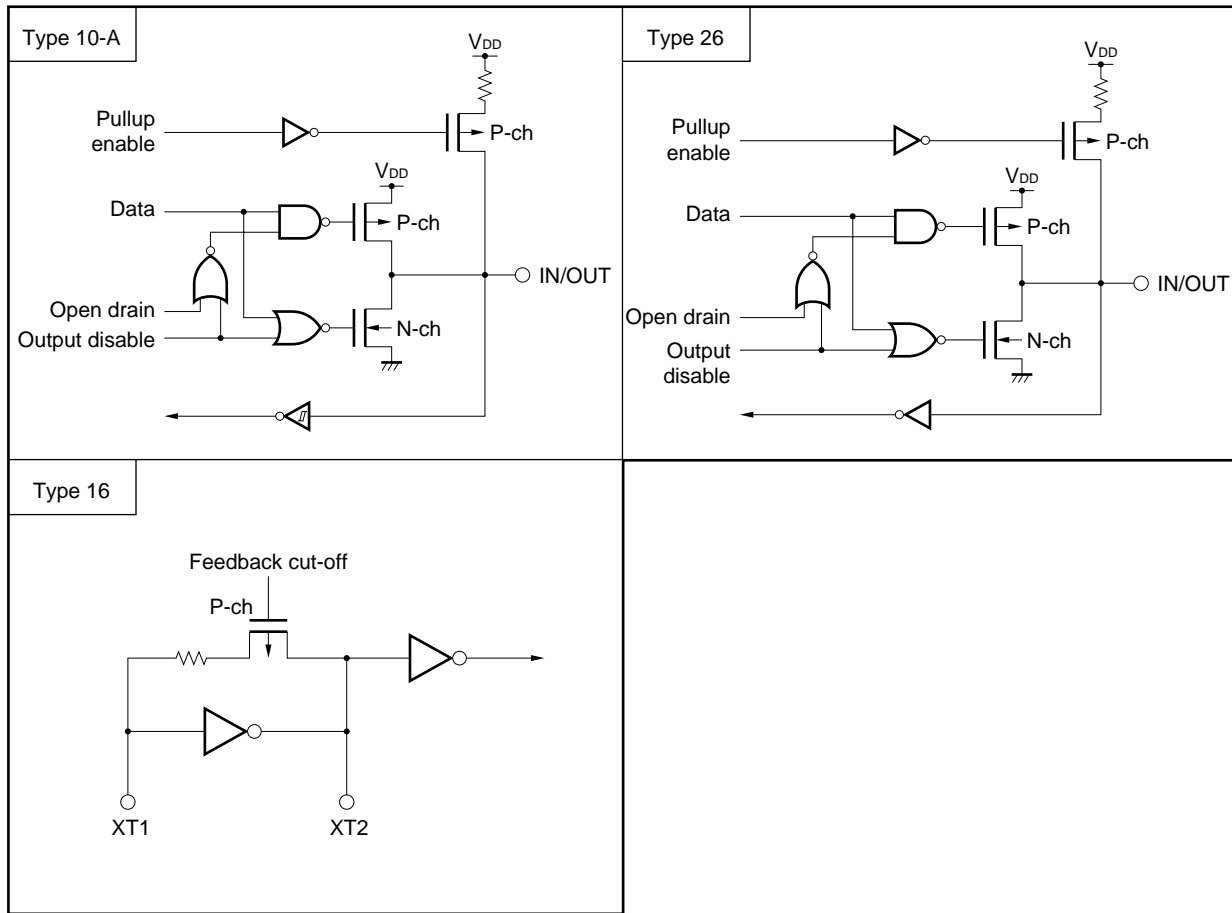


Figure 2-1. Pin Input/Output Circuits (1/2)



**Caution**  $V_{DD}$  in the circuit diagrams can be read as  $EV_{DD}$ ,  $BV_{DD}$ , or  $AV_{DD}$ , as appropriate.

Figure 2-1. Pin Input/Output Circuits (2/2)



**Caution**  $V_{DD}$  in the circuit diagrams can be read as  $EV_{DD}$ ,  $BV_{DD}$ , or  $AV_{DD}$ , as appropriate.

### 3. PROGRAMMING FLASH MEMORY (μPD70F3033A, 70F3033AY ONLY)

There are the following two methods for writing a program to the flash memory.

#### (1) On-board programming

Write a program to the flash memory using a dedicated flash programmer after the μPD70F3033A and 70F3033AY have been mounted on the target board. Also mount a connector, etc. on the target board to communicate with the dedicated flash programmer.

#### (2) Off-board programming

Write a program using a dedicated adapter before the μPD70F3033A and 70F3033AY have been mounted on the target board.

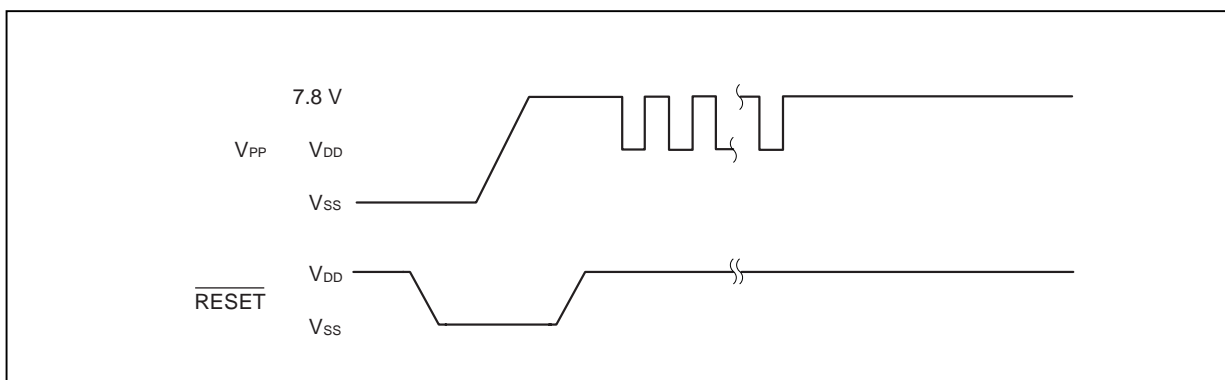
#### 3.1 Selecting Communication Mode

To write the flash memory, use a dedicated flash programmer and serial communication. Select a serial communication mode from those listed in Table 3-1 in the format shown in Figure 3-1. Each communication mode is selected by the number of V<sub>PP</sub> pulses shown in Table 3-1.

Table 3-1. Communication Modes

Communication Mode	Pins Used	Number of V <sub>PP</sub> Pulses
CSI0	SO0 (serial data output) SI0 (serial data input) SCK0 (serial clock input)	0
CSI0 + HS	SO0 (serial data output) SI0 (serial data input) SCK0 (serial clock input) P15 (3-wire + handshake signal output of handshake communication)	3
UART0	TXD0 (serial data output) RXD0 (serial data input)	8

Figure 3-1. Communication Mode Selecting Format



### 3.2 Function of Flash Memory Programming

Operations such as writing to flash memory are performed by various command/data transmission and reception operations according to the selected communication mode. The major functions are shown below.

**Table 3-2. Major Functions of Flash Memory Programming**

Function		Description
Category	Command	
Verify	Batch verify	Compares the contents of the entire memory and the input data.
Erase	Batch erase	Erases the contents of the entire memory.
	Write back	Writes back the contents which is overerased.
Blank check	Batch blank check	Checks the erase state of the entire memory.
Data write	High-speed write	Writes data by the specification of the write start address and the number of bytes to be written, and executes verify check.
	Continuous write	Writes data from the address following the high-speed write command executed immediately before, and executes verify check.
System setting/control	Status read out	Reads out the status of operations.
	Oscillation frequency setting	Sets the oscillation frequency.
	Erase time setting	Sets the erase time of batch erase.
	Write time setting	Sets the write time of data write.
	Write back time setting	Sets the write back time.
	Baud rate setting	Sets the baud rate when using UART0.
	Silicon signature	Reads out the silicon signature information.
	Reset	Restarts the system of flash programmer.

### 3.3 Connecting Dedicated Flash Programmer

The connection of the dedicated flash programmer and the μPD70F3033A and 70F3033AY differs according to the communication mode. The connections for each communication mode are shown below.

**Figure 3-2. Connection of Dedicated Flash Programmer in CSIO Mode**

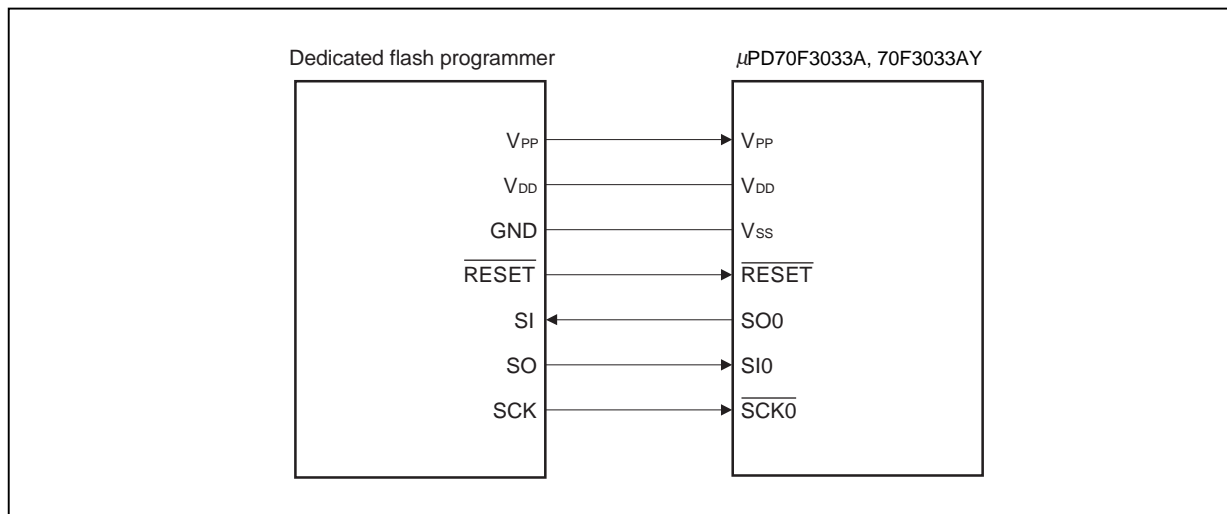


Figure 3-3. Connection of Dedicated Flash Programmer in CSIO + HS Mode

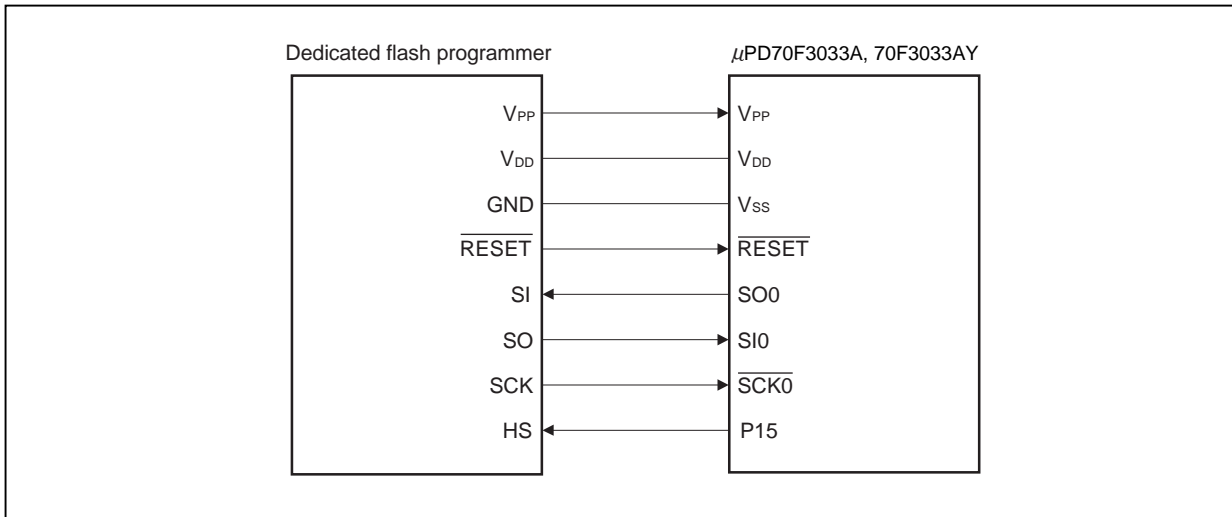
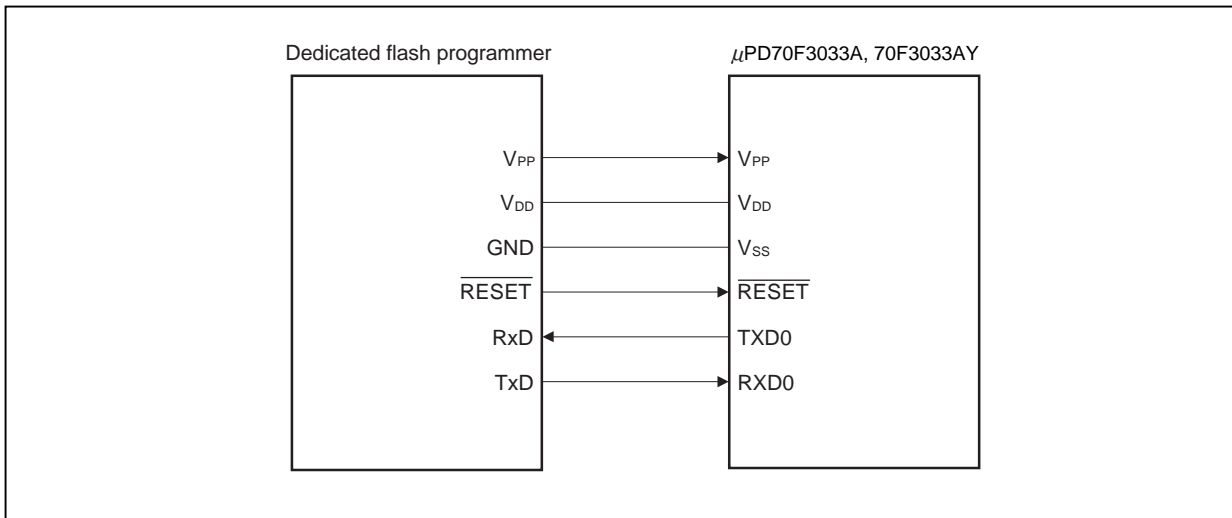


Figure 3-4. Connection of Dedicated Flash Programmer in UART0 Mode



4. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings (T<sub>A</sub> = 25°C, V<sub>SS</sub> = 0 V)

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>DD</sub>	V <sub>DD</sub> pin	-0.5 to +7.0	V
	AV <sub>DD</sub>	AV <sub>DD</sub> pin	-0.5 to +7.0	V
	BV <sub>DD</sub>	BV <sub>DD</sub> pin	-0.5 to +7.0	V
	EV <sub>DD</sub>	EV <sub>DD</sub> pin	-0.5 to +7.0	V
	AV <sub>SS</sub>	AV <sub>SS</sub> pin	-0.5 to +0.5	V
	BV <sub>SS</sub>	BV <sub>SS</sub> pin	-0.5 to +0.5	V
	EV <sub>SS</sub>	EV <sub>SS</sub> pin	-0.5 to +0.5	V
Input voltage	V <sub>I1</sub>	<b>Note 1</b> (BV <sub>DD</sub> pin)	-0.5 to BV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
	V <sub>I2</sub>	<b>Note 2</b> (EV <sub>DD</sub> pin)	-0.5 to EV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
	V <sub>I3</sub>	V <sub>PP</sub> pin (μPD70F3033A, 70F3033AY only)	-0.5 to +8.5	V
Analog input voltage	V <sub>IAN</sub>	<b>Note 3</b> (AV <sub>DD</sub> pin)	-0.5 to AV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
Analog reference input voltage	AV <sub>REF</sub>	AV <sub>REF</sub> pin	-0.5 to AV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
Output current, low	I <sub>OL</sub>	Per pin	4.0	mA
		Total for P00 to P07, P10 to P15, P20 to P25	25	mA
		Total for P26, P27, P30 to P37, P100 to P107, P110 to P113	25	mA
		Total for P40 to P47, P90 to P96, CLKOUT	25	mA
		Total for P50 to P57, P60 to P65	25	mA
Output current, high	I <sub>OH</sub>	Per pin	-4.0	mA
		Total for P00 to P07, P10 to P15, P20 to P25	-25	mA
		Total for P26, P27, P30 to P37, P100 to P107, P110 to P113	-25	mA
		Total for P40 to P47, P90 to P96, CLKOUT	-25	mA
		Total for P50 to P57, P60 to P65	-25	mA
Output voltage	V <sub>O1</sub>	<b>Note 1</b> (BV <sub>DD</sub> pin)	-0.5 to BV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
	V <sub>O2</sub>	<b>Note 2</b> (EV <sub>DD</sub> pin)	-0.5 to EV <sub>DD</sub> + 0.5 <sup>Note 4</sup>	V
Operating ambient temperature	T <sub>A</sub>	Normal operation mode	-40 to +85	°C
		Flash memory programming mode (μPD70F3033A, 70F3033AY only)	10 to 85	°C
Storage temperature	T <sub>stg</sub>	μPD703031A, 703031AY	-65 to +150	°C
		μPD703033A, 703033AY		
		μPD70F3033A, 70F3033AY	-40 to +125	°C

- Notes 1.** Ports 4, 5, 6, 9, CLKOUT, and their alternate-function pins
- 2.** Ports 0, 1, 2, 3, 10, 11,  $\overline{\text{RESET}}$ , and their alternate-function pins
- 3.** Ports 7, 8, and their alternate-function pins
- 4.** Be sure not to exceed the absolute maximum ratings (MAX. value) of each supply voltage.

- Cautions**
1. Do not directly connect the output (or I/O) pins of IC products to each other, or to V<sub>DD</sub>, V<sub>CC</sub>, and GND. Open-drain pins or open-collector pins, however, can be directly connected to each other. Direct connection of the output pins between an IC product and an external circuit is possible, if the output pins can be set to the high-impedance state and the output timing of the external circuit is designed to avoid output conflict.
  2. Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.  
The ratings and conditions indicated for DC characteristics and AC characteristics represent the quality assurance range during normal operation.

**Capacitance (T<sub>A</sub> = 25°C)**

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Input capacitance	C <sub>i</sub>	f <sub>c</sub> = 1 MHz Unmeasured pins returned to 0 V			15	pF
I/O capacitance	C <sub>io</sub>				15	pF
Output capacitance	C <sub>o</sub>				15	pF

**Operating Conditions**

**(1) Operating frequency**

Operating Frequency (f <sub>xx</sub> )		V <sub>DD</sub>	AV <sub>DD</sub>	BV <sub>DD</sub>	EV <sub>DD</sub>	Remark
2 to 20 MHz		4.0 to 5.5 V	4.5 to 5.5 V	4.0 to 5.5 V	4.0 to 5.5 V	<b>Note 1</b>
2 to 17 MHz		4.0 to 5.5 V	4.5 to 5.5 V	3.0 to 5.5 V	3.0 to 5.5 V	<b>Note 1</b>
32.768 kHz	Other than IDLE mode	4.0 to 5.5 V	4.5 to 5.5 V	3.0 to 5.5 V	3.0 to 5.5 V	–
	IDLE mode	3.5 to 5.5 V	4.5 to 5.5 V	3.0 to 5.5 V	3.0 to 5.5 V	<b>Note 2</b>

- Notes**
1. During STOP mode (subsystem oscillator operating), V<sub>DD</sub> = 3.5 to 5.5 V. Shifting to STOP mode or restoring from STOP mode must be performed at V<sub>DD</sub> = 4.0 V min.
  2. Shifting to IDLE mode or restoring from IDLE mode must be performed at V<sub>DD</sub> = 4.0 V min.

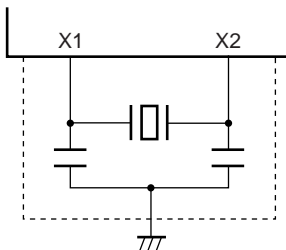
**(2) CPU operating frequency**

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
CPU operating frequency	f <sub>CPU</sub>	Main system clock operation	0.25		20	MHz
		Subsystem clock operation		32.768		kHz

Recommended Oscillator

(1) Main system clock oscillator (T<sub>A</sub> = -40 to +85°C)

(a) Connection of ceramic resonator or crystal resonator



Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Oscillation frequency	f <sub>xx</sub>		2		20	MHz
Oscillation stabilization time	–	Upon reset release		2 <sup>19</sup> /f <sub>xx</sub>		s
	–	Upon STOP mode release		<b>Note</b>		s

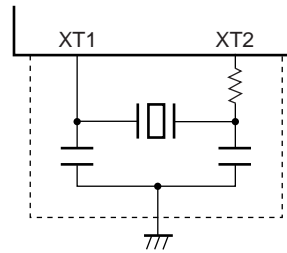
**Note** The TYP. value differs depending on the setting of the oscillation stabilization time select register (OSTS).

- Cautions**
1. Main system clock oscillator operates on the output voltage of the on-chip regulator. External clock input is prohibited.
  2. When using the main system clock oscillator, wire as follows in the area enclosed by the broken lines in the above figure to avoid an adverse effect from wiring capacitance.
    - Keep the wiring length as short as possible.
    - Do not cross the wiring with the other signal lines.
    - Do not route the wiring near a signal line through which a high fluctuating current flows.
    - Always make the ground point of the oscillator capacitor the same potential as V<sub>SS</sub>.
    - Do not ground the capacitor to a ground pattern through which a high current flows.
    - Do not fetch signals from the oscillator.
  3. Ensure that the duty of oscillation waveform is between 5.5 and 4.5.
  4. Sufficiently evaluate the matching between the μPD703031A, 703031AY, 703033A, 703033AY, 70F3033A, 70F3033AY and the resonator.



(2) Subsystem clock oscillator ( $T_A = -40$  to  $+85^\circ\text{C}$ )

(a) Connection of crystal resonator



Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Oscillation frequency	$f_{XT}$		32	32.768	35	kHz
Oscillation stabilization time	–			10		s

- Cautions**
1. Subsystem clock oscillator operates on the output voltage of the on-chip regulator. External clock input is prohibited.
  2. When using the subsystem clock oscillator, wire as follows in the area enclosed by the broken lines in the above figure to avoid an adverse effect from wiring capacitance.
    - Keep the wiring length as short as possible.
    - Do not cross the wiring with the other signal lines.
    - Do not route the wiring near a signal line through which a high fluctuating current flows.
    - Always make the ground point of the oscillator capacitor the same potential as  $V_{SS}$ .
    - Do not ground the capacitor to a ground pattern through which a high current flows.
    - Do not fetch signals from the oscillator.
  3. Sufficiently evaluate the matching between the  $\mu$ PD703031A, 703031AY, 703033A, 703033AY, 70F3033A, 70F3033AY and the resonator.

DC Characteristics

(T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = 4.0 to 5.5 V, BV<sub>DD</sub> = EV<sub>DD</sub> = 3.0 to 5.5 V, AV<sub>DD</sub> = 4.5 to 5.5 V, V<sub>SS</sub> = AV<sub>SS</sub> = BV<sub>SS</sub> = EV<sub>SS</sub> = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit	
Input voltage, high	V <sub>IH1</sub>	<b>Note 1</b>	4.0 V ≤ BV <sub>DD</sub> ≤ 5.5 V	0.7BV <sub>DD</sub>		BV <sub>DD</sub>	V
			3.0 V ≤ BV <sub>DD</sub> < 4.0 V	0.8BV <sub>DD</sub>		BV <sub>DD</sub>	V
	V <sub>IH2</sub>	<b>Note 2</b>	4.0 V ≤ EV <sub>DD</sub> ≤ 5.5 V	0.7EV <sub>DD</sub>		EV <sub>DD</sub>	V
			3.0 V ≤ EV <sub>DD</sub> < 4.0 V	0.8EV <sub>DD</sub>		EV <sub>DD</sub>	V
	V <sub>IH3</sub>	<b>Note 3</b>	4.0 V ≤ EV <sub>DD</sub> ≤ 5.5 V	0.7EV <sub>DD</sub>		EV <sub>DD</sub>	V
			3.0 V ≤ EV <sub>DD</sub> < 4.0 V	0.8EV <sub>DD</sub>		EV <sub>DD</sub>	V
V <sub>IH4</sub>	<b>Note 4</b>	4.5 V ≤ AV <sub>DD</sub> ≤ 5.5 V	0.7AV <sub>DD</sub>		AV <sub>DD</sub>	V	
Input voltage, low	V <sub>IL1</sub>	<b>Note 1</b>	BV <sub>SS</sub>		0.3BV <sub>DD</sub>	V	
	V <sub>IL2</sub>	<b>Note 2</b>	EV <sub>SS</sub>		0.3EV <sub>DD</sub>	V	
	V <sub>IL3</sub>	<b>Note 3</b>	EV <sub>SS</sub>		0.3EV <sub>DD</sub>	V	
	V <sub>IL4</sub>	<b>Note 4</b>	AV <sub>SS</sub>		0.3AV <sub>DD</sub>	V	
Output voltage, high	V <sub>OH1</sub>	<b>Note 1</b>	3.0 V ≤ BV <sub>DD</sub> ≤ 5.5 V, I <sub>OH</sub> = -100 μA	BV <sub>DD</sub> -0.5			V
			4.0 V ≤ BV <sub>DD</sub> ≤ 5.5 V, I <sub>OH</sub> = -3 mA	BV <sub>DD</sub> -1.0			V
	V <sub>OH2</sub>	<b>Notes 2, 3</b> (except RESET)	3.0 V ≤ EV <sub>DD</sub> ≤ 5.5 V, I <sub>OH</sub> = -100 μA	EV <sub>DD</sub> -0.5			V
			4.0 V ≤ EV <sub>DD</sub> ≤ 5.5 V, I <sub>OH</sub> = -3 mA	EV <sub>DD</sub> -1.0			V
Output voltage, low	V <sub>OL</sub>	I <sub>OL</sub> = 3 mA, 3.0 V ≤ BV <sub>DD</sub> , EV <sub>DD</sub> ≤ 5.5 V			0.5	V	
		I <sub>OL</sub> = 3 mA, 4.0 V ≤ BV <sub>DD</sub> , EV <sub>DD</sub> ≤ 5.5 V			0.4	V	
Input leakage current, high	I <sub>LIH</sub>	V <sub>I</sub> = V <sub>DD</sub> = BV <sub>DD</sub> = EV <sub>DD</sub> = AV <sub>DD</sub>			5	μA	
Input leakage current, low	I <sub>LIL</sub>	V <sub>I</sub> = 0 V			-5	μA	
Output leakage current, high	I <sub>LOH</sub>				5	μA	
Output leakage current, low	I <sub>LOL</sub>				-5	μA	

- Notes**
1. Ports 4, 5, 6, 9, CLKOUT, and their alternate-function pins
  2. P11, P14, P21, P24, P34, P35, P110 to P113, and their alternate-function pins
  3. P00 to P07, P10, P12, P13, P15, P20, P22, P23, P25 to P27, P30 to P33, P36, P37, P100 to P107,  $\overline{\text{RESET}}$ , and their alternate-function pins
  4. Ports 7, 8, and their alternate-function pins

DC Characteristics

(T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = 4.0 to 5.5 V, BV<sub>DD</sub> = EV<sub>DD</sub> = 3.0 to 5.5 V, AV<sub>DD</sub> = 4.5 to 5.5 V, V<sub>SS</sub> = AV<sub>SS</sub> = BV<sub>SS</sub> = EV<sub>SS</sub> = 0 V)

Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit	
Supply current	μPD703031A, μPD703031AY, μPD703033A, μPD703033AY	I <sub>DD1</sub>	In normal operation mode <sup>Note 1</sup>		25	40	mA	
		I <sub>DD2</sub>	In HALT mode <sup>Note 1</sup>		10	20	mA	
		I <sub>DD3</sub>	In IDLE mode <sup>Note 2</sup>	Watch timer operating		1	4	mA
				Watch timer, subsystem oscillator operating		13	70	μA
		I <sub>DD4</sub>	In STOP mode	Subsystem oscillator stopped, XT1 = V <sub>SS</sub>		8	70	μA
				In normal mode (subsystem operation) <sup>Note 3</sup>		50	150	μA
	I <sub>DD6</sub>	In IDLE mode (subsystem operation) <sup>Note 3</sup>		13	70	μA		
	μPD70F3033A, μPD70F3033AY	I <sub>DD1</sub>	In normal operation mode <sup>Note 1</sup>		33	60	mA	
		I <sub>DD2</sub>	In HALT mode <sup>Note 1</sup>		10	20	mA	
		I <sub>DD3</sub>	In IDLE mode <sup>Note 2</sup>	Watch timer operating		1	4	mA
				Watch timer, subsystem oscillator operating		13	100	μA
		I <sub>DD4</sub>	In STOP mode	Subsystem oscillator stopped, XT1 = V <sub>SS</sub>		8	100	μA
				In normal mode (subsystem operation) <sup>Note 3</sup>		200	600	μA
	I <sub>DD6</sub>	In IDLE mode (subsystem operation) <sup>Note 3</sup>		90	180	μA		
Pull-up resistance	R <sub>L</sub>	V <sub>IN</sub> = 0 V		10	30	100	kΩ	

- Notes**
1. f<sub>CPU</sub> = f<sub>XX</sub> = 20 MHz, all peripheral functions operating, output buffer: OFF
  2. f<sub>XX</sub> = 20 MHz
  3. f<sub>CPU</sub> = f<sub>XT</sub> = 32.768 kHz, main system clock oscillator stopped

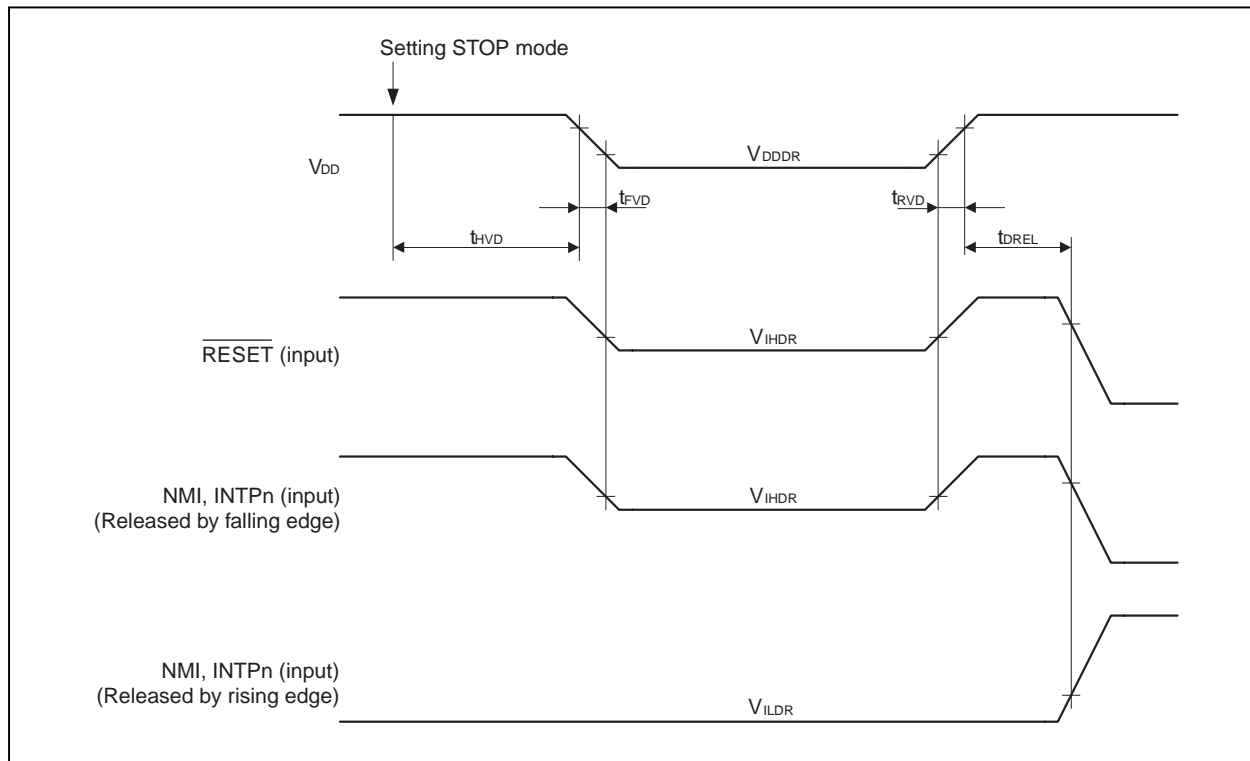
**Remark** TYP. values are reference values for when T<sub>A</sub> = 25°C, V<sub>DD</sub> = BV<sub>DD</sub> = EV<sub>DD</sub> = AV<sub>DD</sub> = 5.0 V. The current consumed by the output buffer is not included.

Data Retention Characteristics (T<sub>A</sub> = -40 to +85°C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention voltage	V <sub>DDDR</sub>	STOP mode	3.0 <sup>Note</sup>		5.5	V
Data retention current	I <sub>DDDR</sub>	V <sub>DD</sub> = V <sub>DDDR</sub> , XT1 = V <sub>SS</sub> (subsystem stopped)	μPD703031A, μPD703031AY, μPD703033A, μPD703033AY	8	70	μA
			μPD70F3033A, μPD70F3033AY	8	100	μA
Supply voltage rise time	t <sub>RVD</sub>		200			μs
Supply voltage fall time	t <sub>FVD</sub>		200			μs
Supply voltage hold time (from STOP mode setting)	t <sub>HVD</sub>		0			ms
STOP release signal input time	t <sub>DREL</sub>		0			ms
Data retention high-level input voltage	V <sub>IHDR</sub>	All input ports	0.9V <sub>DDDR</sub>		V <sub>DDDR</sub>	V
Data retention low-level input voltage	V <sub>ILDR</sub>	All input ports	0		0.1V <sub>DDDR</sub>	V

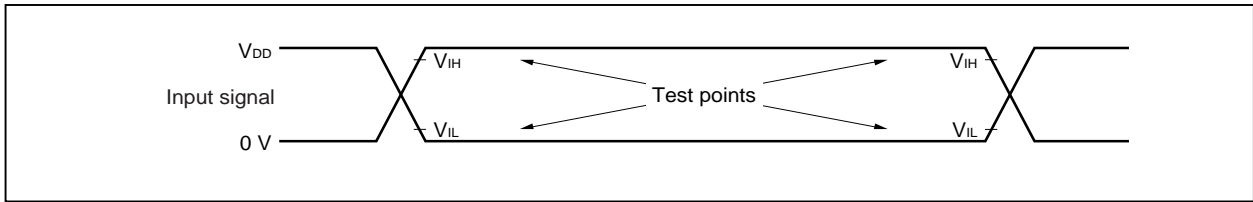
**Note** During STOP mode (subsystem oscillator operating), V<sub>DD</sub> = 3.5 to 5.5 V. Shifting to STOP mode or restoring from STOP mode must be performed at V<sub>DD</sub> = 4.0 V min.

**Remark** TYP. values are reference values for when T<sub>A</sub> = 25°C.

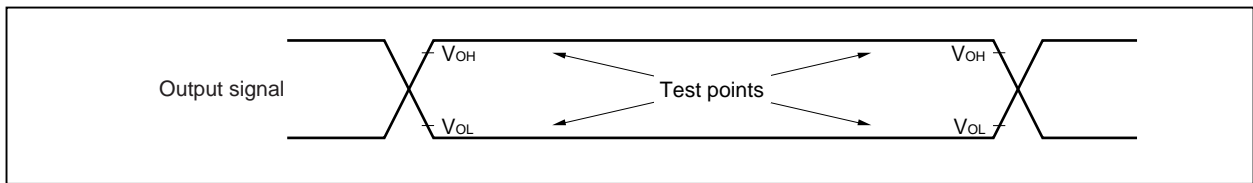


AC Characteristics ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $BV_{DD} = EV_{DD} = 3.0$  to  $5.5$  V,  $AV_{DD} = 4.5$  to  $5.5$  V,  $V_{SS} = AV_{SS} = BV_{SS} = EV_{SS} = 0$  V)

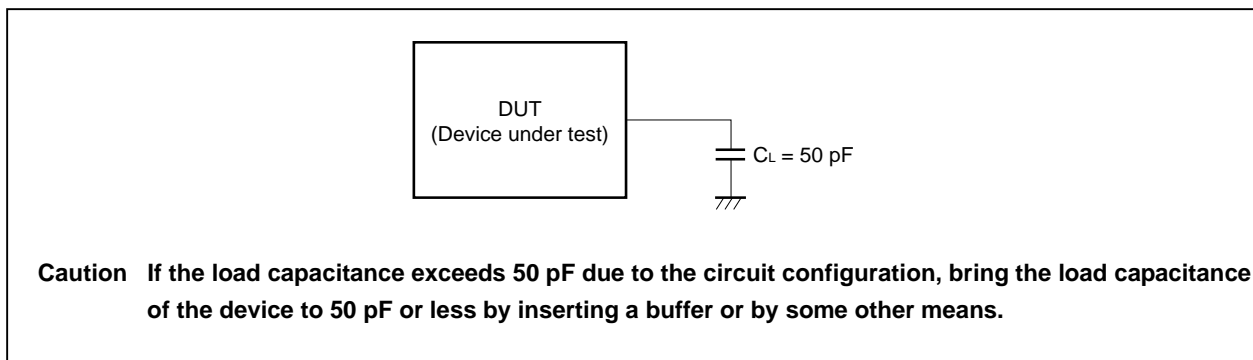
AC Test Input Waveform ( $V_{DD}$ :  $EV_{DD}$ ,  $BV_{DD}$ ,  $AV_{DD}$ )



AC Test Output Test Points ( $EV_{DD}$ ,  $BV_{DD}$ )



Load Conditions



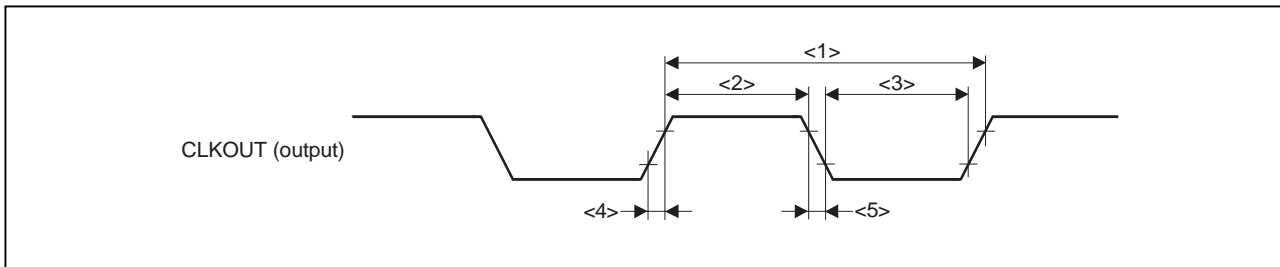
(1) Clock timing

(a)  $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = BV_{DD} = 4.0$  to  $5.5$  V,  $V_{SS} = BV_{SS} = 0$  V

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
CLKOUT output cycle	<1> $t_{CYK}$		50 ns	31.2 $\mu\text{s}$	
CLKOUT high-level width	<2> $t_{WKH}$		$0.4t_{CYK} - 12$		ns
CLKOUT low-level width	<3> $t_{WKL}$		$0.4t_{CYK} - 12$		ns
CLKOUT rise time	<4> $t_{KR}$			12	ns
CLKOUT fall time	<5> $t_{KF}$			12	ns

(b)  $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $BV_{DD} = 3.0$  to  $4.0$  V,  $V_{SS} = BV_{SS} = 0$  V

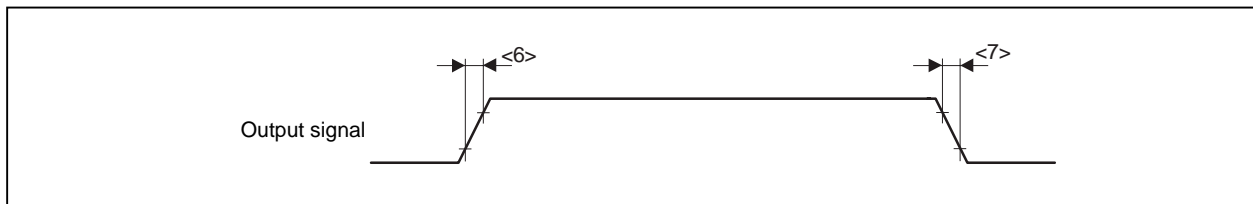
Parameter	Symbol	Conditions	MIN.	MAX.	Unit
CLKOUT output cycle	<1> $t_{CYK}$		58.8 ns	31.2 $\mu\text{s}$	
CLKOUT high-level width	<2> $t_{WKH}$		$0.4t_{CYK} - 15$		ns
CLKOUT low-level width	<3> $t_{WKL}$		$0.4t_{CYK} - 15$		ns
CLKOUT rise time	<4> $t_{KR}$			15	ns
CLKOUT fall time	<5> $t_{KF}$			15	ns



(2) Output waveform (other than port 4, port 5, port 6, port 9, X1, and CLKOUT)

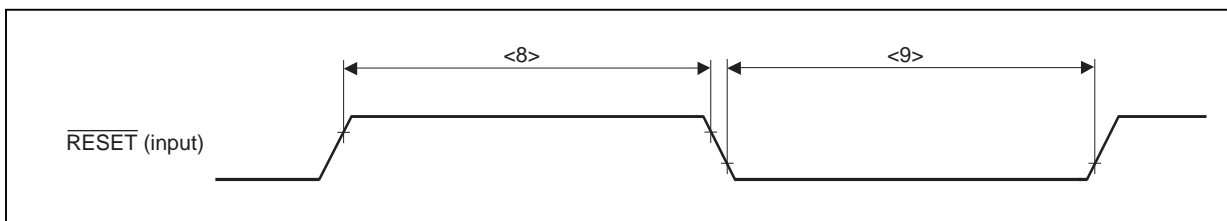
(T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = 4.0 to 5.5 V, BV<sub>DD</sub> = EV<sub>DD</sub> = 3.0 to 5.5 V, V<sub>SS</sub> = BV<sub>SS</sub> = EV<sub>SS</sub> = 0 V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Output rise time	<6>   t <sub>OR</sub>			20	ns
Output fall time	<7>   t <sub>OF</sub>			20	ns



(3) Reset timing

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
RESET pin high-level width	<8>   t <sub>WRSH</sub>		500		ns
RESET pin low-level width	<9>   t <sub>WRSL</sub>		500		ns



(4) Bus timing

(a) Clock asynchronous ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = BV_{DD} = 4.0$  to  $5.5$  V,  $V_{SS} = BV_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Address setup time (to $\overline{\text{ASTB}}\downarrow$ )	<10> $t_{\text{SAST}}$		$0.5T - 16$		ns
Address hold time (from $\overline{\text{ASTB}}\downarrow$ )	<11> $t_{\text{HSTA}}$		$0.5T - 15$		ns
Address float from $\overline{\text{DSTB}}\downarrow$	<12> $t_{\text{FDA}}$			0	ns
Data input setup time from address	<13> $t_{\text{SAID}}$			$(2 + n)T - 40$	ns
Data input setup time from $\overline{\text{DSTB}}\downarrow$	<14> $t_{\text{SDID}}$			$(1 + n)T - 40$	ns
Delay time from $\overline{\text{ASTB}}\downarrow$ to $\overline{\text{DSTB}}\downarrow$	<15> $t_{\text{DSTD}}$		$0.5T - 15$		ns
Data input hold time (from $\overline{\text{DSTB}}\uparrow$ )	<16> $t_{\text{HDID}}$		0		ns
Address output time from $\overline{\text{DSTB}}\uparrow$	<17> $t_{\text{DDA}}$		$(1 + i)T - 15$		ns
Delay time from $\overline{\text{DSTB}}\uparrow$ to $\overline{\text{ASTB}}\uparrow$	<18> $t_{\text{DDST1}}$		$0.5T - 15$		ns
Delay time from $\overline{\text{DSTB}}\uparrow$ to $\overline{\text{ASTB}}\downarrow$	<19> $t_{\text{DDST2}}$		$(1.5 + i)T - 15$		ns
$\overline{\text{DSTB}}$ low-level width	<20> $t_{\text{WDL}}$		$(1 + n)T - 22$		ns
$\overline{\text{ASTB}}$ high-level width	<21> $t_{\text{WSTH}}$		$T - 15$		ns
Data output time from $\overline{\text{DSTB}}\downarrow$	<22> $t_{\text{DOD}}$			10	ns
Data output setup time (to $\overline{\text{DSTB}}\uparrow$ )	<23> $t_{\text{SODD}}$		$(1 + n)T - 25$		ns
Data output hold time (from $\overline{\text{DSTB}}\uparrow$ )	<24> $t_{\text{HODD}}$		$T - 20$		ns
$\overline{\text{WAIT}}$ setup time (to address)	<25> $t_{\text{SAWT1}}$	$n \geq 1$		$1.5T - 40$	ns
	<26> $t_{\text{SAWT2}}$	$n \geq 1$		$(1.5 + n)T - 40$	ns
$\overline{\text{WAIT}}$ hold time (from address)	<27> $t_{\text{HAWT1}}$	$n \geq 1$	$(0.5 + n)T$		ns
	<28> $t_{\text{HAWT2}}$	$n \geq 1$	$(1.5 + n)T$		ns
$\overline{\text{WAIT}}$ setup time (to $\overline{\text{ASTB}}\downarrow$ )	<29> $t_{\text{SSTWT1}}$	$n \geq 1$		$T - 32$	ns
	<30> $t_{\text{SSTWT2}}$	$n \geq 1$		$(1 + n)T - 32$	ns
$\overline{\text{WAIT}}$ hold time (from $\overline{\text{ASTB}}\downarrow$ )	<31> $t_{\text{HSTWT1}}$	$n \geq 1$	$nT$		ns
	<32> $t_{\text{HSTWT2}}$	$n \geq 1$	$(1 + n)T$		ns
$\overline{\text{HLDRQ}}$ high-level width	<33> $t_{\text{WHQH}}$		$T + 10$		ns
$\overline{\text{HLDAK}}$ low-level width	<34> $t_{\text{WHAL}}$		$T - 15$		ns
Bus output delay time from $\overline{\text{HLDAK}}\uparrow$	<35> $t_{\text{DHAC}}$		-6		ns
Delay time from $\overline{\text{HLDRQ}}\downarrow$ to $\overline{\text{HLDAK}}\downarrow$	<36> $t_{\text{DQHA1}}$			$(2n + 7.5)T + 25$	ns
Delay time from $\overline{\text{HLDRQ}}\uparrow$ to $\overline{\text{HLDAK}}\uparrow$	<37> $t_{\text{DQHA2}}$		$0.5T$	$1.5T + 25$	ns

Remarks 1.  $T = 1/f_{\text{CPU}}$  ( $f_{\text{CPU}}$ : CPU clock frequency)

2.  $n$ : Number of wait clocks inserted in the bus cycle.

The sampling timing changes when a programmable wait is inserted.

3. The values in the above specifications are values for when clocks with a 5:5 duty ratio are input from X1.



(b) Clock asynchronous ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $BV_{DD} = 3.0$  to  $4.0$  V,  $V_{SS} = BV_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Address setup time (to ASTB↓)	<10> $t_{sAST}$		0.5T – 20		ns
Address hold time (from ASTB↓)	<11> $t_{hSTA}$		0.5T – 20		ns
Address float from $\overline{DSTB}\downarrow$	<12> $t_{fDA}$			0	ns
Data input setup time from address	<13> $t_{sAID}$			(2 + n)T – 50	ns
Data input setup time from $\overline{DSTB}\downarrow$	<14> $t_{sDID}$			(1 + n)T – 50	ns
Delay time from ASTB↓ to $\overline{DSTB}\downarrow$	<15> $t_{dSTD}$		0.5T – 15		ns
Data input hold time (from $\overline{DSTB}\uparrow$ )	<16> $t_{hDID}$		0		ns
Address output time from $\overline{DSTB}\uparrow$	<17> $t_{DDA}$		(1 + i)T – 15		ns
Delay time from $\overline{DSTB}\uparrow$ to ASTB↑	<18> $t_{DDST1}$		0.5T – 15		ns
Delay time from $\overline{DSTB}\uparrow$ to ASTB↓	<19> $t_{DDST2}$		(1.5 + i)T – 15		ns
$\overline{DSTB}$ low-level width	<20> $t_{WDL}$		(1 + n)T – 35		ns
ASTB high-level width	<21> $t_{WSTH}$		T – 15		ns
Data output time from $\overline{DSTB}\downarrow$	<22> $t_{DDOD}$			10	ns
Data output setup time (to $\overline{DSTB}\uparrow$ )	<23> $t_{sODD}$		(1 + n)T – 35		ns
Data output hold time (from $\overline{DSTB}\uparrow$ )	<24> $t_{hDOD}$		T – 25		ns
$\overline{WAIT}$ setup time (to address)	<25> $t_{sAWT1}$	$n \geq 1$		1.5T – 55	ns
	<26> $t_{sAWT2}$	$n \geq 1$		(1.5 + n)T – 55	ns
$\overline{WAIT}$ hold time (from address)	<27> $t_{hAWT1}$	$n \geq 1$	(0.5 + n)T		ns
	<28> $t_{hAWT2}$	$n \geq 1$	(1.5 + n)T		ns
$\overline{WAIT}$ setup time (to ASTB↓)	<29> $t_{sSTWT1}$	$n \geq 1$		T – 45	ns
	<30> $t_{sSTWT2}$	$n \geq 1$		(1 + n)T – 45	ns
$\overline{WAIT}$ hold time (from ASTB↓)	<31> $t_{hSTWT1}$	$n \geq 1$	nT		ns
	<32> $t_{hSTWT2}$	$n \geq 1$	(1 + n)T		ns
$\overline{HLDRQ}$ high-level width	<33> $t_{WHQH}$		T + 10		ns
$\overline{HLDAK}$ low-level width	<34> $t_{WHAL}$		T – 25		ns
Bus output delay time from $\overline{HLDAK}\uparrow$	<35> $t_{DHAC}$		–6		ns
Delay time from $\overline{HLDRQ}\downarrow$ to $\overline{HLDAK}\downarrow$	<36> $t_{DHQHA1}$			(2n + 7.5)T + 25	ns
Delay time from $\overline{HLDRQ}\uparrow$ to $\overline{HLDAK}\uparrow$	<37> $t_{DHQHA2}$		0.5T	1.5T + 25	ns

Remarks 1.  $T = 1/f_{CPU}$  ( $f_{CPU}$ : CPU clock frequency)

2. n: Number of wait clocks inserted in the bus cycle.

The sampling timing changes when a programmable wait is inserted.

3. The values in the above specifications are values for when clocks with a 5:5 duty ratio are input from X1.

(c) Clock synchronous ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = BV_{DD} = 4.0$  to  $5.5$  V,  $V_{SS} = BV_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Delay time from CLKOUT↑ to address	<38> $t_{DKA}$		0	19	ns
Delay time from CLKOUT↑ to address float	<39> $t_{FKA}$		-12	10	ns
Delay time from CLKOUT↓ to ASTB	<40> $t_{DKST}$		0	19	ns
Delay time from CLKOUT↑ to $\overline{DSTB}$	<41> $t_{DKD}$		0	19	ns
Data input setup time (to CLKOUT↑)	<42> $t_{SIDK}$		20		ns
Data input hold time (from CLKOUT↑)	<43> $t_{HKID}$		5		ns
Data output delay time from CLKOUT↑	<44> $t_{DKOD}$			19	ns
$\overline{WAIT}$ setup time (to CLKOUT↓)	<45> $t_{SWTK}$		20		ns
$\overline{WAIT}$ hold time (from CLKOUT↓)	<46> $t_{HKWT}$		5		ns
$\overline{HLDRQ}$ setup time (to CLKOUT↓)	<47> $t_{SHQK}$		20		ns
$\overline{HLDRQ}$ hold time (from CLKOUT↓)	<48> $t_{HKHQ}$		5		ns
Delay time from CLKOUT↑ to address float (during bus hold)	<49> $t_{DKF}$			19	ns
Delay time from CLKOUT↑ to $\overline{HLDAK}$	<50> $t_{DKHA}$			19	ns

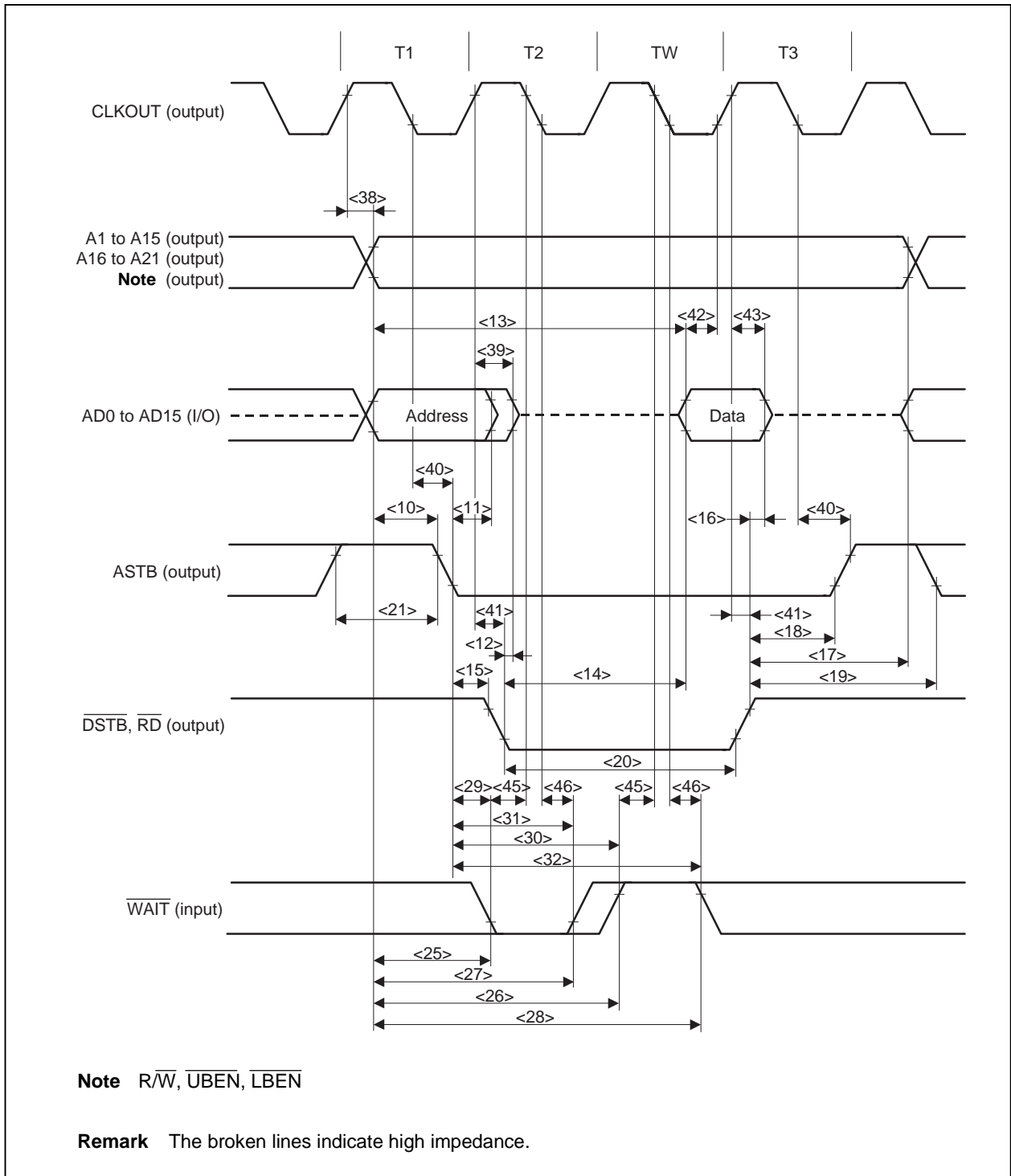
**Remark** The values in the above specifications are values for when clocks with a 5:5 duty ratio are input from X1.

(d) Clock synchronous ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $BV_{DD} = 3.0$  to  $4.0$  V,  $V_{SS} = BV_{SS} = 0$  V)

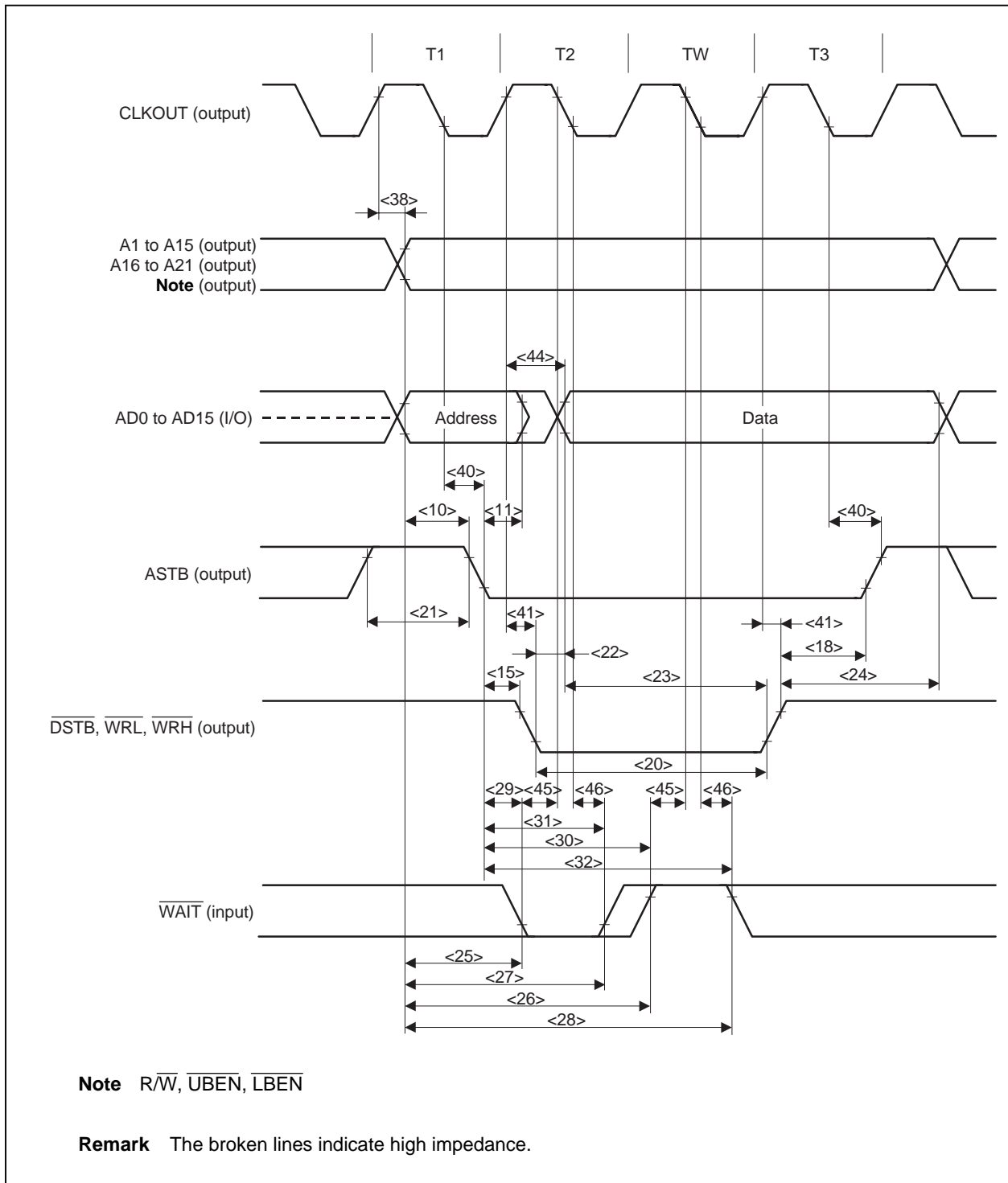
Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Delay time from CLKOUT↑ to address	<38> $t_{DKA}$		0	22	ns
Delay time from CLKOUT↑ to address float	<39> $t_{FKA}$		-16	10	ns
Delay time from CLKOUT↓ to ASTB	<40> $t_{DKST}$		0	19	ns
Delay time from CLKOUT↑ to $\overline{DSTB}$	<41> $t_{DKD}$		0	22	ns
Data input setup time (to CLKOUT↑)	<42> $t_{SIDK}$		20		ns
Data input hold time (from CLKOUT↑)	<43> $t_{HKID}$		5		ns
Data output delay time from CLKOUT↑	<44> $t_{DKOD}$			22	ns
$\overline{WAIT}$ setup time (to CLKOUT↓)	<45> $t_{SWTK}$		24		ns
$\overline{WAIT}$ hold time (from CLKOUT↓)	<46> $t_{HKWT}$		5		ns
$\overline{HLDRQ}$ setup time (to CLKOUT↓)	<47> $t_{SHQK}$		24		ns
$\overline{HLDRQ}$ hold time (from CLKOUT↓)	<48> $t_{HKHQ}$		5		ns
Delay time from CLKOUT↑ to address float (during bus hold)	<49> $t_{DKF}$			19	ns
Delay time from CLKOUT↑ to $\overline{HLDAK}$	<50> $t_{DKHA}$			19	ns

**Remark** The values in the above specifications are values for when clocks with a 5:5 duty ratio are input from X1.

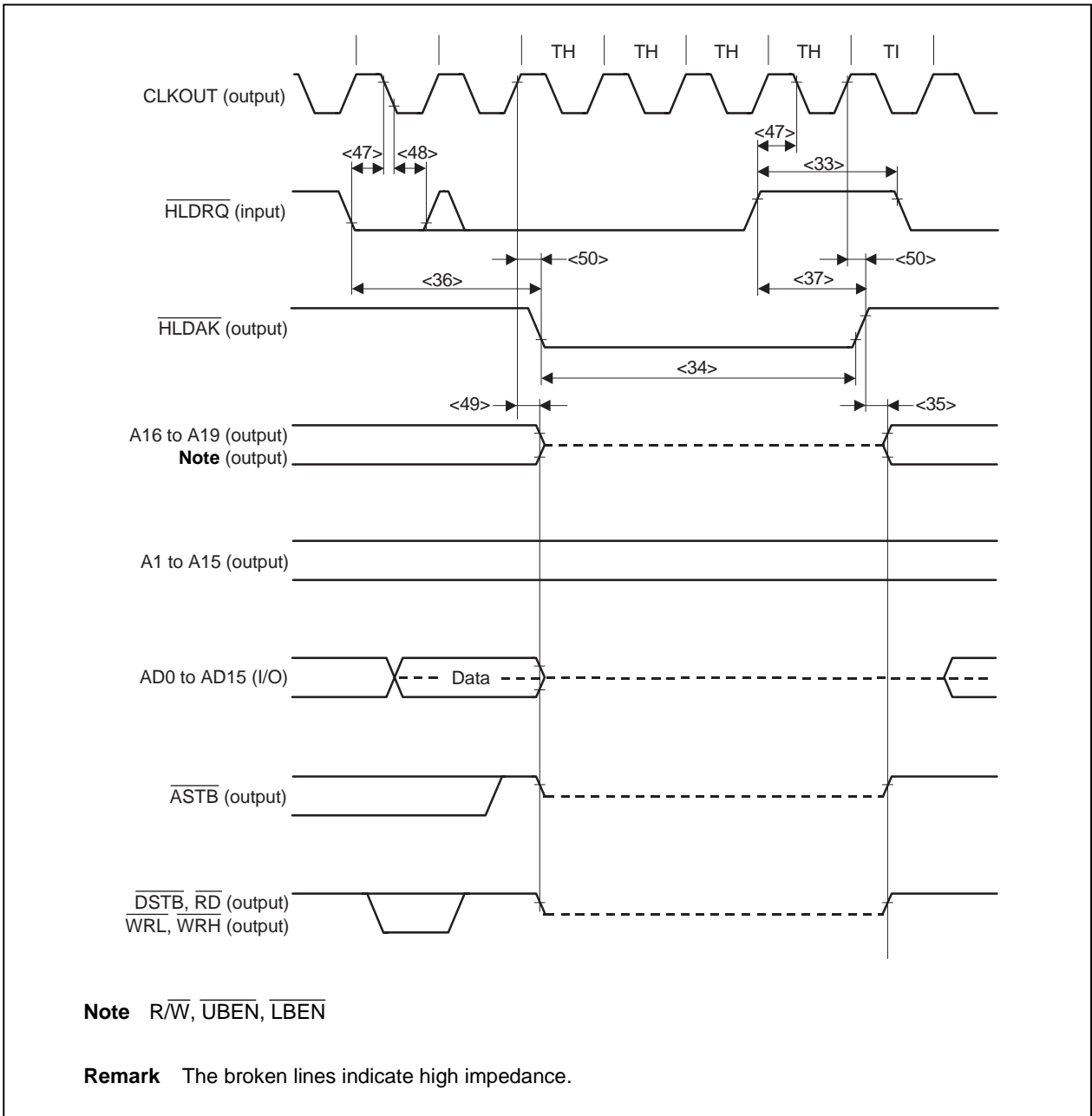
(e) Read cycle (CLKOUT synchronous/asynchronous, 1 wait)



(f) Write cycle (CLKOUT synchronous/asynchronous, 1 wait)



(g) Bus hold timing



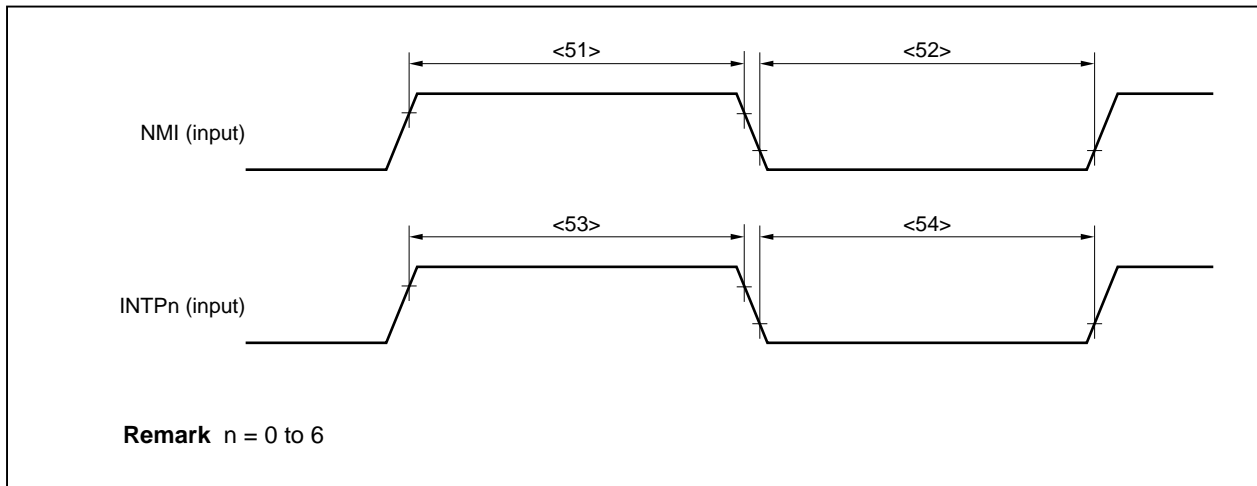
(5) Interrupt timing

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $E_{VDD} = 3.0$  to  $5.5$  V,  $V_{SS} = A_{VSS} = B_{VSS} = E_{VSS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
NMI high-level width	<51> $t_{WNIH}$		500		ns
NMI low-level width	<52> $t_{WNIL}$		500		ns
INTPn high-level width	<53> $t_{WITH}$	n = 0 to 3, analog noise elimination	500		ns
		n = 4, 5, digital noise elimination	$3T + 20$		ns
		n = 6, digital noise elimination	$3T_{\text{smp}} + 20$		ns
INTPn low-level width	<54> $t_{WITL}$	n = 0 to 3, analog noise elimination	500		ns
		n = 4, 5, digital noise elimination	$3T + 20$		ns
		n = 6, digital noise elimination	$3T_{\text{smp}} + 20$		ns

Remarks 1.  $T = 1/f_{xx}$

2.  $T_{\text{smp}}$  = Noise elimination sampling clock cycle



(6) RPU timing (T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = 4.0 to 5.5 V, EV<sub>DD</sub> = 3.0 to 5.5 V, V<sub>SS</sub> = AV<sub>SS</sub> = BV<sub>SS</sub> = EV<sub>SS</sub> = 0 V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
TIn0, TIn1 high-level width	<55>   t <sub>TIHn</sub>	n = 0, 1	2T <sub>sam</sub> + 20 <sup>Note</sup>		ns
TIn0, TIn1 low-level width	<56>   t <sub>TILn</sub>	n = 0, 1	2T <sub>sam</sub> + 20 <sup>Note</sup>		ns
TIn high-level width	<57>   t <sub>TIHn</sub>	n = 2 to 5	3T + 20		ns
TIn low-level width	<58>   t <sub>TILn</sub>	n = 2 to 5	3T + 20		ns

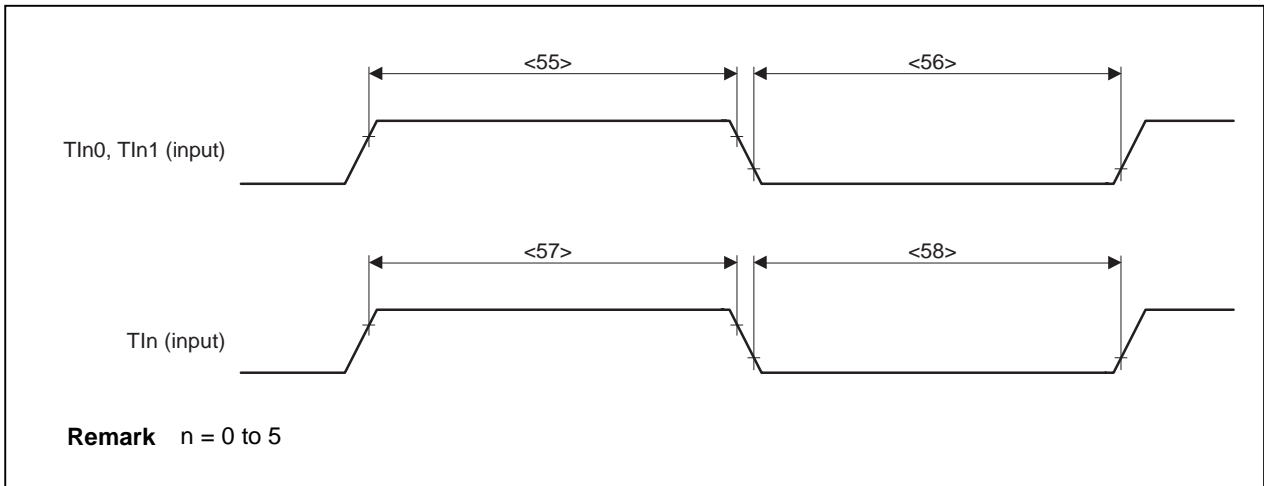
**Note** T<sub>sam</sub> can select the following count clocks by setting the PRMn2 to PRMn0 bits of prescaler mode registers n0, n1 (PRMn0, PRMn1).

When n = 0 (TM0), T<sub>sam</sub> = 2T, 4T, 16T, 64T, 256T, or 1/INTWTONI cycle

When n = 1 (TM1), T<sub>sam</sub> = 2T, 4T, 16T, 32T, 128T, or 256T

However, when the TIn0 valid edge is selected as the count clock, T<sub>sam</sub> = 4T.

**Remark** T = 1/f<sub>xx</sub>

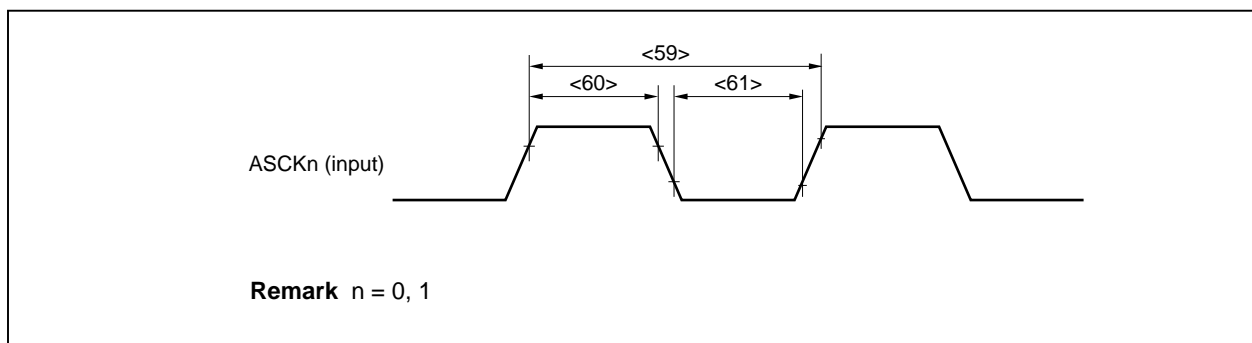


(7) Asynchronous serial interface (UART0, UART1) timing

( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $E_{VDD} = 3.0$  to  $5.5$  V,  $V_{SS} = E_{VSS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
ASCKn cycle time	<59> $t_{CY13}$		200		ns
ASCKn high-level width	<60> $t_{KH13}$		80		ns
ASCKn low-level width	<61> $t_{KO13}$		80		ns

Remark n = 0, 1





(8) 3-wire serial interface (CSI0 to CSI3) timing

(a) Master mode ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $EV_{DD} = 3.0$  to  $5.5$  V,  $V_{SS} = EV_{SS} = 0$  V)

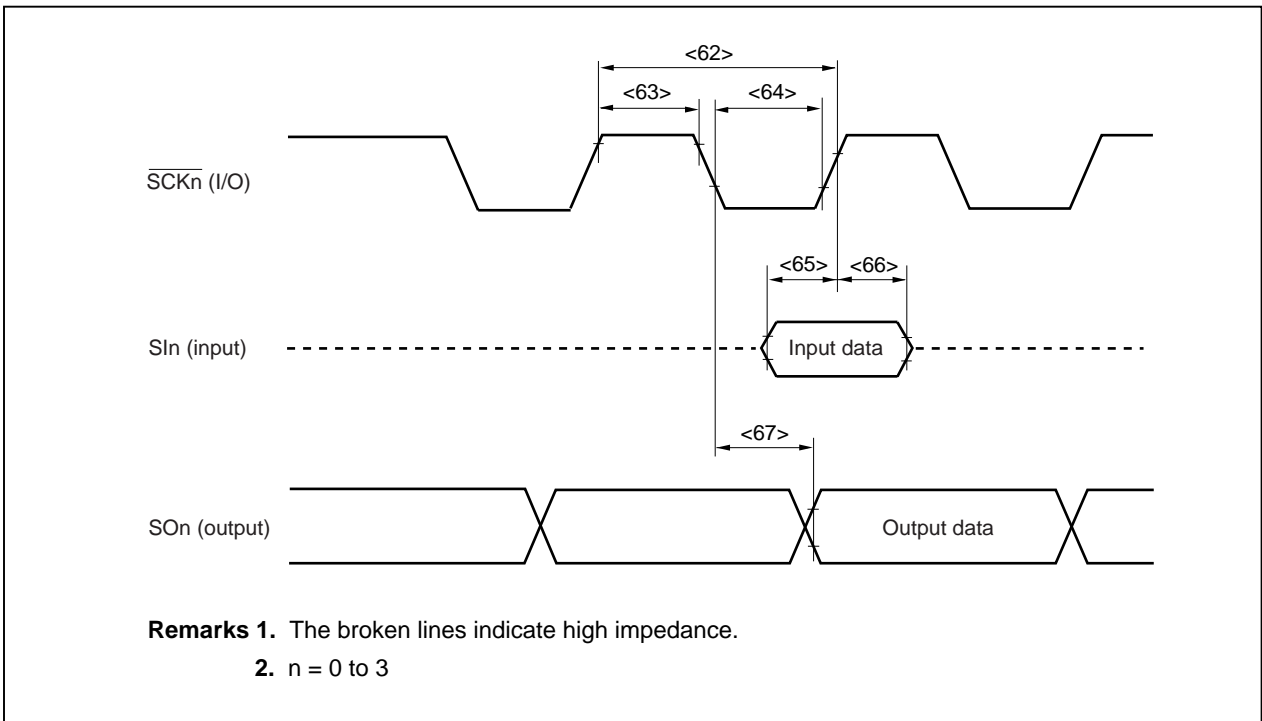
Parameter	Symbol		Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKn}}$ cycle	<62>	$t_{\text{CY1}}$		400		ns
$\overline{\text{SCKn}}$ high-level width	<63>	$t_{\text{KH1}}$		140		ns
$\overline{\text{SCKn}}$ low-level width	<64>	$t_{\text{KL1}}$		140		ns
SIn setup time (to $\overline{\text{SCKn}}\uparrow$ )	<65>	$t_{\text{SIK1}}$		50		ns
SIn hold time (from $\overline{\text{SCKn}}\uparrow$ )	<66>	$t_{\text{KSH1}}$		50		ns
Delay time from $\overline{\text{SCKn}}\downarrow$ to SOn output	<67>	$t_{\text{KSO1}}$			60	ns

Remark n = 0 to 3

(b) Slave mode ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $EV_{DD} = 3.0$  to  $5.5$  V,  $V_{SS} = EV_{SS} = 0$  V)

Parameter	Symbol		Conditions	MIN.	MAX.	Unit
$\overline{\text{SCKn}}$ cycle	<62>	$t_{\text{CY2}}$		400		ns
$\overline{\text{SCKn}}$ high-level width	<63>	$t_{\text{KH2}}$		140		ns
$\overline{\text{SCKn}}$ low-level width	<64>	$t_{\text{KL2}}$		140		ns
SIn setup time (to $\overline{\text{SCKn}}\uparrow$ )	<65>	$t_{\text{SIK2}}$		50		ns
SIn hold time (from $\overline{\text{SCKn}}\uparrow$ )	<66>	$t_{\text{KSI2}}$		50		ns
Delay time from $\overline{\text{SCKn}}\downarrow$ to SOn output	<67>	$t_{\text{KSO2}}$	$4.0\text{ V} \leq EV_{DD} \leq 5.5\text{ V}$		60	ns
			$3.0\text{ V} \leq EV_{DD} < 4.0\text{ V}$		100	ns

Remark n = 0 to 3



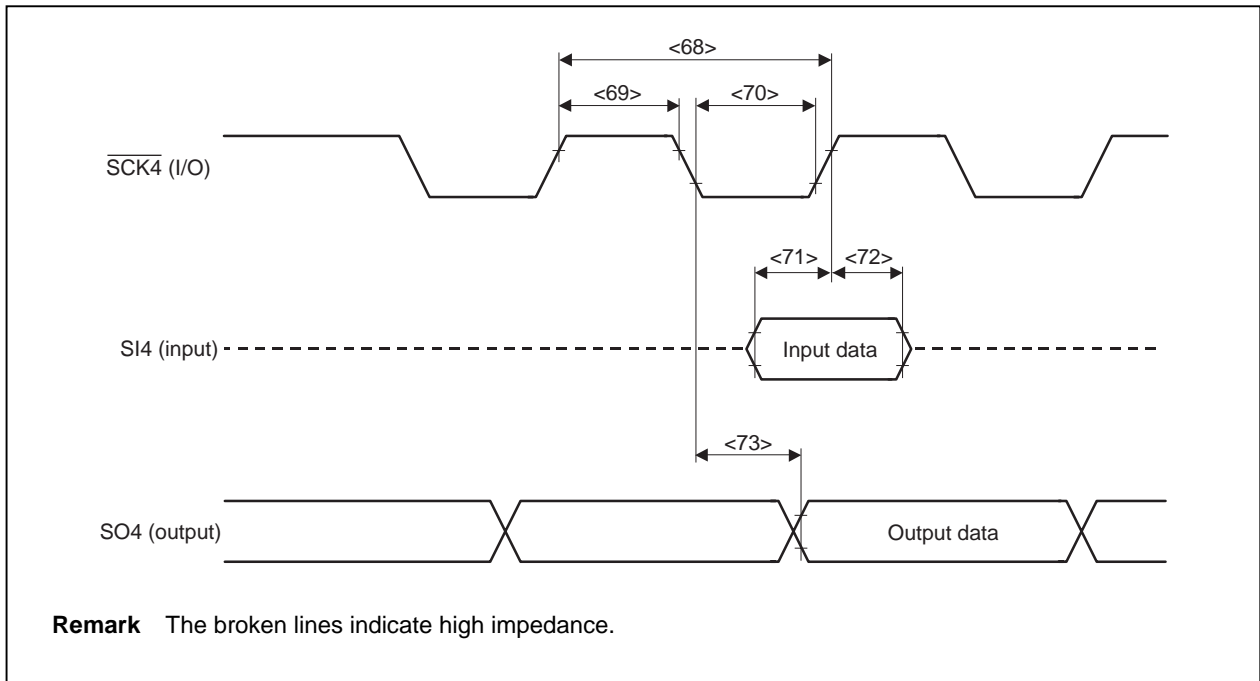
(9) 3-wire variable length serial interface (CSI4) timing

(a) Master mode ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $EV_{DD} = 3.0$  to  $5.5$  V,  $V_{SS} = EV_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit	
$\overline{\text{SCK4}}$ cycle	<68>	$t_{\text{KCY1}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	200		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	400		ns
$\overline{\text{SCK4}}$ high-level width	<69>	$t_{\text{KH1}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	60		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	140		ns
$\overline{\text{SCK4}}$ low-level width	<70>	$t_{\text{KL1}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	60		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	140		ns
SI4 setup time (to $\overline{\text{SCK4}}\uparrow$ )	<71>	$t_{\text{SIK1}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	25		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	50		ns
SI4 hold time (from $\overline{\text{SCK4}}\uparrow$ )	<72>	$t_{\text{KS1}}$	20		ns	
Delay time from $\overline{\text{SCK4}}\downarrow$ to SO4 output	<73>	$t_{\text{KSO1}}$		55	ns	

(b) Slave mode ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $EV_{DD} = 3.0$  to  $5.5$  V,  $V_{SS} = EV_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit	
$\overline{\text{SCK4}}$ cycle	<68>	$t_{\text{KCY2}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	200		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	400		ns
$\overline{\text{SCK4}}$ high-level width	<69>	$t_{\text{KH2}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	60		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	140		ns
$\overline{\text{SCK4}}$ low-level width	<70>	$t_{\text{KL2}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	60		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	140		ns
SI4 setup time (to $\overline{\text{SCK4}}\uparrow$ )	<71>	$t_{\text{SIK2}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$	25		ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$	50		ns
SI4 hold time (from $\overline{\text{SCK4}}\uparrow$ )	<72>	$t_{\text{KS2}}$	20		ns	
Delay time from $\overline{\text{SCK4}}\downarrow$ to SO4 output	<73>	$t_{\text{KSO2}}$	$4.0 \text{ V} \leq EV_{DD} \leq 5.5 \text{ V}$		55	ns
			$3.0 \text{ V} \leq EV_{DD} < 4.0 \text{ V}$		100	ns



(10) I<sup>2</sup>C bus mode (μPD703031AY, 703033AY, 70F3033AY only)

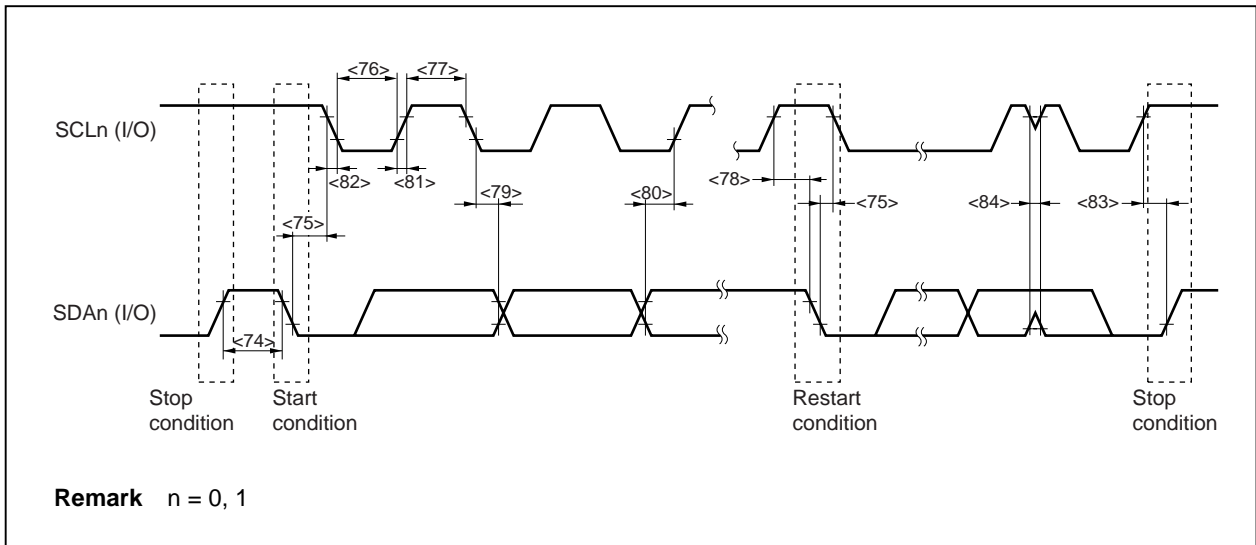
(T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = 4.0 to 5.5 V, EV<sub>DD</sub> = 3.0 to 5.5 V, V<sub>SS</sub> = EV<sub>SS</sub> = 0 V)

Parameter		Symbol	Normal Mode		High-Speed Mode		Unit	
			MIN.	MAX.	MIN.	MAX.		
SCLn clock frequency		-	f <sub>CLK</sub>	0	100	0	400	kHz
Bus-free time (between stop/start conditions)		<74>	t <sub>BUF</sub>	4.7	-	1.3	-	μs
Hold time <sup>Note 1</sup>		<75>	t <sub>HD:STA</sub>	4.0	-	0.6	-	μs
SCLn clock low-level width		<76>	t <sub>LOW</sub>	4.7	-	1.3	-	μs
SCLn clock high-level width		<77>	t <sub>HIGH</sub>	4.0	-	0.6	-	μs
Setup time for start/restart conditions		<78>	t <sub>SU:STA</sub>	4.7	-	0.6	-	μs
Data hold time	CBUS compatible master	<79>	t <sub>HD:DAT</sub>	5.0	-	-	-	μs
	I <sup>2</sup> C mode			0 <sup>Note 2</sup>	-	0 <sup>Note 2</sup>	0.9 <sup>Note 3</sup>	μs
Data setup time		<80>	t <sub>SU:DAT</sub>	250	-	100 <sup>Note 4</sup>	-	ns
SDAn and SCLn signal rise time		<81>	t <sub>R</sub>	-	1000	20 + 0.1Cb <sup>Note 5</sup>	300	ns
SDAn and SCLn signal fall time		<82>	t <sub>F</sub>	-	300	20 + 0.1Cb <sup>Note 5</sup>	300	ns
Stop condition setup time		<83>	t <sub>SU:STO</sub>	4.0	-	0.6	-	μs
Pulse width of spike suppressed by input filter		<84>	t <sub>SP</sub>	-	-	0	50	ns
Capacitance load of each bus line		-	C <sub>b</sub>	-	400	-	400	pF

- Notes**
- At the start condition, the first clock pulse is generated after the hold time.
  - The system requires a minimum of 300 ns hold time internally for the SDAn signal (at V<sub>IHmin.</sub> of SCLn signal) in order to occupy the undefined area at the falling edge of SCLn.
  - If the system does not extend the SCLn signal low hold time (t<sub>LOW</sub>), only the maximum data hold time (t<sub>HD:DAT</sub>) needs to be satisfied.
  - The high-speed mode I<sup>2</sup>C bus can be used in the normal-mode I<sup>2</sup>C bus system. In this case, set the high-speed mode I<sup>2</sup>C bus so that it meets the following conditions.
    - If the system does not extend the SCLn signal's low state hold time:
 
$$t_{HD:DAT} \geq 250 \text{ ns}$$
    - If the system extends the SCLn signal's low state hold time:
 

Transmit the following data bit to the SDAn line prior to the SCLn line release (t<sub>Rmax.</sub> + t<sub>SU:DAT</sub> = 1000 + 250 = 1250 ns: Normal mode I<sup>2</sup>C bus specification).
  - C<sub>b</sub>: Total capacitance of one bus line (unit: pF)

**Remark** n = 0, 1



**A/D Converter Characteristics (T<sub>A</sub> = -40 to +85°C, V<sub>DD</sub> = AV<sub>DD</sub> = AV<sub>REF</sub>, V<sub>SS</sub> = AV<sub>SS</sub> = 0 V, Output pin load capacitance: C<sub>L</sub> = 50 pF)**

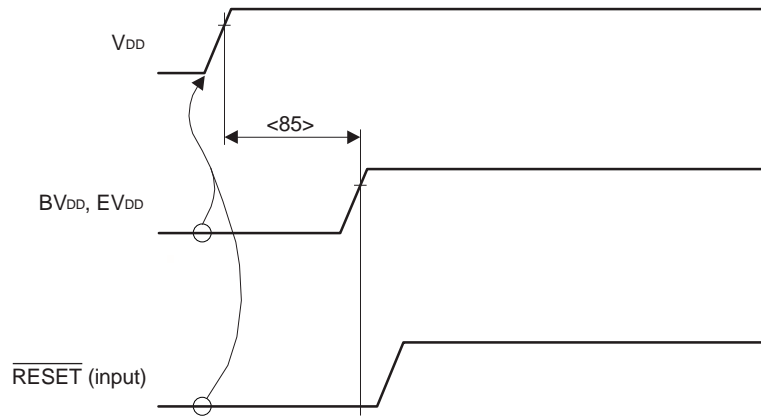
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution	—		10	10	10	bit
Overall error <sup>Note 1</sup>	—	ADM2 = 00H			±0.6	%FSR
		ADM2 = 01H			±1.0	%FSR
Conversion time	t <sub>CONV</sub>		5		10	μs
Zero-scale error <sup>Note 1</sup>	AINL				±0.4	%FSR
Full-scale error <sup>Note 1</sup>	AINL	ADM2 = 00H			±0.4	%FSR
		ADM2 = 01H			±0.6	%FSR
Integral linearity error <sup>Note 2</sup>	INL	ADM2 = 00H			±4.0	LSB
		ADM2 = 01H			±6.0	LSB
Differential linearity error <sup>Note 2</sup>	DNL	ADM2 = 00H			±4.0	LSB
		ADM2 = 01H			±6.0	LSB
Analog reference voltage	AV <sub>REF</sub>	AV <sub>REF</sub> = AV <sub>DD</sub>	4.5		5.5	V
Analog power supply voltage	AV <sub>DD</sub>		4.5		5.5	V
Analog input voltage	V <sub>IAN</sub>		AV <sub>SS</sub>		AV <sub>REF</sub>	V
AV <sub>REF</sub> input current	AI <sub>REF</sub>			1	2	mA
AV <sub>DD</sub> current	AI <sub>DD</sub>	ADM2 = 00H		3	6	mA
		ADM2 = 01H		4	8	mA

- Notes** 1. Excluding quantization error (±0.05 %FSR)  
 2. Excluding quantization error (±0.5 LSB)

- Remarks** 1. LSB: Least Significant Bit  
 FSR: Full Scale Range  
 2. ADM2: A/D converter mode register 2

Regulator ( $T_A = -40$  to  $+85^\circ\text{C}$ ,  $V_{DD} = 4.0$  to  $5.5$  V,  $V_{SS} = 0$  V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Output stabilization time	<85> $t_{REG}$	Stabilization capacitance $C = 1 \mu\text{F}$ (Connected to REGC pin)	1			ms



- Cautions**
1. Be sure to start inputting supply voltage ( $V_{DD}$ ) when  $\overline{\text{RESET}} = V_{SS} = EV_{SS} = BV_{SS} = 0$  V (the above state), and make  $\overline{\text{RESET}}$  high level after the  $t_{REG}$  period has elapsed.
  2. If supply voltage ( $BV_{DD}$  or  $EV_{DD}$ ) is input before the  $t_{REG}$  period has elapsed following the input of supply voltage ( $V_{DD}$ ), data may be driven from the pins until the  $t_{REG}$  period has elapsed because the I/O buffers' power supply was turned on while the circuit was in an undefined state. To avoid this situation, it is recommended to input supply voltage ( $BV_{DD}$  or  $EV_{DD}$ ) after the  $t_{REG}$  period has elapsed following the input of supply voltage ( $V_{DD}$ ).

4.1 Flash Memory Programming Mode (μPD70F3033A, 70F3033AY only)

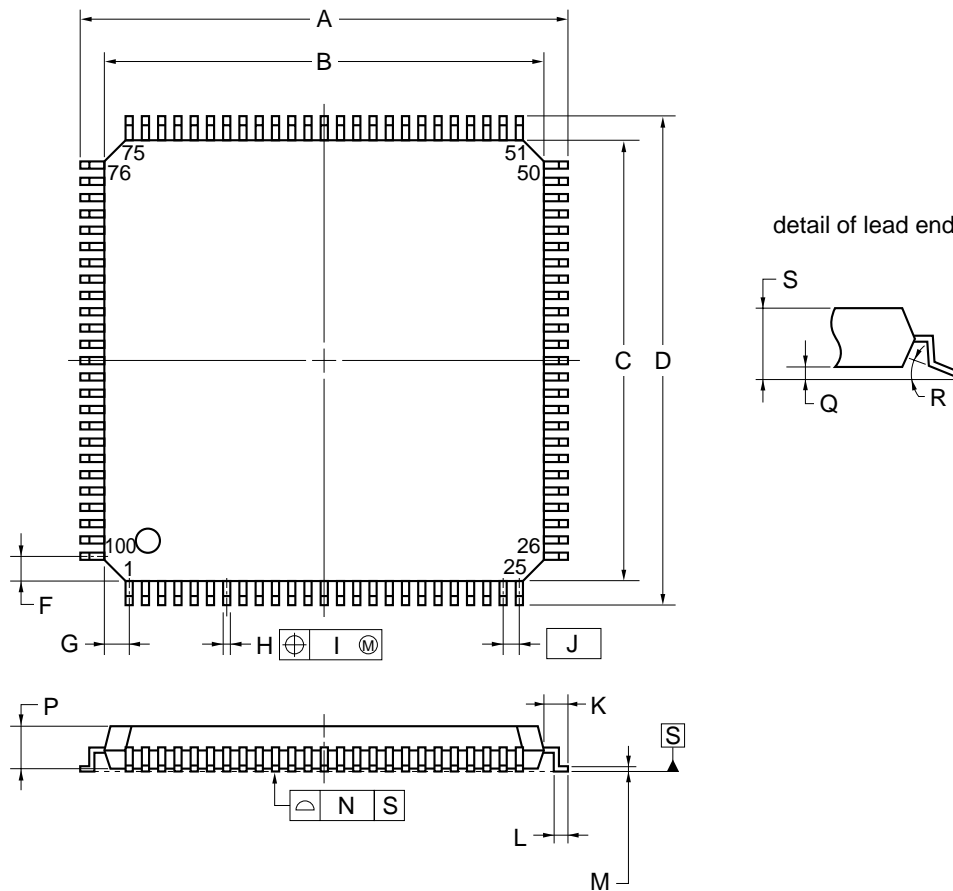
Basic characteristics (T<sub>A</sub> = 10 to 85°C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Operating frequency	f <sub>X</sub>		2		20	MHz
Power supply voltage	V <sub>DD</sub>		4.5		5.5	V
Write current	I <sub>DDW</sub>	When V <sub>PP</sub> = V <sub>PP1</sub>	V <sub>DD</sub> pin		63	mA
	I <sub>PPW</sub>		V <sub>PP</sub> pin		50	mA
Erase current	I <sub>DDE</sub>	When V <sub>PP</sub> = V <sub>PP1</sub>	V <sub>DD</sub> pin		63	mA
	I <sub>PPE</sub>		V <sub>PP</sub> pin		100	mA
V <sub>PP</sub> power supply voltage	V <sub>PP0</sub>	During normal operation	0		0.6	V
	V <sub>PP1</sub>	During flash memory programming	7.5	7.8	8.1	V
Write count <sup>Note</sup>	C <sub>WRT</sub>		20	20	20	Times
Unit erase time	t <sub>ER</sub>		0.2	0.2	0.2	s
Total erase time	t <sub>ERT</sub>				5.8	s

**Note** Erase/write are regarded as 1 cycle.

5. PACKAGE DRAWINGS

100-PIN PLASTIC LQFP (FINE PITCH) (14x14)



NOTE

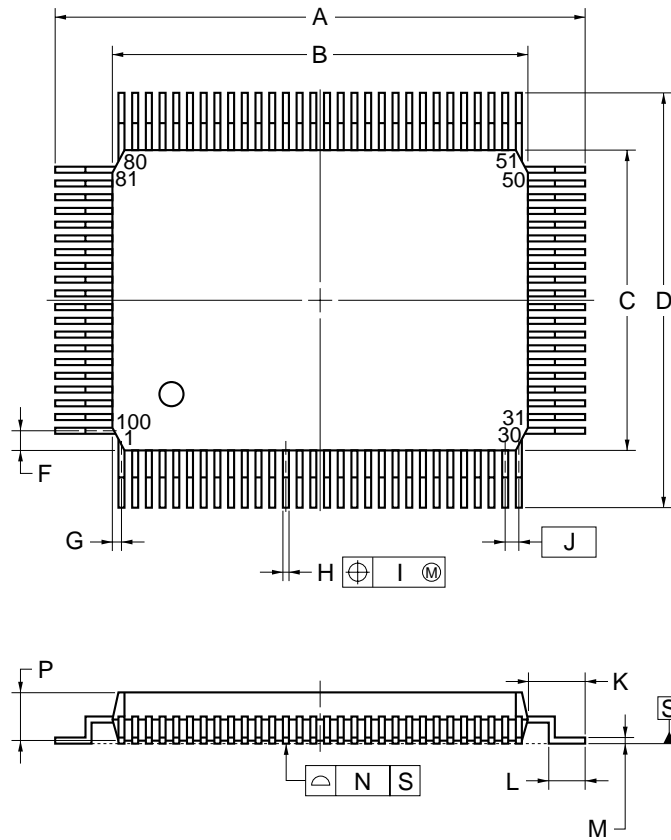
Each lead centerline is located within 0.08 mm of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS
A	16.00±0.20
B	14.00±0.20
C	14.00±0.20
D	16.00±0.20
F	1.00
G	1.00
H	0.22 <sup>+0.05</sup> <sub>-0.04</sub>
I	0.08
J	0.50 (T.P.)
K	1.00±0.20
L	0.50±0.20
M	0.17 <sup>+0.03</sup> <sub>-0.07</sub>
N	0.08
P	1.40±0.05
Q	0.10±0.05
R	3° <sup>+7°</sup> <sub>-3°</sub>
S	1.60 MAX.

S100GC-50-8EU-1



100-PIN PLASTIC QFP (14x20)



detail of lead end

NOTE

Each lead centerline is located within 0.15 mm of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS
A	23.6±0.4
B	20.0±0.2
C	14.0±0.2
D	17.6±0.4
F	0.8
G	0.6
H	0.30±0.10
I	0.15
J	0.65 (T.P.)
K	1.8±0.2
L	0.8±0.2
M	0.15 <sup>+0.10</sup> <sub>-0.05</sub>
N	0.10
P	2.7±0.1
Q	0.1±0.1
R	5°±5°
S	3.0 MAX.

P100GF-65-3BA1-4

6. RECOMMENDED SOLDERING CONDITIONS

The μPD703031A, 703031AY, 703033A, 703033AY, 70F3033A, and 70F3033AY should be soldered and mounted under the following recommended conditions.

For the details of the recommended soldering conditions, refer to the document **Semiconductor Device Mounting Technology Manual (C10535E)**.

For soldering methods and conditions other than those recommended below, contact your NEC sales representative.

Table 6-1. Surface Mounting Type Soldering Conditions (1/2)

- (1) μPD703031AGC-xxx-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)
- μPD703031AYGC-xxx-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)
- μPD703033AGC-xxx-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)
- μPD703033AYGC-xxx-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less Exposure limit: 7 days <sup>Note</sup> (after that, prebake at 125°C for 10 hours)	IR35-107-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less Exposure limit: 7 days <sup>Note</sup> (after that, prebake at 125°C for 10 hours)	VP15-107-2
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	—

**Note** After opening the dry pack, store it at 25°C or less and 65% RH or less for the allowable storage period.

**Caution** Do not use different soldering methods together (except for partial heating).

- (2) μPD70F3033AGC-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)
- μPD70F3033AYGC-8EU: 100-pin plastic LQFP (fine pitch) (14 × 14)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less Exposure limit: 3 days <sup>Note</sup> (after that, prebake at 125°C for 10 hours)	IR35-103-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less Exposure limit: 3 days <sup>Note</sup> (after that, prebake at 125°C for 10 hours)	VP15-103-2
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	—

**Note** After opening the dry pack, store it at 25°C or less and 65% RH or less for the allowable storage period.

**Caution** Do not use different soldering methods together (except for partial heating).

Table 6-1. Surface Mounting Type Soldering Conditions (2/2)

- (3) μPD703031AGF-xxx-3BA: 100-pin plastic QFP (14 × 20)
- μPD703031AYGF-xxx-3BA: 100-pin plastic QFP (14 × 20)
- μPD703033AGF-xxx-3BA: 100-pin plastic QFP (14 × 20)
- μPD703033AYGF-xxx-3BA: 100-pin plastic QFP (14 × 20)
- μPD70F3033AGF-3BA: 100-pin plastic QFP (14 × 20)
- μPD70F3033AYGF-3BA: 100-pin plastic QFP (14 × 20)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less Exposure limit: 7 days <sup>Note</sup> (after that, prebake at 125°C for 20 hours)	IR35-207-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less Exposure limit: 7 days <sup>Note</sup> (after that, prebake at 125°C for 20 hours)	VP15-207-2
Wave soldering	Solder bath temperature: 260°C max., Time: 10 seconds max., Count: once Preheating temperature: 120°C max. (package surface temperature) Exposure limit: 7 days <sup>Note</sup> (after that, prebake at 125°C for 20 hours)	WS60-207-1
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	–

**Note** After opening the dry pack, store it at 25°C or less and 65% RH or less for the allowable storage period.

**Caution** Do not use different soldering methods together (except for partial heating).

[MEMO]

[MEMO]

## NOTES FOR CMOS DEVICES

**① PRECAUTION AGAINST ESD FOR SEMICONDUCTORS**

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

**② HANDLING OF UNUSED INPUT PINS FOR CMOS**

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to  $V_{DD}$  or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

**③ STATUS BEFORE INITIALIZATION OF MOS DEVICES**

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

**Caution** Purchase of NEC I<sup>2</sup>C components conveys a license under the Philips I<sup>2</sup>C Patent Rights to use these components in an I<sup>2</sup>C system, provided that the system conforms to the I<sup>2</sup>C Standard Specification as defined by Philips.

**Reference document** Electrical Characteristics for Microcomputer (IEI-601)<sup>Note</sup>

**Note** This document number is that of the Japanese version.

**V850/SB1, V850/SB2, and V850 Family are trademarks of NEC Corporation.**

## Regional Information

Some information contained in this document may vary from country to country. Before using any NEC product in your application, please contact the NEC office in your country to obtain a list of authorized representatives and distributors. They will verify:

- Device availability
- Ordering information
- Product release schedule
- Availability of related technical literature
- Development environment specifications (for example, specifications for third-party tools and components, host computers, power plugs, AC supply voltages, and so forth)
- Network requirements

In addition, trademarks, registered trademarks, export restrictions, and other legal issues may also vary from country to country.

### NEC Electronics Inc. (U.S.)

Santa Clara, California  
Tel: 408-588-6000  
800-366-9782  
Fax: 408-588-6130  
800-729-9288

### NEC Electronics (Germany) GmbH

Duesseldorf, Germany  
Tel: 0211-65 03 02  
Fax: 0211-65 03 490

### NEC Electronics (UK) Ltd.

Milton Keynes, UK  
Tel: 01908-691-133  
Fax: 01908-670-290

### NEC Electronics Italiana s.r.l.

Milano, Italy  
Tel: 02-66 75 41  
Fax: 02-66 75 42 99

### NEC Electronics (Germany) GmbH

Benelux Office  
Eindhoven, The Netherlands  
Tel: 040-2445845  
Fax: 040-2444580

### NEC Electronics (France) S.A.

Velizy-Villacoublay, France  
Tel: 01-30-67 58 00  
Fax: 01-30-67 58 99

### NEC Electronics (France) S.A.

Spain Office  
Madrid, Spain  
Tel: 91-504-2787  
Fax: 91-504-2860

### NEC Electronics (Germany) GmbH

Scandinavia Office  
Taeby, Sweden  
Tel: 08-63 80 820  
Fax: 08-63 80 388

### NEC Electronics Hong Kong Ltd.

Hong Kong  
Tel: 2886-9318  
Fax: 2886-9022/9044

### NEC Electronics Hong Kong Ltd.

Seoul Branch  
Seoul, Korea  
Tel: 02-528-0303  
Fax: 02-528-4411

### NEC Electronics Singapore Pte. Ltd.

United Square, Singapore 1130  
Tel: 65-253-8311  
Fax: 65-250-3583

### NEC Electronics Taiwan Ltd.

Taipei, Taiwan  
Tel: 02-2719-2377  
Fax: 02-2719-5951

### NEC do Brasil S.A.

Electron Devices Division  
Rodovia Presidente Dutra, Km 214  
07210-902-Guarulhos-SP Brasil  
Tel: 55-11-6465-6810  
Fax: 55-11-6465-6829

J99.1

The export of these products from Japan is regulated by the Japanese government. The export of some or all of these products may be prohibited without governmental license. To export or re-export some or all of these products from a country other than Japan may also be prohibited without a license from that country. Please call an NEC sales representative.

- **The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version.**

- No part of this document may be copied or reproduced in any form or by any means without the prior written consent of NEC Corporation. NEC Corporation assumes no responsibility for any errors which may appear in this document.
- NEC Corporation does not assume any liability for infringement of patents, copyrights or other intellectual property rights of third parties by or arising from use of a device described herein or any other liability arising from use of such device. No license, either express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of NEC Corporation or others.
- Descriptions of circuits, software, and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software, and information in the design of the customer's equipment shall be done under the full responsibility of the customer. NEC Corporation assumes no responsibility for any losses incurred by the customer or third parties arising from the use of these circuits, software, and information.
- While NEC Corporation has been making continuous effort to enhance the reliability of its semiconductor devices, the possibility of defects cannot be eliminated entirely. To minimize risks of damage or injury to persons or property arising from a defect in an NEC semiconductor device, customers must incorporate sufficient safety measures in its design, such as redundancy, fire-containment, and anti-failure features.
- NEC devices are classified into the following three quality grades:  
"Standard", "Special", and "Specific". The Specific quality grade applies only to devices developed based on a customer designated "quality assurance program" for a specific application. The recommended applications of a device depend on its quality grade, as indicated below. Customers must check the quality grade of each device before using it in a particular application.

Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots

Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)

Specific: Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

The quality grade of NEC devices is "Standard" unless otherwise specified in NEC's Data Sheets or Data Books. If customers intend to use NEC devices for applications other than those specified for Standard quality grade, they should contact an NEC sales representative in advance.